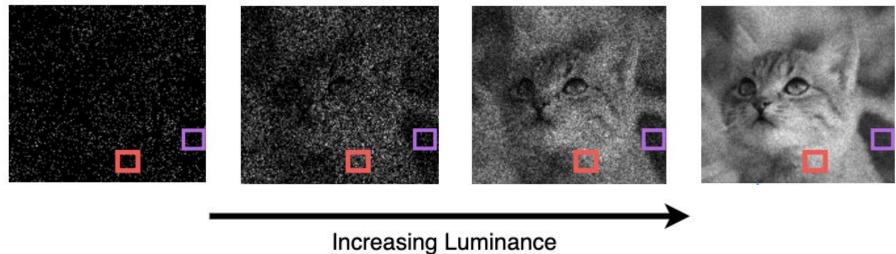
# Seeing Into Darkness: Scotopic Visual Recognition

By Bo Chen and Pietro Perona

Yash Sanghvi ML Reading Group October 30th, 2019

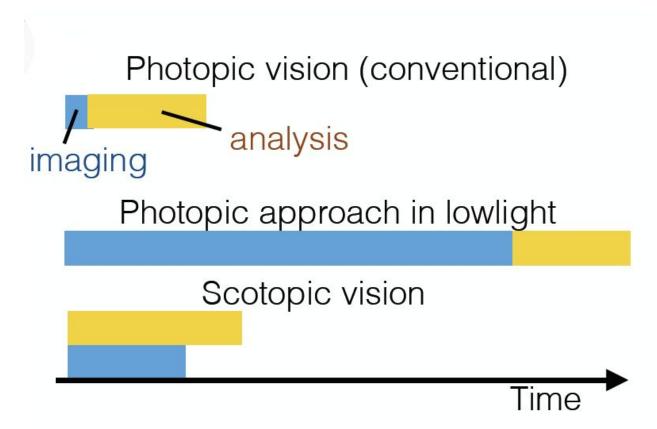
### Scotopic: Vision in the Dark



PPP: Photons Per Pixel

PPP a Exposure Time

# What's Different from Photopic Vision?



### Some Mathematical Formulation

 $X_{1:t}$ : Stream of Photons incident on sensors

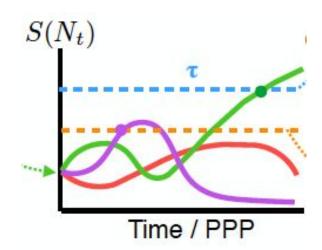
Photons incident on pixel 'i' during time bin 't'

$$P(\overrightarrow{X_{t,i}} = k) = Poisson(k|\lambda_i t)$$

### Classification with Scotopic Vision

Sequential Probability Ratio Test

Compute 
$$c^* = \arg\max_{c=1,2,...,} S_C(X_{1:t})$$
 if  $S_{c^*} > au$ : report  $\hat{C} = c^*$  otherwise increase exposure time  $t$ 

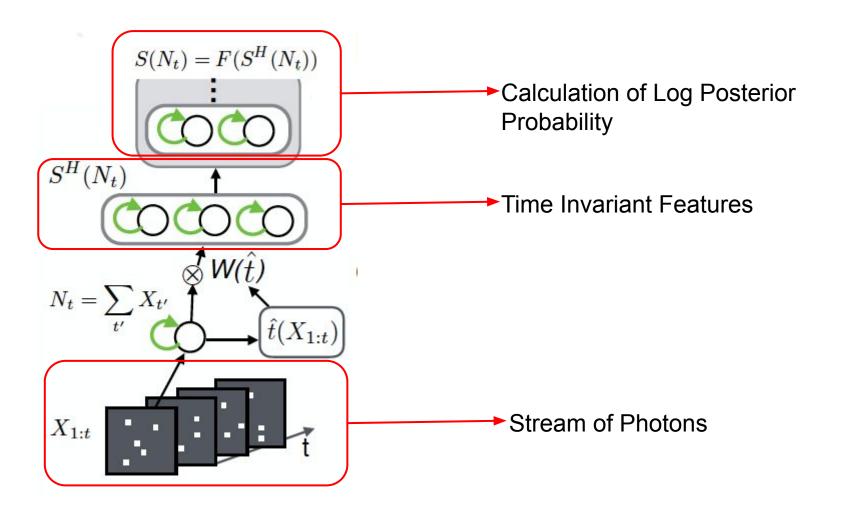


### WaldNet

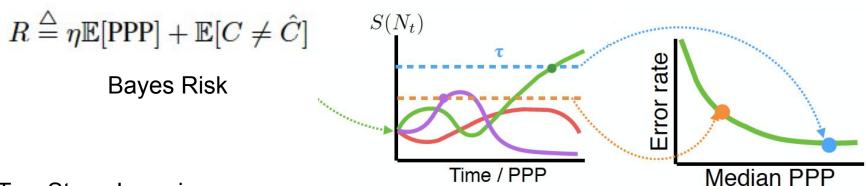
- Standard ConvNets not applicable
- Instead work with High Exposure Time 'T'
- Working with partial observations  $N_t = \sum\limits_{t=1}^t X_{t'}$
- Uncounted Photons  $\Delta N = \sum\limits_{t'=t+1}^{r} X_{t'}$

