

Module 9: Equilibrium and Torque

Conditions for Equilibrium

OBJECTIVES:

1

Identify the different conditions for equilibrium

2

Define torque physically and mathematically

3

Cite real life situations where torque can be seen or applied

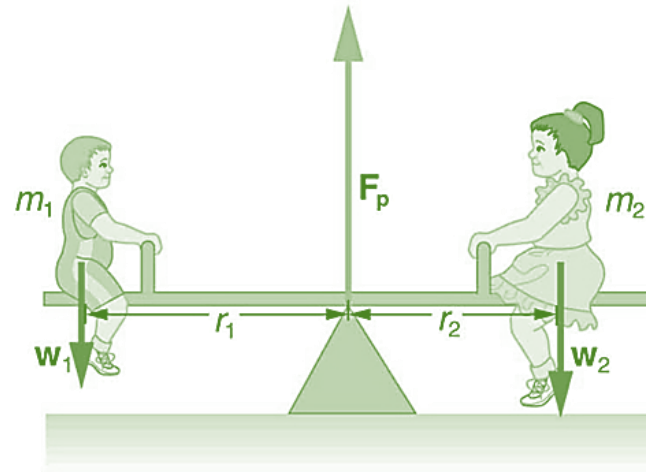
4

Solve problems involving equilibrium and torque



What does “equilibrium” mean?

- An object at equilibrium has **no net influences** to cause it to move, either in **translation** (linear motion) or rotation.
- REMEMBER IN NEWTON’S LAWS APPLICATIONS, WE DISCUSSED “**TRANSLATIONAL EQUILIBRIUM**” WHICH WILL ONLY BE ATTAINED WHEN THE SUMMATIONS OF FORCES ALONG X AND Y ARE ZERO.



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Conditions for Equilibrium

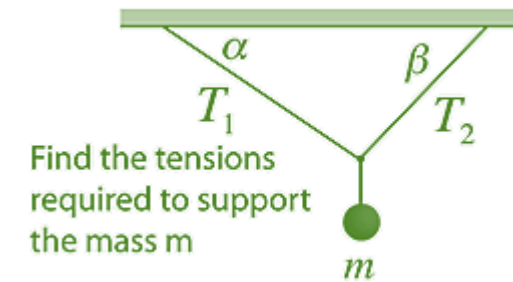
- The basic conditions for equilibrium are:

1. Net force = 0

$$\sum_i \mathbf{F}_i = 0$$

x and y components of force may be separately set = 0.

Forces left = forces right
Forces up = forces down.



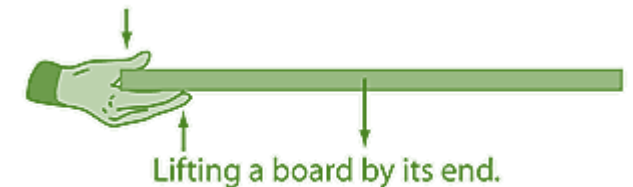
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2. Net torque = 0

$$\sum_i \tau_i = 0$$

The axis may be chosen for advantage to eliminate some unknown forces..

The sum of the clockwise torques is equal to the sum of the counterclockwise torques.

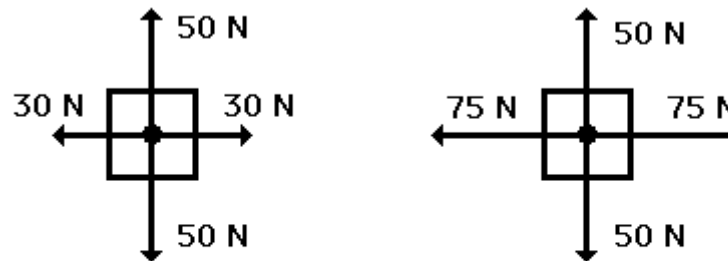


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Static vs. Dynamic Equilibrium

- **Dynamic equilibrium** is the steady state of a **reversible reaction** where the rate of the forward reaction is the same as the reaction rate in the backward direction.
- **Static equilibrium**, also known as mechanical equilibrium, means the reaction has stopped. In other words, the **system is at rest**.
- Example is an object (e.g book) lying still on the surface (e.g table). no resultant moment about a pivot, so clockwise moment equals anticlockwise moment and there is no resultant force and no motion either.



