

Q1 LSTM Numerical - (Forward Pass)

$$x_t = [0.5, -0.1]^T \approx \mathbb{R}^2$$

$$h_{t-1} = [0.0, 0.1]^T \approx \mathbb{R}^2$$

$$c_{t-1} = [0.2, -0.2]^T \approx \mathbb{R}^2$$

$$w_{xi} = \begin{bmatrix} 0.5 & -0.3 \\ 0.4 & 0.1 \end{bmatrix}$$

$$w_{hi} = \begin{bmatrix} 0.1 & 0.2 \\ -0.2 & 0.05 \end{bmatrix}$$

Find out
h_t and c_t

$$w_{xf} = \begin{bmatrix} -0.4 & 0.2 \\ 0.3 & 0.3 \end{bmatrix}$$

$$w_{hf} = \begin{bmatrix} 0.05 & -0.1 \\ 0.2 & 0.1 \end{bmatrix}$$

$$w_{xo} = \begin{bmatrix} 0.3 & 0.25 \\ -0.2 & 0.2 \end{bmatrix}$$

$$w_{ho} = \begin{bmatrix} 0.15 & 0.05 \\ 0.1 & -0.2 \end{bmatrix}$$

$$w_{xg} = \begin{bmatrix} -0.5 & 0.4 \\ 0.2 & -0.3 \end{bmatrix}$$

$$w_{hg} = \begin{bmatrix} 0.2 & 0.1 \\ -0.1 & 0.05 \end{bmatrix}$$

$$\text{Ans. :- } \hat{t}_t = \sigma(W_{hi}h_{t-1} + W_{xi}x_t)$$

$$W_{hi}h_{t-1} = \begin{bmatrix} 0.1 & 0.2 \\ -0.2 & 0.05 \end{bmatrix}_{2 \times 2} \cdot \begin{bmatrix} 0.0 & 0.1 \end{bmatrix}_{1 \times 2}^T$$

$$W_{hi}h_{t-1} = \begin{bmatrix} (0.1 \times 0.0) + (0.1 \times 0.1) \\ (-0.2 \times 0.0) + (0.05 \times 0.1) \end{bmatrix}_{2 \times 1} = \begin{bmatrix} 0.0 \\ 0.1 \end{bmatrix}_{2 \times 1}$$

$$W_{hi}h_{t-1} = \begin{bmatrix} 0 + 0.02 \\ 0 + 0.005 \end{bmatrix} = \begin{bmatrix} 0.02 \\ 0.005 \end{bmatrix}_{2 \times 1}$$

$$W_{xi}x_t = \begin{bmatrix} 0.5 & -0.3 \\ 0.4 & 0.1 \end{bmatrix} \cdot \begin{bmatrix} 0.5 \\ -0.1 \end{bmatrix}$$

$$W_{xi}x_t = \begin{bmatrix} (0.5 \times 0.5) + (-0.3 \times -0.1) \\ (0.4 \times 0.5) + (0.1 \times -0.1) \end{bmatrix} = \begin{bmatrix} 0.25 + 0.03 \\ 0.2 + (-0.01) \end{bmatrix}$$

$$W_{xi}x_t = \begin{bmatrix} 0.28 \\ 0.19 \end{bmatrix}$$

$$W_{hi}h_{t-1} + W_{xi}x_t = \begin{bmatrix} 0.02 \\ 0.005 \end{bmatrix} + \begin{bmatrix} 0.28 \\ 0.19 \end{bmatrix}$$

$$W_{hi}h_{t-1} + W_{xi}x_t = \begin{bmatrix} 0.3 \\ 0.195 \end{bmatrix}$$

$$\sigma \begin{bmatrix} 0.3 \\ 0.195 \end{bmatrix} = \begin{bmatrix} \frac{1}{1+e^{-0.3}} \\ \frac{1}{1+e^{-0.195}} \end{bmatrix} = \begin{bmatrix} 0.57 \\ 0.54 \end{bmatrix}$$

