

OPERATING SYSTEM CONCEPTS

Chapter 4. Threads

A/Prof. Kai Dong



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 - How to speed up execution?



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 - Example #1: adding two large arrays together
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 - Example #2: some elements need input
 - How to speed up execution?
- Why multiple threads, not multiple processes?
 - We are now detailing the reasons.

Objectives

- To introduce the notion of a thread a fundamental unit of CPU utilization that forms the basis of multithreaded computer systems
- To discuss the APIs for the Pthreads, Windows, and Java thread libraries
- To explore several strategies that provide implicit threading
- To examine issues related to multithreaded programming
- To cover operating system support for threads in Windows and Linux

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- 1. Overview
- 2. Multicore Programming
- 3. Multithreading Models
- 4. Thread Libraries
- 5. Implicit Threading
- 6. Threading Issues



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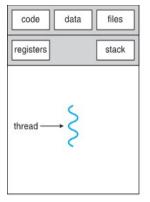


Motivation

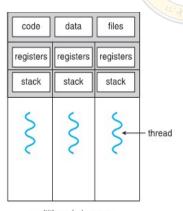
- Most modern applications are multithreaded
- Threads run within application
- Multiple tasks with the application can be implemented by separate threads
 - Update display
 - Fetch data
 - Spell checking
 - Answer a network request
- Process creation is heavy-weight while thread creation is light-weight
- Can simplify code, increase efficiency
- Kernels are generally multithreaded



Single and Multithreaded Processes



single-threaded process



multithreaded process

Benefits



 Responsiveness — may allow continued execution if part of process is blocked, especially important for user interfaces

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- Economy cheaper than process creation, thread switching lower overhead than context switching

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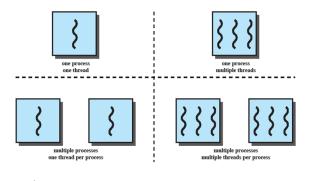
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- Resource Sharing threads share resources of process, easier than shared memory or message passing
- Economy cheaper than process creation, thread switching lower overhead than context switching
- Scalability process can take advantage of multiprocessor architectures

Multithreading

= instruction trace

MS-DOS	JRE
UNIX	most OS





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- Multicore or multiprocessor systems putting pressure on programmers, challenges include:
 - Dividing activities
 - Balance
 - Data splitting
 - Data dependency
 - Testing and debugging

- 京南大學
- Multicore or multiprocessor systems putting pressure on programmers, challenges include:
 - Dividing activities
 - Balance
 - Data splitting
 - Data dependency
 - Testing and debugging
- Parallelism implies a system can perform more than one task simultaneously
- Concurrency supports more than one task making progress
 - Single processor / core, scheduler providing concurrency

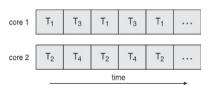
Concurrency Vs. Parallelism



• Concurrent execution on single-core system:



• Parallelism on a multi-core system:



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- Types of parallelism
 - Data parallelism distributes subsets of the same data across multiple cores, same operation on each
 - Task parallelism distributing threads across cores, each thread performing unique operation

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 - CPUs have cores as well as hardware threads
 - Consider Oracle SPARC T4 with 8 cores, and 8 hardware threads per core

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 - Task parallelism distributing threads across cores, each thread performing unique operation
- As # of threads grows, so does architectural support for threading
 - CPUs have cores as well as hardware threads
 - Consider Oracle SPARC T4 with 8 cores, and 8 hardware threads per core
- How much performance can we gain from adding additional cores? Suppose we have N processing cores.

Amdahl's Law

 Identifies performance gains from adding additional cores to an application that has both serial and parallel components

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- That is, if application is 75% parallel / 25% serial, moving from 1 to 2 cores results in speedup of 1.6 times
- As N approaches infinity, speedup approaches 1/S
- Serial portion of an application has disproportionate effect on performance gained by adding additional cores



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User Threads and Kernel Threads

• Who/How to provide support for threads?



