Maths secrets behind Supervised Learning

Animated by: Yesmine Makkes

GDSC HICS ISI Ariana

Some notations:

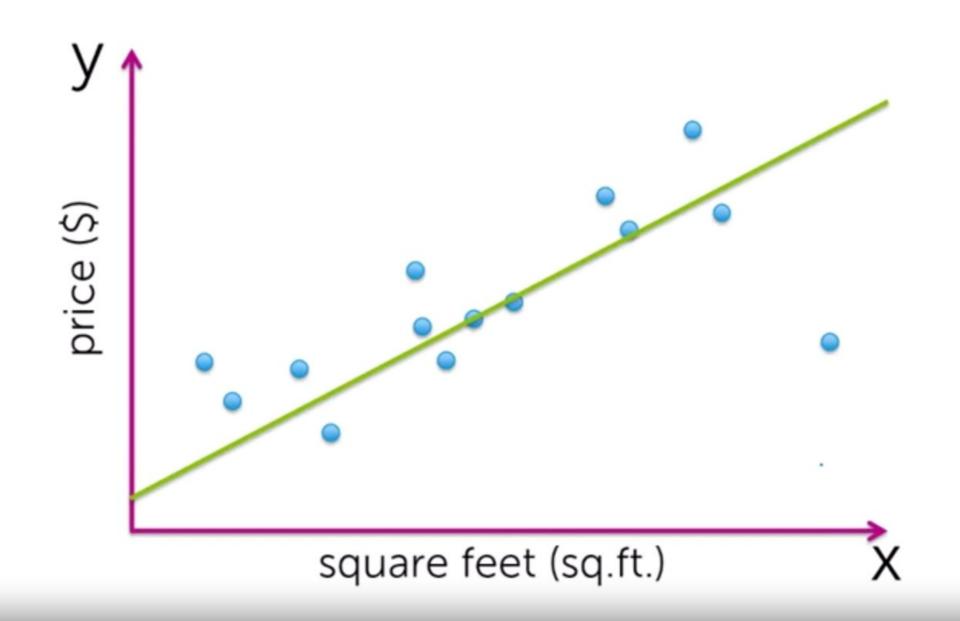
m: number of training examples

x : feature (input) *

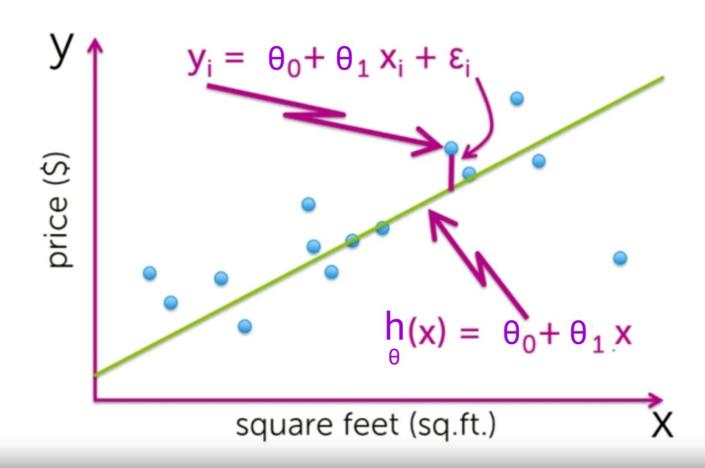
y: target / label (output)

| Attributes | | | | Decision |
|------------|--------|-------|--------|----------|
| Length | Height | Width | Weight | Quality |
| 4.7 | 1.8 | 1.7 | 1.7 | high |
| 4.5 | 1.4 | 1.8 | 0.9 | high |
| 4.7 | 1.8 | 1.9 | 1.3 | high |
| 4.5 | 1.8 | 1.7 | 1.3 | medium |
| 4.3 | 1.6 | 1.9 | 1.7 | medium |
| 4.3 | 1.4 | 1.7 | 0.9 | low |
| 4.5 | 1.6 | 1.9 | 0.9 | very-low |
| 4.5 | 1.4 | 1.8 | 1.3 | very-low |

