Chapter 4 Network Layer: Data Plane Part 2

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Miscellaneous

PA3 release today

- Project specification released
 - https://docs.qq.com/sheet/DSUNqSmJYVnJMb2Nk?groupUin=0laSTOMmleqHpllKdKvaLw%253D%253D&tab=BB08J2
 - https://github.com/Nancyzxy/CS305-proj

Quick review

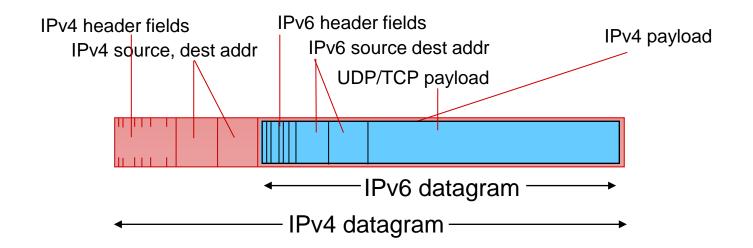
- Network-layer
 - Queue drop policy and scheduling
 - IP datagram structure: 20-60 Bytes
 - IP addressing: CIDR, subnet part, host part
 - DHCP
 - NAT
 - IPv6

ipconfig /renew

| Г | 843 13.098103 | 10.16.95.67 | 172.18.19.31 | DHCP | 358 DHCP Request | - Transaction ID 0xa4f8c833 |
|---|---------------|--------------|--------------|------|------------------|-----------------------------|
| L | 845 13.133405 | 172.18.19.31 | 10.16.95.67 | DHCP | 342 DHCP ACK | - Transaction ID 0xa4f8c833 |

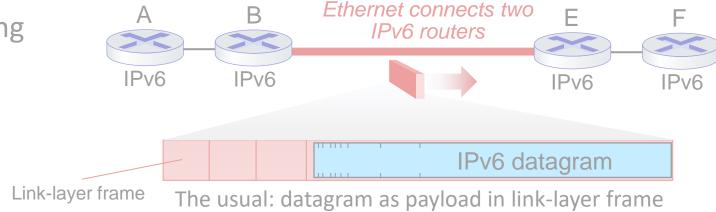
Transition from IPv4 to IPv6

- not all routers can be upgraded simultaneously
 - no "flag days"
 - how will network operate with mixed IPv4 and IPv6 routers?
- tunneling: IPv6 datagram carried as payload in IPv4 datagram among IPv4 routers ("packet within a packet")
 - tunneling used extensively in other contexts (4G/5G)

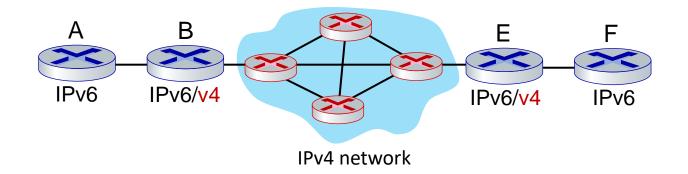


Tunneling and encapsulation

Ethernet connecting two IPv6 routers:

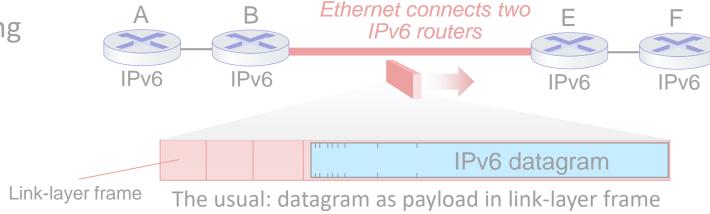


IPv4 network connecting two IPv6 routers

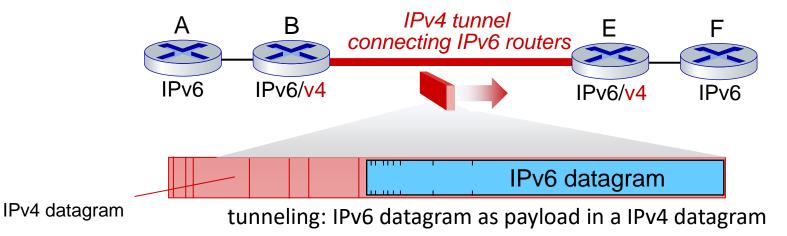


Tunneling and encapsulation

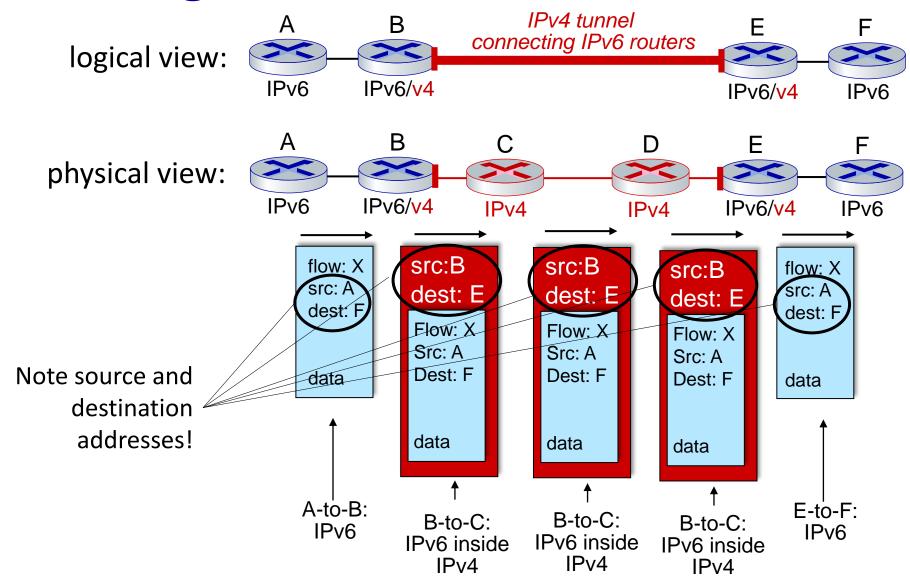
Ethernet connecting two IPv6 routers:



IPv4 tunnel connecting two IPv6 routers

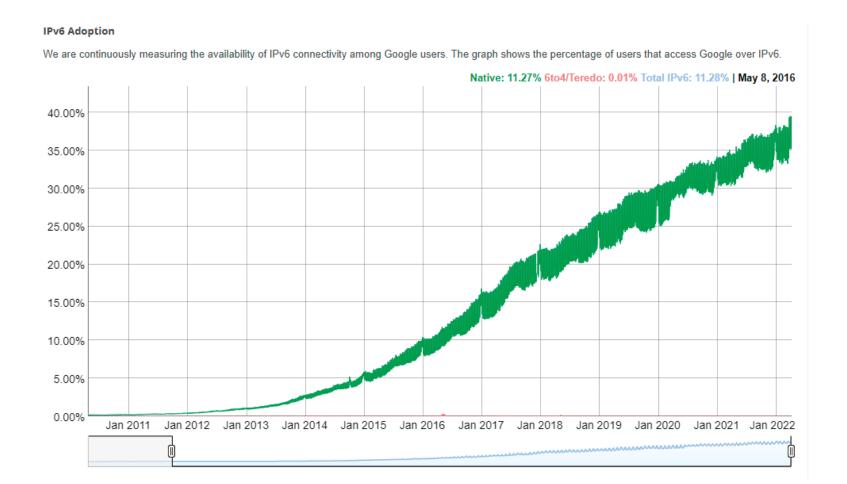


Tunneling



IPv6: adoption

Google¹: ~ 40% of clients access services via IPv6



https://www.google.com/intl/en/ipv6/statistics.html

IPv6: adoption

- 中央部委、省级政府门户网站IPv6支持率达到81.42%
- 互联网网站对IPv6的支持率仅为33.7%



https://network.51cto.com/article/685981.html

IPv6: adoption

- Google¹: ~ 30% of clients access services via IPv6
- Long (long!) time for deployment, use
 - 25 years and counting!
 - think of application-level changes in last 25 years: WWW, social media, streaming media, gaming, telepresence, ...
 - · Why?

