Vector Derivative Identities and Properties

$$f = f(x, y, z) = f(\vec{\mathbf{x}})$$
 $\vec{\mathbf{x}} = x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + z\hat{\mathbf{k}}$

$$\mathbf{F}(x, y, z) = P(x, y, z)\hat{\mathbf{i}} + Q(x, y, z)\hat{\mathbf{j}} + R(x, y, z)\hat{\mathbf{k}}$$
$$\nabla \equiv \hat{\mathbf{i}}\partial_x + \hat{\mathbf{j}}\partial_y + \hat{\mathbf{k}}\partial_z$$

$$\operatorname{grad} f \equiv \nabla f = \frac{\partial f}{\partial x} \hat{\mathbf{i}} + \frac{\partial f}{\partial y} \hat{\mathbf{j}} + \frac{\partial f}{\partial z} \hat{\mathbf{k}} \qquad (\text{vector})$$

div
$$\mathbf{F} \equiv \nabla \cdot \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$
 (scalar)

$$\operatorname{curl} \mathbf{F} \equiv \nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \partial_x & \partial_y & \partial_z \\ P & Q & R \end{vmatrix}$$
 (vector)

\mathbf{F}, \mathbf{G} : vector fields, f: scalar function, ψ : either

- 1. Orthogonality of the gradient to level curves or surfaces: $\nabla f(\vec{\mathbf{x}}_0) \perp \{f(\vec{\mathbf{x}}) = f_0\}$ at $\vec{\mathbf{x}}_0$
- 2. Vector forms of the product rule (derivative of first times second plus first times derivative of second):

$$\nabla \cdot (f\mathbf{F}) = \mathbf{F} \cdot \nabla f + f \, \nabla \cdot \mathbf{F} \tag{1a}$$

$$\nabla \times (f\mathbf{F}) = (\nabla f) \times \mathbf{F} + f(\nabla \times \mathbf{F})$$
 (1b)

$$\nabla(\mathbf{F} \cdot \mathbf{G}) = \frac{(\mathbf{G} \cdot \nabla)\mathbf{F} + \mathbf{G} \times (\nabla \times \mathbf{F})}{+ (\mathbf{F} \cdot \nabla)\mathbf{G} + \mathbf{F} \times (\nabla \times \mathbf{G})}$$
(1c)

$$\nabla \cdot (\mathbf{F} \times \mathbf{G}) = (\nabla \times \mathbf{F}) \cdot \mathbf{G} - \mathbf{F} \cdot (\nabla \times \mathbf{G}) \qquad (1d)$$

$$\nabla \times (\mathbf{F} \times \mathbf{G}) = \frac{(\mathbf{G} \cdot \nabla)\mathbf{F} - (\nabla \cdot \mathbf{F})\mathbf{G}}{-(\mathbf{F} \cdot \nabla)\mathbf{G} + (\nabla \cdot \mathbf{G})\mathbf{F}}$$
(1e)

$$\nabla \cdot (\mathbf{F}\mathbf{G}) = (\nabla \cdot \mathbf{F})\mathbf{G} + (\mathbf{F} \cdot \nabla)\mathbf{G}$$
 (1f)

- 3. Curl-free property of gradient fields $(\forall f)$: $\boxed{\nabla \times \nabla f = \mathbf{0}}$
- 4. Divergence-free property of curl fields $(\forall \mathbf{F})$: $\nabla \cdot (\nabla \times \mathbf{F}) = 0$
- 5. $\operatorname{div(grad)=Laplacian:}$ $\nabla \cdot \nabla \psi = \nabla^2 \psi \equiv \Delta \psi$ (alternative math notation)
- 6. <u>curl-curl-grad(div)-Laplacian identity:</u>

$$\nabla \times (\nabla \times \mathbf{F}) = \nabla(\nabla \cdot \mathbf{F}) - \nabla^2 \mathbf{F}$$

Domains and boundaries

- 1D) domain=interval $a \le x \le b$, bdry=endpts x = a, x = b
- 2D) domain=region in xy, bdry=oriented closed curve

Righthand rule defines the "inside" of the curve

3D) domain=region in xyz, bdry=closed surface

Integral Theorems of Vector Calculus

Green's theorem in the xy plane

For region \overline{D} inside closed-curve C with no singularities of P(x,y), Q(x,y) inside C:

$$\oint_C P dx + Q dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

If singularities are present, then the values of the line and double integral are not promised to be equal.