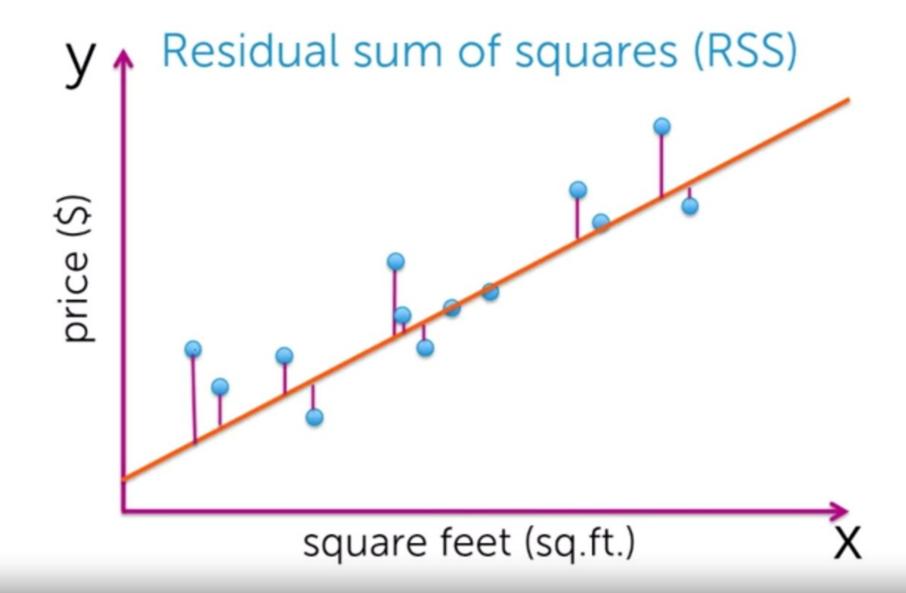
Simple linear regression model



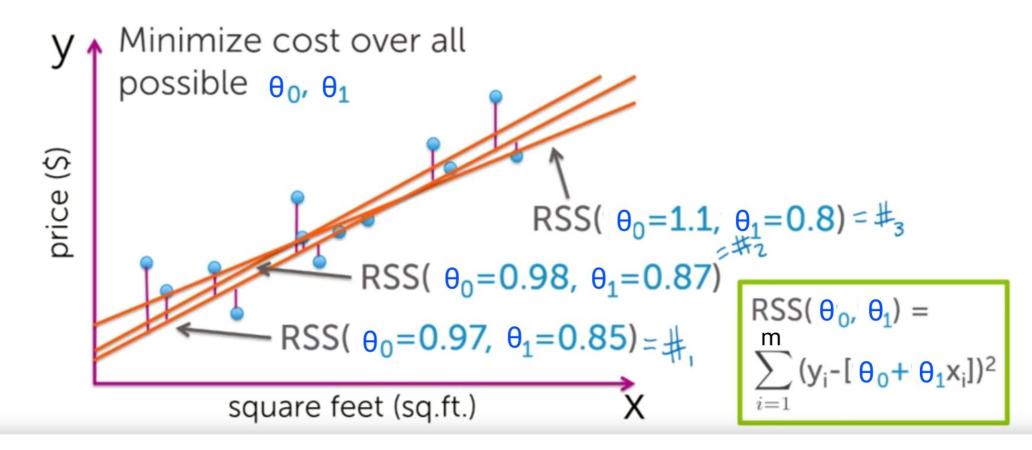
Simple linear regression model



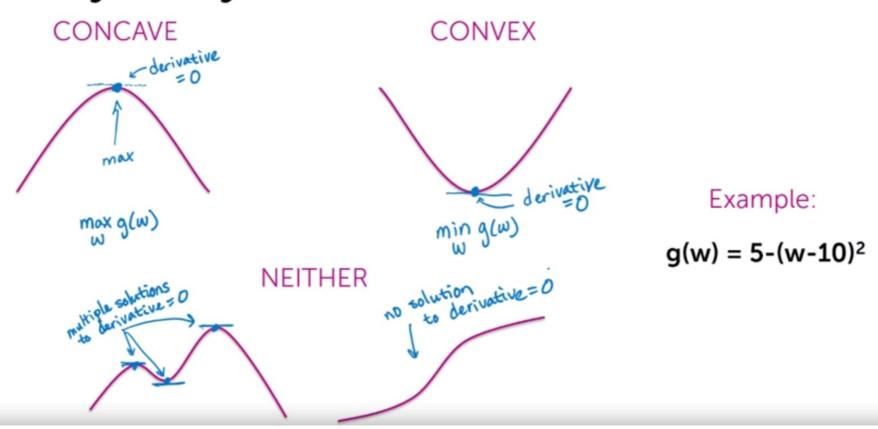
"Cost" of using a given line

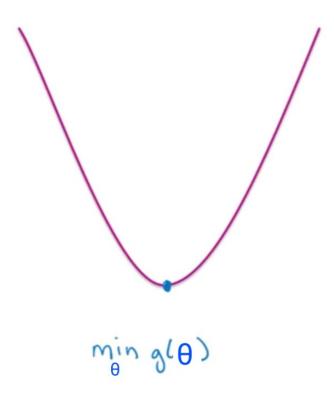


Find "best" line



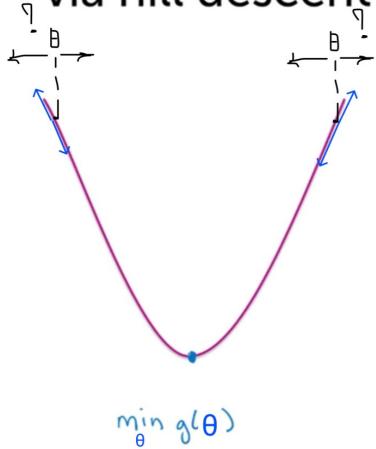
Finding the max or min analytically





Algorithm:

while not converged
$$\frac{\theta^{(t+1)} \leftarrow \theta^{(t)} - \eta}{d\theta}$$

