

Practical Machine Learning

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Introduction

This report is to solve the final project in the coursera course “practical machine learning”. Two .csv documents are used in this report: pml-testing.csv, and pml-training.csv. The training document contains all the information from six user’s movement, which includes five classes (A, B, C, D, and E). Then, we need to build and train a model from all the training information, and finally evaluate the model in the test data set.

Data clean

First of all, let’s import all the data into R. And then, let’s take a look what they look like.

```
train.data <- read.csv("pml-training.csv", header = TRUE, stringsAsFactors = TRUE)
test.data <- read.csv("pml-testing.csv", header = TRUE, stringsAsFactors = TRUE)
cat(noquote("Here is the summary of training data: "))
```

```
## Here is the summary of training data:
```

```
summary(train.data)
```

```
##           X           user_name raw_timestamp_part_1 raw_timestamp_part_2
## Min.      :    1      adelmo :3892      Min.      :1.322e+09      Min.      :    294
## 1st Qu.: 4906      carlitos:3112      1st Qu.:1.323e+09      1st Qu.:252912
## Median : 9812      charles :3536      Median :1.323e+09      Median :496380
## Mean    : 9812      eurico  :3070      Mean    :1.323e+09      Mean    :500656
## 3rd Qu.:14717      jeremy  :3402      3rd Qu.:1.323e+09      3rd Qu.:751891
## Max.    :19622      pedro   :2610      Max.    :1.323e+09      Max.    :998801
##
##           cvtd_timestamp new_window num_window roll_belt
## 28/11/2011 14:14: 1498    no :19216      Min.      :    1.0      Min.      : -28.90
## 05/12/2011 11:24: 1497    yes: 406      1st Qu.:222.0      1st Qu.:    1.10
## 30/11/2011 17:11: 1440                                Median :424.0      Median :113.00
## 05/12/2011 11:25: 1425                                Mean    :430.6      Mean    :   64.41
## 02/12/2011 14:57: 1380                                3rd Qu.:644.0      3rd Qu.:123.00
## 02/12/2011 13:34: 1375                                Max.    :864.0      Max.    :162.00
## (Other)           :11007
##           pitch_belt      yaw_belt      total_accel_belt kurtosis_roll_belt
## Min.      : -55.8000      Min.      : -180.00      Min.      :    0.00      :19216
## 1st Qu.:    1.7600      1st Qu.:  -88.30      1st Qu.:    3.00      #DIV/0! :    10
## Median :    5.2800      Median :  -13.00      Median :17.00      -1.908453:    2
## Mean    :    0.3053      Mean    :  -11.21      Mean    :11.31      -0.016850:    1
## 3rd Qu.:   14.9000      3rd Qu.:   12.90      3rd Qu.:18.00      -0.021024:    1
## Max.    :   60.3000      Max.    :  179.00      Max.    :29.00      -0.025513:    1
##                                     (Other) :   391
## kurtosis_picth_belt kurtosis_yaw_belt skewness_roll_belt
##           :19216           :19216           :19216
## #DIV/0! :    32      #DIV/0! :   406      #DIV/0! :    9
## 47.000000:    4              0.000000 :    4
```

```

## -0.150950:    3                0.422463 :    2
## -0.684748:    3                -0.003095:    1
## -1.750749:    3                -0.010002:    1
## (Other) :   361                (Other) :   389
## skewness_roll_belt.1 skewness_yaw_belt max_roll_belt    max_pitch_belt
##           :19216                :19216    Min.   : -94.300    Min.   : 3.00
## #DIV/0! :    32          #DIV/0! :   406    1st Qu.: -88.000    1st Qu.: 5.00
## 0.000000 :    4                Median :  -5.100    Median :18.00
## -2.156553:    3                Mean    :  -6.667    Mean    :12.92
## -3.072669:    3                3rd Qu.: 18.500    3rd Qu.:19.00
## -6.324555:    3                Max.    :180.000    Max.    :30.00
## (Other) :   361                NA's    :19216    NA's    :19216
## max_yaw_belt min_roll_belt min_pitch_belt min_yaw_belt
##           :19216    Min.   : -180.00    Min.   : 0.00           :19216
## -1.1 :    30    1st Qu.: -88.40    1st Qu.: 3.00    -1.1 :    30
## -1.4 :    29    Median :  -7.85    Median :16.00    -1.4 :    29
## -1.2 :    26    Mean    : -10.44    Mean    :10.76    -1.2 :    26
## -0.9 :    24    3rd Qu.:  9.05    3rd Qu.:17.00    -0.9 :    24
## -1.3 :    22    Max.    : 173.00    Max.    :23.00    -1.3 :    22
## (Other): 275    NA's    :19216    NA's    :19216    (Other): 275
## amplitude_roll_belt amplitude_pitch_belt amplitude_yaw_belt
## Min.   : 0.000    Min.   : 0.000           :19216
## 1st Qu.: 0.300    1st Qu.: 1.000          #DIV/0! :   10
## Median : 1.000    Median : 1.000          0.00    :   12
## Mean    : 3.769    Mean    : 2.167          0.0000 :  384
## 3rd Qu.: 2.083    3rd Qu.: 2.000
## Max.    :360.000    Max.    :12.000
## NA's    :19216    NA's    :19216
## var_total_accel_belt avg_roll_belt stddev_roll_belt var_roll_belt
## Min.   : 0.000    Min.   : -27.40    Min.   : 0.000    Min.   : 0.000
## 1st Qu.: 0.100    1st Qu.:  1.10    1st Qu.: 0.200    1st Qu.: 0.000
## Median : 0.200    Median :116.35    Median : 0.400    Median : 0.100
## Mean    : 0.926    Mean    : 68.06    Mean    : 1.337    Mean    : 7.699
## 3rd Qu.: 0.300    3rd Qu.:123.38    3rd Qu.: 0.700    3rd Qu.: 0.500
## Max.    :16.500    Max.    :157.40    Max.    :14.200    Max.    :200.700
## NA's    :19216    NA's    :19216    NA's    :19216    NA's    :19216
## avg_pitch_belt stddev_pitch_belt var_pitch_belt avg_yaw_belt
## Min.   : -51.400    Min.   : 0.000    Min.   : 0.000    Min.   : -138.300
## 1st Qu.:  2.025    1st Qu.: 0.200    1st Qu.: 0.000    1st Qu.: -88.175
## Median :  5.200    Median : 0.400    Median : 0.100    Median :  -6.550
## Mean    :  0.520    Mean    : 0.603    Mean    : 0.766    Mean    : -8.831
## 3rd Qu.: 15.775    3rd Qu.: 0.700    3rd Qu.: 0.500    3rd Qu.: 14.125
## Max.    : 59.700    Max.    : 4.000    Max.    :16.200    Max.    : 173.500
## NA's    :19216    NA's    :19216    NA's    :19216    NA's    :19216
## stddev_yaw_belt var_yaw_belt gyros_belt_x
## Min.   : 0.000    Min.   :  0.000    Min.   : -1.040000
## 1st Qu.: 0.100    1st Qu.:  0.010    1st Qu.: -0.030000
## Median : 0.300    Median :  0.090    Median : 0.030000
## Mean    : 1.341    Mean    : 107.487    Mean    : -0.005592
## 3rd Qu.: 0.700    3rd Qu.:  0.475    3rd Qu.: 0.110000
## Max.    :176.600    Max.    :31183.240    Max.    : 2.220000
## NA's    :19216    NA's    :19216
## gyros_belt_y gyros_belt_z accel_belt_x accel_belt_y
## Min.   : -0.64000    Min.   : -1.4600    Min.   : -120.000    Min.   : -69.00

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## 1st Qu.: 0.00000 1st Qu.: -0.2000 1st Qu.: -21.000 1st Qu.: 3.00
## Median : 0.02000 Median : -0.1000 Median : -15.000 Median : 35.00
## Mean : 0.03959 Mean : -0.1305 Mean : -5.595 Mean : 30.15
## 3rd Qu.: 0.11000 3rd Qu.: -0.0200 3rd Qu.: -5.000 3rd Qu.: 61.00
## Max. : 0.64000 Max. : 1.6200 Max. : 85.000 Max. : 164.00
##
## accel_belt_z magnet_belt_x magnet_belt_y magnet_belt_z
## Min. : -275.00 Min. : -52.0 Min. : 354.0 Min. : -623.0
## 1st Qu.: -162.00 1st Qu.: 9.0 1st Qu.: 581.0 1st Qu.: -375.0
## Median : -152.00 Median : 35.0 Median : 601.0 Median : -320.0
## Mean : -72.59 Mean : 55.6 Mean : 593.7 Mean : -345.5
## 3rd Qu.: 27.00 3rd Qu.: 59.0 3rd Qu.: 610.0 3rd Qu.: -306.0
## Max. : 105.00 Max. : 485.0 Max. : 673.0 Max. : 293.0
##
## roll_arm pitch_arm yaw_arm total_accel_arm
## Min. : -180.00 Min. : -88.800 Min. : -180.0000 Min. : 1.00
## 1st Qu.: -31.77 1st Qu.: -25.900 1st Qu.: -43.1000 1st Qu.: 17.00
## Median : 0.00 Median : 0.000 Median : 0.0000 Median : 27.00
## Mean : 17.83 Mean : -4.612 Mean : -0.6188 Mean : 25.51
## 3rd Qu.: 77.30 3rd Qu.: 11.200 3rd Qu.: 45.8750 3rd Qu.: 33.00
## Max. : 180.00 Max. : 88.500 Max. : 180.0000 Max. : 66.00
##
## var_accel_arm avg_roll_arm stddev_roll_arm var_roll_arm
## Min. : 0.00 Min. : -166.67 Min. : 0.000 Min. : 0.000
## 1st Qu.: 9.03 1st Qu.: -38.37 1st Qu.: 1.376 1st Qu.: 1.898
## Median : 40.61 Median : 0.00 Median : 5.702 Median : 32.517
## Mean : 53.23 Mean : 12.68 Mean : 11.201 Mean : 417.264
## 3rd Qu.: 75.62 3rd Qu.: 76.33 3rd Qu.: 14.921 3rd Qu.: 222.647
## Max. : 331.70 Max. : 163.33 Max. : 161.964 Max. : 26232.208
## NA's : 19216 NA's : 19216 NA's : 19216 NA's : 19216
## avg_pitch_arm stddev_pitch_arm var_pitch_arm avg_yaw_arm
## Min. : -81.773 Min. : 0.000 Min. : 0.000 Min. : -173.440
## 1st Qu.: -22.770 1st Qu.: 1.642 1st Qu.: 2.697 1st Qu.: -29.198
## Median : 0.000 Median : 8.133 Median : 66.146 Median : 0.000
## Mean : -4.901 Mean : 10.383 Mean : 195.864 Mean : 2.359
## 3rd Qu.: 8.277 3rd Qu.: 16.327 3rd Qu.: 266.576 3rd Qu.: 38.185
## Max. : 75.659 Max. : 43.412 Max. : 1884.565 Max. : 152.000
## NA's : 19216 NA's : 19216 NA's : 19216 NA's : 19216
## stddev_yaw_arm var_yaw_arm gyros_arm_x
## Min. : 0.000 Min. : 0.000 Min. : -6.37000
## 1st Qu.: 2.577 1st Qu.: 6.642 1st Qu.: -1.33000
## Median : 16.682 Median : 278.309 Median : 0.08000
## Mean : 22.270 Mean : 1055.933 Mean : 0.04277
## 3rd Qu.: 35.984 3rd Qu.: 1294.850 3rd Qu.: 1.57000
## Max. : 177.044 Max. : 31344.568 Max. : 4.87000
## NA's : 19216 NA's : 19216
## gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y
## Min. : -3.4400 Min. : -2.3300 Min. : -404.00 Min. : -318.0
## 1st Qu.: -0.8000 1st Qu.: -0.0700 1st Qu.: -242.00 1st Qu.: -54.0
## Median : -0.2400 Median : 0.2300 Median : -44.00 Median : 14.0
## Mean : -0.2571 Mean : 0.2695 Mean : -60.24 Mean : 32.6
## 3rd Qu.: 0.1400 3rd Qu.: 0.7200 3rd Qu.: 84.00 3rd Qu.: 139.0
## Max. : 2.8400 Max. : 3.0200 Max. : 437.00 Max. : 308.0
##

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## accel_arm_z magnet_arm_x magnet_arm_y magnet_arm_z