¹ https://www.google.com/intl/en/ipv6/statistics.html

Network layer: "data plane" roadmap

- Network layer: overview
 - data plane
 - control plane
- What's inside a router
 - input ports, switching, output ports
 - buffer management, scheduling
- IP: the Internet Protocol
 - datagram format
 - addressing
 - network address translation
 - IPv6

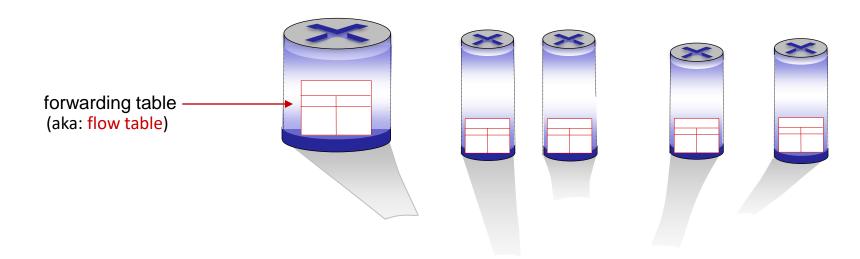


- Generalized Forwarding, SDN
 - Match+action
 - OpenFlow: match+action in action

Generalized forwarding: match plus action

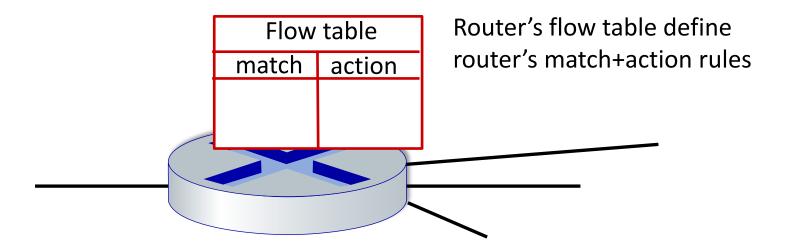
Review: each router contains a forwarding table (aka: flow table)

- "match plus action" abstraction: match bits in arriving packet, take action
 - destination-based forwarding: forward based on dest. IP address
 - generalized for warding
 - many header fields can determine action
 - many action possible: drop/copy/modify/log packet



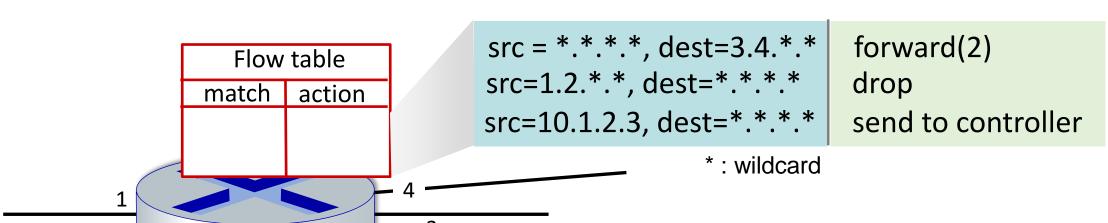
Flow table abstraction

- flow: defined by header field values (in link-, network-, transport-layer fields)
- generalized forwarding: simple packet-handling rules
 - match: pattern values in packet header fields
 - actions: for matched packet: drop, forward, modify, matched packet or send matched packet to controller
 - priority: disambiguate overlapping patterns
 - counters: #bytes and #packets

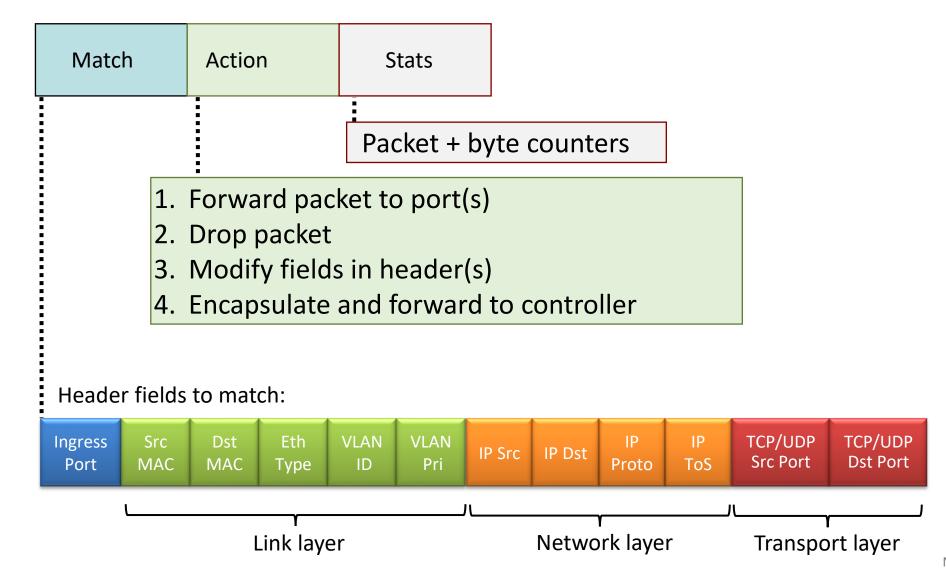


Flow table abstraction

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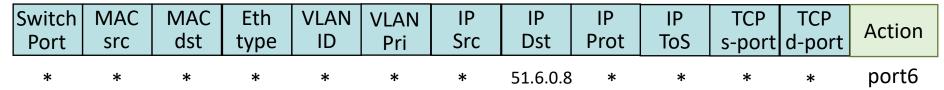


OpenFlow: flow table entries



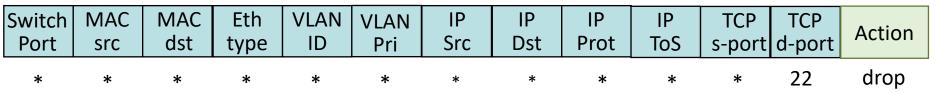
OpenFlow: examples

Destination-based forwarding:

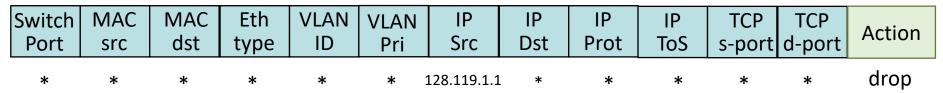


IP datagrams destined to IP address 51.6.0.8 should be forwarded to router output port 6

Firewall:



Block (do not forward) all datagrams destined to TCP port 22 (ssh port #)



Block (do not forward) all datagrams sent by host 128.119.1.1

OpenFlow: examples

Layer 2 destination-based forwarding:

| Switch | MAC | MAC | Eth | VLAN | VLAN | IP | IP | IP | IP | TCP | TCP | Action |
|--------|-----|-----------------------|------|------|------|-----|-----|------|-----|--------|--------|--------|
| Port | src | dst | type | ID | Pri | Src | Dst | Prot | ToS | s-port | d-port | |
| * | * | 22:A7:23: 11:E1:02 | * | * | * | * | * | * | * | * | * | port3 |

layer 2 frames with destination MAC address 22:A7:23:11:E1:02 should be forwarded to output port 3