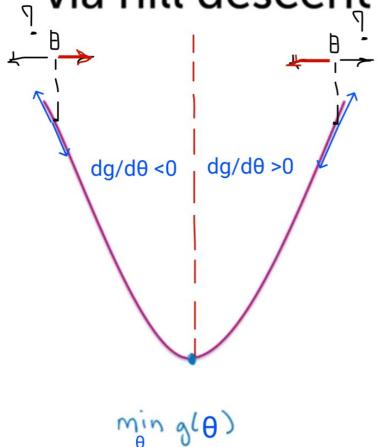


Algorithm:

while not converged

$$\theta^{(t+1)} \leftarrow \theta^{(t)} - \eta \frac{dg}{d\theta}$$

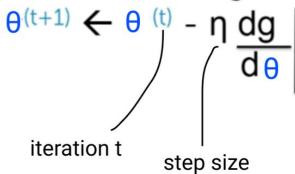
iteration t step size

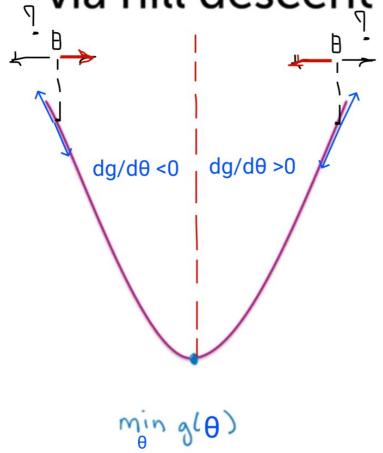


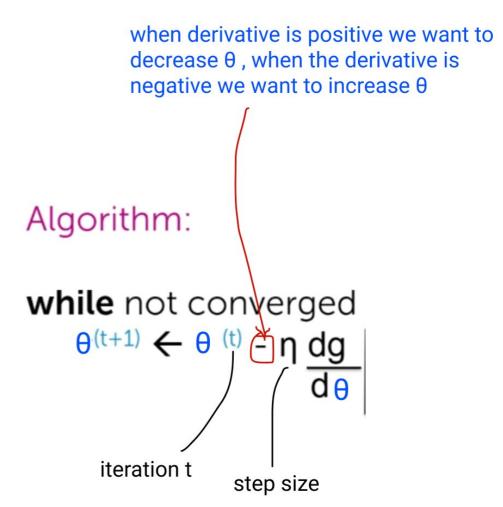
when derivative is positive we want to decrease θ , when the derivative is negative we want to increase θ

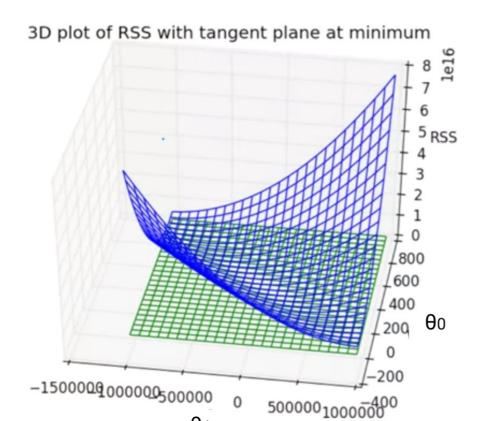
Algorithm:

