

OPERATING SYSTEM CONCEPTS

Chapter 5. CPU Scheduling

A/Prof. Kai Dong

Warm-up

Process Execution — Time-sharing

OS @run (kernel mode) Hardware

Program (user mode)

Process A

timer interrupt save regs(A) to k-stack(A) move to kernel mode jump to timer handler

handle *trap* call switch() routine

save regs(A) to PCB(A) restore regs(B) from PCB(B) switch to k-stack(B) return-from-trap (into B)

> restore regs(B) from k-stack(B) move to user mode jump to B's PC

> > Process B

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Warm-up Scheduler & Dispatcher



- Who makes the decision of which runs next?
 - CPU scheduler

Warm-up

Scheduler & Dispatcher



- Who makes the decision of which runs next?
 - CPU scheduler
- Who performs the context switch?
 - Dispatcher

Objectives



- To introduce CPU scheduling, which is the basis for multiprogrammed operating systems
- To describe various CPU-scheduling algorithms
- To discuss evaluation criteria for selecting a CPU-scheduling algorithm for a particular system
- To examine the scheduling algorithms of several operating systems

Contents

- Basic Concepts
- 2. Scheduling Criteria
- 3. Simple Scheduling Algorithms
- 4. Multilevel Feedback Queue
- Lottery Scheduling
- Thread Scheduling
- Multiple-Processor Scheduling
- 8. Real-Time CPU Scheduling



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 - 3. Switches from waiting to ready
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 - 1. Switches from running to waiting state
 - 2. Switches from running to ready state
 - 3. Switches from waiting to ready
 - 4. Terminates
- Scheduling under 1 and 4 is nonpreemptive
- All other scheduling is preemptive
 - Consider access to shared data
 - Consider preemption while in kernel mode
 - Consider interrupts occurring during crucial OS activities

Dispatcher



• **Dispatcher** module gives control of the CPU to the process selected by the short-term scheduler; this involves:

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 - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running

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Methodology on Evaluation



• How to conduct evaluation in a scientific paper?

Methodology on Evaluation



- How to conduct evaluation in a scientific paper?
- Benchmark
 - Comparing algorithms
 - Datasets, or scenario assumptions
 - Certain metrics

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- Benchmark
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- For CPU scheduling
 - Scheduling algorithms
 - Workload assumptions
 - Scheduling criteria

Common Scheduling Criteria

• CPU utilization — keep the CPU as busy as possible



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- Throughput # of processes that complete their execution per time unit

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 Waiting time — amount of time a process has been waiting in the ready queue

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- Waiting time amount of time a process has been waiting in the ready queue
- Response time amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)

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Simple Scheduling Algorithms Workload Assumptions



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 - Assume also that each job runs for 10 seconds.



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 - Assume that while they all arrived simultaneously, A arrived just a hair before B which arrived just a hair before C.
 - Assume also that each job runs for 10 seconds.
- What will the average turnaround time be for these jobs?

FCFS (contd.)



• First draw a Gantt Chart

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30

A

B

C

FCFS (contd.)



First draw a Gantt Chart

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
				,	4									E	3									(2					

- Then compute
 - A finished at 10, B at 20, and C at 30.
 - The average turnaround time is

$$\frac{10 + 20 + 30}{3} = 20$$



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 - Let's relax assumption 1. How does FIFO perform now?



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Question:

- Is FIFO optimal given assumptions 1-5?
- Let's relax assumption 1. How does FIFO perform now?
- What kind of workload could you construct to make FIFO perform poorly?



• Assume three jobs (A, B, and C), but this time A runs for 10 seconds while B and C run for 1 second each.

FCFS (contd.)



Assume three jobs (A, B, and C), but this time A runs for 10 seconds while B and C run for 1 second each.

1	2	3	4	5	6	7	8	9	10	11	12	
				A	4					В	С	

- A finished at 10, B at 11, and C at 12.
- The average turnaround time is

$$\frac{10+11+12}{3}=1$$



 Convoy effect — number of relatively-short potential consumers of a resource get queued behind a heavyweight resource consumer.



