Bayesian Optimization

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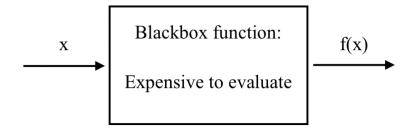
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Bayesian Optimization

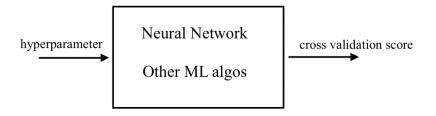
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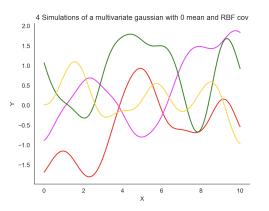


Context



Gaussian Process

 $\{\hat{f}(x_t)\}_{t\in\mathbb{R}}$ is a gaussian process, i.e. any finite collection is a gaussian vector.

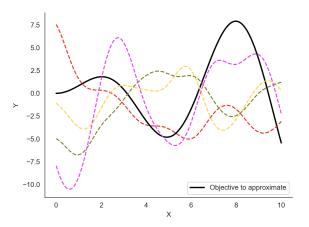


$$\{\hat{f}(x_t)\}_{t\in\mathcal{I}}\sim\mathcal{N}(\mathbf{0},\Sigma)$$
, where $\Sigma_{i,j}:=\exp(-|x_i-x_j|^2/2l^2)$



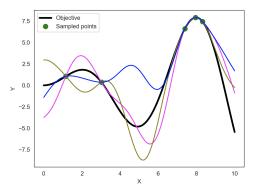
Gaussian Process

Can we approximate an objective f using gaussian processes?



Gaussian Process

We need to add **knowledge** about the objective, i.e. its values at some points.



Can be done by considering the posterior distribution

$$\hat{f}(x)|\hat{f}(x_1),...,\hat{f}(x_n)$$



Gaussian Process Regression: Model

We suppose that :

$$\hat{f}(x_1), ..., \hat{f}(x_n) \sim \mathcal{N}(\mu_0(x_{1:n}), \Sigma_0(x_{1:n}))$$

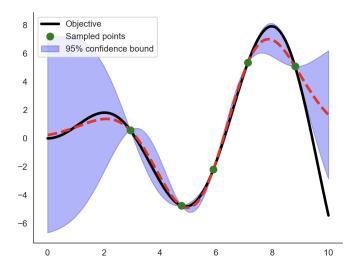
where: $\Sigma_0(x_{1:n})_{i,j} = \Sigma_0(x_i, x_j)$

We can access the conditional distribution [1] $\hat{\mathbf{f}}(\mathbf{x})|\hat{\mathbf{f}}(\mathbf{x}_{1:n})$, $\forall x \in \mathcal{D}$:

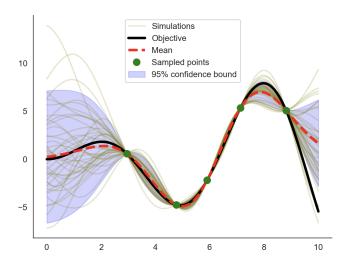
$$\hat{f}(x)|\hat{f}(x_{1:n}) \sim \mathcal{N}(\mu_n(x), \sigma_n(x)^2)$$

Gaussian Process Regression: Model

Prediction: mean and variance at each x



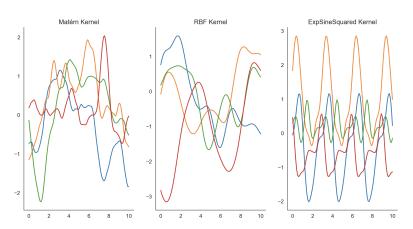
Gaussian Process Regression: Model



Gaussian Process Regression: Model selection

Hyperparameters?

Which kernel to use: RBF, Matèrn, Exp Spine?

