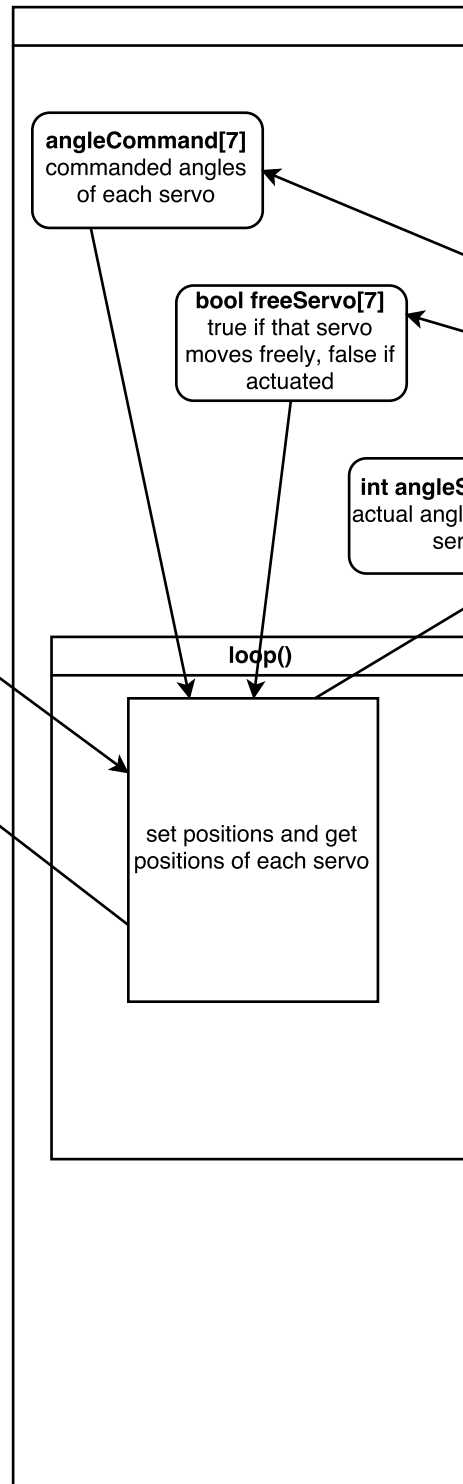
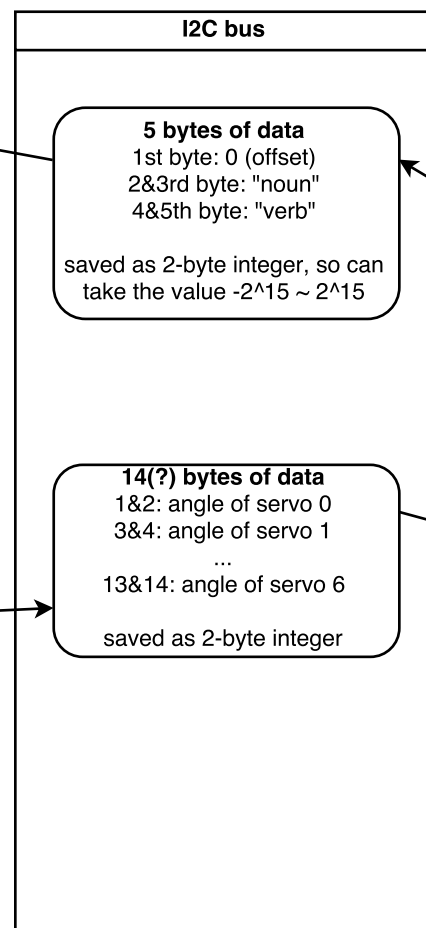
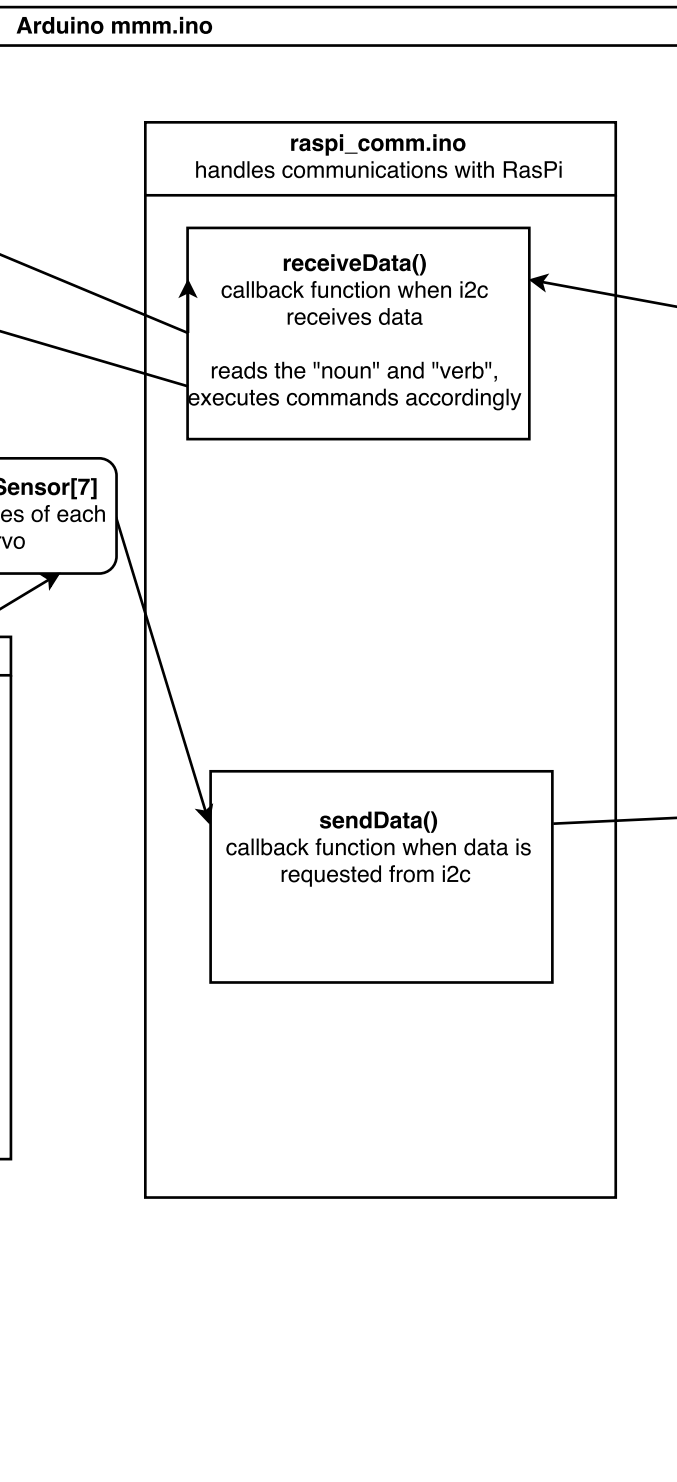