## Min. : -636.00 Min. : -584.0 Min. : -392.0 Min. : -597.0
## 1st Qu.: -143.00 1st Qu.: -300.0 1st Qu.: -9.0 1st Qu.: 131.2
## Median : -47.00 Median : 289.0 Median : 202.0 Median : 444.0
## Mean : -71.25 Mean : 191.7 Mean : 156.6 Mean : 306.5
## 3rd Qu.: 23.00 3rd Qu.: 637.0 3rd Qu.: 323.0 3rd Qu.: 545.0
## Max. : 292.00 Max. : 782.0 Max. : 583.0 Max. : 694.0
##
## kurtosis_roll_arm kurtosis_picth_arm kurtosis_yaw_arm skewness_roll_arm
## :19216 :19216 :19216 :19216
## #DIV/0! : 78 #DIV/0! : 80 #DIV/0! : 11 #DIV/0! : 77
## -0.02438: 1 -0.00484: 1 0.55844 : 2 -0.00051: 1
## -0.04190: 1 -0.01311: 1 0.65132 : 2 -0.00696: 1
## -0.05051: 1 -0.02967: 1 -0.01548: 1 -0.01884: 1
## -0.05695: 1 -0.07394: 1 -0.01749: 1 -0.03359: 1
## (Other) : 324 (Other) : 322 (Other) : 389 (Other) : 325
## skewness_pitch_arm skewness_yaw_arm max_roll_arm max_picth_arm
## :19216 :19216 Min. : -73.100 Min. : -173.000
## #DIV/0! : 80 #DIV/0! : 11 1st Qu.: -0.175 1st Qu.: -1.975
## -0.00184: 1 -1.62032: 2 Median : 4.950 Median : 23.250
## -0.01185: 1 0.55053 : 2 Mean : 11.236 Mean : 35.751
## -0.01247: 1 -0.00311: 1 3rd Qu.: 26.775 3rd Qu.: 95.975
## -0.02063: 1 -0.00562: 1 Max. : 85.500 Max. : 180.000
## (Other) : 322 (Other) : 389 NA's :19216 NA's :19216
## max_yaw_arm min_roll_arm min_pitch_arm min_yaw_arm
## Min. : 4.00 Min. : -89.10 Min. : -180.00 Min. : 1.00
## 1st Qu.:29.00 1st Qu.: -41.98 1st Qu.: -72.62 1st Qu.: 8.00
## Median :34.00 Median : -22.45 Median : -33.85 Median :13.00
## Mean :35.46 Mean : -21.22 Mean : -33.92 Mean :14.66
## 3rd Qu.:41.00 3rd Qu.: 0.00 3rd Qu.: 0.00 3rd Qu.:19.00
## Max. :65.00 Max. : 66.40 Max. : 152.00 Max. :38.00
## NA's :19216 NA's :19216 NA's :19216 NA's :19216
## amplitude_roll_arm amplitude_pitch_arm amplitude_yaw_arm
## Min. : 0.000 Min. : 0.000 Min. : 0.00
## 1st Qu.: 5.425 1st Qu.: 9.925 1st Qu.:13.00
## Median : 28.450 Median : 54.900 Median :22.00
## Mean : 32.452 Mean : 69.677 Mean :20.79
## 3rd Qu.: 50.960 3rd Qu.:115.175 3rd Qu.:28.75
## Max. :119.500 Max. :360.000 Max. :52.00
## NA's :19216 NA's :19216 NA's :19216
## roll_dumbbell pitch_dumbbell yaw_dumbbell
## Min. : -153.71 Min. : -149.59 Min. : -150.871
## 1st Qu.: -18.49 1st Qu.: -40.89 1st Qu.: -77.644
## Median : 48.17 Median : -20.96 Median : -3.324
## Mean : 23.84 Mean : -10.78 Mean : 1.674
## 3rd Qu.: 67.61 3rd Qu.: 17.50 3rd Qu.: 79.643
## Max. : 153.55 Max. : 149.40 Max. : 154.952
##
## kurtosis_roll_dumbbell kurtosis_picth_dumbbell kurtosis_yaw_dumbbell
## :19216 :19216 :19216
## #DIV/0! : 5 -0.5464: 2 #DIV/0! : 406
## -0.2583: 2 -0.9334: 2
## -0.3705: 2 -2.0833: 2
## -0.5855: 2 -2.0851: 2

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## -2.0851: 2 -2.0889: 2
## (Other): 393 (Other): 396
## skewness_roll_dumbbell skewness_pitch_dumbbell skewness_yaw_dumbbell
## :19216 :19216 :19216
## #DIV/0!: 4 -0.2328: 2 #DIV/0!: 406
## -0.9324: 2 -0.3521: 2
## 0.1110 : 2 -0.7036: 2
## 1.0312 : 2 0.1090 : 2
## -0.0082: 1 1.0326 : 2
## (Other): 395 (Other): 396
## max_roll_dumbbell max_pitch_dumbbell max_yaw_dumbbell min_roll_dumbbell
## Min. :-70.10 Min. :-112.90 :19216 Min. :-149.60
## 1st Qu.: -27.15 1st Qu.: -66.70 -0.6 : 20 1st Qu.: -59.67
## Median : 14.85 Median : 40.05 0.2 : 19 Median : -43.55
## Mean : 13.76 Mean : 32.75 -0.8 : 18 Mean : -41.24
## 3rd Qu.: 50.58 3rd Qu.: 133.22 -0.3 : 16 3rd Qu.: -25.20
## Max. :137.00 Max. : 155.00 -0.2 : 15 Max. : 73.20
## NA's :19216 NA's :19216 (Other): 318 NA's :19216
## min_pitch_dumbbell min_yaw_dumbbell amplitude_roll_dumbbell
## Min. :-147.00 :19216 Min. : 0.00
## 1st Qu.: -91.80 -0.6 : 20 1st Qu.: 14.97
## Median : -66.15 0.2 : 19 Median : 35.05
## Mean : -33.18 -0.8 : 18 Mean : 55.00
## 3rd Qu.: 21.20 -0.3 : 16 3rd Qu.: 81.04
## Max. : 120.90 -0.2 : 15 Max. :256.48
## NA's :19216 (Other): 318 NA's :19216
## amplitude_pitch_dumbbell amplitude_yaw_dumbbell total_accel_dumbbell
## Min. : 0.00 :19216 Min. : 0.00
## 1st Qu.: 17.06 #DIV/0!: 5 1st Qu.: 4.00
## Median : 41.73 0.00 : 401 Median :10.00
## Mean : 65.93 Mean :13.72
## 3rd Qu.: 99.55 3rd Qu.:19.00
## Max. :273.59 Max. :58.00
## NA's :19216
## var_accel_dumbbell avg_roll_dumbbell stddev_roll_dumbbell
## Min. : 0.000 Min. :-128.96 Min. : 0.000
## 1st Qu.: 0.378 1st Qu.: -12.33 1st Qu.: 4.639
## Median : 1.000 Median : 48.23 Median : 12.204
## Mean : 4.388 Mean : 23.86 Mean : 20.761
## 3rd Qu.: 3.434 3rd Qu.: 64.37 3rd Qu.: 26.356
## Max. :230.428 Max. : 125.99 Max. :123.778
## NA's :19216 NA's :19216 NA's :19216
## var_roll_dumbbell avg_pitch_dumbbell stddev_pitch_dumbbell
## Min. : 0.00 Min. :-70.73 Min. : 0.000
## 1st Qu.: 21.52 1st Qu.: -42.00 1st Qu.: 3.482
## Median : 148.95 Median :-19.91 Median : 8.089
## Mean : 1020.27 Mean :-12.33 Mean :13.147
## 3rd Qu.: 694.65 3rd Qu.: 13.21 3rd Qu.:19.238
## Max. :15321.01 Max. : 94.28 Max. :82.680
## NA's :19216 NA's :19216 NA's :19216
## var_pitch_dumbbell avg_yaw_dumbbell stddev_yaw_dumbbell
## Min. : 0.00 Min. :-117.950 Min. : 0.000
## 1st Qu.: 12.12 1st Qu.: -76.696 1st Qu.: 3.885
## Median : 65.44 Median : -4.505 Median : 10.264

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## Mean      : 350.31      Mean      : 0.202      Mean      : 16.647
## 3rd Qu.: 370.11      3rd Qu.: 71.234      3rd Qu.: 24.674
## Max.      :6836.02      Max.      : 134.905      Max.      :107.088
## NA's      :19216      NA's      :19216      NA's      :19216
## var_yaw_dumbbell      gyros_dumbbell_x      gyros_dumbbell_y
## Min.      : 0.00      Min.      :-204.0000      Min.      :-2.10000
## 1st Qu.: 15.09      1st Qu.: -0.0300      1st Qu.: -0.14000
## Median : 105.35      Median : 0.1300      Median : 0.03000
## Mean      : 589.84      Mean      : 0.1611      Mean      : 0.04606
## 3rd Qu.: 608.79      3rd Qu.: 0.3500      3rd Qu.: 0.21000
## Max.      :11467.91      Max.      : 2.2200      Max.      :52.00000
## NA's      :19216
## gyros_dumbbell_z      accel_dumbbell_x      accel_dumbbell_y      accel_dumbbell_z
## Min.      : -2.380      Min.      :-419.00      Min.      :-189.00      Min.      :-334.00
## 1st Qu.: -0.310      1st Qu.: -50.00      1st Qu.: -8.00      1st Qu.: -142.00
## Median : -0.130      Median : -8.00      Median : 41.50      Median : -1.00
## Mean      : -0.129      Mean      : -28.62      Mean      : 52.63      Mean      : -38.32
## 3rd Qu.: 0.030      3rd Qu.: 11.00      3rd Qu.: 111.00      3rd Qu.: 38.00
## Max.      :317.000      Max.      : 235.00      Max.      : 315.00      Max.      : 318.00
##
## magnet_dumbbell_x      magnet_dumbbell_y      magnet_dumbbell_z      roll_forearm
## Min.      : -643.0      Min.      : -3600      Min.      : -262.00      Min.      : -180.0000
## 1st Qu.: -535.0      1st Qu.: 231      1st Qu.: -45.00      1st Qu.: -0.7375
## Median : -479.0      Median : 311      Median : 13.00      Median : 21.7000
## Mean      : -328.5      Mean      : 221      Mean      : 46.05      Mean      : 33.8265
## 3rd Qu.: -304.0      3rd Qu.: 390      3rd Qu.: 95.00      3rd Qu.: 140.0000
## Max.      : 592.0      Max.      : 633      Max.      : 452.00      Max.      : 180.0000
##
## pitch_forearm      yaw_forearm      kurtosis_roll_forearm
## Min.      : -72.50      Min.      : -180.00      :19216
## 1st Qu.: 0.00      1st Qu.: -68.60      #DIV/0!: 84
## Median : 9.24      Median : 0.00      -0.8079: 2
## Mean      : 10.71      Mean      : 19.21      -0.9169: 2
## 3rd Qu.: 28.40      3rd Qu.: 110.00      -0.0227: 1
## Max.      : 89.80      Max.      : 180.00      -0.0359: 1
##                                     (Other): 316
## kurtosis_pitch_forearm      kurtosis_yaw_forearm      skewness_roll_forearm
## :19216      :19216      :19216
## #DIV/0!: 85      #DIV/0!: 406      #DIV/0!: 83
## -0.0073: 1      -0.1912: 2
## -0.0442: 1      -0.4126: 2
## -0.0489: 1      -0.0004: 1
## -0.0523: 1      -0.0013: 1
## (Other): 317      (Other): 317
## skewness_pitch_forearm      skewness_yaw_forearm      max_roll_forearm
## :19216      :19216      Min.      : -66.60
## #DIV/0!: 85      #DIV/0!: 406      1st Qu.: 0.00
## 0.0000 : 4      Median : 26.80
## -0.6992: 2      Mean : 24.49
## -0.0113: 1      3rd Qu.: 45.95
## -0.0131: 1      Max. : 89.80
## (Other): 313      NA's :19216
## max_pitch_forearm      max_yaw_forearm      min_roll_forearm      min_pitch_forearm
## Min.      : -151.00      :19216      Min.      : -72.500      Min.      : -180.00

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## 1st Qu.: 0.00 #DIV/0!: 84 1st Qu.: -6.075 1st Qu.: -175.00
## Median : 113.00 -1.2 : 32 Median : 0.000 Median : -61.00
## Mean : 81.49 -1.3 : 31 Mean : -0.167 Mean : -57.57
## 3rd Qu.: 174.75 -1.4 : 24 3rd Qu.: 12.075 3rd Qu.: 0.00
## Max. : 180.00 -1.5 : 24 Max. : 62.100 Max. : 167.00
## NA's :19216 (Other): 211 NA's :19216 NA's :19216
## min_yaw_forearm amplitude_roll_forearm amplitude_pitch_forearm
## :19216 Min. : 0.000 Min. : 0.0
## #DIV/0!: 84 1st Qu.: 1.125 1st Qu.: 2.0
## -1.2 : 32 Median : 17.770 Median : 83.7
## -1.3 : 31 Mean : 24.653 Mean : 139.1
## -1.4 : 24 3rd Qu.: 39.875 3rd Qu.: 350.0
## -1.5 : 24 Max. : 126.000 Max. : 360.0
## (Other): 211 NA's :19216 NA's :19216
## amplitude_yaw_forearm total_accel_forearm var_accel_forearm
## :19216 Min. : 0.00 Min. : 0.000
## #DIV/0!: 84 1st Qu.: 29.00 1st Qu.: 6.759
## 0.00 : 322 Median : 36.00 Median : 21.165
## Mean : 34.72 Mean : 33.502
## 3rd Qu.: 41.00 3rd Qu.: 51.240
## Max. : 108.00 Max. : 172.606
## NA's :19216
## avg_roll_forearm stddev_roll_forearm var_roll_forearm
## Min. : -177.234 Min. : 0.000 Min. : 0.00
## 1st Qu.: -0.909 1st Qu.: 0.428 1st Qu.: 0.18
## Median : 11.172 Median : 8.030 Median : 64.48
## Mean : 33.165 Mean : 41.986 Mean : 5274.10
## 3rd Qu.: 107.132 3rd Qu.: 85.373 3rd Qu.: 7289.08
## Max. : 177.256 Max. : 179.171 Max. : 32102.24
## NA's :19216 NA's :19216 NA's :19216
## avg_pitch_forearm stddev_pitch_forearm var_pitch_forearm
## Min. : -68.17 Min. : 0.000 Min. : 0.000
## 1st Qu.: 0.00 1st Qu.: 0.336 1st Qu.: 0.113
## Median : 12.02 Median : 5.516 Median : 30.425
## Mean : 11.79 Mean : 7.977 Mean : 139.593
## 3rd Qu.: 28.48 3rd Qu.: 12.866 3rd Qu.: 165.532
## Max. : 72.09 Max. : 47.745 Max. : 2279.617
## NA's :19216 NA's :19216 NA's :19216
## avg_yaw_forearm stddev_yaw_forearm var_yaw_forearm gyros_forearm_x
## Min. : -155.06 Min. : 0.000 Min. : 0.00 Min. : -22.000
## 1st Qu.: -26.26 1st Qu.: 0.524 1st Qu.: 0.27 1st Qu.: -0.220
## Median : 0.00 Median : 24.743 Median : 612.21 Median : 0.050
## Mean : 18.00 Mean : 44.854 Mean : 4639.85 Mean : 0.158
## 3rd Qu.: 85.79 3rd Qu.: 85.817 3rd Qu.: 7368.41 3rd Qu.: 0.560
## Max. : 169.24 Max. : 197.508 Max. : 39009.33 Max. : 3.970
## NA's :19216 NA's :19216 NA's :19216
## gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## Min. : -7.02000 Min. : -8.0900 Min. : -498.00 Min. : -632.0
## 1st Qu.: -1.46000 1st Qu.: -0.1800 1st Qu.: -178.00 1st Qu.: 57.0
## Median : 0.03000 Median : 0.0800 Median : -57.00 Median : 201.0
## Mean : 0.07517 Mean : 0.1512 Mean : -61.65 Mean : 163.7
## 3rd Qu.: 1.62000 3rd Qu.: 0.4900 3rd Qu.: 76.00 3rd Qu.: 312.0
## Max. : 311.00000 Max. : 231.0000 Max. : 477.00 Max. : 923.0
##