$$f_t = \tanh(w_{xg}x_{t-1} + w_{xg}x_t)$$

$$\begin{aligned}w_{xg}x_{t-1} &= \begin{bmatrix} 0.2 & 0.1 \\ -0.1 & 0.05 \end{bmatrix} \begin{bmatrix} 0.1 \\ 0.1 \end{bmatrix} \\&= \begin{bmatrix} (0.0 \times 0.2) + (0.1 \times 0.1) \\ (-0.1 \times 0.0) + (0.05 \times 0.1) \end{bmatrix} \\&= \begin{bmatrix} 0 + 0.01 \\ 0 + 0.005 \end{bmatrix} = \begin{bmatrix} 0.01 \\ 0.005 \end{bmatrix}\end{aligned}$$

$$\begin{aligned}w_{xg}x_t &= \begin{bmatrix} -0.5 & 0.4 \\ 0.2 & -0.3 \end{bmatrix} \begin{bmatrix} 0.5 \\ -0.1 \end{bmatrix} \\&= \begin{bmatrix} (0.5 \times -0.5) + (0.4 \times -0.1) \\ (0.2 \times 0.5) + (-0.3 \times -0.1) \end{bmatrix} \\&= \begin{bmatrix} -0.25 - 0.04 \\ 0.1 + 0.03 \end{bmatrix} = \begin{bmatrix} -0.29 \\ 0.13 \end{bmatrix}\end{aligned}$$

$$\begin{aligned}w_{xg}x_{t-1} + w_{xg}x_t &= \begin{bmatrix} 0.01 - 0.29 \\ 0.005 + 0.13 \end{bmatrix} \\&= \begin{bmatrix} -0.28 \\ 0.135 \end{bmatrix}\end{aligned}$$

$$\tanh \begin{bmatrix} -0.28 \\ 0.135 \end{bmatrix} = \begin{bmatrix} -0.27 \\ 0.13 \end{bmatrix}$$

$$y_t = \sigma (w_{yf} d_{t-1} + w_{xf} x_t)$$

$$\begin{aligned} w_{yf} d_{t-1} &= \begin{bmatrix} 0.05 & -0.1 \\ 0.2 & 0.1 \end{bmatrix} \begin{bmatrix} 0.10 \\ 0.1 \end{bmatrix} \\ &= \begin{bmatrix} 0 - 0.10 \\ 0 + 0.10 \end{bmatrix} = \begin{bmatrix} -0.10 \\ 0.10 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} w_{xf} x_t &= \begin{bmatrix} -0.4 & 0.2 \\ 0.3 & 0.3 \end{bmatrix} \begin{bmatrix} 0.5 \\ -0.1 \end{bmatrix} \\ &= \begin{bmatrix} -0.2 - 0.02 \\ 0.15 - 0.03 \end{bmatrix} = \begin{bmatrix} -0.22 \\ 0.12 \end{bmatrix} \end{aligned}$$

$$w_{yf} d_{t-1} + w_{xf} x_t = \begin{bmatrix} -0.23 \\ 0.13 \end{bmatrix}$$

$$\sigma \begin{bmatrix} -0.23 \\ 0.13 \end{bmatrix} = \begin{bmatrix} \frac{1}{1+e^{-0.23}} \\ \frac{1}{1+e^{0.13}} \end{bmatrix} = \begin{bmatrix} 0.44 \\ 0.53 \end{bmatrix}$$

element-wise multiplication

$$\boxed{y_t \circ g_t} \Rightarrow \begin{bmatrix} 0.57 \\ 0.54 \end{bmatrix} \odot \begin{bmatrix} -0.27 \\ 0.13 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 0.57 \times -0.27 \\ 0.54 \times 0.13 \end{bmatrix} = \begin{bmatrix} -0.15 \\ 0.07 \end{bmatrix}$$