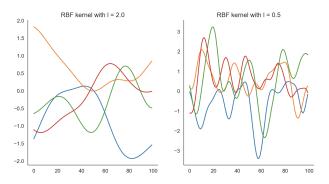


Gaussian Process Regression: Model selection

Hyperparameters?

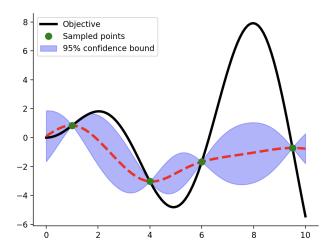
How to choose the hyperparameters of the kernel?

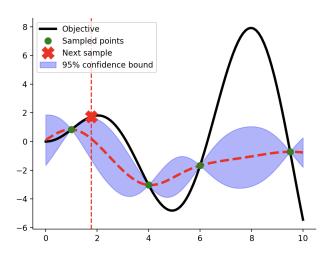
RBF kernel: $cov(x_i, x_i) := exp(-|x_i - x_i|^2/2l^2)$

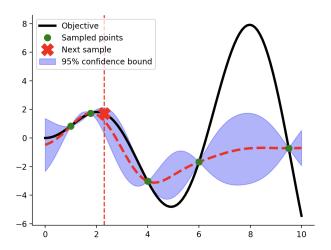


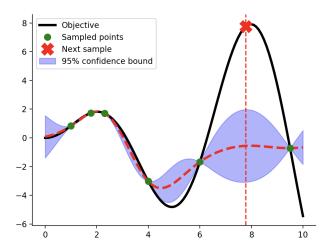
via likelihood maximization [1]:

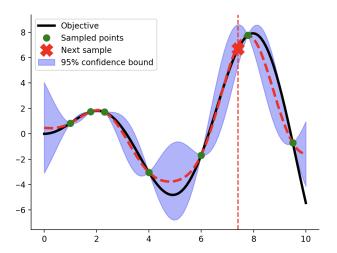
$$\log p(y|X,\theta) = \frac{1}{2}y^{T}K_{y}^{-1}y - \frac{1}{2}\log|K_{y}| - \frac{n}{2}\log(2\pi)$$











Bayesian Optimization: Summary

Instead of directly optimizing the objective, we instead optimize a surrogate: e.g. Upper Confidence Bound [3]:

$$UCB_n(x) = \mu_n(x) + \beta_n^* \sigma_n(x)$$

Algorithm [2]:

- Fit a gaussian process regression model using the known points $A = \{(x_i, f(x_i))\}_i$.
- ► Solve $\operatorname{argmax}_{x \in \mathcal{D}} \mu_n(x) + \beta_n \sigma_n(x)$ and append solution to A.
- Restart.

Return arg of the best value visited.

*typically [3]: $\beta_n = \sqrt{\log(n)}$.



Simple regret :
$$|f(x^*) - \operatorname{argmax}_{x \in \mathcal{D}} f(x)|$$

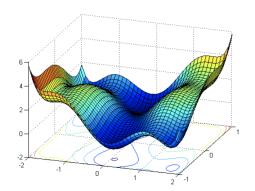
Experiment: run Bayesian Optimization 10 times and average the results.

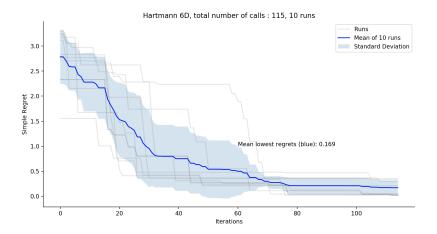
- Two synthetic functions: Ackley and Hartmann
- One real world example: DBSCAN on car scenarios (Renault's Data).