```

```
## accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## Min. : -446.00 Min. : -1280.0 Min. : -896.0 Min. : -973.0
## 1st Qu.: -182.00 1st Qu.: -616.0 1st Qu.: 2.0 1st Qu.: 191.0
## Median : -39.00 Median : -378.0 Median : 591.0 Median : 511.0
## Mean : -55.29 Mean : -312.6 Mean : 380.1 Mean : 393.6
## 3rd Qu.: 26.00 3rd Qu.: -73.0 3rd Qu.: 737.0 3rd Qu.: 653.0
## Max. : 291.00 Max. : 672.0 Max. : 1480.0 Max. : 1090.0
##
## classe
## A:5580
## B:3797
## C:3422
## D:3216
## E:3607
##
##
```

```
cat(noquote("Here is the summary of test data: "))
```

```
## Here is the summary of test data:
```

```
summary(test.data)
```

```
##      X      user_name raw_timestamp_part_1 raw_timestamp_part_2
## Min.   : 1.00   adelmo   :1   Min.   :1.322e+09   Min.   : 36553
## 1st Qu.: 5.75   carlitos:3   1st Qu.:1.323e+09   1st Qu.:268655
## Median :10.50   charles  :1   Median :1.323e+09   Median :530706
## Mean   :10.50   eurico   :4   Mean   :1.323e+09   Mean   :512167
## 3rd Qu.:15.25   jeremy   :8   3rd Qu.:1.323e+09   3rd Qu.:787738
## Max.   :20.00   pedro    :3   Max.   :1.323e+09   Max.   :920315
##
##      cvtd_timestamp new_window num_window roll_belt
## 30/11/2011 17:11:4   no:20     Min.   : 48.0   Min.   : -5.9200
## 05/12/2011 11:24:3           1st Qu.:250.0   1st Qu.: 0.9075
## 30/11/2011 17:12:3           Median :384.5   Median : 1.1100
## 05/12/2011 14:23:2           Mean   :379.6   Mean   : 31.3055
## 28/11/2011 14:14:2           3rd Qu.:467.0   3rd Qu.: 32.5050
## 02/12/2011 13:33:1           Max.   :859.0   Max.   :129.0000
## (Other)              :5
##      pitch_belt      yaw_belt      total_accel_belt kurtosis_roll_belt
## Min.   : -41.600   Min.   : -93.70   Min.   : 2.00   Mode:logical
## 1st Qu.: 3.013     1st Qu.: -88.62   1st Qu.: 3.00   NA's:20
## Median : 4.655     Median : -87.85   Median : 4.00
## Mean   : 5.824     Mean   : -59.30   Mean   : 7.55
## 3rd Qu.: 6.135     3rd Qu.: -63.50   3rd Qu.: 8.00
## Max.   : 27.800     Max.   :162.00   Max.   :21.00
##
##      kurtosis_picth_belt kurtosis_yaw_belt skewness_roll_belt
## Mode:logical           Mode:logical           Mode:logical
## NA's:20                NA's:20                NA's:20
##
##
##
##
```



```

## skewness_roll_belt.1 skewness_yaw_belt max_roll_belt max_pitch_belt
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## max_yaw_belt      min_roll_belt      min_pitch_belt min_yaw_belt
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## amplitude_roll_belt amplitude_pitch_belt amplitude_yaw_belt
## Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20
##
##
##
##
## var_total_accel_belt avg_roll_belt      stddev_roll_belt var_roll_belt
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## avg_pitch_belt      stddev_pitch_belt var_pitch_belt avg_yaw_belt
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## stddev_yaw_belt var_yaw_belt      gyros_belt_x      gyros_belt_y
## Mode:logical      Mode:logical      Min.      :-0.500      Min.      :-0.050
## NA's:20           NA's:20           1st Qu.: -0.070      1st Qu.: -0.005
##                      Median : 0.020      Median : 0.000
##                      Mean      :-0.045      Mean      : 0.010
##                      3rd Qu.: 0.070      3rd Qu.: 0.020
##                      Max.      : 0.240      Max.      : 0.110
##
## gyros_belt_z      accel_belt_x      accel_belt_y      accel_belt_z
## Min.      :-0.4800      Min.      :-48.00      Min.      :-16.00      Min.      :-187.00
## 1st Qu.: -0.1375      1st Qu.: -19.00      1st Qu.: 2.00      1st Qu.: -24.00
## Median : -0.0250      Median : -13.00      Median : 4.50      Median : 27.00
## Mean      :-0.1005      Mean      :-13.50      Mean      : 18.35      Mean      : -17.60
## 3rd Qu.: 0.0000      3rd Qu.: -8.75      3rd Qu.: 25.50      3rd Qu.: 38.25