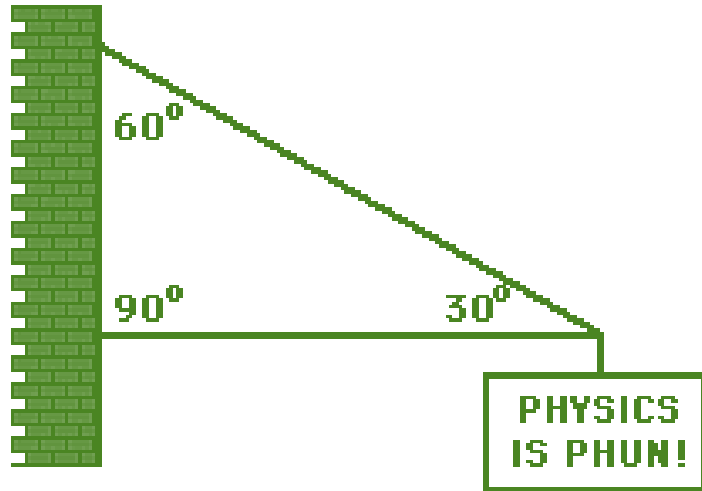
These two objects are at equilibrium since the forces are balanced. However, the forces are not equal.

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Example

The sign below hangs outside the physics classroom, advertising the most important truth to be found inside. The sign is supported by a diagonal cable and a rigid horizontal bar. If the sign has a mass of 50 kg, then determine the tension in the diagonal cable that supports its weight.

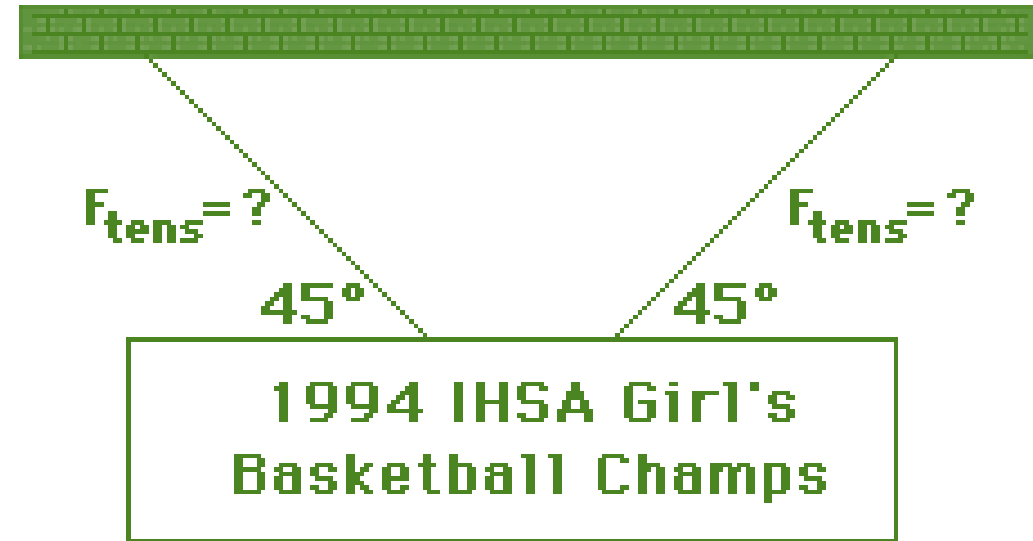


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Example

A sign board below can be found hanging outside a boutique. The sign has a mass of 50 kg. Determine the tension in the cables.

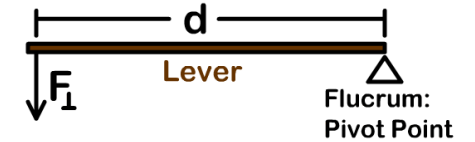


Torque

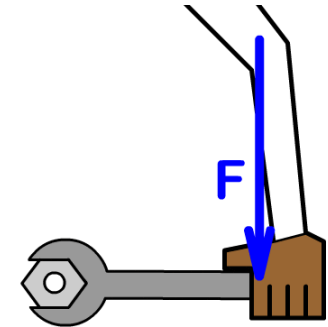
- Torque, also called moment of a force, in physics, the tendency of a force to rotate the body to which it is applied.
- The torque, specified with regard to the axis of rotation, is equal to the magnitude of the component of the force vector, multiplied by the shortest distance between the axis and the direction of the force component.
- Mathematically, torque is given by:

$$\text{Torque} = \text{Force applied} \times \text{lever arm}$$

The lever arm is defined as the perpendicular distance from the axis of rotation to the line of action of the force.



