FOUNDATIONS FOR A GENERAL THEORY OF FUNCTIONS OF A VARIABLE COMPLEX MAGNITUDE

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If we consider z to be a variable magnitude which can gradually assume all possible real values, then we call w a function of z, when each of its real values corresponds to a single value of undetermined magnitude such as w_0 . If w also constantly change while z continuously goes through all the value lying between two fixed values, then we call this function within these intervals a constant or a continuous function.

Obviously, this definition does not set up any absolute law between the individual values of the function, because when we assign a determinate value to this function, the way in which it continues outside of this interval remains totally arbitrary.

We can express the slope function (dependence) of magnitude w(z) by a mathematical law so that we can find the corresponding value of w for every value of z through determinate numerical operations (Groessen operationen). Previously, people have only considered a certain kind of function (functiones continuae according to Euler's usage) as having the ability of being able to determine all the value of z lying between a given interval by using that same slope function law; however, in the meantime, new research has shown that there are analytic expressions that can represent each and every constant function for a given interval z. This holds, regardless of whether the slope function of magnitude z is conditionally defined as an arbitrary given numerical operation, or as an determinate numerical operation. As a result of the theorems mentioned above, both concepts are congruent.

But the situation is different when we do not limit the variability of magnitude z to real values, but instead allow complex values of the form x + yi (where $i = \sqrt{-1}$).

Assume that x+yi and x+yi+dx+dyi are two infinitesimally slightly different values for magnitude z, which correspond to the values u+vi and u+vi+du+dvi for magnitude w. So then, if the slope function of magnitude w(z) is an arbitrarily given one, then generally speaking, the ratio $\frac{du+dvi}{dx+dyi}$ changes for the values for

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¹Sentences which I do not understand are typeset in blue.

²Fourier theorem.

dx, dy, because when we have $dx + dyi = \varepsilon e^{\varphi i}$, then

$$\begin{array}{lcl} \frac{du+dv\,i}{dx+dy\,i} & = & \frac{1}{2}\left(\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}\right)+\frac{1}{2}\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right)i\\ \\ & & +\frac{1}{2}\left[\frac{\partial u}{\partial x}-\frac{\partial v}{\partial y}+\left(\frac{\partial v}{\partial x}+\frac{\partial u}{\partial y}\right)i\right]\frac{dx-dy\,i}{dx+dy\,i}\\ \\ & = & \frac{1}{2}\left(\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}\right)+\frac{1}{2}\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right)i\\ \\ & & +\frac{1}{2}\left[\frac{\partial u}{\partial x}-\frac{\partial v}{\partial y}+\left(\frac{\partial v}{\partial x}+\frac{\partial u}{\partial y}\right)i\right]e^{-2\varphi i} \end{array}$$

³ However, regardless of the manner in which we define w as a function of z through these simple numerical operation, the value of the differential quotient $\frac{dw}{dz}$ is always independent of the special values of differential dz. Obviously, not every arbitrary slope function of complex magnitude w (complex magnitude z) can be expressed in this manner.

$$\begin{pmatrix} du \\ dv \end{pmatrix} = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix}.$$

We also want that

$$du + dvi = (c + di)(dx + dyi) + o(dx + dyi),$$

where c + di is a complex number, and

$$\lim_{dx+dyi\to 0} \frac{o(dx+dyi)}{dx+dyi} = 0.$$

So

$$\begin{pmatrix} du \\ dv \end{pmatrix} = \begin{pmatrix} c & -d \\ d & c \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix}.$$

So

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} = c, \frac{\partial v}{\partial x} = -\frac{\partial u}{\partial y} = d.$$

Riemann's derivation gives us more information than the modern method we give above. If the Cauchy-Riemann equations are not satisfied by $\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}$, then the linear map from \mathbf{R}^2 to \mathbf{R}^2 maps a circle centering at the (0,0) to an ellipse, Riemann's derivation provide us error term $\frac{1}{2} \left[\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) i \right] e^{-2\varphi i}$.

³Here we give a modern derivation of the Cauchy-Riemann equations.Let f(x,y)=(u,v), where $f: \mathbf{R}^2 \to \mathbf{R}^2$ is differentiable. So there is a linear map which maps (dx,dy) to (du,dv), i.e,