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 - B or C runs first, and A runs at last.



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1	2	3	4	5	6	7	8	9	10	11	12	
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- B finished at 1, C at 2, and A at 12, .
- The average turnaround time is

$$\frac{12+1+2}{3} = \frac{1}{3}$$

Simple Scheduling Algorithms Priority



 The SJF algorithm is a special case of the general priority-scheduling algorithm.

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- Example

Procsss	Burst Time	Priority
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• Draw the Gantt chart for priority scheduling, considering all processes P_1 - P_5 arrived at time 0.

Simple Scheduling Algorithms Priority (contd.)



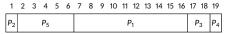
• We assume that low numbers represent high priority

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
P ₂			P ₅							F	1					F	3	P ₄

Simple Scheduling Algorithms Priority (contd.)



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Problem: Starvation — low priority processes may never execute

Simple Scheduling Algorithms Priority (contd.)



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1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
P_2			P ₅							F	P ₁					F	3	P ₄

- Problem: Starvation low priority processes may never execute
- Solution: Aging as time progresses increase the priority



 Highest Response Ratio Next (HRRN) — the next job is not that with the shorted estimated run time, but that with the highest response ratio defined as

$$response_ratio = 1 + \frac{waiting_time}{estimated_run_time}$$



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Another modification of SJF or Priority.



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 - Is SJF optimal given assumption 2-5?
 - Let's relax assumption 2. How does SJF perform now?



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Assume three jobs (A, B, and C), but this time A arrives at T = 0 and needs to run for 10 seconds, whereas B and C arrive at T = 1 and each need to run for 1 second.



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- A finished at 10, B at 11, and C at 12.
- The average turnaround time is

$$\frac{10 + (11 - 1) + (12 - 1)}{3} = 10.33$$



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 - 5. The run-time of each job is known.
- To address this concern, we need to relax assumption 3.

Preemptive Vs. Non-preemptive



 Preemptive, and non-preemptive schedulers — Whether a job can preempt another job

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- The dispatcher performs a context switch.
- Think of preemptive version of SJF and Priority.

Preemptive SJF



 Preemptive Shortest Job First (preemptive SJF, or Shortest Time-to-Completion First (STCF), or Shortest-Remaining-Time First (SRTF)

Preemptive SJF



Preemptive Shortest Job First (preemptive SJF, or Shortest
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 First (SRTF)

- A finished at 12, B at 2, and C at 3.
- The average turnaround time is

$$\frac{12+(2-1)+(3-1)}{3}=1$$

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- Preemptive SJF is not good for response time.
- Can you build a scheduler that is sensitive to response time?

RR

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- RR is sometimes called time-slicing.
- Assume three jobs A, B, and C arrive at the same time in the system, and that they each wish to run for 5 seconds, the length of time slice is 1 second

- The average response time is

$$\frac{0+1+2}{3} = \frac{1}{3}$$



• For the length of time slice, the shorter the better?



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- For the length of time slice, the shorter the better?
 - Take into account the cost in context switch.
- RR is awful in turnaround time. Is it?
 - Any policy that is fair, performs poorly on performance metrics such as turnaround time.
 - Trade-off between fairness and performance.

Simple Scheduling Algorithms Incorporating I/O



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 - 5. The run-time of each job is known.
- Let's relax assumption 4.

Simple Scheduling Algorithms Incorporating I/O (contd.)



 Assume two jobs, A and B. A runs for 1 second and then issues an I/O request which also takes 1 second, B simply uses the CPU for 5 seconds and performs no I/O.



Incorporating I/O (contd.)



 Assume two jobs, A and B. A runs for 1 second and then issues an I/O request which also takes 1 second, B simply uses the CPU for 5 seconds and performs no I/O.

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
CPU	Α		Α		Α		Α		Α		Α			В		
I/O		Α		Α		Α		Α		Α						

Break a job to sub-jobs due to I/O requests.

