

# Inductive logic programming

Simon Jacquet

Faculty of Computer Science  
Unamur

December 20th 2021

$$B \wedge H \models E \quad (1)$$

$$B \wedge \overline{E} \models \overline{H} \quad (2)$$

$$B \wedge \overline{E} \models \overline{\perp} \quad (3)$$

$$\overline{\perp} \models \overline{H} \quad (4)$$

$$H \models \perp \quad (5)$$

- $B$ : background knowledge
- $H$ : hypothesis
- $E$ : examples
- $\overline{\perp}$ : set of all true literals (wrt.  $B \wedge \overline{E}$ )
- $\perp$ : most specific clause

# Covering algorithm

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## Algorithm 1: Cover set algorithm

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**input:**  $h, i, B, M, E$

- 1 If  $E = \emptyset$  return  $B$
  - 2 Let  $e$  be the first example in  $E$
  - 3 Construct clause  $\perp_i$  for  $e$  ; // Algorithm 2
  - 4 Construct clause  $H$  from  $\perp_i$  ; // Algorithm 3
  - 5 Let  $B = B \cup H$
  - 6 Let  $E' = \{e : e \in E \text{ and } B \models e\}$
  - 7 Let  $E = E - E'$
  - 8 Goto 1
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## Algorithm 2: Constructing $\perp_i$

1. Add  $\bar{e}$  to the background knowledge
2.  $InTerms = \emptyset$ ,  $\perp = \emptyset$
3. Find the first head mode declaration  $h$  such that  $h$  subsumes  $a$  with substitution  $\theta$   
For each  $v/t$  in  $\theta$ ,
  - if  $v$  corresponds to a #type, replace  $v$  in  $h$  by  $t$
  - if  $v$  corresponds to a +type or -type, replace  $v$  in  $h$  by  $v_k$   
where  $v_k$  is the variable such that  $k = hash(t)$
  - if  $v$  corresponds to a +type, add  $t$  to the set  $InTerms$ .Add  $h$  to  $\perp$ .
4. For each body mode declaration  $b$   
For every possible substitution  $\theta$  of variables corresponding to +type  
by terms from the set  $InTerms$   
Repeat recall times
  - If Prolog succeeds on goal  $b$  with answer substitution  $\theta'$   
For each  $v/t$  in  $\theta$  and  $\theta'$ 
    - if  $v$  corresponds to #type, replace  $v$  in  $b$  by  $t$
    - otherwise replace  $v$  in  $b$  by  $v_k$  where  $k = hash(t)$
    - if  $v$  corresponds to a -type, add  $t$  to the set  $InTerms$Add  $\bar{b}$  to  $\perp$ .
5. Increment the variable depth
6. Goto step 4 if the maximum variable depth has been achieved.

# Algorithm for searching the lattice

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## Algorithm 3: Lattice search algorithm

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**input:**  $h, i, B, M, E$

```
1  $Open = \{\square\}, Closed = \emptyset$ 
2  $s = best(Open), Open = Open - s, Closed = Closed \cup \{s\};$            // Node selection
3 if  $prune(s)$  then goto 5;                                           // Node pruning
4  $Open = (Open \cup \rho(s)) - Closed;$                                 // Clause refinement
5 if  $terminated(Closed, Open)$  then return  $best(Closed);$            // End of search
6 if  $Open = \emptyset$  then return  $e;$                                 // No generalisation
7 Goto 2
```

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# Algorithm for searching the lattice

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## Algorithm 3: Lattice search algorithm

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**input:**  $h, i, B, M, E$

```
1  $Open = \{\square\}, Closed = \emptyset$ 
2  $s = best(Open), Open = Open - s, Closed = Closed \cup \{s\}$  ;           // Node selection
3 if  $prune(s)$  then goto 5 ;                                           // Node pruning
4  $Open = (Open \cup \rho(s)) - Closed$  ;                                // Clause refinement
5 if  $terminated(Closed, Open)$  then return  $best(Closed)$  ;          // End of search
6 if  $Open = \emptyset$  then return  $e$  ;                                // No generalisation
7 Goto 2
```

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- To do so, we must be able to:
  - Compare solutions:  $best(\cdot)$
  - Build new hypotheses:  $\rho(\cdot)$
  - Discard wrong solutions:  $prune(\cdot)$
  - End the search:  $terminated(\cdot)$

# Using numbers in the search

- $p_s$ : # true positives
- $n_s$ : # false positives
- $c_s$ : # atoms in body
- $h_s$ : # optimistic estimate of literals needed
- $g_s = p_s - c_s - h_s$
- $f_s = p_s - n_s - c_s - h_s$
- $best(Open)$ : returns state  $s$  in set  $Open$ 
  - $c_s \leq c$
  - with maximum  $f_s$
- $prune(s)$ : returns *true* iff either:
  - $n_s = 0$  and  $f_s > 0$
  - $g_s \leq 0$
  - $c_s > c$
- $terminated(Closed, Open)$ : return *true* iff:
  - $s = best(Closed)$ ,  $n_s = 0$ ,  $f_s > 0$
  - $f_s \geq g_{best(Open)}$

# Learning with only positive examples

- Progol is able to learn from only positive examples
  - $n_s$ , in the previous slide, would always be 0
  - An empty hypothesis would maximize  $f_s$
- It searches for a good compromise between the size of an hypothesis and its generality
- Using probability distributions, it considers the hypothesis maximizing its log-probability:

$$\log(P(H|E)) = d_m - m \log(g(H)) - sz(H)$$

- Work is still necessary to better understand how to compute the generality  $g(H)$  and size  $sz(H)$  of an hypothesis



# Refinement operator $\rho(\cdot)$

- $s_0 = \langle \square, \emptyset, 0 \rangle$
- $\langle C', \theta', k' \rangle \in \rho(\langle C, \theta, k \rangle)$  iff either
  - 1  $C' = C, k' = k + 1, \theta' = \theta$  ( $k < n$ )
  - 2  $C' = C \cup \{l\}, k' = k, \langle l, \theta' \rangle \in \delta(\theta, k)$  and  $C' \in \mathcal{L}_i(M)$

## Splittable variable

A variable is splittable if it corresponds to a +type, -type in a modeh or a -type in a modeb.

## $\langle l, \theta' \rangle \in \delta(\theta, k)$

Let  $l_k = p(u_1, \dots, u_m)$

k-th literal of  $\perp_i$

Let  $l = p(v_1, \dots, v_m)$

- If  $u_j$  is not splittable:  $v_j/u_j \in \theta$
- If  $u_j$  is splittable, either:
  - $v_j/u_j \in \theta'$
  - $v_j \notin \text{dom}(\theta)$ , a new variable, and  $\theta' = \theta \cup \{v_j/u_j\}$