```

```

## Max. : 0.0500 Max. : 46.00 Max. : 72.00 Max. : 49.00
##
## magnet_belt_x magnet_belt_y magnet_belt_z roll_arm
## Min. : -13.00 Min. : 566.0 Min. : -426.0 Min. : -137.00
## 1st Qu.: 5.50 1st Qu.: 578.5 1st Qu.: -398.5 1st Qu.: 0.00
## Median : 33.50 Median : 600.5 Median : -313.5 Median : 0.00
## Mean : 35.15 Mean : 601.5 Mean : -346.9 Mean : 16.42
## 3rd Qu.: 46.25 3rd Qu.: 631.2 3rd Qu.: -305.0 3rd Qu.: 71.53
## Max. : 169.00 Max. : 638.0 Max. : -291.0 Max. : 152.00
##
## pitch_arm yaw_arm total_accel_arm var_accel_arm
## Min. : -63.800 Min. : -167.00 Min. : 3.00 Mode:logical
## 1st Qu.: -9.188 1st Qu.: -60.15 1st Qu.: 20.25 NA's:20
## Median : 0.000 Median : 0.00 Median : 29.50
## Mean : -3.950 Mean : -2.80 Mean : 26.40
## 3rd Qu.: 3.465 3rd Qu.: 25.50 3rd Qu.: 33.25
## Max. : 55.000 Max. : 178.00 Max. : 44.00
##
## avg_roll_arm stddev_roll_arm var_roll_arm avg_pitch_arm
## Mode:logical Mode:logical Mode:logical Mode:logical
## NA's:20 NA's:20 NA's:20 NA's:20
##
##
##
##
## stddev_pitch_arm var_pitch_arm avg_yaw_arm stddev_yaw_arm
## Mode:logical Mode:logical Mode:logical Mode:logical
## NA's:20 NA's:20 NA's:20 NA's:20
##
##
##
##
## var_yaw_arm gyros_arm_x gyros_arm_y gyros_arm_z
## Mode:logical Min. : -3.710 Min. : -2.0900 Min. : -0.6900
## NA's:20 1st Qu.: -0.645 1st Qu.: -0.6350 1st Qu.: -0.1800
## Median : 0.020 Median : -0.0400 Median : -0.0250
## Mean : 0.077 Mean : -0.1595 Mean : 0.1205
## 3rd Qu.: 1.248 3rd Qu.: 0.2175 3rd Qu.: 0.5650
## Max. : 3.660 Max. : 1.8500 Max. : 1.1300
##
## accel_arm_x accel_arm_y accel_arm_z magnet_arm_x
## Min. : -341.0 Min. : -65.00 Min. : -404.00 Min. : -428.00
## 1st Qu.: -277.0 1st Qu.: 52.25 1st Qu.: -128.50 1st Qu.: -373.75
## Median : -194.5 Median : 112.00 Median : -83.50 Median : -265.00
## Mean : -134.6 Mean : 103.10 Mean : -87.85 Mean : -38.95
## 3rd Qu.: 5.5 3rd Qu.: 168.25 3rd Qu.: -27.25 3rd Qu.: 250.50
## Max. : 106.0 Max. : 245.00 Max. : 93.00 Max. : 750.00
##
## magnet_arm_y magnet_arm_z kurtosis_roll_arm kurtosis_pitch_arm
## Min. : -307.0 Min. : -499.0 Mode:logical Mode:logical
## 1st Qu.: 205.2 1st Qu.: 403.0 NA's:20 NA's:20
## Median : 291.0 Median : 476.5