$$\begin{aligned} \boxed{y_t \circ c_{t-1}} &\Rightarrow \begin{bmatrix} 0.44 \\ 0.53 \end{bmatrix} \odot \begin{bmatrix} 0.2 \\ -0.2 \end{bmatrix} \\ &\Rightarrow \begin{bmatrix} 0.088 \\ -0.106 \end{bmatrix} \end{aligned}$$

$$C_t = \gamma_t \Theta C_{t-1} + i_t \Theta g_t$$

$$C_t = \begin{bmatrix} 0.088 \\ -0.106 \end{bmatrix} + \begin{bmatrix} -0.15 \\ 0.07 \end{bmatrix}$$

$$C_t = \begin{bmatrix} -0.06 \\ -0.03 \end{bmatrix}$$

$$O_t = \sigma (w_{ho} d_{t-1} + w_{x_0} x_t)$$

$$w_{ho} d_{t-1} = \begin{bmatrix} 0.15 & 0.05 \\ 0.1 & -0.2 \end{bmatrix} \begin{bmatrix} 0.0 \\ 0.1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 + 0.005 \\ 0 - 0.02 \end{bmatrix} = \begin{bmatrix} 0.005 \\ -0.02 \end{bmatrix}$$

$$w_{x_0} x_t = \begin{bmatrix} 0.3 & 0.25 \\ -0.2 & 0.2 \end{bmatrix} \begin{bmatrix} 0.5 \\ -0.1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.15 + (-0.025) \\ -0.1 - 0.02 \end{bmatrix} = \begin{bmatrix} 0.125 \\ -0.12 \end{bmatrix}$$

$$w_{ho} d_{t-1} + w_{x_0} x_t = \begin{bmatrix} 0.13 \\ -0.14 \end{bmatrix}$$

$$\Gamma \begin{bmatrix} 0.13 \\ -0.14 \end{bmatrix} = \begin{bmatrix} \frac{1}{1+e^{-0.13}} \\ \frac{1}{1+e^{0.14}} \end{bmatrix} = \begin{bmatrix} 0.53 \\ 0.46 \end{bmatrix}$$

$h_t = \Theta \circ \tanh(c_t)$

$$\tanh(c_t) = \tanh \begin{bmatrix} -0.06 \\ -0.03 \end{bmatrix} = \begin{bmatrix} -0.05 \\ -0.029 \end{bmatrix}$$

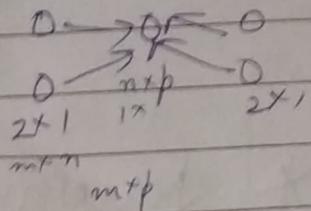
$$h_t = \begin{bmatrix} 0.53 \\ 0.46 \end{bmatrix} \odot \begin{bmatrix} -0.05 \\ -0.029 \end{bmatrix} = \begin{bmatrix} -0.026 \approx -0.03 \\ -0.013 \end{bmatrix}$$

$$x \in \mathbb{R}^2, x = \begin{bmatrix} 2 \\ 0 \end{bmatrix}_{2 \times 1}$$

Autoencoder Numerical

$$h \in \mathbb{R}^1$$

↪ context vector



What, W_e , W_d size?

$$\text{Ans: } W_e = 1 \times 2 = \begin{bmatrix} 0.5 & -1.0 \end{bmatrix}_{1 \times 2}$$

$$(W) W_d = 2 \times 1 = \begin{bmatrix} 1.0 \\ 0.5 \end{bmatrix}_{2 \times 1}$$

$$\text{MSE loss} = \frac{1}{2} \| \hat{x} - x \|_2^2$$

(b) Compute h , \hat{x} , L .

