# Algorithm and Data Structure Analysis (ADSA)

Correctness and Invariants: Example Binary
Search
(Book Chapter 2)

# Overview

- Correctness of algorithms/programs
- Invariants
- Binary Search

# Correctness of Algorithms

You want to have algorithms that are

- Correct
- and efficient

### Correctness has highest priority.

You want to be sure that your program does what you want.

## **Invariants**

- Invariants are a powerful tool to show correctness of an algorithm/program
- An invariant is a property of an algorithm that holds during the execution of the program.
- It is often used to show correctness of loops
- Define: Preconditions, Invariants, and Postconditions

Often it is non-trivial to find an invariant.

# Example

Consider the following while loop

```
int x=10;
while (x < 20){
x=x+1;
}</pre>
```

Precondition: Before entering the while-loop x < 20 holds. Invariant: During the execution of the while-loop x < 20 holds. Postcondition: After execution of the while-loop x < 20 but

not x<20 holds. This implies that x=20 holds.

# Let's play a game

a = {1, ..., 15} consists of all integers from 1, ..., 15.

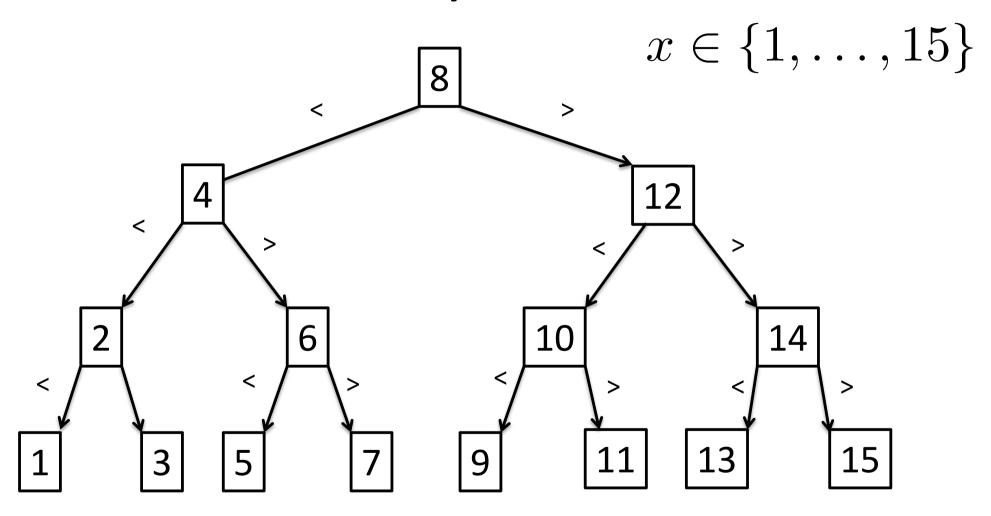
Player 1 picks a secret number x of a. Player 2 has to guess x.

- Player 2: Can query in each step a number y
- Answer of Player 1 is either
  - found if x=y
  - x is greater than y
  - x is smaller than y

#### You are Player 2:

What is your strategy to use the smallest number of queries to reveal x?

# **Binary Search**



At most 3 comparisons to determine x

#### **Problem Statement:**

 Given: A sorted array a[1 ..n] of pairwise distinct elements, i.e.

$$a[1] < a[2] < ... < a[n]$$
, and an element x  $a[0] = -\infty$  and  $a[n+1] = \infty$ 

Find: Index i such that a[i-1] < x ≤ a[i]</li>

# **Binary Search**

#### Divide-and-conquer algorithm

#### Procedure:

- Choose index index  $m \in [1..n]$
- Compare x with a[m]
- If x=a[m] we are done
- If x < a[m], search in the part of the array before a[m].
- If x > a[m], search in the part of the array after a[m].

- Use two indices I and r.
- Maintain the invariant

(I) 
$$0 \le l < r \le n+1$$
 and  $a[l] < x < a[r]$ 

- Start with I=0 and r=n+1
- Choose m in the middle of the interval defined by l and r.
- If x ≠ a[m], change I or r accordingly.
- If I and r are consecutive indices then x is not contained in the array.

# Binary Search Program

Mehlhorn/Sanders (page 35)

Choose the middle of current interval

## **Invariant Part 1**

$$0 \le l < r \le n+1$$

Loop is entered with  $0 \le l < r \le n+1$ 

If l+1=r, we stop

Otherwise,  $l+2 \leq r$ 

and hence l < m < r.

Implies that m is a legal array index

If x = a[m], we stop

Otherwise we set either r = m or l = m

and hence  $0 \le l < r \le n+1$  at the end

of the loop. Algorithm and Data Structure Analysis

## **Invariant Part 2**

Loop is entered with 
$$a[l] < x < a[r]$$
If  $l+1=r$ , we stop
Otherwise,  $l+2 \le r$ 
and hence  $l < m < r$ .
If  $x=a[m]$ , we stop
If  $x < a[m]$ , we set  $r=m$  which implies  $a[l] < x < a[r]$  at the end of the loop.

If  $x > a[m]$ , we set  $l=m$  which implies  $a[l] < x < a[r]$  at the end of the loop.

## **Termination**

- If an iteration is not the last one, we either increase I or decrease r.
- Hence r-l decreases.
- Implies that the search terminates.

## Runtime

#### Theorem:

Binary search finds an element in a sorted array of size n in  $2 + |\log n|$  comparisons between elements.

#### **Proof:**

Study the number of indices i with l < i < r.

There are r - l - 1 such indices.

We call the number of such indices the size of the problem.

#### Idea:

Show that each iteration (except the last one) halves the size of the problem.

## **Proof**

Let r-l-1 be the size of the problem.

Then the size of the problem decreases to

$$\max\{r - \lfloor (r+\ell)/2 \rfloor - 1, \lfloor (r+\ell)/2 \rfloor - \ell - 1\}$$

$$\leq \max\{r - ((r+\ell)/2 - 1/2) - 1, (r+\ell)/2 - \ell - 1\}$$

$$= \max\{(r-\ell-1)/2, (r-\ell)/2 - 1\} = (r-\ell-1)/2$$

Hence the size of the problem is at least halved

## **Proof**

We start with problem size r - l - 1 = n + 1 - 0 - 1 = n.

After 1 iterations:  $r - l - 1 \le \lfloor n/2 \rfloor$ .

After k iterations:  $r - l - 1 \le \lfloor n/2^k \rfloor$ .

Interation k+1 is the last if we enter it with r=l+1.

This holds if  $n/2^k < 1$ .

Choosing  $k = \log n + 1$  implies  $n/2^k < 1$ .

Hence, at most  $2 + \log n$  iterations are performed.

Number of comparisons is natural number which implies the  $2 + \lfloor \log n \rfloor$  bound.

# Summary

- Invariants are an important tool to show correctness of algorithms/programs.
- Binary Search is effective to locate elements in a sorted array.
- Algorithm maintains two invariants.
- It halves the problem size in each iteration.
- This implies O(log n) comparisons.