```

```

## Mean      : 239.4    Mean      : 369.8
## 3rd Qu.: 358.8    3rd Qu.: 517.0
## Max.      : 474.0    Max.      : 633.0
##
## kurtosis_yaw_arm skewness_roll_arm skewness_pitch_arm skewness_yaw_arm
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## max_roll_arm      max_pitch_arm      max_yaw_arm      min_roll_arm
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## min_pitch_arm      min_yaw_arm      amplitude_roll_arm amplitude_pitch_arm
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## amplitude_yaw_arm roll_dumbbell      pitch_dumbbell      yaw_dumbbell
## Mode:logical      Min.      :-111.118    Min.      :-54.97    Min.      :-103.3200
## NA's:20           1st Qu.:   7.494    1st Qu.: -51.89    1st Qu.: -75.2809
##                   Median :  50.403    Median : -40.81    Median :  -8.2863
##                   Mean      :  33.760    Mean      : -19.47    Mean      :  -0.9385
##                   3rd Qu.:  58.129    3rd Qu.:  16.12    3rd Qu.:  55.8335
##                   Max.      : 123.984    Max.      :  96.87    Max.      : 132.2337
##
## kurtosis_roll_dumbbell kurtosis_pitch_dumbbell kurtosis_yaw_dumbbell
## Mode:logical          Mode:logical          Mode:logical
## NA's:20              NA's:20              NA's:20
##
##
##
##
## skewness_roll_dumbbell skewness_pitch_dumbbell skewness_yaw_dumbbell
## Mode:logical          Mode:logical          Mode:logical
## NA's:20              NA's:20              NA's:20
##
##
##
##
## max_roll_dumbbell max_pitch_dumbbell max_yaw_dumbbell min_roll_dumbbell
## Mode:logical      Mode:logical      Mode:logical      Mode:logical

