

Homework 3 – Tony Yuan

Github link for Matlab codes: <https://github.com/YeTonyYuan/Math-714>

A(a i) Taking total derivative w.r.t. to t on $u(x(t), t) = c$, we get $\partial_t u(x(t), t) + \partial_x u(x(t), t)x'(t) = 0$.

(a ii) $x'(t) = -\frac{\partial_t u(x(t), t)}{\partial_x u(x(t), t)} = a$.

(a iii) $x(t) = at + x_0$. Since $u(x(t), t)$ is a constant along $x(t)$, $u(x(t), t) = u(x(0), 0) = u_0(x_0)$.

(a iv) $u(at + x_0, t) = u_0(x_0)$. $u(x, t) = u(at + (x - at), t) = u_0(x - at)$.

(b i) We need $u \in L_1$. $\hat{u}_0(\xi)$ is infinitely differentiable. $u_0(\xi) \rightarrow 0$ as $|\xi| \rightarrow \infty$.

(b ii) $v(x) = \frac{1}{2\pi} \int_{\mathbb{R}} e^{i\xi x} v(\xi) d\xi$. Taking derivative on both sides and move differentiation inside the integral, we have $v'(x) = \frac{1}{2\pi} \int_{\mathbb{R}} e^{i\xi x} i\xi \hat{v}(\xi) d\xi$.

(b iii)

$$\begin{aligned} \mathcal{F}[v(\cdot - h)](\xi) &= \int_{\mathbb{R}} e^{-i\xi x} v(x - h) dx \\ &= \int_{\mathbb{R}} e^{-i\xi(x+h)} v(x) dx \\ &= e^{-i\xi h} \hat{v}(\xi). \end{aligned}$$

(b iv) $\partial_t \hat{u}(\xi, t) = \int_{\mathbb{R}} e^{-i\xi x} u_t(x, t) dx = \int_{\mathbb{R}} e^{-i\xi x} (-a) u_x(x, t) dx = -a i \xi \hat{u}(\xi, t)$ by part (ii).

(b v) By solving the ODE from part (iv), we have $\hat{u}(\xi, t) = e^{-ai\xi t} \hat{u}_0(\xi)$.

(b vi) By Plancherel's Theorem, $\hat{u}_0 \in L_2$. Then $\hat{u}(\cdot, t) \in L_2$ for any fixed t , $u(\cdot, t) \in L_2$ for any fixed t by Plancherel again.

(b vii) This follows directly from taking the inverse FT.

(b viii) $\hat{u}(\xi, t) = e^{-ai\xi t} \hat{u}_0(\xi) = \mathcal{F}[u_0(\cdot - at)](\xi)$. By the inversion formula, $u(x, t) = u_0(x - at)$.

B(a) Let $u = e^{i(kx - wt)}$. Then $-iw = \pm k^4$. $u = e^{ikx} e^{\pm k^4 t}$. It is stable only when we have the minus sign.

B(b) $\frac{\rho-1}{\Delta t} = -\frac{1}{\Delta x^4}$, $|\rho| = |1 - \frac{\Delta t}{\Delta x^4}| < 1$. $\Delta t < 2\Delta x^4$.

B(c) We can use backward Euler method.

C(a)

$$\begin{aligned}
& \frac{u(x, y, t + \Delta t) - 2u(x, y, t) + u(x, y, t - \Delta t))}{\Delta t^2} - \Delta u \\
&= (u_{tt} + \frac{\Delta t^2}{12} u_{tttt} + \dots) - \Delta u \\
&= (u_{tt} - \Delta u) + \frac{\Delta t^2}{12} \Delta^2 u + \mathcal{O}(\Delta t^4)
\end{aligned}$$

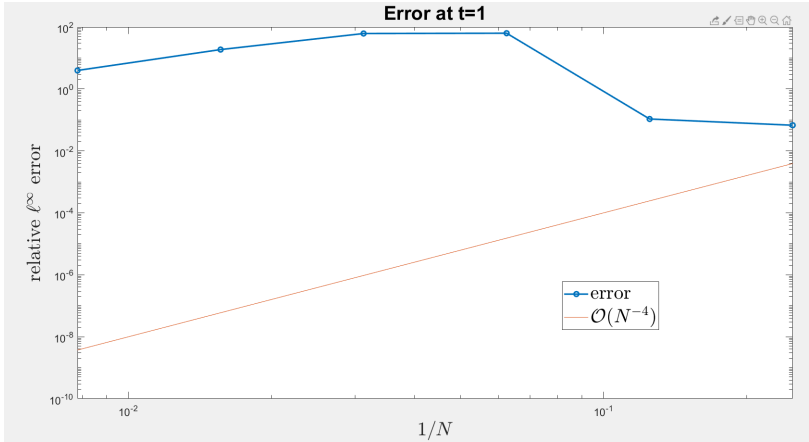
since $u_{tttt} = (\Delta u)_{tt} = \Delta(u_{tt}) = \Delta^2 u$.