	1	2	3	4	5	6	7	8	9	10	11
CPU	Α	В	Α	В	Α	В	Α	В	Α	В	Α
I/O		Α		Α		Α		Α		Α	

Relax All Assumptions



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- Let's relax assumption 5.

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 - How to schedule without perfect knowledge?

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- Let's relax assumption 5.
 - How to schedule without perfect knowledge?
 - How to trade-off between fairness and performance?

Determining Length of Next CPU Burst in SJF



- Can only estimate the length should be similar to the previous one
 - Then pick process with shortest predicted next CPU burst

Determining Length of Next CPU Burst in SJF



- Can only estimate the length should be similar to the previous one
 - Then pick process with shortest predicted next CPU burst
- Can be done by using the length of previous CPU bursts, using exponential averaging
 - 1. $t_n = \text{actual length of } n^{th} \text{ CPU burst}$
 - 2. τ_{n+1} = predicted value for the next CPU burst
 - 3. α , $0 \le \alpha \le 1$
 - 4. Estimate: $\tau_{n+1} = \alpha t_n + (1 \alpha) \tau_n$

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 - 4. Estimate: $\tau_{n+1} = \alpha t_n + (1 \alpha)\tau_n$
- Commonly, α set to 1/2

- Ready queue is partitioned into separate queues, e.g.:
 - foreground (interactive)
 - background (batch)



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- Process permanently in a given queue
- Each queue has its own scheduling algorithm:
 - foreground RR
 - background FCFS
- Scheduling must be done between the queues:
 - Fixed priority scheduling; (i.e., serve all from foreground then from background). Possibility of starvation.
 - Time slice each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR, 20% to background in FCFS

In Class Exercise

Consider the following set of processes, with the length of the CPU burst given in milliseconds:

Process	Burst Time	Priority
P ₁	2	2
P ₂	1	1
P ₃	8	4
P ₄	4	2
P ₅	5	3

The processes are assumed to have arrived in the order of P_1 , P_2 , P_3 , P_4 , P_5 , all at time 0.

- Draw four Gantt charts that illustrate the execution of these processes using the following scheduling algorithms: FCFS, SJF, non-preemptive priority (a larger priority number implies a higher priority), and RR (quantum = 2).
- 2. What is the turnaround time of each process for each of the scheduling algorithms in part 1?
- 3. What is the waiting time of each process for each of these scheduling algorithms?
- 4. Which of the algorithms results in the minimum average waiting time (over all processes)?

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 - MLQ uses priorities to decide which job should run at a given time.
 - » A job with higher priority is chosen to run.
 - » Use round-robin (or other) scheduling among the jobs which have the same priority.

MLQ: Basic Rules



- Two basic rules for MLQ:
 - Rule 1: If Priority(A) > Priority(B), A runs (B doesn't).
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- MLFQ varies the priority of a job based on its behavior.
 - MLFQ will try to learn about processes as they run, and thus use the history of the job to predict its future behavior.

How To Change Priority

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How To Change Priority



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- The scheduler doesn't know whether a job will be a short job or a long-running job.

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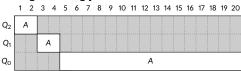


- For a new coming job ...
- The scheduler doesn't know whether a job will be a short job or a long-running job.
- The scheduler first assumes it might be a short job (given high priority).
- If it actually is a short job, it will run quickly and complete;
- If it is not a short job, it will slowly move down the queues, and thus soon prove itself to be a long job.

How To Change Priority (contd.)



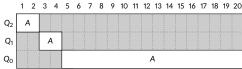
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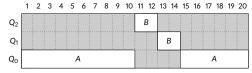
How To Change Priority (contd.)



• A long-running job A:



• Along came a short job B:





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- Is our current version of MLFQ perfect?

Multilevel Feedback Queue Limitations

Starvation

 If there are "too many" interactive jobs in the system, they will combine to consume all CPU time, and thus long-running jobs will never receive any CPU time (they starve).