while not converged







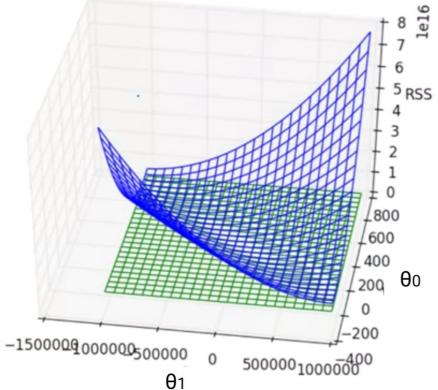


θ1

$$\min_{\boldsymbol{\theta_0},\ \boldsymbol{\theta_1}} \sum_{i=1}^{m} (\mathbf{y_i} \text{-} [\ \boldsymbol{\theta_0} \text{+}\ \boldsymbol{\theta_1} \mathbf{x_i}])^2$$

45





$$h(x) = \theta_0 + \theta_1 x_i$$

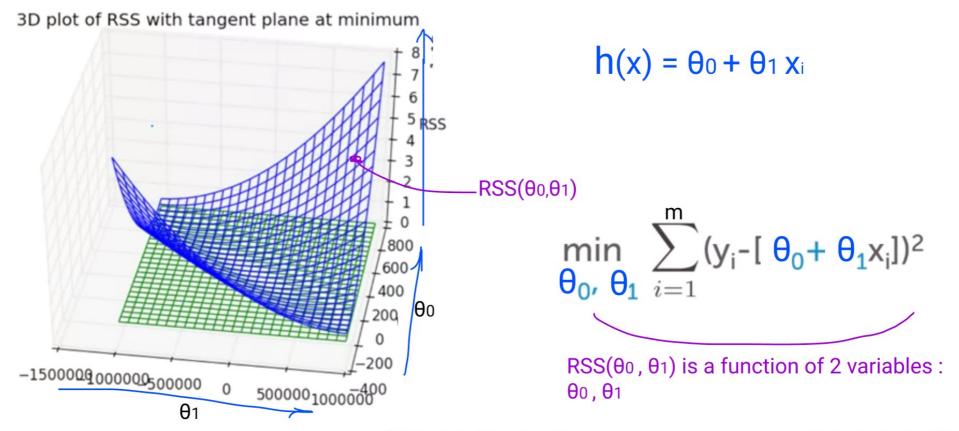
$$\min_{\boldsymbol{\theta}_0, \ \boldsymbol{\theta}_1} \sum_{i=1}^{m} (\mathbf{y}_i - [\ \boldsymbol{\theta}_0 + \ \boldsymbol{\theta}_1 \mathbf{x}_i])^2$$