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- User threads management done by user-level threads library

Kernel threads - Supported by the Kernel



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- Three primary thread libraries:
 - POSIX Pthreads
 - Windows threads
 - Java threads
- Kernel threads Supported by the Kernel

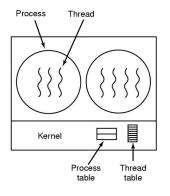


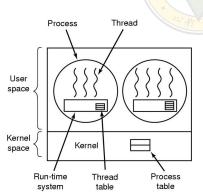
User Threads and Kernel Threads

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- User threads management done by user-level threads library
- Three primary thread libraries:
 - POSIX Pthreads
 - Windows threads
 - Java threads
- Kernel threads Supported by the Kernel
- Examples virtually all general purpose operating systems, including:
 - Windows
 - Solaris
 - Linux
 - Tru64 UNIX
 - Mac OS X



Implementing Threads in Kernel/User Space





Kernel Threads

User Threads

Motivating Kernel/User Threads

• Why we need user threads?



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 - In a multiprocessor environment, the kernel can schedule threads on different processors
- Why kernel threads are not enough?
 - Kernel threads are usually slower than the user threads.





- Many-to-One
- One-to-One
- Many-to-Many

Many-to-One

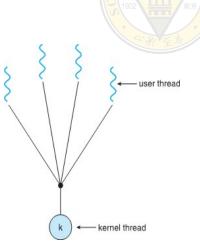
 Many user-level threads mapped to single kernel thread

 One thread blocking causes all to block

 Multiple threads may not run in parallel on multicore system

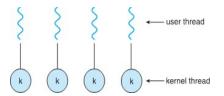
 Used on systems that do not support kernel threads.

 Few systems currently use this model



One-to-One

- Each user-level thread maps to kernel thread
- Creating a user-level thread creates a kernel thread
- More concurrency than many-to-one
- Number of threads per process sometimes restricted due to overhead

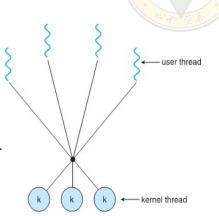




Many-to-Many

Allows many user level threads to be mapped to many kernel threads

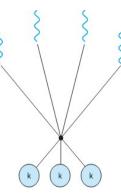
 Allows the operating system to create a sufficient number of kernel threads



Two-Level Model



 Similar to M:M, except that it allows a user thread to be bound to kernel thread





Multithreading Models Aside



- Among the three models, which model(s) are general in modern systems?
 - M:M for server
 - 1:1 for PC
 - To improve LinuxThreads, two competing projects were started to develop a replacement; NGPT (Next Generation POSIX Threads from IBM) and NPTL (Native POSIX Thread Library from Red Hat). NPTL won out and is today shipped with the vast majority of Linux systems
 - » NGPT M:M
 - » NPTL 1:1

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- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS
- Three main thread libraries
 - POSIX Pthreads
 - Windows
 - Java

Pthreads



- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization

Pthreads



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- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- Specification, not implementation
- API specifies behavior of the thread library, implementation is up to development of the library

Pthreads



- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- Specification, not implementation
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Solaris, Linux, Mac OS X)

Pthread Creation

```
#include <pthread.h>
int
pthread_create( pthread_t * thread,

const pthread_attr_t *attr,
void * (*start_routine) (void*),
void * arg);
```

- 1. Which thread is to be created?
 - A pointer to structure of this thread.
- 2. What kind of thread is it?
 - The stack size and priority information, etc.
- 3. How to run the thread?
 - The thread entry function (function pointer in C).
- 4. With what arguments?
 - arg.

Pthread Creation — What is the Output?

```
#include <pthread.h>
2
 3
    typedef struct myarg t {
4
             int a:
            int b:
6
    } myarg t;
7
    void *mythread(void *arg) {
8
9
             myarg t *m = (myarg t *) arg;
             printf("%d %d\n", m->a, m->b):
10
11
             return NULL:
12
13
    int main(int argc, char *argv[]) {
14
15
             pthread t p;
16
             int rc;
17
             myarg_t args;
18
             args.a = 10;
19
             args.b = 20;
             rc = pthread_create(&p, NULL, mythread, &args);
20
21
22
```

Pthread Completion



- 1. Which thread is to be completed?
 - A pointer to structure of this thread.
- 2. What is the return value?
 - void **value_ptr.

