

```

import cv2
import numpy as np
from google.colab.patches import cv2_imshow
from matplotlib import pyplot as plt
from skimage.metrics import
mean_squared_error, peak_signal_noise_ratio, structural_similarity

img1=cv2.imread("/content/Screenshot (2).png")
img2=cv2.imread("/content/Screenshot (3).png")

img1.shape

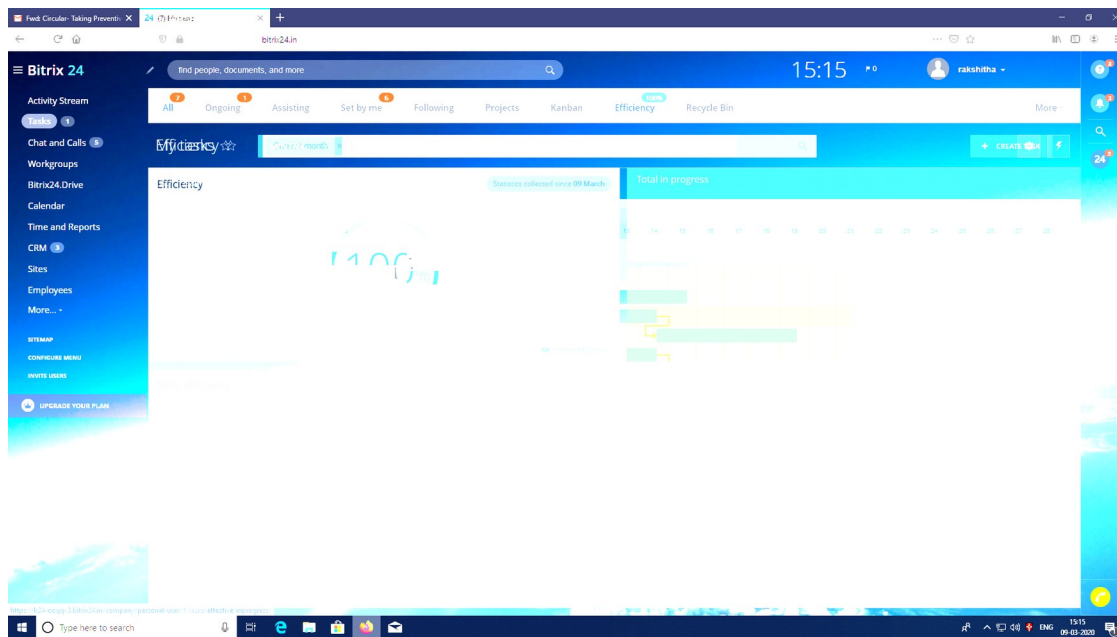
(1080, 1920, 3)

img2.shape

(1080, 1920, 3)

img3=cv2.add(img1,img2)
cv2_imshow(img3)

```



```

img4=cv2.subtract(img1,img2)
cv2_imshow(img4)

```


Browser tabs: Fwd: Circular- Taking Preventiv... 24 (7) Efficiency

Address bar: <https://b24-ooqqv3.bitrix24.in/company/personal/user/1/tasks/effective/>

Search bar: find people, documents, and more


Navigation tabs: All (7), Ongoing (1), Assisting, Set by me (6), Following, Projects, Kanban