OpenFlow abstraction

match+action: abstraction unifies different kinds of devices

Router

- match: longest destination IP prefix
- action: forward out a link

Switch

- match: destination MAC address
- action: forward or flood

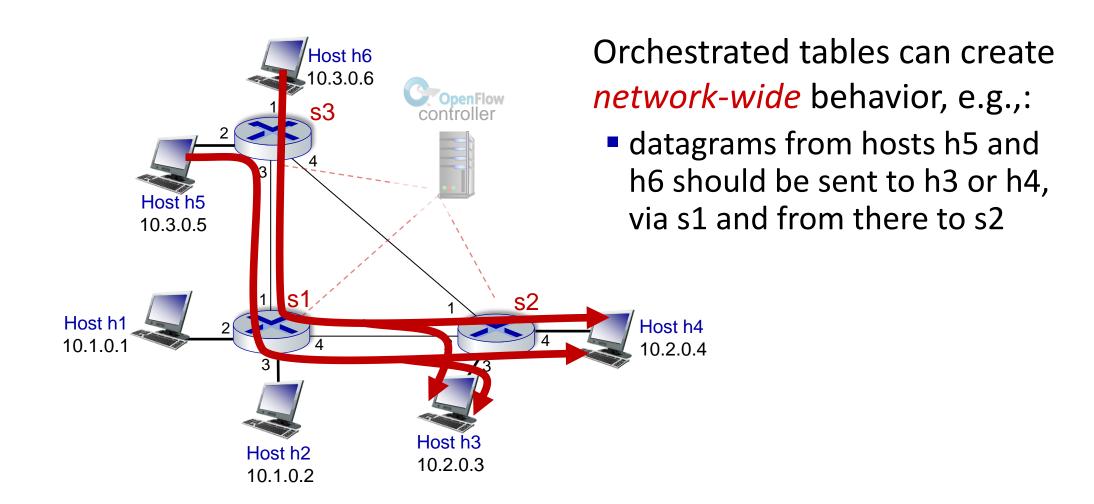
Firewall

- match: IP addresses and TCP/UDP port numbers
- action: permit or deny

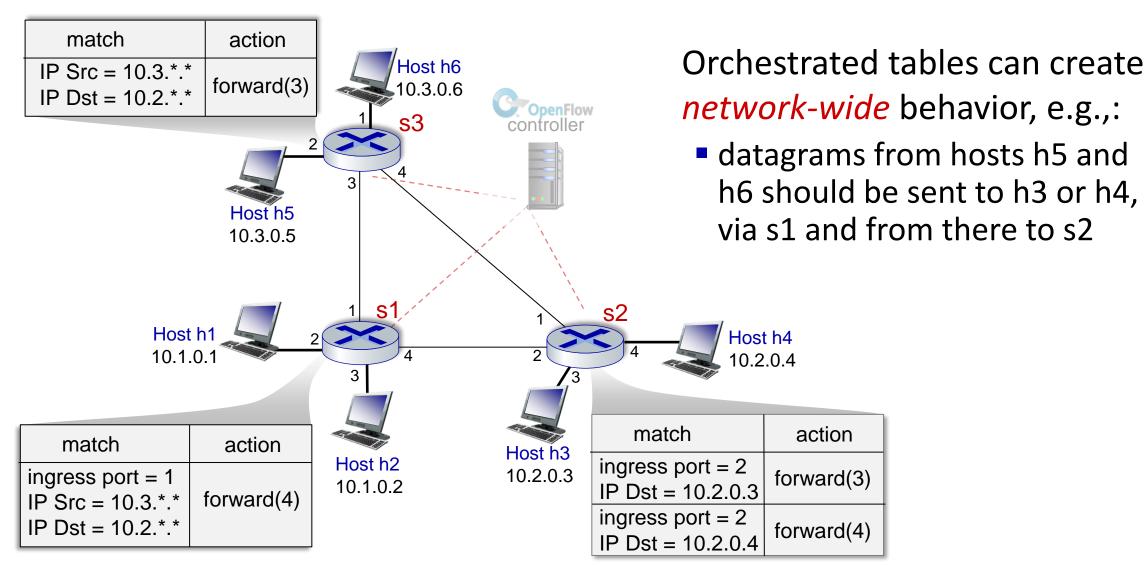
NAT

- match: IP address and port
- action: rewrite address and port

OpenFlow example



OpenFlow example



Generalized forwarding: summary

- "match plus action" abstraction: match bits in arriving packet header(s) in any layers, take action
 - matching over many fields (link-, network-, transport-layer)
 - local actions: drop, forward, modify, or send matched packet to controller
 - "program" network-wide behaviors
- simple form of "network programmability"
 - programmable, per-packet "processing"
 - historical roots: active networking
 - *today:* more generalized programming: P4 (see p4.org).

Chapter 4: done!

- Network layer: overview
- What's inside a router
- IP: the Internet Protocol
- Generalized Forwarding, SDN



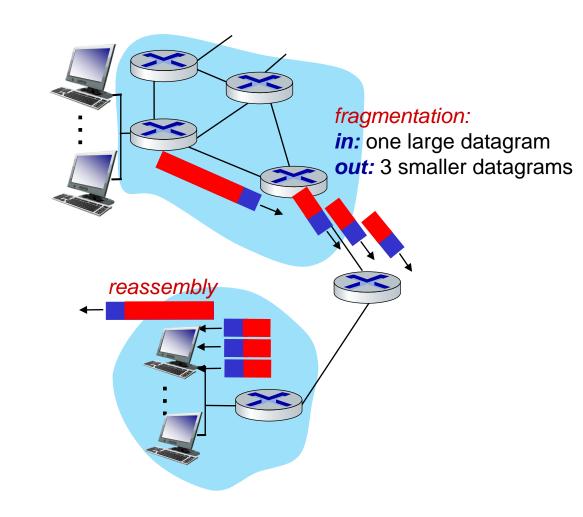
Question: how are forwarding tables (destination-based forwarding) or flow tables (generalized forwarding) computed?

Answer: by the control plane (next chapter)

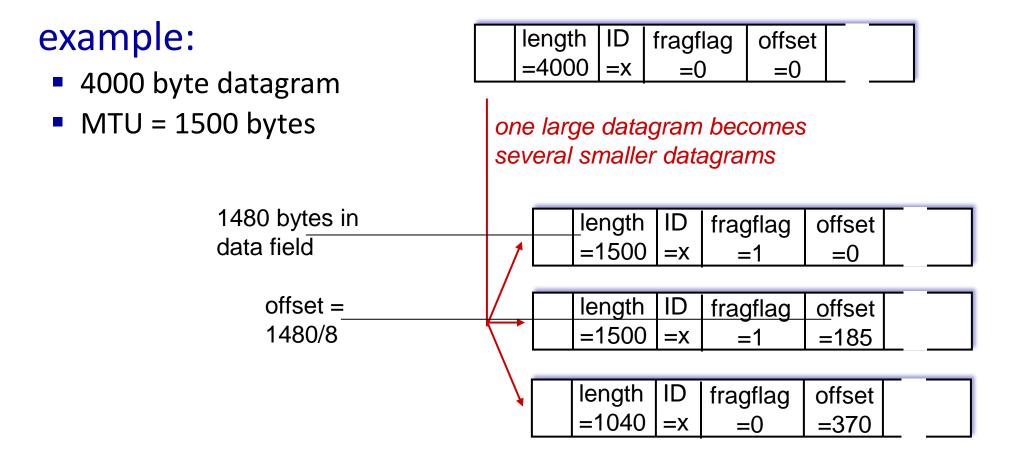
Additional Chapter 4 slides

IP fragmentation/reassembly

- network links have MTU (max. transfer size) - largest possible link-level frame
 - different link types, different MTUs
- large IP datagram divided ("fragmented") within net
 - one datagram becomes several datagrams
 - "reassembled" only at destination
 - IP header bits used to identify, order related fragments



IP fragmentation/reassembly



Chapter 5 Network Layer: Control Plane Part 1

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Network layer: "control plane" roadmap

- introduction
- routing protocols
 - link state
 - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol



- network management, configuration
 - SNMP
 - NETCONF/YANG

Network-layer functions

- forwarding: move packets from router's input to appropriate router output
- routing: determine route taken by packets from source to destination