RSS(θ_0 , θ_1) is a function of 2 variables : θ_0 , θ_1

45

©2015 Emily Fox & Carlos Guestrin

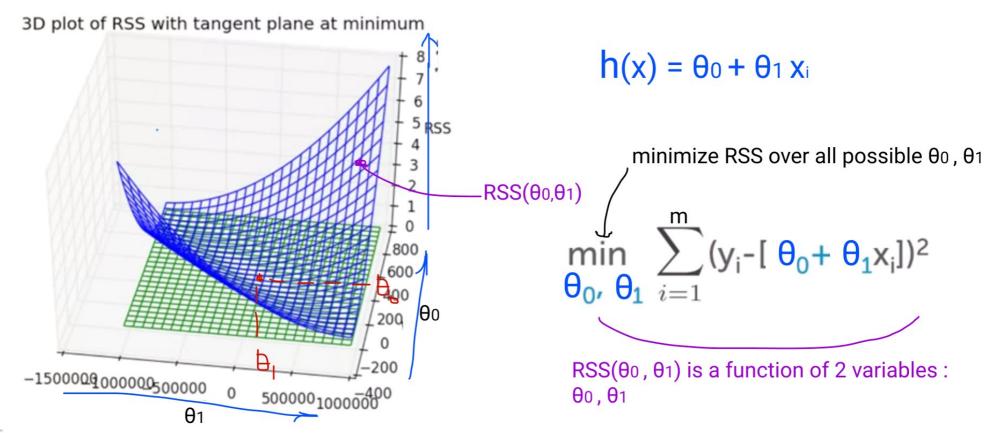
Machine Learning Specialization



45

©2015 Emily Fox & Carlos Guestrin

Machine Learning Specialization

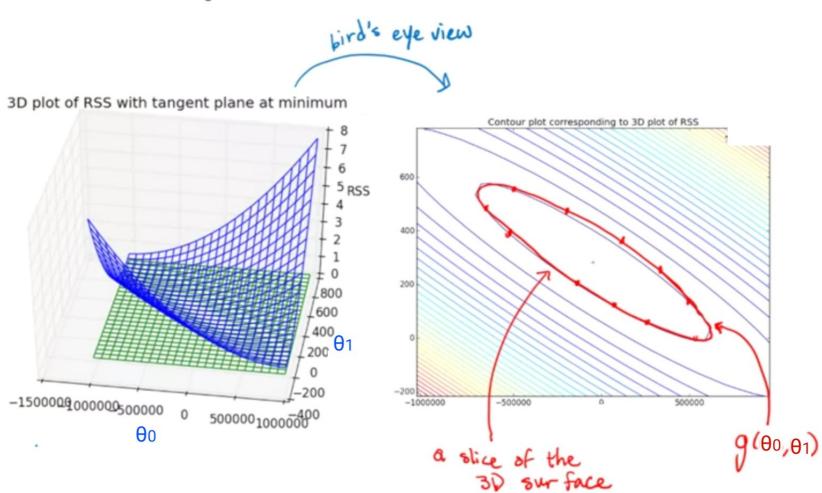


45

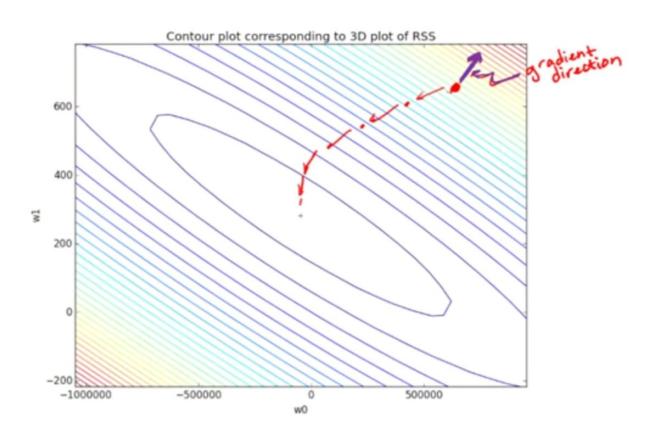
©2015 Emily Fox & Carlos Guestrin

Machine Learning Specialization

Contour plots



Gradient descent



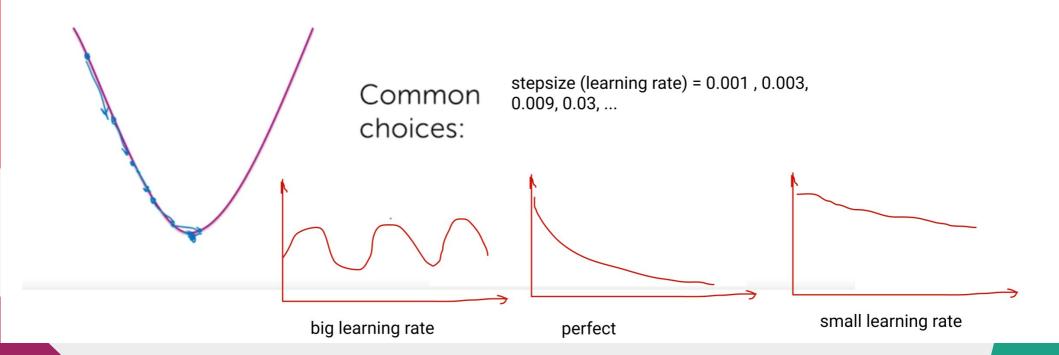
Convergence criteria

For convex functions, optimum occurs when

$$\frac{dg(w)}{dw} = 0$$

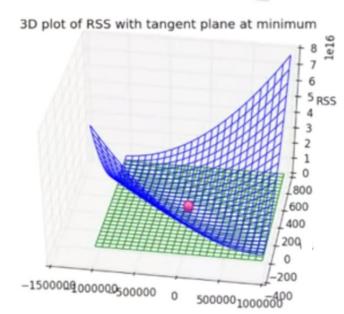
In practice, stop when

Choosing the stepsize



Approach 2: Set gradient = 0

$$\nabla RSS(\theta_0, \theta_1) = \begin{bmatrix} -2\sum_{i=1}^{N} [y_i - (\theta_0 + \theta_1 x_i)] \\ -2\sum_{i=1}^{N} [y_i - (\theta_0 + \theta_1 x_i)] x_i \end{bmatrix}$$



Comparing the approaches

- For most ML problems, cannot solve gradient = 0
- Even if solving gradient = 0
 is feasible, gradient descent
 can be more efficient
- Gradient descent relies on choosing stepsize and convergence criteria

Thank you!