CCW: Counterclockwise 



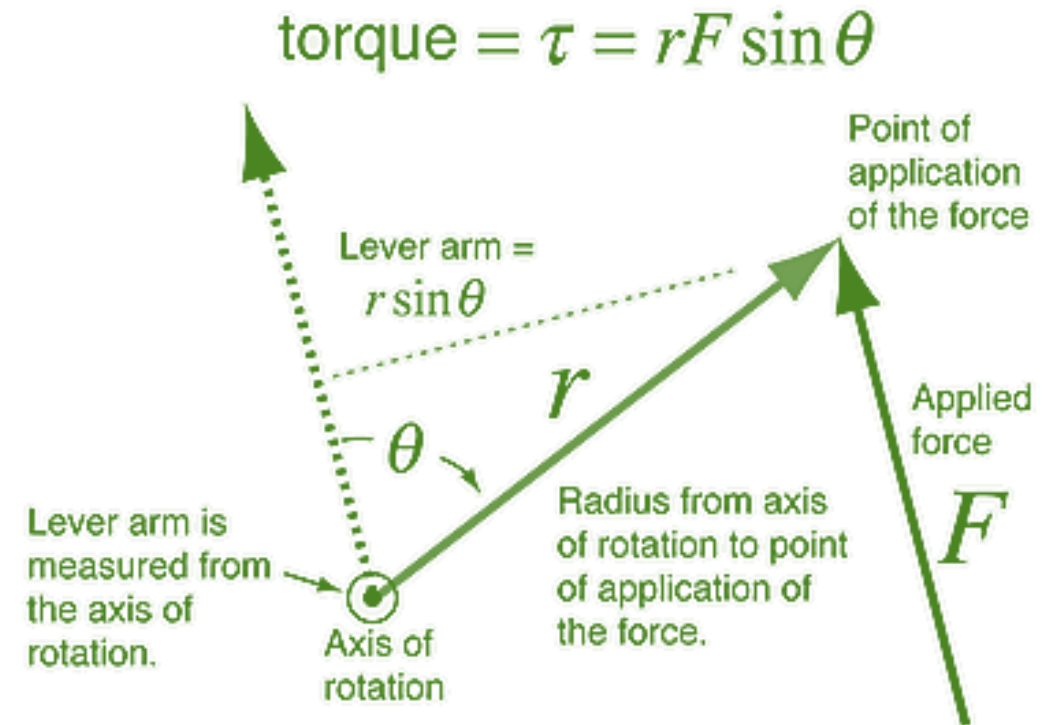
Most torque



- Note that this is “cross product”, meaning:

$$\tau_{\text{Torque}} = \vec{r} \times \vec{F} = r F \sin \theta$$

- Torque always points in the direction of the object's angular acceleration.



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Torque

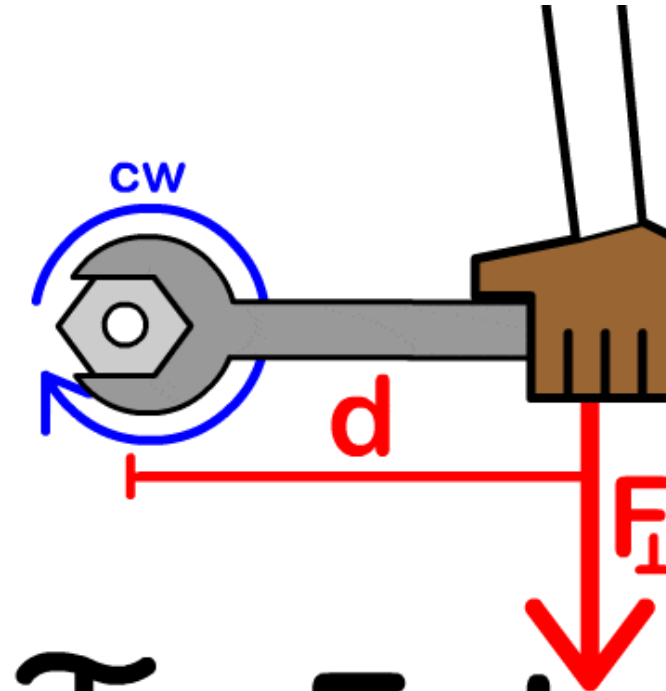
- ❑ **Static torque** does not produce angular acceleration.

Ex. pushing a closed door is a static torque.

- ❑ **Dynamic torque** produces angular acceleration.