data plane

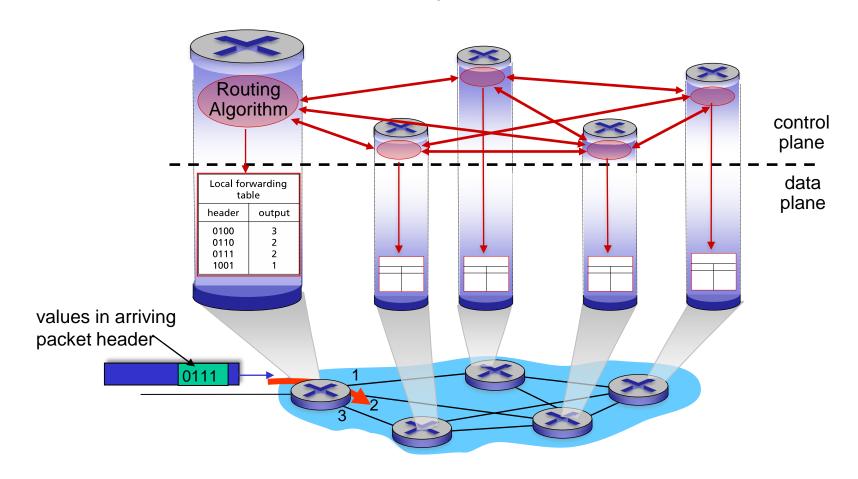
control plane

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

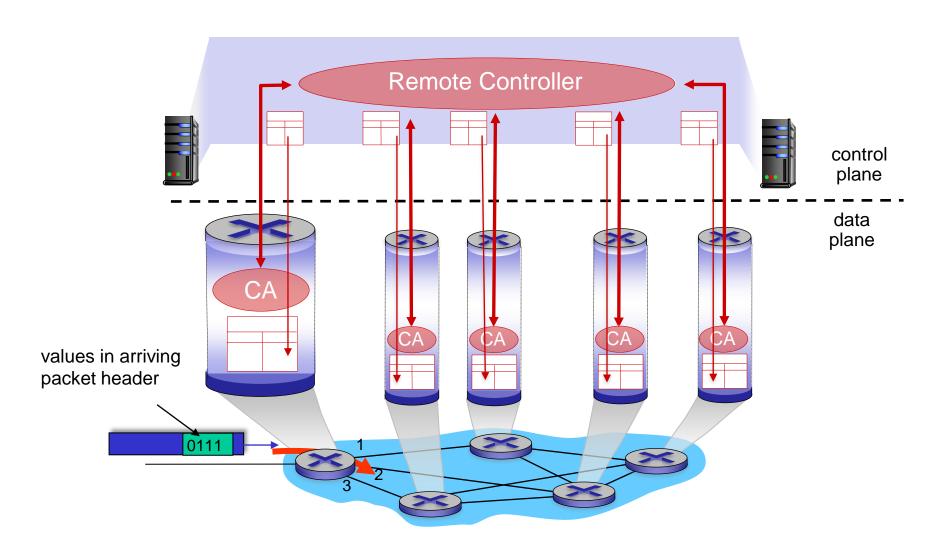
Per-router control plane

Individual routing algorithm components in each and every router interact in the control plane



Software-Defined Networking (SDN) control plane

Remote controller computes, installs forwarding tables in routers



Network layer: "control plane" roadmap

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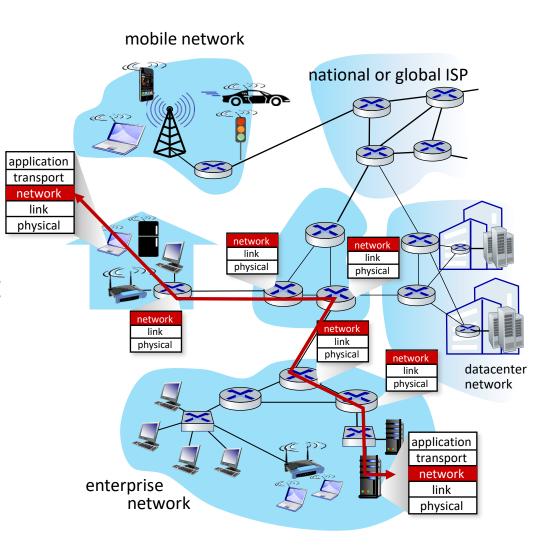


- network management, configuration
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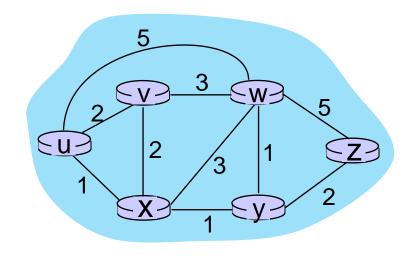
Routing protocols

Routing protocol goal: determine "good" paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- path: sequence of routers packets traverse from given initial source host to final destination host
- "good": least "cost", "fastest", "least congested"
- routing: a "top-10" networking challenge!



Graph abstraction: link costs



graph: G = (N, E)

14p11. 0 - (74,2)

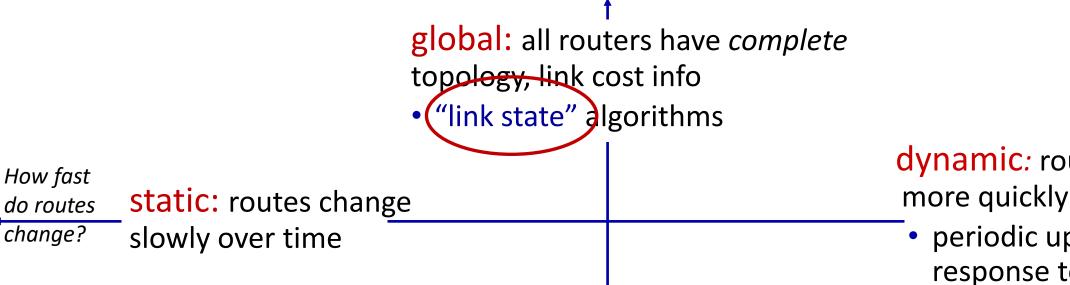
N: set of routers = $\{u, v, w, x, y, z\}$

E: set of links = { (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) }

 $c_{a,b}$: cost of *direct* link connecting a and b e.g., $c_{w,z} = 5$, $c_{u,z} = \infty$

cost defined by network operator: could always be 1, or inversely related to bandwidth, or inversely related to congestion

Routing algorithm classification



dynamic: routes change

 periodic updates or in response to link cost changes

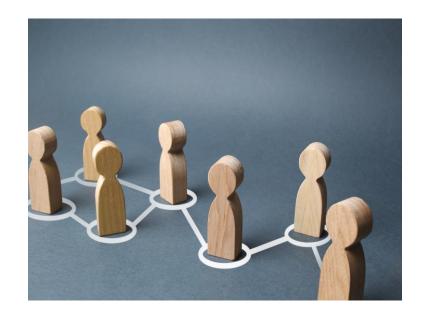
decentralized: iterative process of computation, exchange of info with neighbors

- routers initially only know link costs to attached neighbors
- ("distance vector") algorithms

global or decentralized information?

Network layer: "control plane" roadmap

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Dijkstra's link-state routing algorithm

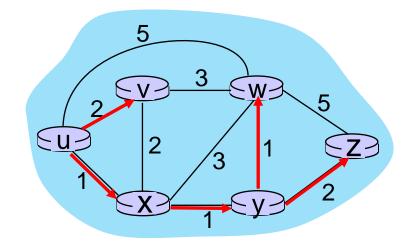
- centralized: network topology, link costs known to all nodes
 - accomplished via "link state broadcast"
 - all nodes have same info
- computes least cost paths from one node ("source") to all other nodes
 - gives *forwarding table* for that node
- iterative: after k iterations, know least cost path to k destinations

notation

- $c_{x,y}$: direct link cost from node x to y; = ∞ if not direct neighbors
- D(v): current estimate of cost of least-cost-path from source to destination v
- p(v): predecessor node along path from source to v
- N': set of nodes whose leastcost-path definitively known

Dijkstra's algorithm: an example

| | | V | W | X | y | \overline{z} |
|------|----------------|----------|-------------|----------|------------|----------------|
| Step | N' | D(y)p(y) | D(w)p(w) | D(x)p(x) | D(y), p(y) | D(z),p(z) |
| 0 | u | / 2,u | 5 u | (1,u) | X | co |
| _1 | U(X) | 2 11 | 4.x | | (2,x) | co |
| 2 | u x y 🗸 | (2,u) | 3 y | | | 4 ,y |
| 3 | uxvv | | 3 ,y | | | 4 <u>,</u> y |
| 4 | uxyvw | | | | | <u>4,y</u> |
| 5 | UXVVVZ) | | | | | |



Initialization (step 0): For all a: if a adjacent to then $D(a) = c_{u,a}$

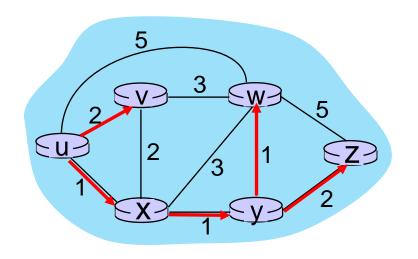
find a not in N' such that D(a) is a minimum add a to N' update D(b) for all b adjacent to a and not in N':

 $D(b) = \min (D(b), D(a) + c_{a,b})$

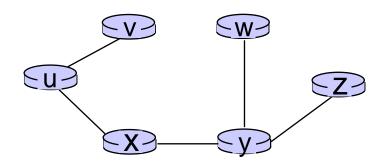
Dijkstra's link-state routing algorithm

```
1 Initialization:
   N' = \{u\}
                                 /* compute least cost path from u to all other nodes */
   for all nodes v
     if v adjacent to u
                                /* u initially knows direct-path-cost only to direct neighbors
      then D(v) = c_{u,v}
                                                                                        */
                                /* but may not be minimum cost!
    else D(v) = \infty
   Loop
     find w not in N' such that D(w) is a minimum
     add w to N'
     update D(v) for all v adjacent to w and not in N':
        D(v) = \min (D(v), D(w) + c_{w,v})
     /* new least-path-cost to v is either old least-cost-path to v or known
     least-cost-path to w plus direct-cost from w to v */
15 until all nodes in N'
```