Efficiency ☆

Current month x

Efficiency

Statistics collected since 05



100%

How doe

Daily efficiency

UPGRADE YOUR PLAN

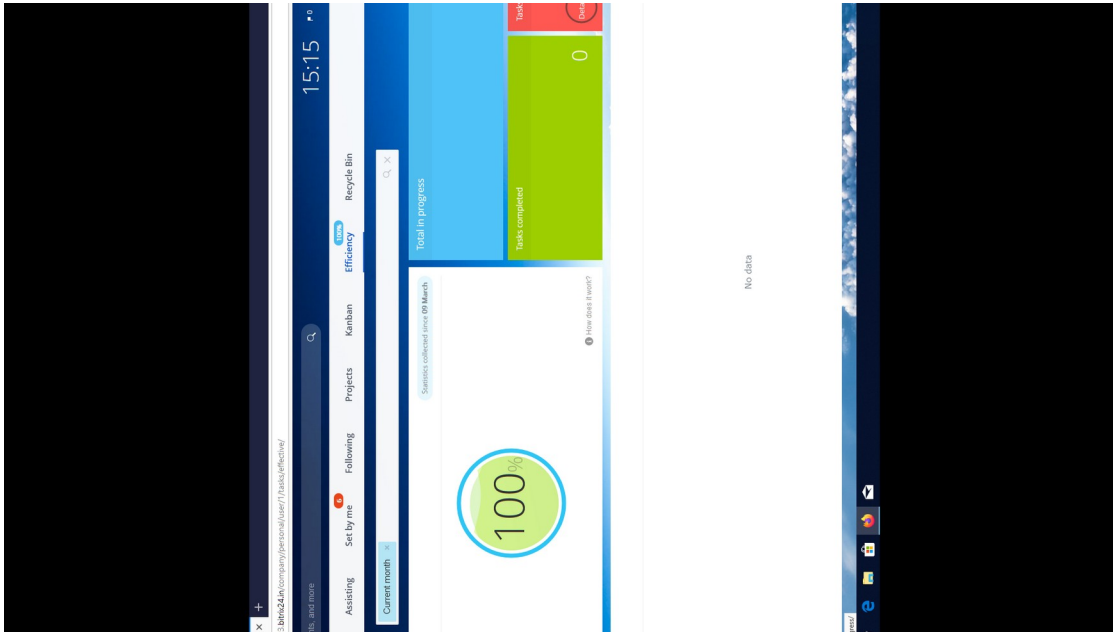
Windows taskbar: Type here to search, icons for File Explorer, Edge, Mail, etc.

Address bar: <https://b24-ooqqv3.bitrix24.in/company/personal/user/1/tasks/effective/inprogress/>

```

rows,cols,cha=img1.shape
M = cv2.getRotationMatrix2D(((cols-1)/2.0,(rows-1)/2.0),90,1)
dst = cv2.warpAffine(img1,M,(cols,rows))
cv2_imshow(dst)

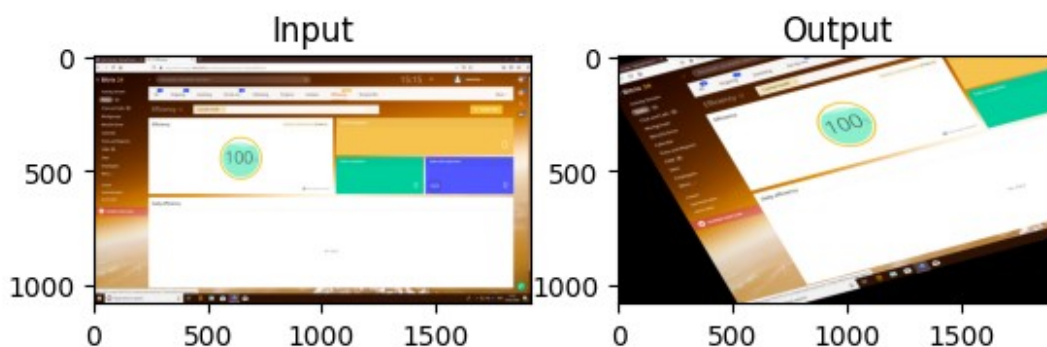
```



```

rows,cols,ch = img1.shape
pts1 = np.float32([[50,50],[200,50],[50,200]])
pts2 = np.float32([[10,100],[200,50],[100,250]])
M = cv2.getAffineTransform(pts1,pts2)
dst = cv2.warpAffine(img1,M,(cols,rows))
plt.subplot(121),plt.imshow(img1),plt.title('Input')
plt.subplot(122),plt.imshow(dst),plt.title('Output')
plt.show()