Pthread Completion — What is the Output?

```
#include <stdio.h>
    #include <pthread.h>
2
    #include <assert h>
    #include < stdlib.h>
 5
    typedef strct __myarg_t {
7
      int a:
8
      int b:
9
    } myarg_t;
10
    typedef struct myret t {
11
12
       int x:
13
       int v:
     } myret t;
14
15
    void *mvthread(void *arg) {
16
17
       myarg t *m = (myarg t *) arg;
18
       printf("%d %d\n", m->a, m->b);
       mvret t *r = Malloc(sizeof(
19
             myret t));
20
      r -> x = 1:
      r -> v = 2:
22
      return (void *) r;
23
```



```
int main(int argc, char *argv[]) {
      int rc;
3
       pthread t p;
4
       mvret t *m:
       myarg t args;
       args \rightarrow a = 10;
       args \rightarrow b = 20:
       Pthread create(&p. NULL.
Q
             mythread, &args);
       Pthread join(p. (void **) &m):
9
       printf("returned %d %d\n", m->x.
10
              m->v):
11
       return 0;
```

Windows Multithreaded C Program

```
#include <windows.h>
    #include <stdio.h>
3
    DWORD Sum:
    DWORD WINAPI Summation (LPVOID
          Param) {
5
      DWORD Upper = *(DWORD *) Param:
      for (DWORD i = 0; i <= Upper; i
6
             ++)
7
        Sum+=i:
8
      return 0:
9
10
11
    int main(int argc. char *argv[]) {
12
      DWORD ThreadId:
      HANDLE ThreadHandle:
14
       int Param:
       if (argc != 2) {
15
         fprintf(stderr, "argc!=2\n");
16
17
         return -1:
18
       Param = atoi(argv[1]):
19
       if (Param < 0) {
21
         fprintf(stderr . "Param < 0 \ n"):</pre>
         return -1:
23
```

```
/* create the thread */
    ThreadHandle = CreateThread(
      NULL, /* default security
            attributes */
      O. /* default stack size */
      Summation, /* thread function */
      &Param. /* parameter to thread
            function */
      O, /* default creation flags */
      &ThreadId): /* returns the
Q
            thread identifier */
9
10
      if (ThreadHandle != NULL) {
        /* now wait for the thread to
11
              finish */
        WaitForSingleObject (
              ThreadHandle . INFINITE):
14
        /* close the thread handle */
        CloseHandle (ThreadHandle):
16
        printf("sum = %d\n", Sum);
18
19
```

Java Threads



- Java threads are managed by the JVM
- Typically implemented using the threads model provided by underlying OS
- Java threads may be created by:

```
public interface Runnable {
   public abstract void run();
}
```

- Extending Thread class
- Implementing the Runnable interface

Java Multithreaded Program

```
class Sum {
      private int sum;
      public int getSum() {
4
        return sum:
      public void setSum(int sum) {
6
        this.sum = sum:
9
    class Summation implements Runnable {
10
11
      private int upper;
      private Sum sumValue:
12
      public Summation(int upper, Sum sumValue) {
14
        this.upper = upper:
15
        this.sumValue = sumValue;
16
      public void run() {
18
        int sum = 0:
19
        for (int i = 0; i \le upper; i ++)
          sum += i:
21
        sumValue.setSum(sum);
```

Java Multithreaded Program (contd.)

```
public class Driver {
      public static void main(String[] args) {
3
        if (args.length > 0) {
          if (Integer.parseInt(args[0]) < 0)</pre>
4
            System.err.println(args[0] + "must be >= 0."):
6
          else {
            Sum sumObject = new Sum();
8
            int upper = Integer.parseInt(args[0]):
9
            Thread thrd = new Thread(new Summation(upper, sumObject)):
            thrd.start():
11
            trv {
               thrd.ioin():
               System.out.println("The sum of " + upper + " is " + sumObiect.
                    getSum());
             } catch (InterruptedException ie) {}
14
15
16
        else
          System.err.println("Usage: Summation <integer value>"):
18
19
```

In Class Exercise

What are Possible Outputs?

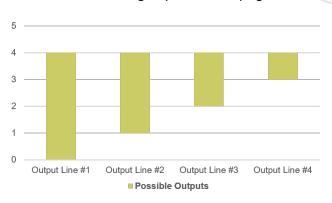


```
void *helloFunc(void *ptr) {
            int *data:
            data = (int *) ptr;
            printf("I'm Thread %d\n", *data):
4
5
6
    int main(int argc, char *argv[]) {
8
            pthread t hThread[4]:
9
            for (int i = 0; i < 4; i ++)
10
                     pthread create(&hThread[i], NULL, helloFunc, (void *) &i);
            for (int i = 0: i < 4: i ++)
11
12
                     pthread ioin(hThread[i], NULL):
            return 0:
14
```

In Class Exercise

Key

Non-decreasing sequence satisfying ...