Dijkstra's algorithm: an example



resulting least-cost-path tree from u:



resulting forwarding table in u:

| destination | outgoing link | |
|-------------|---------------|--|
| V | (u,v) — | route from <i>u</i> to <i>v</i> directly |
| X | (u,x) | |
| У | (u,x) | route from u to all |
| W | (u,x) | other destinations |
| X | (u,x) | via <i>x</i> |

Dijkstra's algorithm: discussion

algorithm complexity: *n* nodes

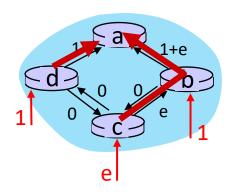
- each of n iteration: need to check all nodes, w, not in N
- n(n+1)/2 comparisons: $O(n^2)$ complexity
- more efficient implementations possible: O(nlogn)

message complexity:

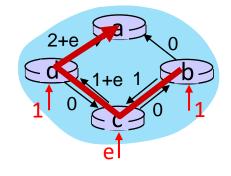
- each router must broadcast its link state information to other n routers
- efficient (and interesting!) broadcast algorithms: O(n) link crossings to disseminate a broadcast message from one source
- each router's message crosses O(n) links: overall message complexity: $O(n^2)$

Dijkstra's algorithm: oscillations possible

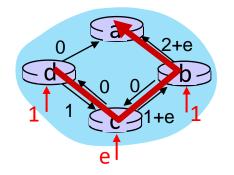
- when link costs depend on traffic volume, route oscillations possible
- sample scenario:
 - routing to destination a, traffic entering at d, c, b with rates 1, e (<1), 1
 - link costs are directional, and volume-dependent



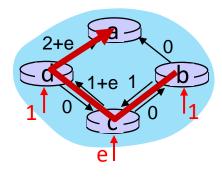




given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs

Network layer: "control plane" roadmap

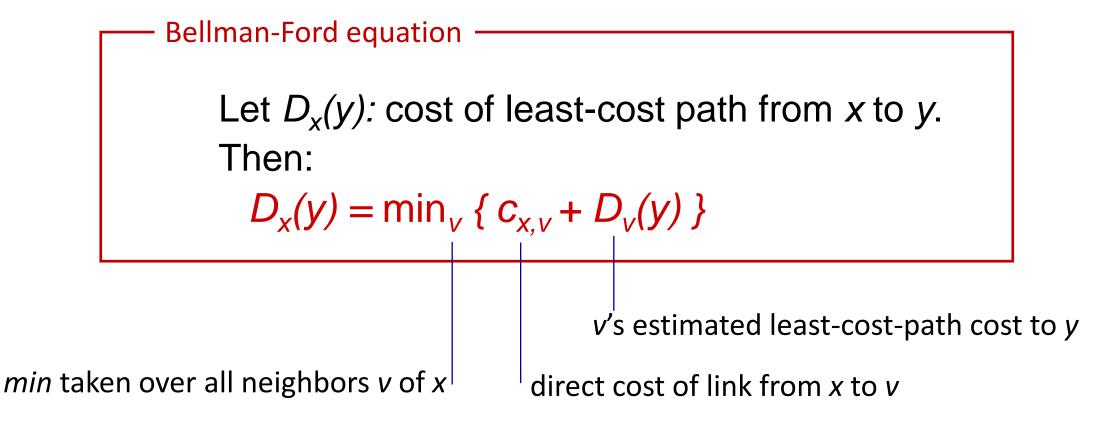
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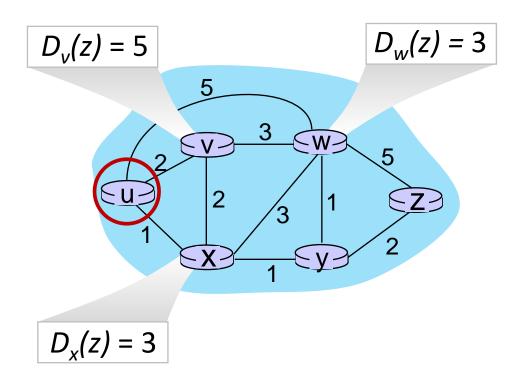
Distance vector algorithm

Based on *Bellman-Ford* (BF) equation (dynamic programming):



Bellman-Ford Example

Suppose that u's neighboring nodes, x,v,w, know that for destination z:



Bellman-Ford equation says:

$$D_{u}(z) = \min \{ c_{u,v} + D_{v}(z), c_{u,x} + D_{x}(z), c_{u,w} + D_{w}(z) \}$$

$$= \min \{ 2 + 5, 1 + 3, 5 + 3 \} = 4$$

node achieving minimum (x) is next hop on estimated leastcost path to destination (z)

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from any neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_{v} \{c_{x,v} + D_v(y)\}$$
 for each node $y \in N$

• under minor, natural conditions, the estimate $D_x(y)$ converge to the actual least cost $d_x(y)$

Distance vector algorithm:

each node:

wait for (change in local link cost or msg from neighbor)

recompute DV estimates using DV received from neighbor

if DV to any destination has changed, *notify* neighbors

iterative, asynchronous: each local iteration caused by:

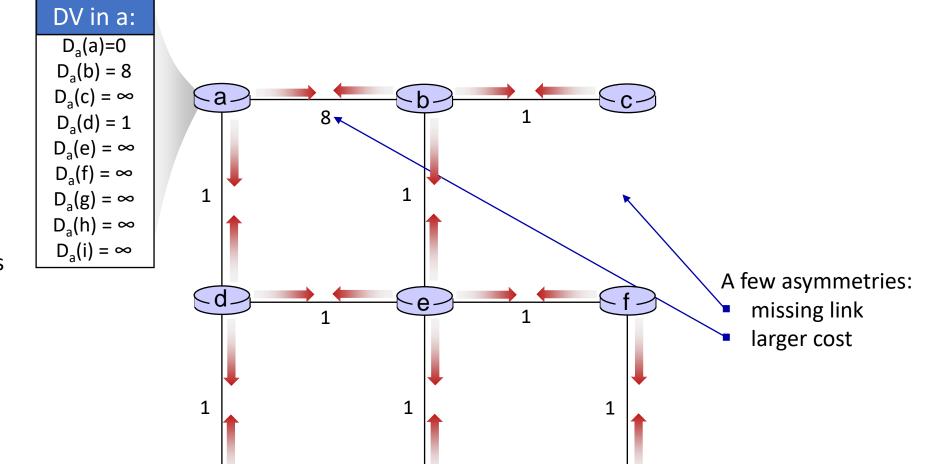
- local link cost change
- DV update message from neighbor

distributed, self-stopping: each node notifies neighbors *only* when its DV changes

- neighbors then notify their neighbors – only if necessary
- no notification received, no actions taken!