```

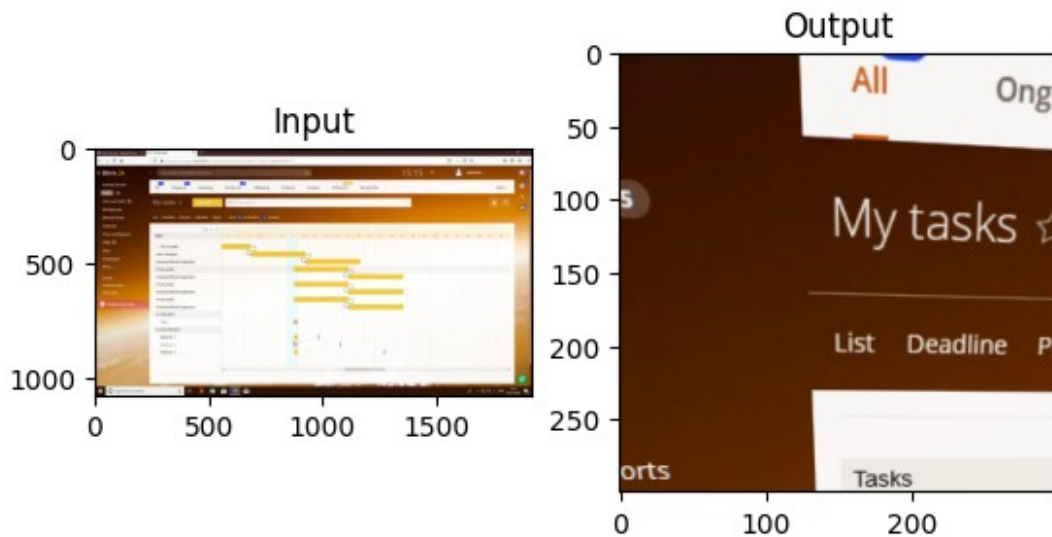


```

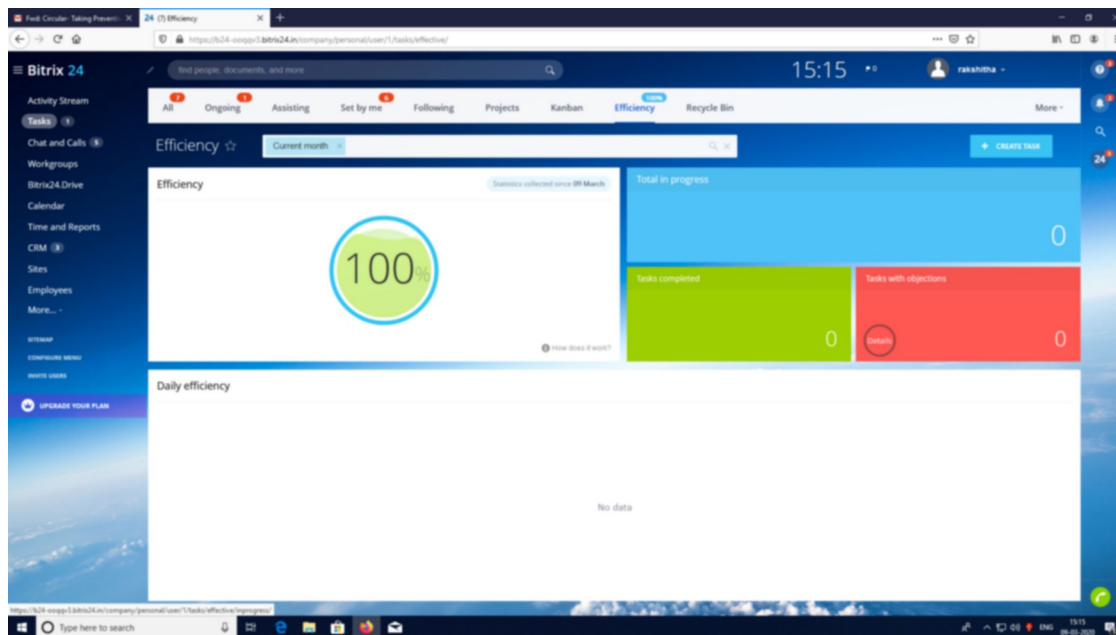
pts1 = np.float32([[156,165],[368,152],[128,387],[389,390]])
pts2 = np.float32([[0,0],[300,0],[0,300],[300,300]])
M = cv2.getPerspectiveTransform(pts1,pts2)
dst = cv2.warpPerspective(img2,M,(300,300))
plt.subplot(121),plt.imshow(img2),plt.title('Input')