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Implicit Threading



- Growing in popularity as numbers of threads increase, program correctness more difficult with explicit threads
- Creation and management of threads done by compilers and run-time libraries rather than programmers

Implicit Threading

Thread Pools

- Create a number of threads in a pool where they await work
- Advantages:
 - Usually slightly faster to service a request with an existing thread than create a new thread
 - Allows the number of threads in the application(s) to be bound to the size of the pool
 - Separating task to be performed from mechanics of creating task allows different strategies for running task
 - » i.e. Tasks could be scheduled to run periodically
- Windows API supports thread pools:

```
DWORD WINAPI PoolFunction(AVOID Param) {

/*

* this function runs as a separate thread.

*/

5 }
```

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- Semantics of fork() and exec() system calls
- Thread cancellation of target thread
 - Asynchronous or deferred
- Signal handling
 - Synchronous and asynchronous
- Thread-local storage
- Scheduler Activations



- If one thread in a program calls fork(), does the new process duplicate all threads, or is the new process single-threaded?
 - Two versions of fork().



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- If one thread in a program calls fork(), does the new process duplicate all threads, or is the new process single-threaded?
 - Two versions of fork().
- What about exec()?
 - Replace the entire process, including all thread.
- Discussion: If exec() is called immediately after forking, which version of fork() do you prefer?
 - If exec() is called immediately after forking, then duplicating all threads is unnecessary

Thread Cancellation

- Terminating a thread before it has finished
- Thread to be canceled is target thread



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- Two general approaches:
 - Asynchronous cancellation terminates the target thread immediately
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Thread Cancellation

- Terminating a thread before it has finished
- Thread to be canceled is target thread
- Two general approaches:
 - Asynchronous cancellation terminates the target thread immediately
 - Deferred cancellation allows the target thread to periodically check if it should be canceled
- Pthread code to create and cancel a thread:

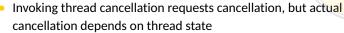
```
pthread_t tid;

/* create the thread */
pthread_create(&tid, 0, worker, NULL);

/* cancel the thread */
pthread_cancel(tid);
```



Thread Cancellation (contd.)





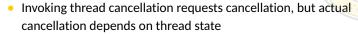
Thread Cancellation (contd.)

 Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Mode	State	Туре
Off	Disabled	_
Deferred	Enabled	Deferred
Asynchronous	Enabled	Asynchronous



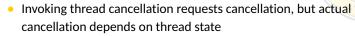
Thread Cancellation (contd.)



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 If thread has cancellation disabled, cancellation remains pending until thread enables it

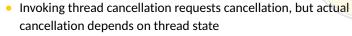
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- Default type is deferred
 - Cancellation only occurs when thread reaches cancellation point
 - » i.e., pthread_testcancel()
 - » Then cleanup handler is invoked

Thread Cancellation (contd.)



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- Default type is deferred
 - Cancellation only occurs when thread reaches cancellation point
 - » i.e., pthread_testcancel()
 - » Then cleanup handler is invoked
- On Linux systems, thread cancellation is handled through signals

Signal Handling

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 - Signal is generated by particular event
 - Signal is delivered to a process
 - Signal is handled by one of two signal handlers:
 - » default
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 - Signal is generated by particular event
 - Signal is delivered to a process
 - Signal is handled by one of two signal handlers:
 - » default
 - user-defined
- Every signal has default handler that kernel runs when handling signal
 - User-defined signal handler can override default
 - For single-threaded, signal delivered to process



Signal Handling (contd.)



- Where should a signal be delivered for multi-threaded?
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals for the process

Signal Handling (contd.)



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 - Assign a specific thread to receive all signals for the process
- Discussion: Can a thread have its own handler?

Signal Handling (contd.)



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 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals for the process
- Discussion: Can a thread have its own handler?
 - All threads in a process share a same signal handler, which can be either a default one or a user-defined one (overridden).

Thread-Local Storage

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 - Life cycle reasons. Local variables are in thread stack



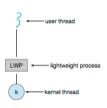
Scheduler Activations

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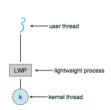
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- Scheduler activations provide upcalls a communication mechanism from the kernel to the upcall handler in the thread library. (vs. downcalls)
- This communication allows an application to maintain the correct number kernel threads



Scheduler Activations (contd.)

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- If we wish to run this application efficiently, how many LWPs are needed for this application.