Thus, $\frac{u(x, y, t + \Delta t) - 2u(x, y, t) + u(x, y, t - \Delta t))}{\Delta t^2} - \Delta u - \frac{\Delta t^2}{12} \Delta^2 u = 0$ yields fourth order accuracy in time in the solution.

C(b)

$$\begin{cases} \frac{u^1 - u^{-1}}{2\Delta t} = u_t^0 + \frac{\Delta t^2}{6} u_{ttt}^0 = u_t^0 + \frac{\Delta t^2}{6} \Delta u_t^0 \\ \frac{u^1 - 2u^0 + u^{-1}}{\Delta t^2} = u_{tt}^0 + \frac{\Delta t^2}{12} u_{tttt}^0 = \Delta u^0 + \frac{\Delta t^2}{12} \Delta^2 u^0 \end{cases}$$

$$u^1 = u^0 + \Delta t u_t^0 + \frac{\Delta t^3}{6} \Delta u_t^0 + \frac{\Delta t^2}{2} \Delta u^0 + \frac{\Delta t^4}{24} \Delta^2 u_t^0.$$

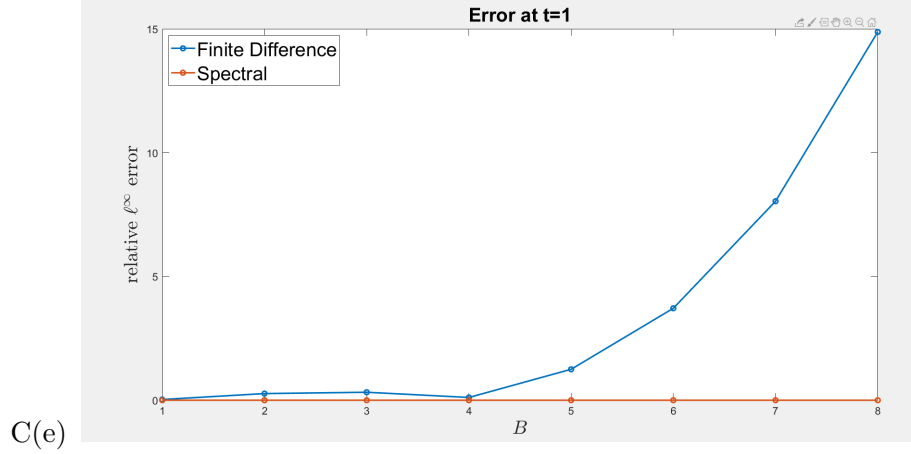


C(c)

C(d) The largest eigenvalue of Δu in magnitude is $-0.096N^4$ and then the largest eigenvalue of $\Delta^2 u$ is $0.096^2 N^8$.

The largest eigenvalue in magnitude of $\Delta u + \frac{\Delta t^2}{12} \Delta^2 u$, $\lambda = -0.096N^4 + \frac{\Delta t^2}{12} \cdot 0.096^2 N^8$.

Since $-4 \leq \lambda \Delta t^2 \leq 0$, then $-4 \leq -0.096 \Delta t^2 N^4 + \frac{\Delta t^4}{12} \cdot 0.096^2 N^8 \leq 0$. $0.096 \Delta t^2 N^4 \leq 12$, $\Delta t \leq 11.18 N^{-2}$.



C(e)

I choose $N = 32$ due to the heavy computations. The number of points per wavelength from my finite difference method is 16 and I am unable to find it for the spectral method due to limitation of computations.

D

$$\begin{aligned}
 |\hat{f}(\xi)| &= \left| \int_{\mathbb{R}} e^{-i\xi x} f(x) dx \right| \\
 &= \frac{1}{|\xi|} \left| \int_{\mathbb{R}} (-i\xi) e^{-i\xi x} f(x) dx \right| \\
 &= \frac{1}{|\xi|} \left| \int_{\mathbb{R}} e^{-i\xi x} f'(x) dx \right| \text{ by integration by parts} \\
 &\leq \frac{1}{|\xi|} \int_{\mathbb{R}} |f'(x)| dx \\
 &= \|f\|_{TV} |\xi|^{-1}.
 \end{aligned}$$

If f is not differentiable almost everywhere, we simply approximate f by C^1 functions that converge to f , which is feasible since $f \in L_1$.