```

```

## NA's:20          NA's:20          NA's:20          NA's:20
##
##
##
##
## min_pitch_dumbbell min_yaw_dumbbell amplitude_roll_dumbbell
## Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20
##
##
##
##
## amplitude_pitch_dumbbell amplitude_yaw_dumbbell total_accel_dumbbell
## Mode:logical      Mode:logical      Min.    : 1.0
## NA's:20           NA's:20           1st Qu.: 7.0
##                                     Median :15.5
##                                     Mean    :17.2
##                                     3rd Qu.:29.0
##                                     Max.    :31.0
##
## var_accel_dumbbell avg_roll_dumbbell stddev_roll_dumbbell
## Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20
##
##
##
##
## var_roll_dumbbell avg_pitch_dumbbell stddev_pitch_dumbbell
## Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20
##
##
##
##
## var_pitch_dumbbell avg_yaw_dumbbell stddev_yaw_dumbbell var_yaw_dumbbell
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
## gyros_dumbbell_x gyros_dumbbell_y gyros_dumbbell_z accel_dumbbell_x
## Min.    :-1.0300 Min.    :-1.1100 Min.    :-1.180 Min.    :-159.00
## 1st Qu.: 0.1600 1st Qu.: -0.2100 1st Qu.: -0.485 1st Qu.: -140.25
## Median : 0.3600 Median : 0.0150 Median : -0.280 Median : -19.00
## Mean    : 0.2690 Mean    : 0.0605 Mean    : -0.266 Mean    : -47.60
## 3rd Qu.: 0.4625 3rd Qu.: 0.1450 3rd Qu.: -0.165 3rd Qu.: 15.75
## Max.    : 1.0600 Max.    : 1.9100 Max.    : 1.100 Max.    : 185.00
##

```

```

## accel_dumbbell_y accel_dumbbell_z magnet_dumbbell_x magnet_dumbbell_y
## Min.      :-30.00    Min.      :-221.0    Min.      :-576.0    Min.      :-558.0
## 1st Qu.:   5.75    1st Qu.: -192.2    1st Qu.: -528.0    1st Qu.:  259.5
## Median :  71.50    Median :   -3.0    Median : -508.5    Median :  316.0
## Mean   :  70.55    Mean   :  -60.0    Mean   : -304.2    Mean   :  189.3
## 3rd Qu.: 151.25    3rd Qu.:   76.5    3rd Qu.: -317.0    3rd Qu.:  348.2
## Max.    : 166.00    Max.    :  100.0    Max.    :  523.0    Max.    :  403.0
##
## magnet_dumbbell_z roll_forearm      pitch_forearm      yaw_forearm
## Min.      :-164.00    Min.      :-176.00    Min.      :-63.500    Min.      :-168.000
## 1st Qu.:  -33.00    1st Qu.:  -40.25    1st Qu.: -11.457    1st Qu.:  -93.375
## Median :   49.50    Median :   94.20    Median :   8.830    Median :  -19.250
## Mean   :   71.40    Mean   :   38.66    Mean   :   7.099    Mean   :   2.195
## 3rd Qu.:   96.25    3rd Qu.:  143.25    3rd Qu.:  28.500    3rd Qu.:  104.500
## Max.    :  368.00    Max.    :  176.00    Max.    :  59.300    Max.    :  159.000
##
## kurtosis_roll_forearm kurtosis_pitch_forearm kurtosis_yaw_forearm
## Mode:logical          Mode:logical          Mode:logical
## NA's:20              NA's:20              NA's:20
##
##
##
##
## skewness_roll_forearm skewness_pitch_forearm skewness_yaw_forearm
## Mode:logical          Mode:logical          Mode:logical
## NA's:20              NA's:20              NA's:20
##
##
##
##
## max_roll_forearm max_pitch_forearm max_yaw_forearm min_roll_forearm
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20          NA's:20          NA's:20          NA's:20
##
##
##
##
## min_pitch_forearm min_yaw_forearm amplitude_roll_forearm
## Mode:logical      Mode:logical      Mode:logical
## NA's:20          NA's:20          NA's:20
##
##
##
##
## amplitude_pitch_forearm amplitude_yaw_forearm total_accel_forearm
## Mode:logical      Mode:logical      Min.      :21.00
## NA's:20          NA's:20          1st Qu.:24.00
##                                     Median :32.50
##                                     Mean   :32.05
##                                     3rd Qu.:36.75