```

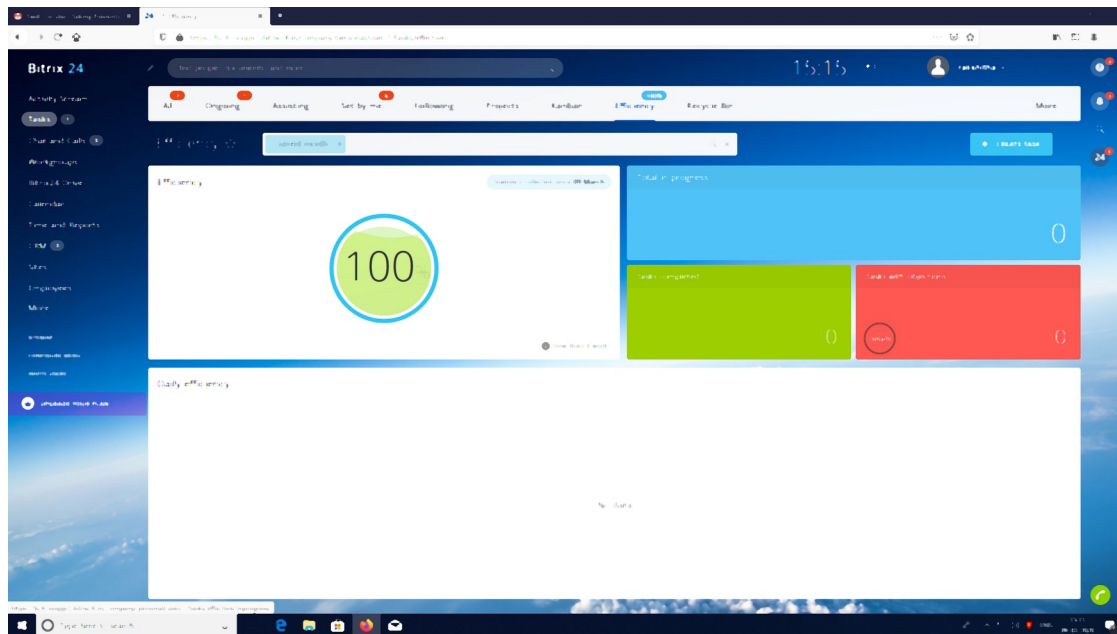
```
plt.subplot(122),plt.imshow(dst),plt.title('Output')
plt.show()
```



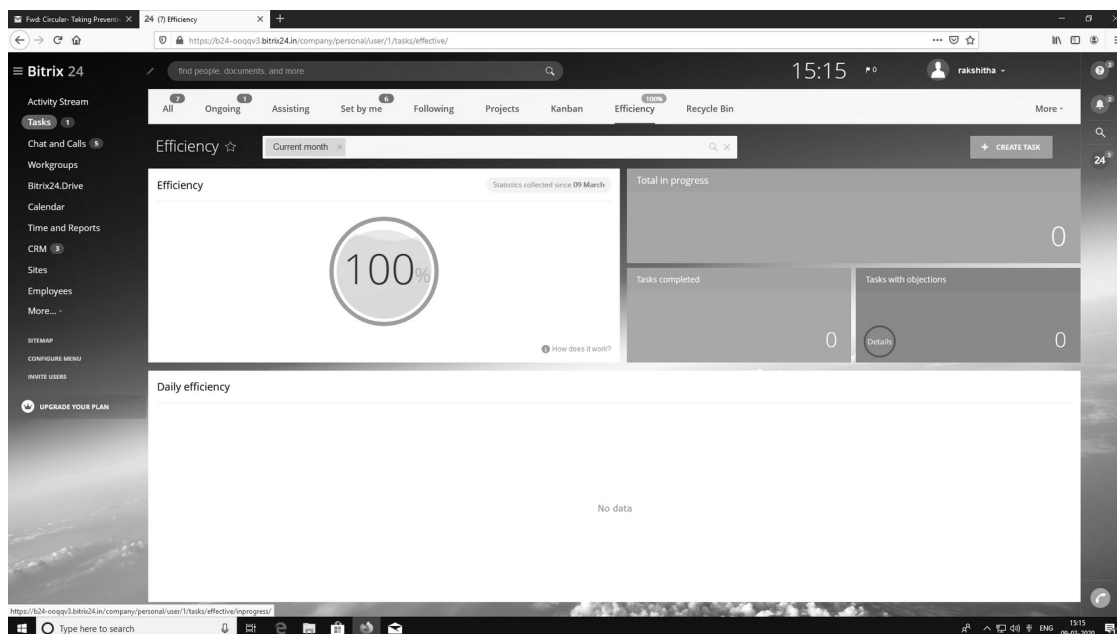
```
Gaussian = cv2.GaussianBlur(img1, (7, 7), 0)
cv2_imshow( Gaussian)
```



