

# Design Review



Gruppe 46

*“Success is not final, failure is not fatal: it is the courage to continue that counts.” -Winston S. Churchill*

# Failure modes

- Network failure
- Elevator motor failure
- Incorrect message data received
- Power loss

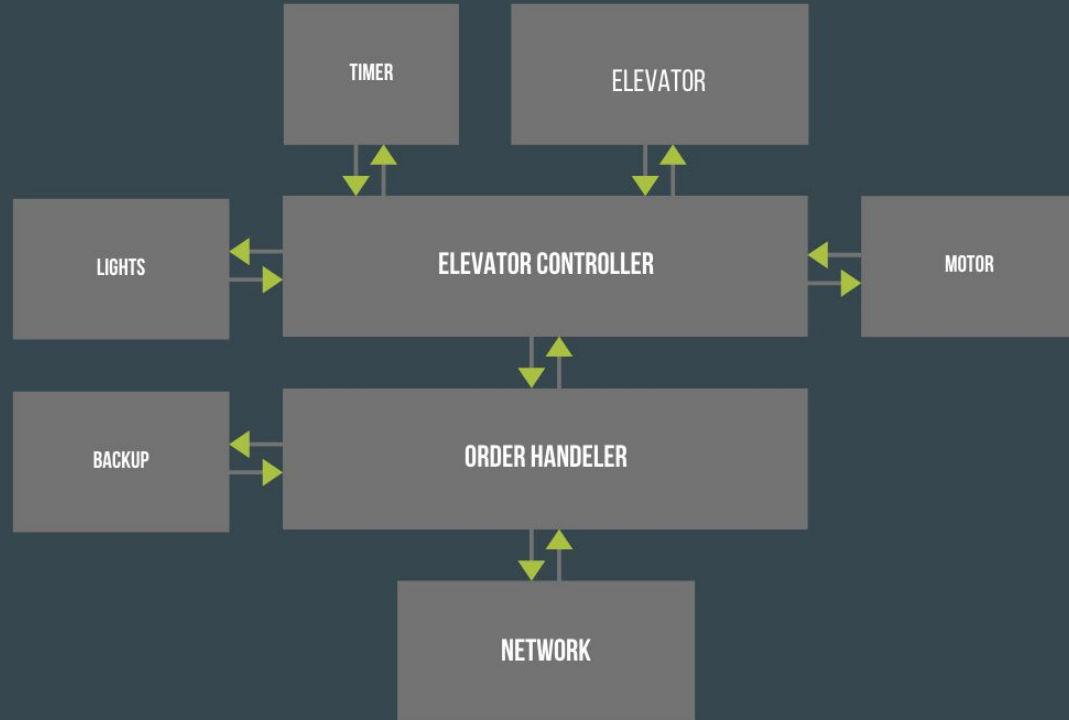
- Nuclear war (or fire, etc.)

# Strengths and weaknesses

- + Elevators function independently (easily scalable)
  - + No master/slave overhead over network
  - + Modular message-passing design
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- Messages are crucial and need redundancy
  - Multiple failures at the same time cannot guarantee orders
  - File synchronization is difficult to manage

# Modules

- Controller
  - Lights
  - Motor
- Order module
  - Backup
- Order module
- Timer module
- Network module

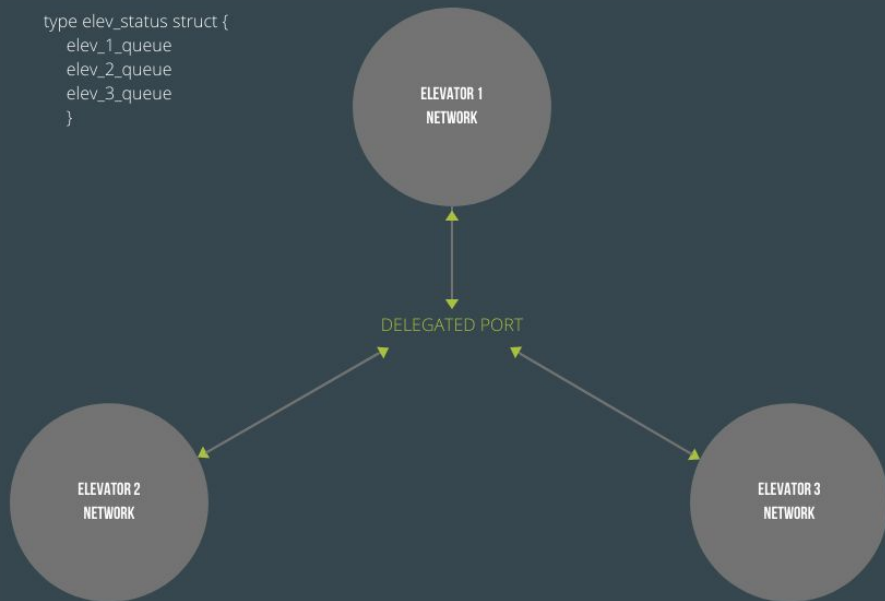


# Network

- UDP
- Implement a struct with the orderlist for all elevators.
- Receives and sends information on pre-delegated ports
- Checks continuously if struct is received

```
type elev_status struct {  
    elev_1_queue  
    elev_2_queue  
    elev_3_queue  
}
```

- cast\_message()
- listen\_message()
- check\_connection()



# Order Module

Gives orders to optimal elevator given status, and handles local order queue.

- `distribute_order(order)` //can go to local or over network
- `best_elevator(elev_status, network_elev_status)`
- `impossible_orders()`
- `enqueue_local(order)`
- `dequeue_local(order)`
- `queue()`

# Backup

Backs up system state (order list) in a .json file on all computers

- `open_file(filename)`
- `close_file(filename)`
- `append_file(filename)`
- `pop_file_element(filename)`
- `backup(order_list)`
- `crosscheck_external_backups(local_backup, network_backup)`

# Elevator controller

Controls general behaviour of the elevator and delivers the status of the elevator.

- `init_elev()`
- `elev_status()`
- `deliver_order()`



# Motor

- `motor_move(dir)`
- `motor_stop()`
- `motor_status()`

# Light

- `light_on(light_num)`
- `light_off(light_num)`
- `check_light_status(light_num)`

# Timer

- `start_timer()`
- `stop_timer()`
- `check_timer()`