Example: Hartmann function:

▶ Domain : [0,1]⁶

► Lowest regret on 10 runs: 0.01

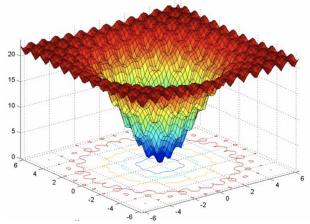


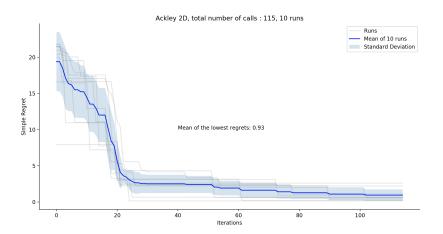


Example: Ackley function:

▶ Domain : $[-32, 32]^2$

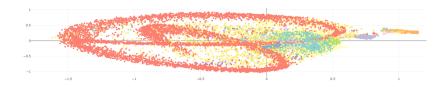
► Lowest regret on 10 runs: 0.13



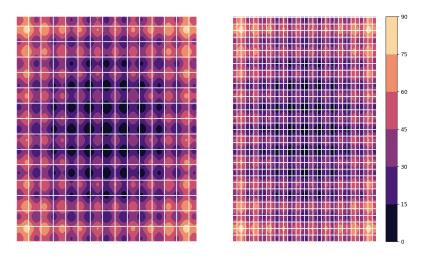


Example:

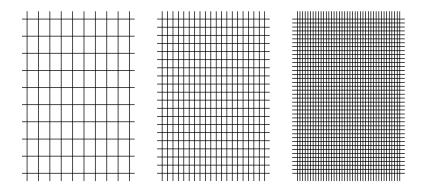
- Clustering of scenarios after performing PCA or MDS.
- Optimization with respect to eps and num samples
- ► Space: $[0,1]^2 \times [0,200]$



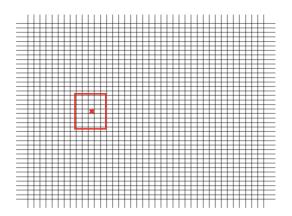
Rastringin 2D contour map

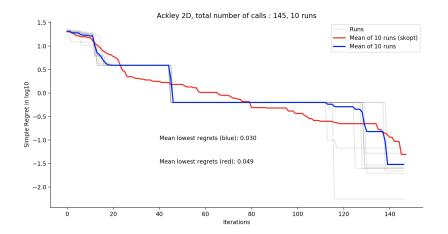


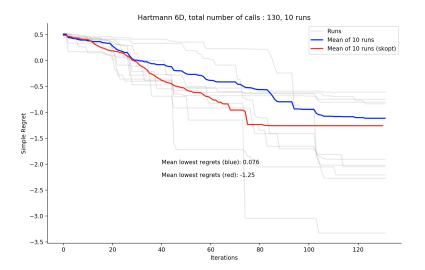
▶ Optimize on grids with decreasing step size. (e.g. divide step size by two at each step)



► Select best point found so far and optimize **continuously** in a ball centered around it.



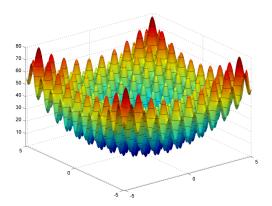


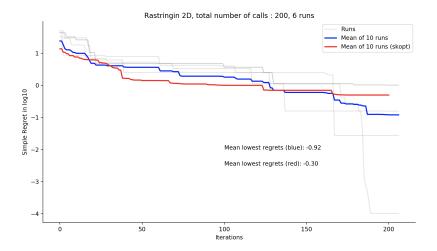


Example: Rastringin function.

ightharpoonup Domain: $[-5.12, 5.12]^2$

► Lowest regret on 6 runs: 1e-3





Software

Bayesian Optimization library in Scala and Python. Features:

- Discrete or continuous optimization. Mixed space also.
- Custom acquisition functions.
- Custom optimizers.
- Easy to use.

Python version available at:

https://github.com/yazidjanati/bayestuner

References

- Rasmussen & Williams, Gaussian Processes For Machine Learning, 2006 MIT, 2006
- Peter I. Frazier, A Tutorial On Bayesian Optimization, 2018
- Niranjan Srinivas et al., Gaussian Process Optimization in the Bandit Setting: No Regret and Experimental Design, 2009