2D Vector versions of Green's theorem

In the xy plane, with $\mathbf{F} = (P(x, y), Q(x, y), 0)$:

• <u>2D Stokes' theorem</u> (Green's Work Theorem)

Work =
$$\oint_C \mathbf{F} \cdot \vec{\mathbf{T}} \, ds = \iint_D (\nabla \times \mathbf{F}) \cdot \hat{\mathbf{k}} \, dA$$

unit tangent vector, $\vec{\mathbf{T}} = (x'(t), y'(t))/|\vec{\mathbf{x}}'(t)|$

• 2D Divergence theorem (Green's Flux Theorem)

Flux =
$$\oint_C \mathbf{F} \cdot \vec{\mathbf{n}} \, ds = \iint_D \nabla \cdot \mathbf{F} \, dA$$

unit outward normal vector, $\vec{\mathbf{n}} = (y'(t), -x'(t))/|\vec{\mathbf{x}}'(t)|$

$$\oint_C -Q \, dx + P \, dy = \iint_D (P_x + Q_y) \, dA$$

3D Stokes' theorem: Surface S with edge curve C

Work =
$$\oint_C \mathbf{F} \cdot \vec{\mathbf{T}} \, ds = \iint_S (\nabla \times \mathbf{F}) \cdot \vec{\mathbf{n}} \, dS$$

Surface integral: $\vec{\mathbf{n}}$ is the "right-thumb" unit normal to S with edge curve C with fingers gripped in the direction of C

3D Divergence theorem: Volume D enclosed by closed surface S

Flux =
$$\iiint_{S} \mathbf{F} \cdot \vec{\mathbf{n}} \, dS = \iiint_{D} \nabla \cdot \mathbf{F} \, dV$$

Other basic results

Line integrals on parametric curve $C = \{t : a \to b\}$

$$x = x(t), \quad y = y(t), \quad z = z(t)$$

unit tangent $\vec{\mathbf{T}} = \vec{\mathbf{x}}'(t)/|\vec{\mathbf{x}}'(t)|$, arclength $ds = |\vec{\mathbf{x}}'(t)| dt$

Work =
$$\int_{C} \mathbf{F} \cdot \vec{\mathbf{T}} ds = \int_{C} \mathbf{F} \cdot d\vec{\mathbf{x}}$$

= $\int_{a}^{b} \mathbf{F}(\vec{\mathbf{x}}(t)) \cdot \vec{\mathbf{x}}'(t) dt = \int_{C} P dx + Q dy + R dz$

Surface integrals

Flux =
$$\iint_S \mathbf{F} \cdot \vec{\mathbf{n}} dS = \iint_S \mathbf{F} \cdot d\mathbf{S}$$

Parametric curves

Position

$$\vec{\mathbf{x}}(t) = (x(t), y(t), z(t))$$

Velocity

$$\vec{\mathbf{v}}(t) = \frac{d\vec{\mathbf{x}}}{dt} = (x'(t), y'(t), z'(t))$$

unit Tangent vector

$$\vec{\mathbf{T}} = \hat{\mathbf{v}} = \frac{1}{|\vec{\mathbf{v}}(t)|} \vec{\mathbf{v}}(t)$$

In 2D: unit tangent and normal $\vec{\mathbf{T}} \cdot \vec{\mathbf{n}} = 0$

$$\vec{\mathbf{T}} = \frac{(x'(t), y'(t))}{\sqrt{x'(t)^2 + y'(t)^2}} \qquad \vec{\mathbf{n}} = \frac{(y'(t), -x'(t))}{\sqrt{x'(t)^2 + y'(t)^2}}$$

Derivative product rules applied to parametric curves $\vec{\mathbf{x}} = \mathbf{p}(t)$, $\vec{\mathbf{x}} = \mathbf{q}(t)$ and scalar function k(t):

$$\frac{d}{dt}(k\mathbf{p}) = \frac{dk}{dt}\mathbf{p} + k\frac{d\mathbf{p}}{dt}$$
 (2a)

$$\frac{d}{dt}(\mathbf{p} \cdot \mathbf{q}) = \frac{d\mathbf{p}}{dt} \cdot \mathbf{q} + \mathbf{p} \cdot \frac{d\mathbf{q}}{dt}$$
 (2b)

$$\frac{d}{dt}(\mathbf{p} \times \mathbf{q}) = \frac{d\mathbf{p}}{dt} \times \mathbf{q} + \mathbf{p} \times \frac{d\mathbf{q}}{dt}$$
 (2c)

Surface integrals: list of unit normal vectors \vec{n}

Parametric surface: x = x(u, v), y = y(u, v), z = z(u, v)

$$\vec{\mathbf{N}} = \frac{\partial \vec{\mathbf{x}}}{\partial u} \times \frac{\partial \vec{\mathbf{x}}}{\partial v} \longrightarrow \vec{\mathbf{n}} = \frac{\vec{\mathbf{N}}}{|\vec{\mathbf{N}}|}$$