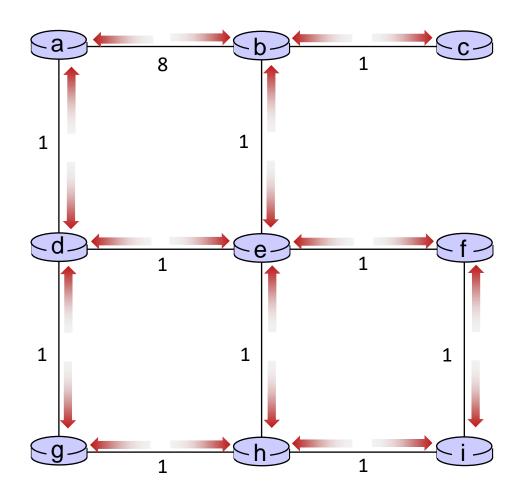


- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors



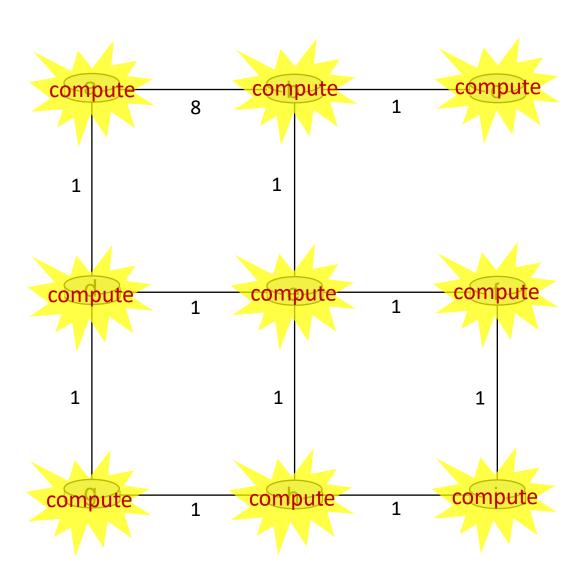


- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



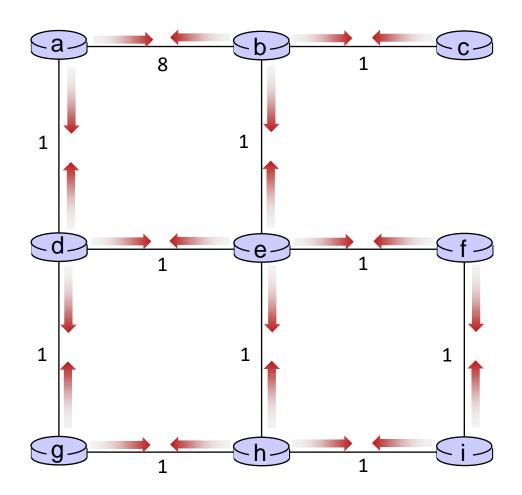


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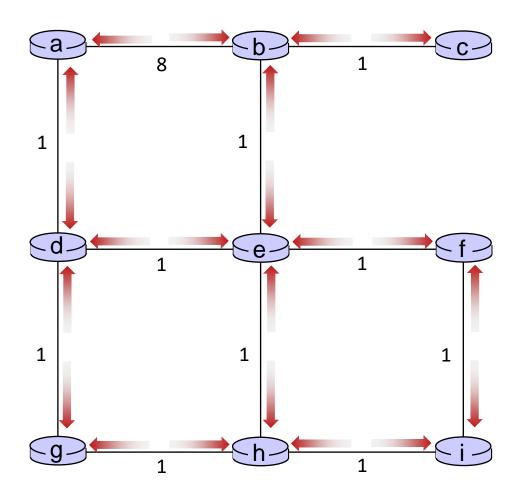


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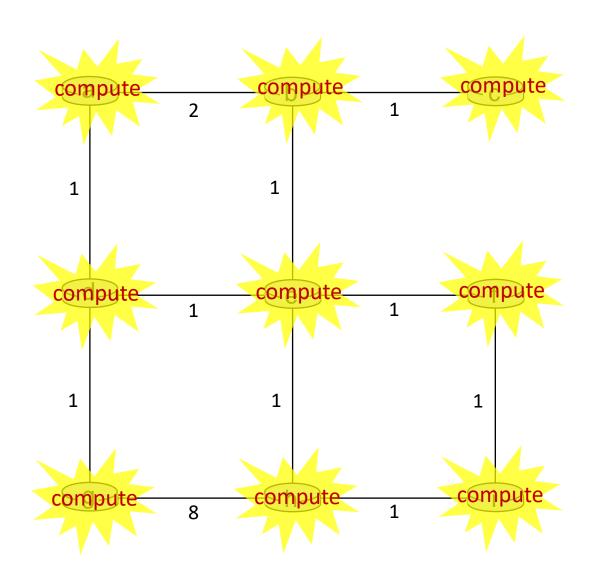


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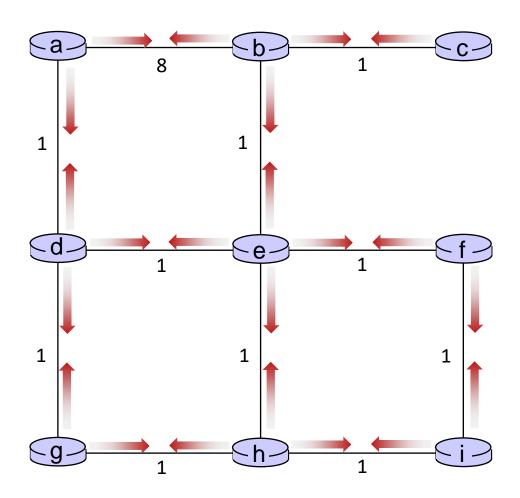


- receive distance vectors from neighbors
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- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



.... and so on

Let's next take a look at the iterative computations at nodes

-a-

-d-

t=1

b receives DVs from a, c, e

DV in a:

 $D_a(a)=0$

$$D_{a}(b) = 8$$

$$D_a(c) = \infty$$

 $D_a(d) = 1$

$$D_a(e) = \infty$$

$$D_a(f) = \infty$$

$$D_a(g) = \infty$$

$$D_a(h) = \infty$$

$$D_a(i) = \infty$$

DV in b:

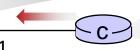
$$D_b(a) = 8$$
 $D_b(f) = \infty$
 $D_b(c) = 1$ $D_b(g) = \infty$

$$D_b(d) = \infty$$
 $D_b(h) = \infty$

$$D_b(e) = 1$$
 $D_b(i) = \infty$

-b-

e-



DV in c:

$$D_c(a) = \infty$$

$$D_{c}(b) = 1$$

$$D_{c}(c) = 0$$

$$D_c(d) = \infty$$

$$D_c(e) = \infty$$

$$D_c(f) = \infty$$

$$D_c(g) = \infty$$

$$D_c(h) = \infty$$

$$D_c(i) = \infty$$

DV in e:

$$D_e(a) = \infty$$

$$D_{e}(b) = 1$$

$$D_e(c) = \infty$$

$$D_{e}(d) = 1$$

$$D_{e}(e) = 0$$

$$D_e(f) = 1$$

$$D_e(g) = \infty$$

$$D_{e}(h) = 1$$

$$D_e(i) = \infty$$

(i) t=1

b receives DVs from a, c, e,

computes:

DV in a:

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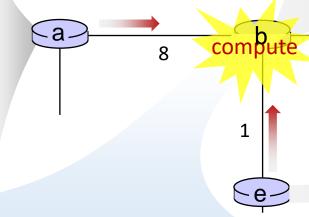
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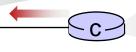
$$D_{a}(h) = \infty$$

$$D_{a}(i) = \infty$$



DV in b:

$$\begin{array}{ll} D_b(a) = 8 & D_b(f) = \infty \\ D_b(c) = 1 & D_b(g) = \infty \\ D_b(d) = \infty & D_b(h) = \infty \\ D_b(e) = 1 & D_b(i) = \infty \end{array}$$



DV in c:

$$D_{c}(a) = \infty$$

$$D_{c}(b) = 1$$

$$D_{c}(c) = 0$$

$$D_{c}(d) = \infty$$

$$D_c(e) = \infty$$

$$D_{c}(f) = \infty$$

$$D_c(g) = \infty$$

$$D_c(h) = \infty$$

$$D_c(i) = \infty$$

DV in e:

$$D_e(a) = \infty$$

$$D_{e}(b) = 1$$

$$D_e(c) = \infty$$

$$D_{e}(d) = 1$$

$$D_{e}(e) = 0$$

$$D_e(f) = 1$$

$$D_e(g) = \infty$$

$$D_{e}(h) = 1$$

$$D_e(i) = \infty$$

$$\begin{split} &D_b(a) = \min\{c_{b,a} + D_a(a), \, c_{b,c} + D_c(a), \, c_{b,e} + D_e(a)\} = \min\{8, \infty, \infty\} = 8 \\ &D_b(c) = \min\{c_{b,a} + D_a(c), \, c_{b,c} + D_c(c), \, c_{b,e} + D_e(c)\} = \min\{\infty, 1, \infty\} = 1 \\ &D_b(d) = \min\{c_{b,a} + D_a(d), \, c_{b,c} + D_c(d), \, c_{b,e} + D_e(d)\} = \min\{9, 2, \infty\} = 2 \\ &D_b(e) = \min\{c_{b,a} + D_a(e), \, c_{b,c} + D_c(e), \, c_{b,e} + D_e(e)\} = \min\{\infty, \infty, 1\} = 1 \\ &D_b(f) = \min\{c_{b,a} + D_a(f), \, c_{b,c} + D_c(f), \, c_{b,e} + D_e(f)\} = \min\{\infty, \infty, 2\} = 2 \\ &D_b(g) = \min\{c_{b,a} + D_a(g), \, c_{b,c} + D_c(g), \, c_{b,e} + D_e(g)\} = \min\{\infty, \infty, \infty\} = \infty \\ &D_b(h) = \min\{c_{b,a} + D_a(h), \, c_{b,c} + D_c(h), \, c_{b,e} + D_e(h)\} = \min\{\infty, \infty, \infty\} = \infty \\ &D_b(i) = \min\{c_{b,a} + D_a(i), \, c_{b,c} + D_c(i), \, c_{b,e} + D_e(i)\} = \min\{\infty, \infty, \infty\} = \infty \\ \end{split}$$