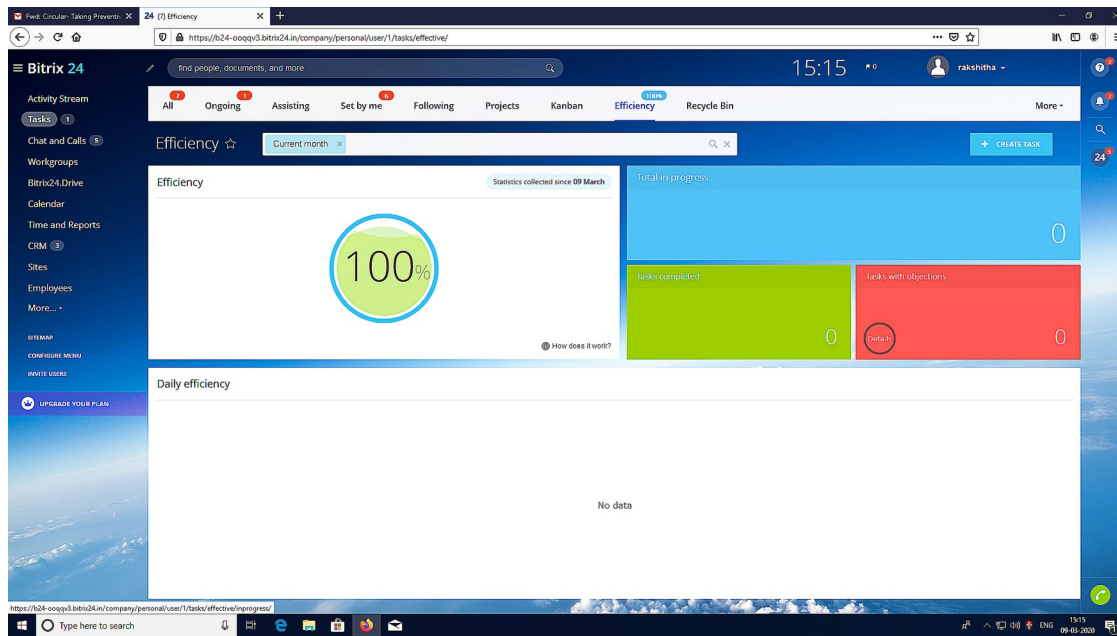
```
median = cv2.medianBlur(img1, 5)
cv2_imshow(median)
```



```
gray = cv2.cvtColor(img1, cv2.COLOR_BGR2GRAY)
cv2_imshow(gray)
```



```
kernel = np.array([[0, -1, 0],
                   [-1, 5, -1],
                   [0, -1, 0]])
image_sharp = cv2.filter2D(src=img1, ddepth=-1, kernel=kernel)
cv2_imshow(image_sharp)
```

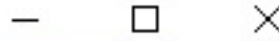


```
capimg=cv2.imread("/content/91190Capture.png")

kernel = np.array([[0, -1, 0],
                   [-1, 5, -1],
                   [0, -1, 0]])

image_sharp = cv2.filter2D(src=capimg, ddepth=-1, kernel=kernel)
cv2_imshow(image_sharp)
```


AV CV- Winter Wonder



```
img1=cv2.imread("/content/Screenshot-from-2022-07-28-16-15-43.png")  
cv2_imshow(img1)
```