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 Doing something sneaky to trick the scheduler into giving you more than your fair share of the resource (e.g., by running for 99% of a time slice before relinquishing the CPU).

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Changeable program behaviors

 A program may change its behavior over time; what was CPU bound may transition to a phase of interactivity. With our current approach, such a job would be out of luck and not be treated like the other interactive jobs in the system.

The Priority Boost

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The Priority Boost

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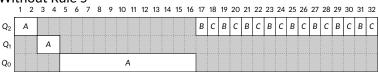


- How to solve these problems?
- Periodically boost the priority
- Rule 5: After some time period S, move all the jobs in the system to the topmost queue.
- Some problems are solved
 - First, processes are guaranteed not to starve.
 - Second, if a CPU-bound job has become interactive, the scheduler treats it properly once it has received the priority boost.

The Priority Boost (contd.)



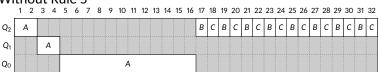
• Without Rule 5



The Priority Boost (contd.)



Without Rule 5



• With Rule 5 (priority boost every 10 ms)

	1 2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21 22	23	24	25	26	27	28	29	30	31 32
Q_2	Α									,	4					В	С	В	С	Α	В	С	В	С	В	С	В	С	Α
Q ₁		Α										1	4																
Q ₀						A	4							A	4														

Better Accounting

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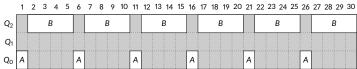


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- Better accounting of CPU time
 - Rule 4: Once a job uses up its time allotment at a given level (regardless of how many times it has given up the CPU), its priority is reduced (i.e., it moves down one queue).

Better Accounting (contd.)



• With old Rule 4



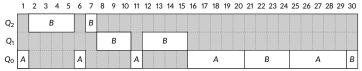
Better Accounting (contd.)



With old Rule 4



• With new Rule 4 (time slice = 5 ms)



Multilevel Feedback Queue Tuning MLFQ

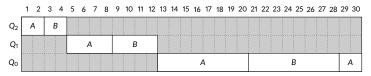


• How big should the time slice be per queue?

Tuning MLFQ



- How big should the time slice be per queue?
- Varying time-slice length across different queues.
 - Lower priority, longer quanta.



MLFQ Rules: The Final Version



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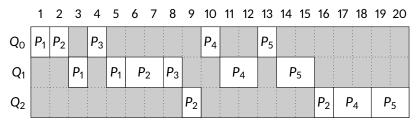
In Class Exercise

Given the table below showing the process information of a system, based on multilevel feedback queuing scheduling scheme. Suppose there are five levels in the system and within each level the FCFS scheduling is used. Draw a Gantt chart to show the time of CPU allocated to each process until all processes are finished using time quantum $q=2^i$, (where q= time allocated for a process to run in its turn, and i ranges from 0 to 4 indicating the i^{th} level queue).

Process	Arrival Time	Service Time						
P ₁	0	3						
P ₂	1	5						
P ₃	3	2						
P ₄	9	5						
P ₅	12	5						

Кеу





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Proportional Share



- Suppose a virtualized data center, where
 - You might like to assign one-quarter of your CPU cycles to the Windows VM and the rest to your base Linux installation

Proportional Share



- Suppose a virtualized data center, where
 - You might like to assign one-quarter of your CPU cycles to the Windows VM and the rest to your base Linux installation
- Proportional-share scheduler (fair-share scheduler)
 - Instead of optimizing for turnaround or response time, a scheduler might instead try to guarantee that each job obtain a certain percentage of CPU time.

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- Every so often, hold a lottery to determine which process should get to run next;
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- Tickets are used to represent the share of a resource that a process (or user or whatever) should receive.
 - Ticket currency Currency allows a user with a set of tickets to allocate tickets among their own jobs in whatever currency they would like; the system then automatically converts said currency into the correct global value.
 - Ticket transfer A process can temporarily hand off its tickets to another process.
 - Ticket inflation A process can temporarily raise or lower the number of tickets it owns.