$$\text{Ans: } h = W_e x$$

$$h = \begin{bmatrix} 0.5 & -1.0 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$h = 2 \times 0.5 + 0 \times (-1.0) = 1.0$$

$$\hat{x} = W_d h$$

$$\hat{x} = \begin{bmatrix} 1.0 \\ 0.5 \end{bmatrix} \times 1.0 = \begin{bmatrix} 1.0 \\ 0.5 \end{bmatrix}$$

$$L = \begin{bmatrix} 1.0 \\ 0.5 \end{bmatrix} - \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0.5 \end{bmatrix}$$

$$L = \frac{1}{2} \times \left(\begin{bmatrix} -1 \\ 0.5 \end{bmatrix} \right)^2 = \frac{1}{2} \times \begin{bmatrix} 1 \\ 0.25 \end{bmatrix}$$

$$L = \begin{bmatrix} 0.5 \\ 0.125 \end{bmatrix}$$

$$L = 0.5 + 0.125$$

$$L = 0.625$$

(Total loss)

Attention Numerical

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$$\mathbf{h}_1 = [1, 0, 1]$$

$$\mathbf{h}_2 = [0, 1, 1]$$

$$\mathbf{h}_3 = [1, 1, 0]$$

$$\mathbf{s}_{t-1} = [1, 0, 1]$$

Score function = dot product

$$c_t = ?$$

$$\text{Ans: } c_t = \sum_{j=1}^3 x_{t,j} \cdot h_j$$

$$c_t = x_{t,1} \cdot h_1 + x_{t,2} \cdot h_2 + x_{t,3} \cdot h_3$$

$$x_{t,j} = \frac{\exp(\text{score}(s_{t-1}, h_j))}{\exp(\text{score}(s_{t-1}, h_1)) + \exp(\text{score}(s_{t-1}, h_2)) + \exp(\text{score}(s_{t-1}, h_3))}$$

$$\begin{aligned} \therefore \text{Score}(s_{t-1}, h_1) &= s_{t-1} \cdot h_1 \\ &= \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \\ &= 1 \times 1 + 0 \times 0 + 1 \times 1 = 2 \end{aligned}$$

$$\begin{aligned} \exp(\text{score}(s_{t-1}, h_1)) &= \exp(2) \\ &= 7.389 \end{aligned}$$

$$\begin{aligned} \text{Score}(s_{t-1}, h_2) &= s_{t-1} \cdot h_2 \\ &= \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \\ &= 0 + 0 + 1 = 1 \\ &= 2.718 \end{aligned}$$

$$\text{Score}(s_{t-1}, a_3) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\frac{\text{dep}}{(\text{score})} = 2.718$$

$$x_{t-1} = \frac{7.389}{7.389 + 2.718 + 2.718} = \frac{7.389}{12.825}$$

$$x_{t-1} = 0.57$$

∴ $x_{t,2} = ?$

$$\text{Score}(s_{t-1}, a_2) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 2.718$$

$$\text{Score}(s_{t-1}, a_3) = 2.718$$

$$\text{Score}(s_{t-1}, a_1) = 7.389$$

$$x_{t-2} = \frac{2.718}{2.718 + 2.718 + 7.389}$$

$$x_{t-2} = 0.211 \approx 0.2$$

∴ $x_{t,3} = ?$

$$x_{t,3} = \frac{2.718}{12.825} = 0.211 \approx 0.2$$

$$\therefore C_t = ?$$

$$x_{t+1} \cdot u_1 = 0.57 \times \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
$$= \begin{bmatrix} 0.57 \\ 0 \\ 0.57 \end{bmatrix}$$

$$x_{t+2} \cdot u_2 = 0.2 \times \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
$$= \begin{bmatrix} 0 \\ 0.2 \\ 0.2 \end{bmatrix}$$

$$x_{t+3} \cdot u_3 = 0.2 \times \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
$$= \begin{bmatrix} 0.2 \\ 0 \\ 0.2 \end{bmatrix}$$

$$C_t = \begin{bmatrix} 0.57 \\ 0 \\ 0.57 \end{bmatrix} + \begin{bmatrix} 0 \\ 0.2 \\ 0.2 \end{bmatrix} + \begin{bmatrix} 0.2 \\ 0 \\ 0.2 \end{bmatrix}$$

$$C_t = \begin{bmatrix} 0.77 \\ 0.4 \\ 0.77 \end{bmatrix} \approx \begin{bmatrix} 0.77 & 0.4 & 0.77 \end{bmatrix}^T$$