DV in b:

$$D_b(a) = 8$$
 $D_b(f) = 2$
 $D_b(c) = 1$ $D_b(g) = \infty$
 $D_b(d) = 2$ $D_b(h) = 2$
 $D_b(e) = 1$ $D_b(i) = \infty$

t=1

c receives DVs from b

DV in a:

 $D_a(a)=0$

$$D_{a}(b) = 8$$

$$D_a(c) = \infty$$

 $D_a(d) = 1$

$$D_a(e) = \infty$$

$$D_a(f) = \infty$$

$$D_a(g) = \infty$$

$$D_a(h) = \infty$$

$$D_a(i) = \infty$$

DV in b:

$$D_b(a) = 8$$
 $D_b(f) = \infty$
 $D_b(c) = 1$ $D_b(g) = \infty$

$$D_b(d) = \infty$$
 $D_b(h) = \infty$

$$D_b(e) = 1$$
 $D_b(i) = \infty$

DV in c:

$$D_c(a) = \infty$$

$$D_{c}(b) = 1$$

$$D_{c}(c) = 0$$

$$D_c(d) = \infty$$

$$D_c(e) = \infty$$

$$D_c(f) = \infty$$

$$D_c(g) = \infty$$

$$D_c(h) = \infty$$

$$D_c(i) = \infty$$

DV in e:

$$D_e(a) = \infty$$

$$D_{e}(b) = 1$$

$$D_e(c) = \infty$$

$$D_{e}(d) = 1$$

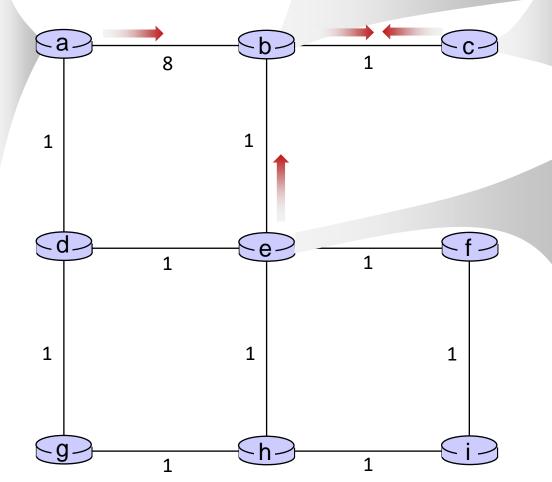
$$D_{e}(e) = 0$$

$$D_e(f) = 1$$

$$D_e(g) = \infty$$

$$D_{e}(h) = 1$$

$$D_e(i) = \infty$$



DV in b:

$$D_b(a) = 8$$
 $D_b(f) = \infty$
 $D_b(c) = 1$ $D_b(g) = \infty$
 $D_b(d) = \infty$ $D_b(h) = \infty$
 $D_b(e) = 1$ $D_b(i) = \infty$

compute

DV in c:

 $D_c(a) = \infty$ $D_c(b) = 1$

 $D_c(c) = 0$

 $D_c(d) = \infty$

 $D_c(e) = \infty$

 $D_c(f) = \infty$

 $D_c(g) = \infty$

 $D_c(h) = \infty$

$$D_c(i) = \infty$$



t=1

c receives DVs from b computes:

$$D_c(a) = min\{c_{c,b} + D_b(a)\} = 1 + 8 = 9$$

$$D_c(b) = min\{c_{c,b} + D_b(b)\} = 1 + 0 = 1$$

$$D_c(d) = \min\{c_{c,b} + D_b(d)\} = 1 + \infty = \infty$$

$$D_c(e) = min\{c_{c,b} + D_b(e)\} = 1 + 1 = 2$$

$$D_c(f) = min\{c_{c,b} + D_b(f)\} = 1 + \infty = \infty$$

$$D_c(g) = min\{c_{c,b} + D_b(g)\} = 1 + \infty = \infty$$

$$D_c(h) = min\{c_{bc,b} + D_b(h)\} = 1 + \infty = \infty$$

$$D_c(i) = \min\{c_{c,b} + D_b(i)\} = 1 + \infty = \infty$$

DV in c:

$$D_{c}(a) = 9$$

$$D_c(b) = 1$$

$$D_c(c) = 0$$

$$D_c(d) = 2$$

$$D_c(e) = \infty$$

$$D_c(f) = \infty$$

$$D_c(g) = \infty$$

$$D_c(h) = \infty$$

$$D_c(i) = \infty$$

-a-

DV in b:

$$D_b(a) = 8 D_b(f) = \infty$$

$$D_b(c) = 1 D_b(g) = \infty$$

$$D_b(d) = \infty D_b(h) = \infty$$

$$D_b(e) = 1 D_b(i) = \infty$$

DV in e:

$$D_{e}(a) = \infty$$
$$D_{e}(b) = 1$$

$$D_e(c) = \infty$$

$$D_{e}(d) = 1$$

$$D_{e}(e) = 0$$

$$D_e(f) = 1$$

$$D_e(g) = \infty$$

$$D_e(h) = 1$$

$$D_e(i) = \infty$$



t=1

e receives DVs from b, d, f, h

DV in d:

$$D_{c}(a) = 1$$

$$D_c(b) = \infty$$

$$D_c(c) = \infty$$

$$D_c(d) = 0$$

$$D_{c}(e) = 1$$

$$D_c(f) = \infty$$

$$D_{c}(g) = 1$$

$$D_c(h) = \infty$$

$$D_c(i) = \infty$$

DV in h:

$$D_c(a) = \infty$$

$$D_c(b) = \infty$$

$$D_c(c) = \infty$$

$$D_c(d) = \infty$$

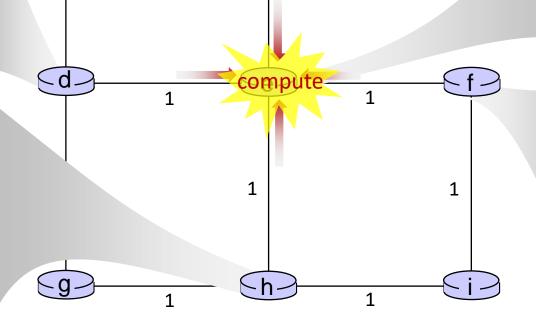
$$D_{c}(e) = 1$$

$$D_c(f) = \infty$$

$$D_c(g) = 1$$

$$D_c(h) = 0$$

$$D_c(i) = 1$$



b-

Q: what is new DV computed in e at

t=1?