```

```

##                                     Max.      :47.00
##
##  var_accel_forearm avg_roll_forearm stddev_roll_forearm var_roll_forearm
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
##  avg_pitch_forearm stddev_pitch_forearm var_pitch_forearm avg_yaw_forearm
## Mode:logical      Mode:logical      Mode:logical      Mode:logical
## NA's:20           NA's:20           NA's:20           NA's:20
##
##
##
##
##  stddev_yaw_forearm var_yaw_forearm gyros_forearm_x  gyros_forearm_y
## Mode:logical      Mode:logical      Min.      :-1.0600 Min.      :-5.9700
## NA's:20           NA's:20           1st Qu.: -0.5850 1st Qu.: -1.2875
##                                     Median : 0.0200 Median : 0.0350
##                                     Mean   :-0.0200 Mean   :-0.0415
##                                     3rd Qu.: 0.2925 3rd Qu.: 2.0475
##                                     Max.    : 1.3800 Max.    : 4.2600
##
##  gyros_forearm_z  accel_forearm_x accel_forearm_y accel_forearm_z
## Min.      :-1.2600 Min.      :-212.0 Min.      :-331.0 Min.      :-282.0
## 1st Qu.: -0.0975 1st Qu.: -114.8 1st Qu.: 8.5 1st Qu.: -199.0
## Median : 0.2300 Median : 86.0 Median : 138.0 Median : -148.5
## Mean   : 0.2610 Mean   : 38.8 Mean   : 125.3 Mean   : -93.7
## 3rd Qu.: 0.7625 3rd Qu.: 166.2 3rd Qu.: 268.0 3rd Qu.: -31.0
## Max.    : 1.8000 Max.    : 232.0 Max.    : 406.0 Max.    : 179.0
##
##  magnet_forearm_x magnet_forearm_y magnet_forearm_z  problem_id
## Min.      :-714.0 Min.      :-787.0 Min.      :-32.0 Min.      : 1.00
## 1st Qu.: -427.2 1st Qu.: -328.8 1st Qu.: 275.2 1st Qu.: 5.75
## Median : -189.5 Median : 487.0 Median : 491.5 Median : 10.50
## Mean   : -159.2 Mean   : 191.8 Mean   : 460.2 Mean   : 10.50
## 3rd Qu.: 41.5 3rd Qu.: 720.8 3rd Qu.: 661.5 3rd Qu.: 15.25
## Max.    : 532.0 Max.    : 800.0 Max.    : 884.0 Max.    : 20.00
##

```

It seems that both data sets have 160 columns, and there are many columns in the test data set containing only NA values. So, we will have to select the columns containing no missing values.

```

test.data.select <- test.data[, colSums(is.na(test.data)) < nrow(test.data)]
cat(noquote("Here is the list of all columns with NO nas in test data set: "))

```

```

## Here is the list of all columns with NO nas in test data set:

```

```

colnames(test.data.select)

```

```

## [1] "X" "user_name" "raw_timestamp_part_1"
## [4] "raw_timestamp_part_2" "cvtd_timestamp" "new_window"
## [7] "num_window" "roll_belt" "pitch_belt"

```

```
## [10] "yaw_belt"           "total_accel_belt"      "gyros_belt_x"
## [13] "gyros_belt_y"       "gyros_belt_z"         "accel_belt_x"
## [16] "accel_belt_y"       "accel_belt_z"         "magnet_belt_x"
## [19] "magnet_belt_y"      "magnet_belt_z"        "roll_arm"
## [22] "pitch_arm"          "yaw_arm"              "total_accel_arm"
## [25] "gyros_arm_x"        "gyros_arm_y"          "gyros_arm_z"
## [28] "accel_arm_x"        "accel_arm_y"          "accel_arm_z"
## [31] "magnet_arm_x"       "magnet_arm_y"         "magnet_arm_z"
## [34] "roll_dumbbell"      "pitch_dumbbell"       "yaw_dumbbell"
## [37] "total_accel_dumbbell" "gyros_dumbbell_x"     "gyros_dumbbell_y"
## [40] "gyros_dumbbell_z"   "accel_dumbbell_x"     "accel_dumbbell_y"
## [43] "accel_dumbbell_z"   "magnet_dumbbell_x"    "magnet_dumbbell_y"
## [46] "magnet_dumbbell_z"  "roll_forearm"         "pitch_forearm"
## [49] "yaw_forearm"        "total_accel_forearm"  "gyros_forearm_x"
## [52] "gyros_forearm_y"    "gyros_forearm_z"      "accel_forearm_x"
## [55] "accel_forearm_y"    "accel_forearm_z"      "magnet_forearm_x"
## [58] "magnet_forearm_y"   "magnet_forearm_z"     "problem_id"
```

```
cat(noquote("Check whether the names of all these features are the same as the names in train.data:"))
```

```
## Check whether the names of all these features are the same as the names in train.data:
```

```
cat("\n")
```

```
colnames(test.data.select) %in% colnames(train.data)
```

```
## [1] TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE
## [12] TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE
## [23] TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE
## [34] TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE
## [45] TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE TRUE
## [56] TRUE TRUE TRUE TRUE FALSE
```

We can see that these names are common in the train data set, except the last feature “problem_id”, so we can select the all other features to build the model. Of course, we also need the predicted output “classe” in the model. Also, the first feature “X” is not that important in the model at all, so we will just abandon it. In addition, I don’t think the features “raw_timestamp_part_1”, “raw_timestamp_part_2”, “cvtd_timestamp”, “new_window”, “num_window” are really related to the “classe”, so these features are dropped also.

```
features.select <- colnames(test.data.select)
features.delete <- c("X", "raw_timestamp_part_1", "raw_timestamp_part_2", "cvtd_timestamp", "new_window", "num_window")
features.input <- features.select[!(features.select %in% features.delete)]
train.data <- train.data[, c(features.input, "classe")]
```

So, we will use only two data sets in the following analysis: “train.data” and “test.data”.

Let’s start with simple decision tree first.

Decision tree

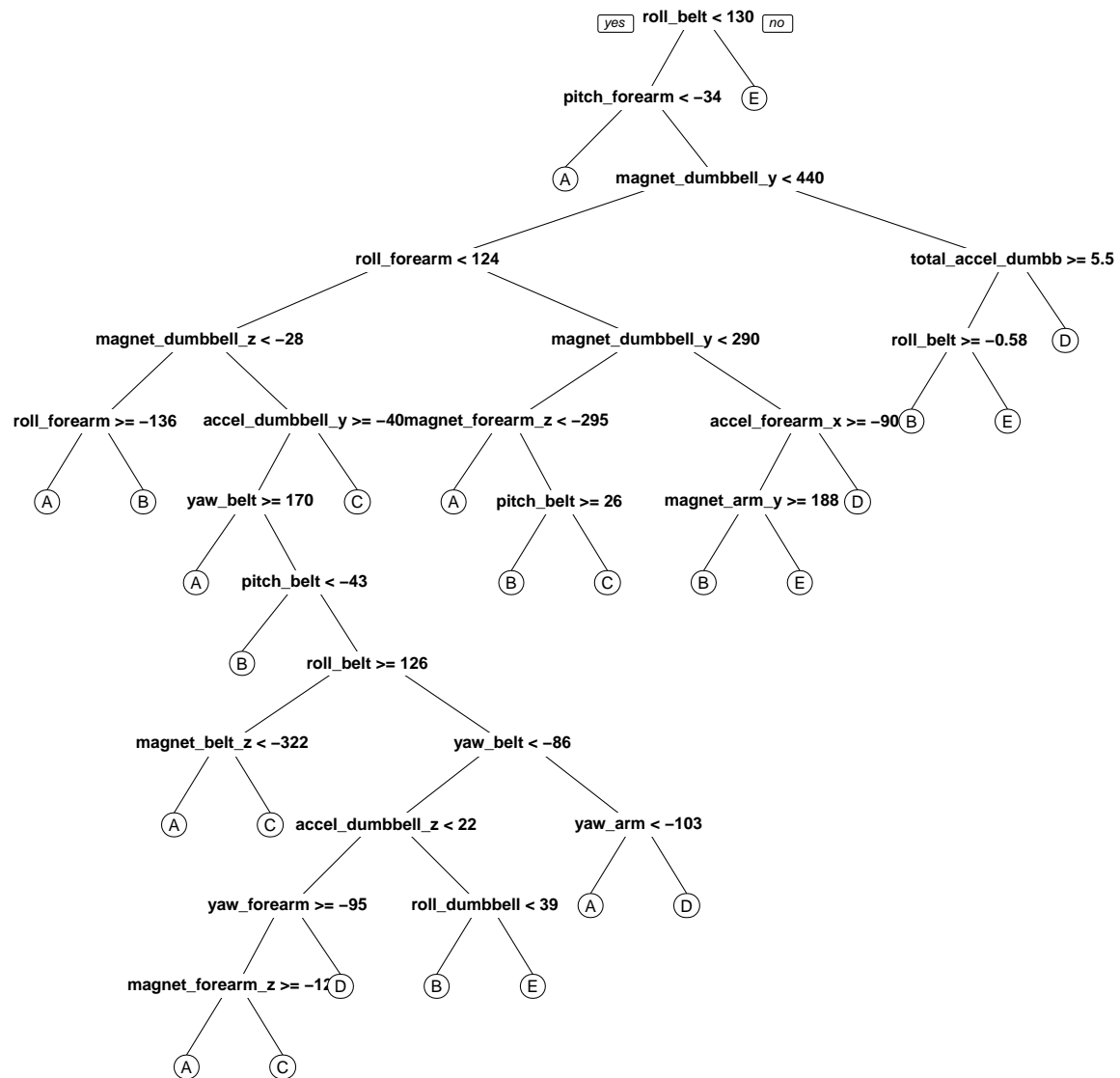
In this basic decision tree model, we can use “classe” as the output, and all other variables as “inputs”.

```
set.seed(1217)
# Get the random 30% of the rows in the train.data as crossing validation test, and 70% as train.train
index.train <- sample(c(1:nrow(train.data)), 0.7 * nrow(train.data))
train.train <- train.data[index.train, ]
```

```
train.cv <- train.data[-index.train, ]
tree <- rpart(classe ~ ., train.train, method = "class")
cat(noquote("Here is the decision tree built with all features from train data:"))
```