An Unfairness Metric



 Suppose two jobs competing against one another, each with the same number of tickets and same run time.

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 - The time the first job completes divided by the time that the second job completes.

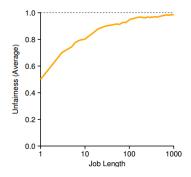
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Probabilistic Vs. Deterministic



- Lottery scheduling is probabilistic.
 - Only as the jobs run for a significant number of time slices does the lottery scheduler approach the desired fairness.
- Stride scheduling, is a deterministic fair-share scheduler.
 - Each job in the system has a stride, which is inverse in proportion to the number of tickets it has.
 - Every time a process runs, we will increment a counter for it (called its pass value) by its stride to track its global progress.
 - At any given time, pick the process to run that has the lowest pass value so far.

Stride Scheduling

 Suppose three processes (A, B and C), with stride values of 100, 200 and 40, and all with pass values initially at 0.

Pass(A) (stride=100)	Pass(B) Pass(C) (stride=200)		Who Runs?
0	0	0	Α
100	0	0	В
100	200	0	С
100	200	40	С
100	200	80	С
100	200	120	Α
200	200	120	С
200	200	160	С
200	200	200	•••

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100	200	80	С
100	200	120	Α
200	200	120	С
200	200	160	С
200	200	200	•••

• Why using probabilistic, not deterministic?

Lottery Scheduling Why Not Deterministic?



- Lottery scheduling has one nice property that stride scheduling does not: no global state.
 - Imagine a new job enters in the middle of our stride scheduling example above; what should its pass value be? Should it be set to 0? If so, it will monopolize the CPU.

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- Many-to-one and many-to-many models, thread library schedules user-level threads to run on LWP
 - Typically done via priority set by programmer
 - Known as process-contention scope (PCS) since scheduling competition is within the process

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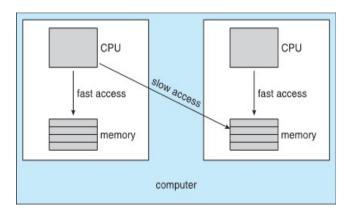
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- Caches in multi-processor Architecture
 - Cache Affinity (a.k.a., Processor Affinity) A process, when run on a particular CPU, builds up a fair bit of state in the caches of the CPU. The next time the process runs, it is often advantageous to run it on the same CPU, as it will run faster if some of its state is already present in the caches on that CPU

Multiple-Processor Scheduling Cache Affinity

Memory-placement algorithms can also consider affinity.



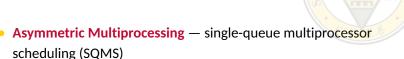




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CPU ₁	В	Α	Ε	D	С
CPU ₂	С	В	Α	Ε	D
CPU ₃	D	С	В	Α	Ε

CPU ₀	Α	Ε		Α	
CPU ₁	E	3	Е В		3
CPU ₂	С			Ε	С
CPU ₃		ı)		Ε



Symmetric Multiprocessing



 Symmetric Multiprocessing — multi-queue multiprocessor scheduling (MQMS)



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- Load imbalance problem.
 - Migration By migrating a job from one CPU to another, true load balance can be achieved.

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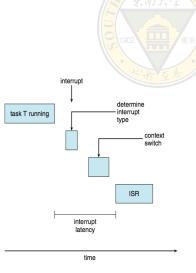
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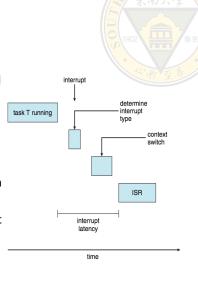
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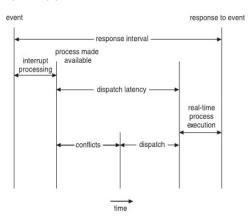
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 - Dispatch latency time for schedule to take current process off CPU and switch to another



- Conflict phase of dispatch latency:
 - Preemption of any process running in kernel mode
 - Release by low-priority process of resources needed by high-priority processes



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