~~Q :-~~

Key	Value
[1.0, 0.5, 0.2]	"Action movie" "Die Hard"
[0.3, 1.0, 0.1]	"Romance" "Titanic"
[0.9, 0.4, 0.8]	"Action movie" "John wien"

similarity
(dot product)
Numerical



$Q = \text{"looking for a action movies"}$
 $\downarrow \text{word2vec}$
 $[1.0, 0.3, 0.5]$

Ans:- Dot product

- $Q \odot \text{Key-1} \rightarrow [1.0 \ 0.3 \ 0.5] \odot [1.0 \ 0.5 \ 0.2]$
(rank-2) $\rightarrow 1 + 0.15 + 0.1 = 1.25$
- $Q \odot \text{Key-2} \rightarrow [1.0 \ 0.3 \ 0.5] \odot [0.3 \ 1.0 \ 0.1]$
(rank-3) $\rightarrow 0.3 + 0.3 + 0.05 = 0.65$
- $Q \odot \text{Key-3} \rightarrow [1.0 \ 0.3 \ 0.5] \odot [0.9 \ 0.4 \ 0.8]$
(rank-1) $\rightarrow 0.9 + 0.12 + 0.4 = 1.42$

Q1 Transformers (self-attention) → Scaled dot product Numerical
 $\exists | P \rightarrow \text{Playing Outside}$
 Find q_1 and q_2 ?

Given :- $\begin{cases} q_1 = [0.212 \ 0.04 \ 0.63 \ 0.36]^T \\ K_1 = [0.31 \ 0.84 \ 0.963 \ 0.57]^T \\ V_1 = [0.36 \ 0.83 \ 0.1 \ 0.38]^T \end{cases}$

For "Playing"

$\therefore \begin{cases} q_2 = [0.1 \ 0.14 \ 0.86 \ 0.77]^T \\ K_2 = [0.45 \ 0.94 \ 0.73 \ 0.58]^T \\ V_2 = [0.31 \ 0.36 \ 0.19 \ 0.72]^T \end{cases}$

For "Outside"

Playing

Outside

Ans :-

$\text{Score} \rightarrow q_1 \cdot K_1$

$$\rightarrow \begin{bmatrix} 0.212 \\ 0.04 \\ 0.63 \\ 0.36 \end{bmatrix} \cdot \begin{bmatrix} 0.31 \\ 0.84 \\ 0.963 \\ 0.57 \end{bmatrix}$$

$\text{Score} \rightarrow q_2 \cdot K_1$

$$\rightarrow \begin{bmatrix} 0.1 \\ 0.14 \\ 0.86 \\ 0.77 \end{bmatrix} \cdot \begin{bmatrix} 0.31 \\ 0.84 \\ 0.963 \\ 0.57 \end{bmatrix}$$

$$q_1 \cdot K_1 = 0.06572 \\ + 0.0336 + 0.60669 \\ + 0.2052$$

$$q_1 \cdot K_1 = 0.91121$$

Also, $q_1 \cdot K_2$

$$= \begin{bmatrix} 0.212 \\ 0.64 \\ 0.63 \\ 0.36 \end{bmatrix} \cdot \begin{bmatrix} 0.45 \\ 0.94 \\ 0.73 \\ 0.58 \end{bmatrix}$$