Graph of fcn:
$$z = g(x,y)$$

$$\vec{\mathbf{n}} = \frac{(-g_x, -g_y, 1)}{\sqrt{1 + g_x^2 + g_y^2}}$$

Plane:
$$ax + by + cz = d$$
 $\vec{\mathbf{n}} = \frac{(a, b, c)}{\sqrt{a^2 + b^2 + c^2}}$

Sphere:
$$\rho = a$$
 $\vec{\mathbf{n}} = \frac{1}{a}(x, y, z)$

Circular cylinder:
$$r = a$$
 $\vec{\mathbf{n}} = \frac{\vec{a}}{a}(x, y, 0)$

$$\underline{\mathbf{Area}} \ (2D) \ \vec{\mathbf{x}}(u,v) = x \,\hat{\mathbf{i}} + y \,\hat{\mathbf{j}} \qquad x = x(u,v), \ y = y(u,v)$$

$$dA = J du dv$$
 $J = \begin{vmatrix} \frac{\partial \vec{\mathbf{x}}}{\partial u} \times \frac{\partial \vec{\mathbf{x}}}{\partial v} \end{vmatrix} = \begin{vmatrix} \begin{vmatrix} x_u & y_u \\ x_v & y_v \end{vmatrix} \end{vmatrix}$

Rectangular Area Polar Area

$$\frac{dA = dy \, dx = dx \, dy}{dA = r \, dr \, d\theta}$$

Volume (3D) $\vec{\mathbf{x}}(u, v, w) = x \,\hat{\mathbf{i}} + y \,\hat{\mathbf{j}} + z \,\hat{\mathbf{k}}$

$$x = x(u, v, w), y = y(u, v, w), z = z(u, v, w)$$

$$dV = J du dv dw$$

$$J = \left| \frac{\partial \vec{\mathbf{x}}}{\partial w} \cdot \left(\frac{\partial \vec{\mathbf{x}}}{\partial u} \times \frac{\partial \vec{\mathbf{x}}}{\partial v} \right) \right| = \left| \begin{array}{ccc} x_u & y_u & z_u \\ x_v & y_v & z_v \\ x_w & y_w & z_w \end{array} \right|$$

Rectangular Volume Cylindrical Volume Spherical Volume dV = dz dy dx $dV = r dz dr d\theta$ $dV = \rho^2 \sin \phi d\rho d\phi d\theta$

Arclength (1D) Param curves $\vec{\mathbf{x}}(t) = x(t)\hat{\mathbf{i}} + y(t)\hat{\mathbf{j}} + z(t)\hat{\mathbf{k}}$

$$ds = |\vec{\mathbf{x}}'(t)| dt = \sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2} dt$$

Graph of fcn: x = t, y = f(x), z = 0 $ds = \sqrt{1 + f'(x)^2} dx$ $\underline{\mathbf{Surface Area}}$ (2D) Param surfaces $\mathbf{\vec{x}}(u, v) = x \,\hat{\mathbf{i}} + y \,\hat{\mathbf{j}} + z \,\hat{\mathbf{k}}$ x = x(u, v), y = y(u, v), $z = z(u, v)^{-1}$

$$dS = \left| \frac{\partial \vec{\mathbf{x}}}{\partial u} \times \frac{\partial \vec{\mathbf{x}}}{\partial v} \right| du dv = \left| \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ x_u & y_u & z_u \\ x_v & y_v & z_v \end{vmatrix} \right| du dv$$

Graph of fcn: x = u, y = v, z = f(x, y) $\vec{\mathbf{x}} = x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + f(x, y)\hat{\mathbf{k}}$

$$dS = \sqrt{1 + f_x^2 + f_y^2} \, dy \, dx$$

Area in xy plane: x = u, y = v, z = 0 dS = dACircular Cylinder surface, radius r = a:

- Using Cyl coords: z = u, $\theta = v dS = a dz d\theta$ Sphere surface, radius $\rho = a$:
- Using Sph coords: $\theta = u, \phi = v \left[dS = a^2 \sin \phi \, d\phi \, d\theta \right]$ Cone surface, angle $\phi = \alpha$:
- Using Sph coords: $\theta = u, \rho = v dS = \rho \sin \alpha d\rho d\theta$
- Using Cyl coords: $\theta = u, r = v, \overline{z = r/\tan \alpha}$

 $dS = r \csc \alpha \, dr \, d\theta$

Rectangular	Cylindrical	Spherical	General
x = x	$x = r \cos \theta$	$x = \rho \sin \phi \cos \theta$	x = x(u, v, w)
y = y	$y = r \sin \theta$	$y = \rho \sin \phi \sin \theta$	y = y(u, v, w)
z = z	z = z	$z = \rho \cos \phi$	z = z(u, v, w)

Note: The "||stuff||" in the general formula for dS means "the <u>length</u> of the cross product vector given by the <u>determinant</u>." For the Jacobian in dA and dV the double bars mean the <u>absolute value</u> of the determinant.