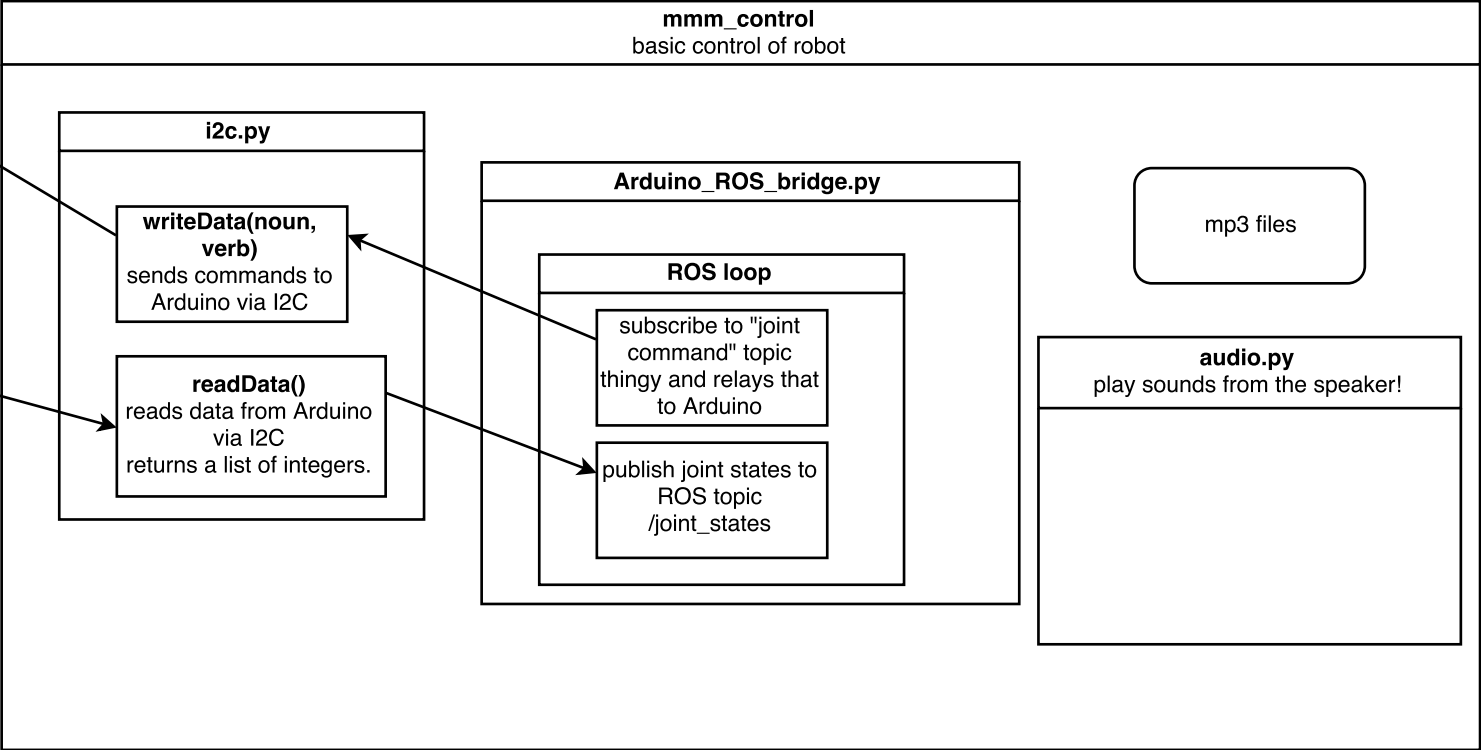


getPos()
get angle data

setPos()
setFree()
determine behaviour of servos







this robot.