$$q_1 \cdot K_2 = 0.0954 + 0.0376 \\ + 0.4599 + 0.2088$$

$$q_1 \cdot K_2 = 0.8017$$

$$\text{Scaling} \Rightarrow \frac{q_1 \cdot K_1}{\sqrt{K_1}} = \frac{0.91121}{\sqrt{4}}$$

$$= \frac{0.91121}{2} \\ = 0.455605$$

$$\frac{q_1 \cdot K_2}{\sqrt{K_2}} = \frac{0.8017}{2} \\ = 0.40085$$

$$\text{Software-1} \Rightarrow e^{0.455605} \\ + e^{0.40085}$$

$$\Rightarrow \frac{1.577127}{1.577127 + 1.493093}$$

$$q_2 \cdot K_1 = 0.031 + 0.1176 + \\ 1.823 + 0.4389 \\ q_2 \cdot K_1 = 2.4105$$

$$\text{Also, } q_2 \cdot K_2 = \begin{bmatrix} 0.1 \\ 0.14 \\ 0.86 \\ 0.77 \end{bmatrix} \cdot \begin{bmatrix} 0.45 \\ 0.94 \\ 0.73 \\ 0.58 \end{bmatrix}$$

$$q_2 \cdot K_2 = 0.045 + 0.1316 + \\ 0.6278 + 0.4466$$

$$q_2 \cdot K_2 = 1.251$$

$$\text{Scaling} \Rightarrow \frac{q_2 \cdot K_1}{\sqrt{K_1}} = \frac{2.4105}{2}$$

$$= 1.20525$$

$$\Rightarrow \frac{q_2 \cdot K_2}{\sqrt{K_2}} = 0.6255$$

$$\text{Software-1} \Rightarrow \frac{e^{1.20525}}{e^{1.20525} + e^{0.6255}}$$

$$\Rightarrow \frac{3.33759}{3.33759 + 1.086918}$$

$$\Rightarrow \frac{3.33759}{5.20677}$$

$$\Rightarrow 0.64100$$

$$\text{Software-2} \Rightarrow \frac{e^{0.6255}}{e^{1.20525} + e^{0.6255}}$$

$$\Rightarrow 0.35899$$

$$\Rightarrow \frac{1.577127}{3.07022}$$

$$\Rightarrow 0.513685$$

Also,

$$\Rightarrow \frac{0.40085}{3.07022}$$

$$\Rightarrow \frac{1.493093}{3.07022}$$

$$\text{softmax}_2 \Rightarrow 0.486314$$

$$z_1 \Rightarrow \text{softmax}_1 \times v_1 + \text{softmax}_2 \times v_2$$

$$z_1 \Rightarrow 0.513685 \times \begin{bmatrix} 0.36 \\ 0.83 \\ 0.1 \\ 0.38 \end{bmatrix}$$

$$z_2 \Rightarrow \text{softmax}_1 \times v_1 + \text{softmax}_2 \times v_2$$

$$z_2 = 0.64100 \times \begin{bmatrix} 0.36 \\ 0.83 \\ 0.1 \\ 0.38 \end{bmatrix}$$

$$+ 0.35899 \times \begin{bmatrix} 0.31 \\ 0.36 \\ 0.19 \\ 0.72 \end{bmatrix}$$

$$z_2 = \begin{bmatrix} 0.2307 \\ 0.5320 \\ 0.0641 \\ 0.2435 \end{bmatrix} + \begin{bmatrix} 0.1112 \\ 0.1292 \\ 0.0682 \\ 0.2584 \end{bmatrix}$$

$$z_2 = \begin{bmatrix} 0.3419 & 0.6612 & 0.1323 \\ 0.5019 \end{bmatrix}^T$$

~~$$z_2$$~~
$$+ 0.486314 \times \begin{bmatrix} 0.31 \\ 0.36 \\ 0.19 \\ 0.72 \end{bmatrix}$$

$$z_1 \Rightarrow \begin{bmatrix} 0.1836 \\ 0.4233 \\ 0.05 \\ 0.1938 \end{bmatrix} + \begin{bmatrix} 0.1488 \\ 0.1728 \\ 0.0912 \\ 0.3456 \end{bmatrix}$$

$$z_1 \Rightarrow \begin{bmatrix} 0.332 & 0.596 & 0.142 & 0.539 \end{bmatrix}^T$$

Positional Embedding Numerical

Q1

I am a robot



$$PE : d = \mathbb{R}^4 \rightarrow \mathbb{H}$$

I	→	0
am	→	1
a	→	2
robot	→	3
...		