Gamma Prior on photon emission rate:  $Gam(\mu_i t_0, t_0)$ 

First "Convolutional" Layer 
$$S^{H}(N_{t}) = \sum_{AN} (W(N_{t} + \Delta N) + b^{H}) P(\Delta N | N_{t}) \approx \alpha(t) W N_{t} + \beta(t) \qquad (4)$$
 
$$\alpha(t) \stackrel{\triangle}{=} \frac{T + t_{0}}{t + t_{0}} \qquad \beta_{j}(t) \stackrel{\triangle}{=} \frac{t_{0}(T - t)}{t + t_{0}} \sum_{i} W_{ij} \mu_{i} + b_{j}$$



### Learning



#### Two Stage Learning

- (I) Learning ConvNet/Waldnet
- (II) Threshold Learning

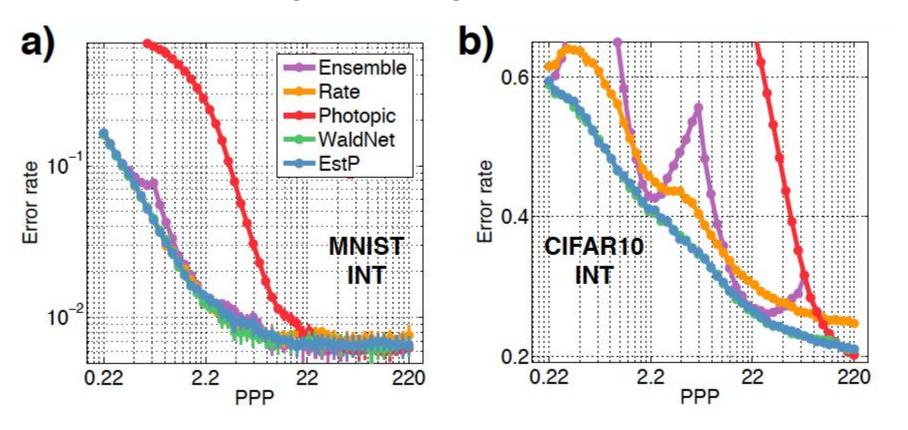
### Threshold Learning

Bayes Risk at time t

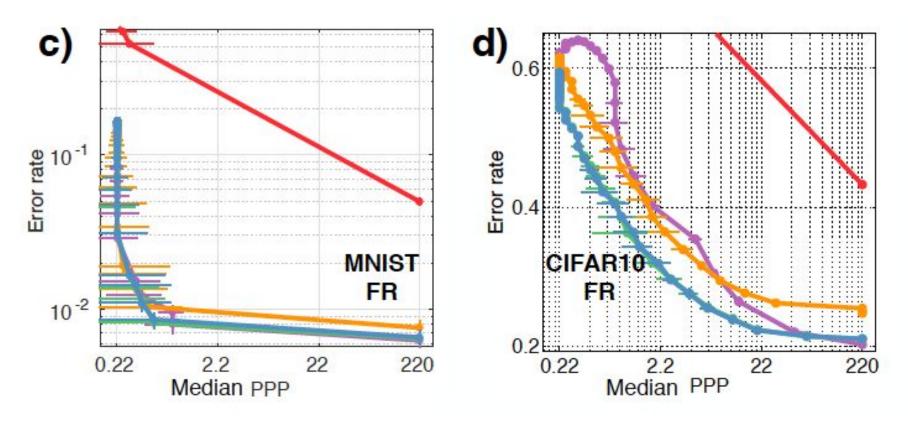
$$R_t^{(n)} = \eta \Delta + q_t^{(n)} e_t^{(n)} + (1 - q_t^{(n)}) R_{t+1}^{(n)}$$

Bayes Risk:  $R=E_{(n)}[R_0^{(n)}]$ 

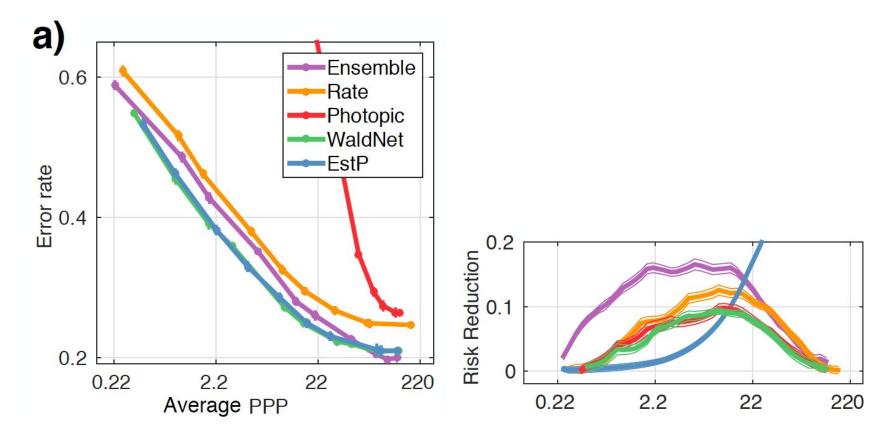
# Results - Interrogation Regime



# Results - Free Response Regime



### Risk Reduction with Threshold Learning



### Conclusion

 WaldNet for Scotopic Vision, Designed to process images as they hit the photoreceptors

Provide a transform to convert stream of photons to "time invariant features"

$$S^{H}(N_{t}) = \sum_{\Delta N} (W(N_{t} + \Delta N) + b^{H}) P(\Delta N | N_{t}) \approx \alpha(t) W N_{t} + \beta(t)$$
 (4)

Allows tradeoff between computational time vs. accuracy.

\*Did not talk about Sensor noise and Spiking Implementation in this presentation