DV in f:

$$D_c(a) = \infty$$

$$D_c(b) = \infty$$

$$D_c(c) = \infty$$

$$D_c(d) = \infty$$

$$D_{c}(e) = 1$$

$$D_c(f) = 0$$

$$D_c(g) = \infty$$

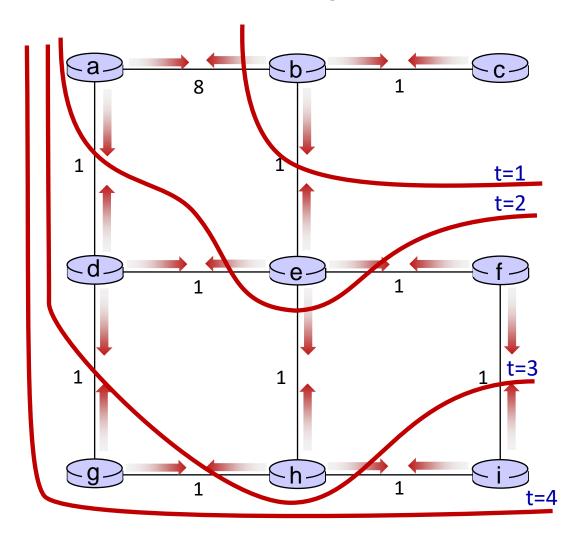
$$D_c(h) = \infty$$

$$D_c(i) = 1$$

Distance vector: state information diffusion

Iterative communication, computation steps diffuses information through network:

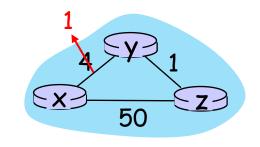
- t=0 c's state at t=0 is at c only
- c's state at t=0 has propagated to b, and may influence distance vector computations up to **1** hop away, i.e., at b
- c's state at t=0 may now influence distance vector computations up to 2 hops away, i.e., at b and now at a, e as well
- c's state at t=0 may influence distance vector computations up to **3** hops away, i.e., at b,a,e and now at c,f,h as well
- c's state at t=0 may influence distance vector computations up to 4 hops away, i.e., at b,a,e, c, f, h and now at g,i as well



Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- updates routing info, recalculates local DV
- if DV changes, notify neighbors



"good news travels fast"

 t_0 : y detects link-cost change, updates its DV, informs its neighbors.

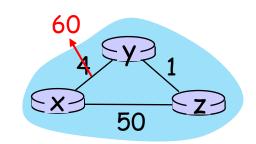
 t_1 : z receives update from y, updates its table, computes new least cost to x, sends its neighbors its DV.

 t_2 : y receives z's update, updates its distance table. y's least costs do not change, so y does not send a message to z.

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- "bad news travels slow" count-to-infinity problem:



- y sees direct link to x has new cost 60, but z has said it has a path at cost of 5. So y computes "my new cost to x will be 6, via z); notifies z of new cost of 6 to x.
- z learns that path to x via y has new cost 6, so z computes "my new cost to x will be 7 via y), notifies y of new cost of 7 to x.
- y learns that path to x via z has new cost 7, so y computes "my new cost to x will be 8 via y), notifies z of new cost of 8 to x.
- z learns that path to x via y has new cost 8, so z computes "my new cost to x will be 9 via y), notifies y of new cost of 9 to x.

• • •

see text for solutions. Distributed algorithms are tricky!

Comparison of LS and DV algorithms

message complexity

LS: n routers, $O(n^2)$ messages sent

DV: exchange between neighbors; convergence time varies

speed of convergence

LS: $O(n^2)$ algorithm, $O(n^2)$ messages

may have oscillations

DV: convergence time varies

- may have routing loops
- count-to-infinity problem

robustness: what happens if router malfunctions, or is compromised?

LS:

- router can advertise incorrect link cost
- each router computes only its own table

DV:

- DV router can advertise incorrect path cost ("I have a really low cost path to everywhere"): black-holing
- each router's table used by others: error propagate thru network

Network layer: "control plane" roadmap

- introduction
- routing protocols
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control MessageProtocol



- network management, configuration
 - SNMP
 - NETCONF/YANG

Making routing scalable

our routing study thus far - idealized

- all routers identical
- network "flat"
- ... not true in practice

scale: billions of destinations:

- can't store all destinations in routing tables!
- routing table exchange would swamp links!

administrative autonomy:

- Internet: a network of networks
- each network admin may want to control routing in its own network

Internet approach to scalable routing

aggregate routers into regions known as "autonomous systems" (AS) (a.k.a. "domains")

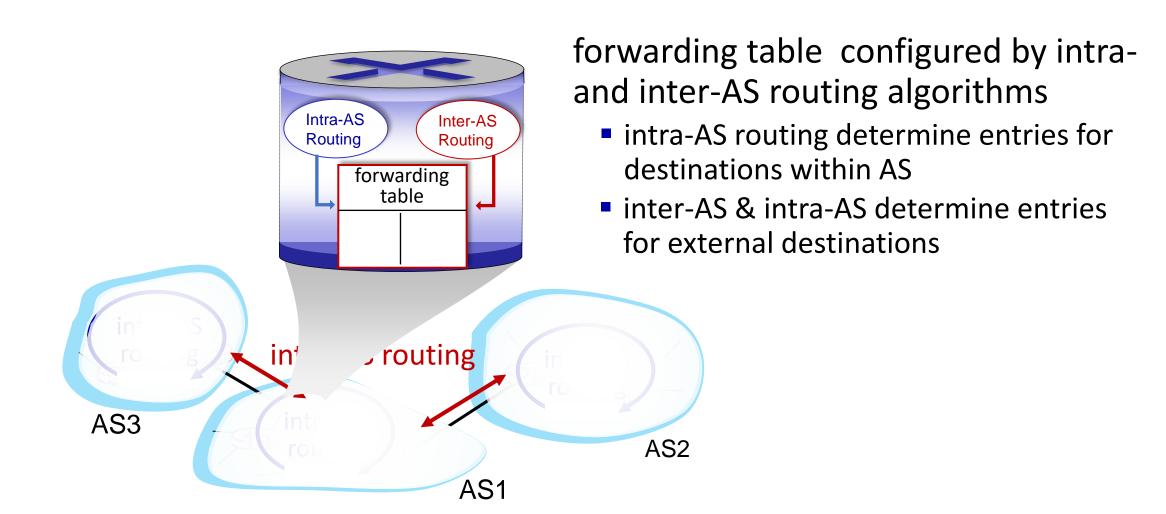
intra-AS (aka "intra-domain"):
routing among within same AS
("network")

- all routers in AS must run same intradomain protocol
- routers in different AS can run different intra-domain routing protocols
- gateway router: at "edge" of its own AS, has link(s) to router(s) in other AS'es

inter-AS (aka "inter-domain"): routing *among* AS'es

 gateways perform inter-domain routing (as well as intra-domain routing)

Interconnected ASes

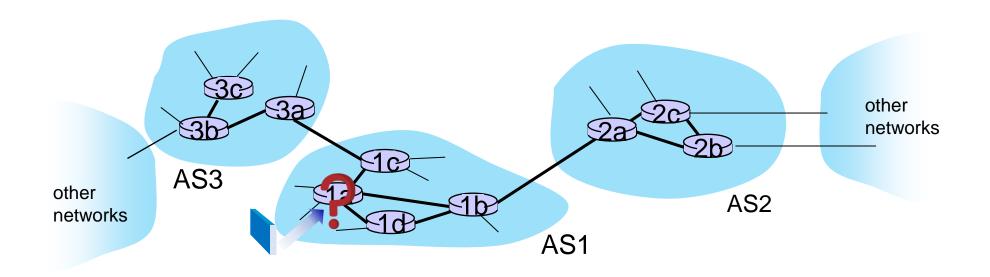


Inter-AS routing: a role in intradomain forwarding

- suppose router in AS1 receives datagram destined outside of AS1:
- router should forward packet to gateway router in AS1, but which one?

AS1 inter-domain routing must:

- 1. learn which destinations reachable through AS2, which through AS3
- 2. propagate this reachability info to all routers in AS1



Intra-AS routing: routing within an AS

most common intra-AS routing protocols:

- RIP: Routing Information Protocol [RFC 1723]
 - classic DV: DVs exchanged every 30 secs
 - no longer widely used
- EIGRP: Enhanced Interior Gateway Routing Protocol
 - DV based
 - formerly Cisco-proprietary for decades (became open in 2013 [RFC 7868])
- OSPF: Open Shortest Path First [RFC 2328]
 - link-state routing
 - IS-IS protocol (ISO standard, not RFC standard) essentially same as OSPF

OSPF (Open Shortest Path First) routing

- "open": publicly available
- classic link-state
 - each router floods OSPF link-state advertisements (directly over IP rather than using TCP/UDP) to all other routers in entire AS
 - multiple link costs metrics possible: bandwidth, delay
 - each router has full topology, uses Dijkstra's algorithm to compute forwarding table
 - security: all OSPF messages authenticated (to prevent malicious intrusion)

Hierarchical OSPF

- two-level hierarchy: local area, backbone.
 - link-state advertisements flooded only in area, or backbone
 - each node has detailed area topology; only knows direction to reach other destinations