0	→	0
1	→	1
2	→	2
3	→	3

$i=0$	$i=1$
P_{00} sin	P_{01} cos
P_{10}	P_{11}
P_{20}	P_{21}
P_{30}	P_{31}
P_{22}	P_{23}
P_{32}	P_{33}

Notation
↓

$P_{pos\cdot 0}$

$P_{pos\cdot 1}$

$P_{pos\cdot 2}$

$P_{pos\cdot 3}$

Find these four pos. embedding
vectors for your positions?

Degree \rightarrow Radian

$$\hookrightarrow 1 \text{ deg} \times \frac{\pi}{180} = 0.01744 \text{ rad.}$$

Date _____

Aus:- For pos.-o,

- All the values currently are in degrees but later can be converted to radians.

$$P_{00} = \sin \left(\frac{0}{100 \times \frac{2\pi}{4}} \right)$$

$$P_{00} = \sin \left(\frac{0}{100 \times \frac{2(0)}{4}} \right) = \sin(0) = 0$$

(in degrees)

\hookrightarrow convert later into radians

$$P_{01} = \cos \left(\frac{0}{100 \times \frac{2(0)}{4}} \right) = \cos(0) = 1$$

$$P_{02} = \sin \left(\frac{0}{100 \times \frac{2(1)}{4}} \right) = 0$$

$$P_{03} = \cos \left(\frac{0}{100 \times \frac{2(1)}{4}} \right) = 1$$

0	1	0	1
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 $\Rightarrow \text{For pos.-o}$

Now, for pos.-1,

$$P_{10} = \sin \left(\frac{1}{100 \times \frac{2(0)}{4}} \right) = \sin(1) = 0.017 \approx 0$$

$$P_{11} = \cos \left(\frac{1}{100 \times \frac{2(0)}{4}} \right) = \cos(1) = 0.99 \approx 1$$

$$P_{12} = \sin \left(\frac{1}{100 \times \frac{2(1)}{4}} \right) = \sin \left(\frac{1}{50} \right)$$

$$= \sin(0.02)$$

$$= 0.0003$$

$$= \sin \left(\frac{1}{100 \times 0.5} \right)$$

$$= \sin \left(\frac{1}{50} \right) = 0.9997$$

$$P_{13} = \cos\left(\frac{1}{100^{(0.5)}}\right) = \cos\left(\frac{1}{10}\right) = 0.999$$

Now, for pos. -2,

$$P_{20} = \sin\left(\frac{2}{100^{(2(0)/4)}}\right) = \sin\left(\frac{2}{10}\right) = 0.0348$$

$$P_{21} = \cos\left(\frac{2}{100^{(2(1)/4)}}\right) = \cos(2) = 0.99$$

$$\begin{aligned} P_{22} &= \sin\left(\frac{2}{100^{(2(1)/4)}}\right) = \sin(0.2) \\ &= 3.49 \times 10^{-3} \\ &= \frac{3.49}{100000} \\ &= 0.00349 \end{aligned}$$

$$P_{23} = \cos\left(\frac{2}{100^{(2(1)/4)}}\right) = \cos(0.2) = 0.99$$

For pos. -2 \Rightarrow

$$\begin{array}{|c|c|c|c|c|} \hline & 0.0348 & 0.99 & 0.00349 & 0.99 \\ \hline \end{array}$$