Ex. The drive shaft of a racing car produces angular acceleration allowing the race car to drive on its track.

A wrench is activated by force applied at one end, creating an unbalanced torque on the tightened element.



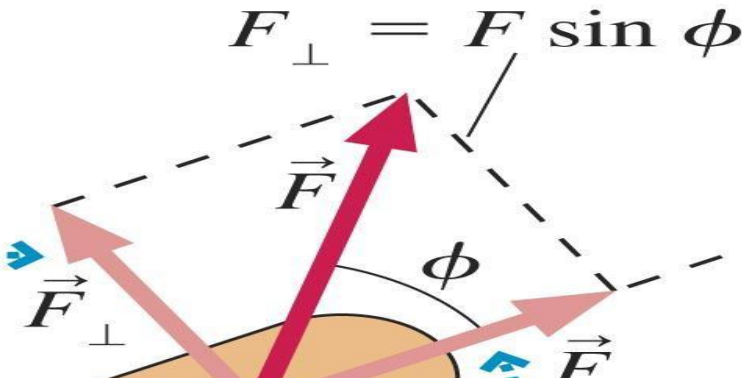
$$\tau = F_{\perp} d$$

- ❑ Torque is also called **moment of force**, r is called the **length of the moment arm or lever arm**. Notice that the longer the lever arm, the higher the torque.

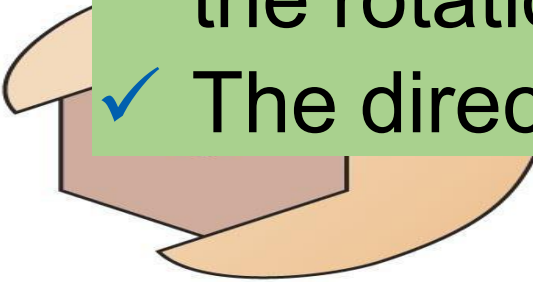


What does torque depend on?

The component of \vec{F} that is *perpendicular* to the radial line causes a torque.



- ✓ The size of the force (how hard you push).
- ✓ The point where the force is applied relative to the rotation point.
- ✓ The direction of the force.



Example

A 4 m beam of negligible weight balances in equilibrium with a fulcrum placed 1.5 m from its left end. If a force of 60 N is applied on its right end, how much force must be applied to the left?

Solution:

Given:

$$F_1 = ?$$

$$r_1 = 1.5 \text{ m}$$

$$F_2 = 60 \text{ N}$$

$$\begin{aligned} r_2 &= 4 \text{ m} - 1.5 \text{ m} \\ &= 2.5 \text{ m} \end{aligned}$$

$$\text{Torque on the left lever arm } (\tau) = r_1 \times F_1 = 1.5 \text{ m} \times F_1$$

$$\begin{aligned} \text{Torque on the right lever arm } (\tau) &= r_2 \times F_2 \\ &= 2.5 \text{ m} \times 60 \text{ N} = 150 \text{ N}\cdot\text{m} \end{aligned}$$

Since the beam is balanced, the two torques cancel out. Therefore,

$$\begin{aligned} \tau_1 &= \tau_2 \\ 1.5 \text{ m} \times F_1 &= 150 \text{ N}\cdot\text{m} \\ F_1 &= 150 \text{ N}\cdot\text{m} / 1.5 \text{ m} = 100 \text{ N} \end{aligned}$$



Example

One side of a seesaw carries a 32 kg mass four meters from the fulcrum and a 36.5 kg mass two meters from the fulcrum. To balance the seesaw, what mass should be placed eight meters from the fulcrum on the side opposite the first two masses?

Solution

Given: $m_1 = 32 \text{ kg}$, $r_1 = 4 \text{ m}$, $m_2 = 36.5 \text{ kg}$, $r_2 = 2 \text{ m}$, $m_3 = ?$, $r_3 = 8 \text{ m}$

Using the torque balance equation

$$\begin{aligned} r_1 \cdot F_1 + r_2 \cdot F_2 + r_3 \cdot F_3 &= 0 \\ 4 \text{ m} \cdot 32 \text{ kg} \cdot g + 2 \text{ m} \cdot 36.5 \text{ kg} \cdot g - 8 \text{ m} \cdot m_3 \cdot g &= 0 \\ m_3 &= (4 \text{ m} \cdot 32 \text{ kg} + 2 \text{ m} \cdot 36.5 \text{ kg}) / 8 \text{ m} = 25.1 \text{ kg} \end{aligned}$$



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Got any questions???



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