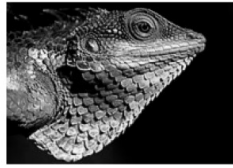

```
gray1=cv2.cvtColor(imga1,cv2.COLOR_BGR2GRAY)
cv2_imshow(gray1)
```



```
blurred = cv2.GaussianBlur(gray1, (5, 5), 0)
# Perform the canny operator
canny = cv2.Canny(blurred, 30, 150)

fig,ax = plt.subplots(1,2,figsize=(18, 18))
ax[0].imshow(gray1,cmap='gray')
ax[1].imshow(canny,cmap='gray')
ax[0].axis('off')
ax[1].axis('off')

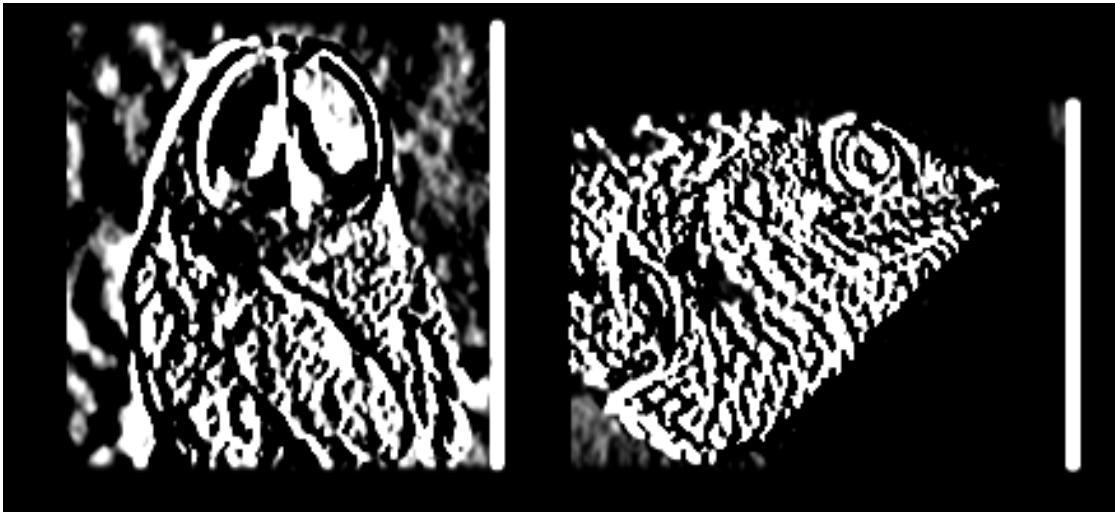
(-0.5, 439.5, 199.5, -0.5)
```



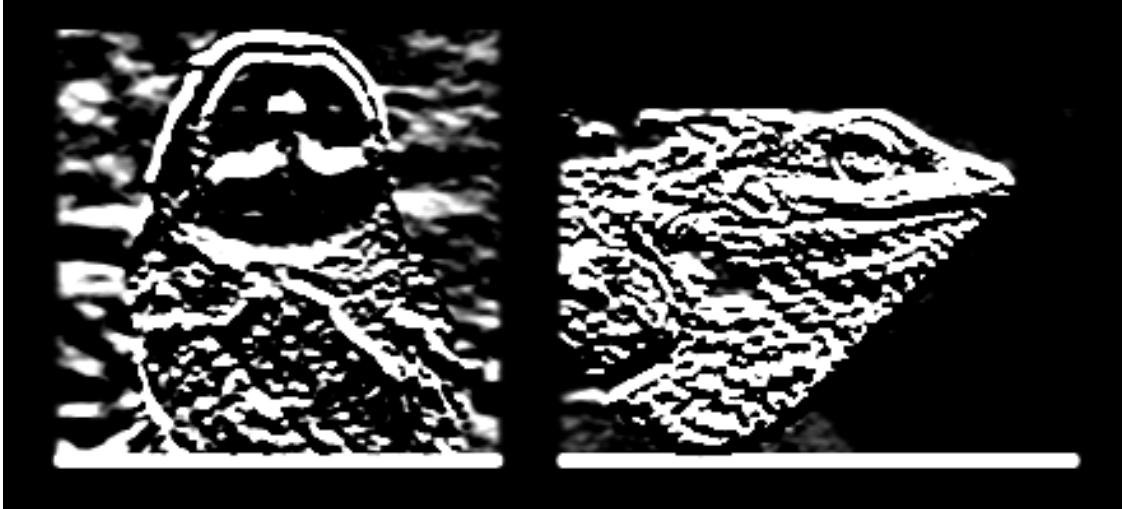
```
# Convert to grayscale
img_gray = cv2.cvtColor(imga1, cv2.COLOR_BGR2GRAY)
# Blur the image for better edge detection
img_blur = cv2.GaussianBlur(img_gray, (3,3), 0)

sobelx = cv2.Sobel(src=img_blur, ddepth=cv2.CV_64F, dx=1, dy=0,
ksize=5) # Sobel Edge Detection on the X axis
sobely = cv2.Sobel(src=img_blur, ddepth=cv2.CV_64F, dx=0, dy=1,
ksize=5) # Sobel Edge Detection on the Y axis
sobelxy = cv2.Sobel(src=img_blur, ddepth=cv2.CV_64F, dx=1, dy=1,
ksize=5)

cv2.imshow( sobelx);
```



```
cv2.imshow( sobely);
```



```
cv2_imshow( sobelxy);
```