$$P_{30} = \sin\left(\frac{3}{100^{(2(0)/4)}}\right) = \sin(3) = 0.05$$

$$P_{31} = \cos\left(\frac{3}{100^{(2(0)/4)}}\right) = \cos(3) = 0.99$$

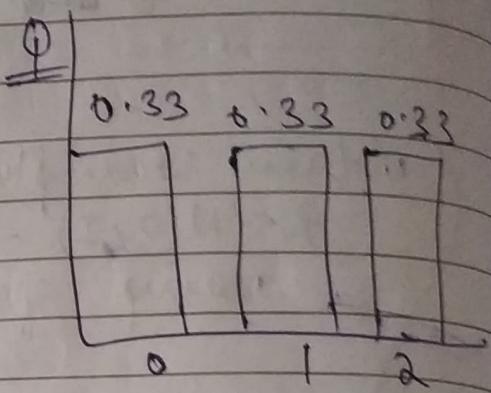
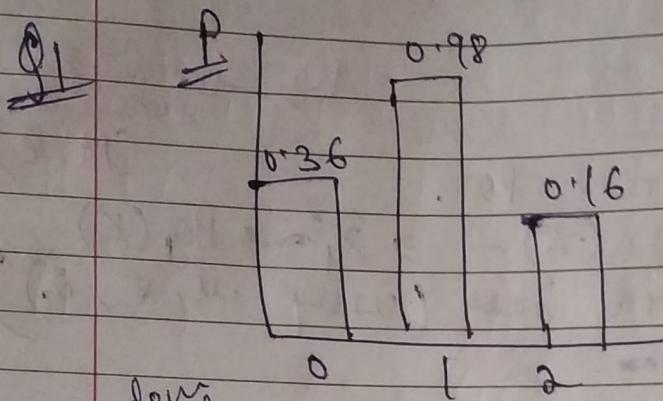
$$P_{32} = \sin\left(\frac{3}{100^{(2(1)/4)}}\right) = \sin(0.3) = 5.23 \times 10^{-3} = 0.00523$$

$$P_{33} = \cos\left(\frac{3}{100^{(2(1)/4)}}\right) = \cos(0.3) = 0.99$$

For pos. 3 \Rightarrow

0.05	0.99	0.005	0.99
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KL-example -



$X \rightarrow$ random variable
takes values 0, 1, 2

Binomial distn:

Uniform distn:
(Q)

In P distn:
takes 0 = prob " = 0.36
1 = " " = 0.98
2 = " " = 0.16

Distrn. X	0	1	2
P(X)	$\frac{9}{25}$	$\frac{12}{25}$	$\frac{4}{25}$
Q(X)	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{3}$

$$\text{Ans: } DKL(P||Q) = \sum_{x \in X} P(x=x) \ln \frac{P(x=x)}{Q(x=x)}$$

$$DKL(P||Q) = \frac{9}{25} \ln \left(\frac{9/25}{1/3} \right) + \frac{12}{25} \ln \left(\frac{12/25}{1/3} \right) + \frac{4}{25} \ln \left(\frac{4/25}{1/3} \right)$$

$$DKL(P||Q) = 0.0852996$$

If DKL equal to 0,
then $P = Q$ (want)
use don't want)

more closer
DKL
to zero,
more similar
given P
are.

$$\begin{aligned} D_{KL}(Q \parallel P) &= \frac{1}{3} \ln \left(\frac{1/3}{9/25} \right) + \frac{1}{3} \ln \left(\frac{1/3}{12/25} \right) \\ &\quad + \frac{1}{3} \ln \left(\frac{1/3}{4/25} \right) \end{aligned}$$

$$D_{KL}(Q \parallel P) \approx 0.09745$$

$$\therefore D_{KL}(P \parallel Q) \neq D_{KL}(Q \parallel P)$$

\hookrightarrow KL-divergence is not symmetric (always).