Here is the decision tree built with all features from train data:

```
prp(tree, faclen = 0, cex = 0.8)
```



Then, let's take a look at how the model performs.

```
prediction.tree <- predict(tree, train.cv, type = "class")
tree.performance <- confusionMatrix(prediction.tree, train.cv$classe)
cat(noquote("Here is the performance of the decision tree model in the cross validation data set:"))
```

Here is the performance of the decision tree model in the cross validation data set:


```
cat("\n")
```

```
tree.performance
```

```
## Confusion Matrix and Statistics
##
##           Reference
## Prediction    A    B    C    D    E
##           A 1557  174   19   40   17
##           B   56  677   94   83  100
##           C   53  109  829  151  121
##           D   19   87   63  608   62
##           E   33   46   28   90  771
##
## Overall Statistics
##
##           Accuracy : 0.7545
##           95% CI : (0.7433, 0.7655)
##           No Information Rate : 0.2918
##           P-Value [Acc > NIR] : < 2.2e-16
##
##           Kappa : 0.6883
##           McNemar's Test P-Value : < 2.2e-16
##
## Statistics by Class:
##
##           Class: A Class: B Class: C Class: D Class: E
## Sensitivity          0.9063   0.6194   0.8025   0.6255   0.7199
## Specificity          0.9400   0.9305   0.9106   0.9530   0.9591
## Pos Pred Value       0.8616   0.6703   0.6564   0.7247   0.7965
## Neg Pred Value       0.9605   0.9147   0.9559   0.9279   0.9390
## Prevalence           0.2918   0.1857   0.1755   0.1651   0.1819
## Detection Rate       0.2645   0.1150   0.1408   0.1033   0.1310
## Detection Prevalence 0.3069   0.1716   0.2145   0.1425   0.1644
## Balanced Accuracy    0.9232   0.7750   0.8566   0.7893   0.8395
```

So, we can see that the overall accuracy is 0.7545.

Random forest

In this section, the random forest model is used in the train.train data set.

```
rf <- randomForest(classe ~ ., data = train.train, type = "class")
prediction.rf <- predict(rf, train.cv, type = "class")
rf.performance <- confusionMatrix(prediction.rf, train.cv$classe)
cat(noquote("Here is the performance of the random forest model in the cross validation data set:"))
```

```
## Here is the performance of the random forest model in the cross validation data set:
```

```
cat("\n")
```

```
rf.performance
```

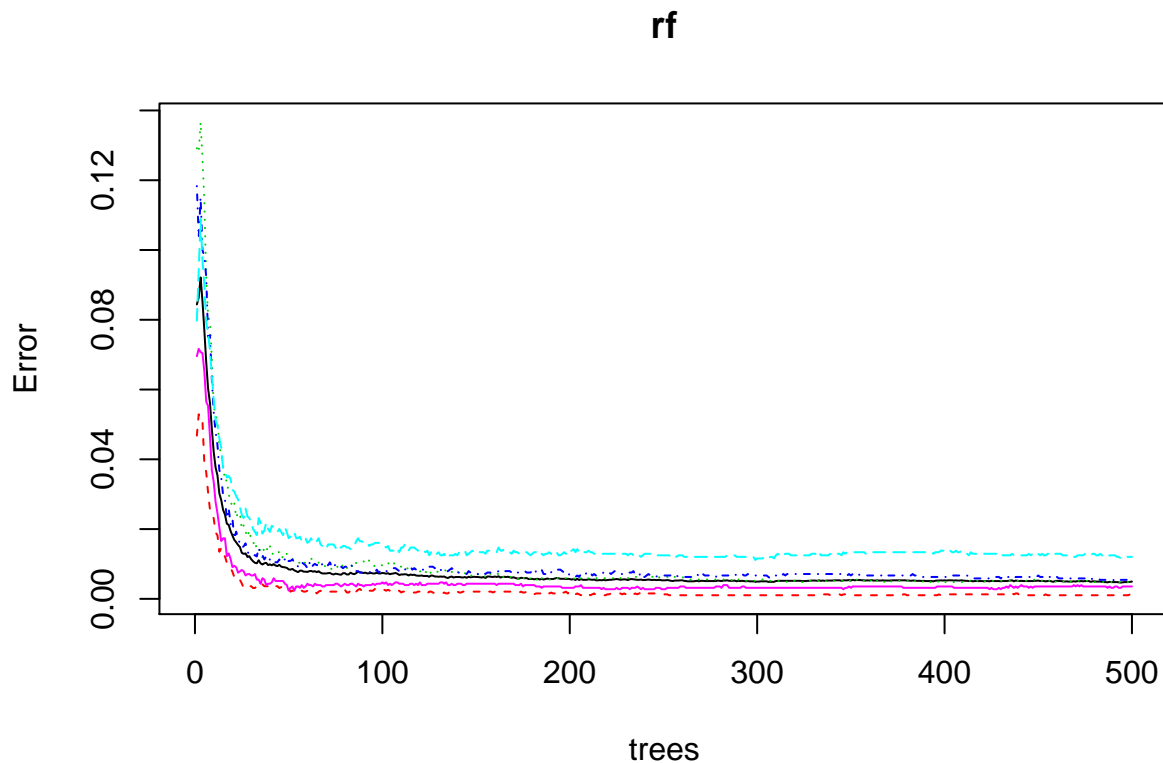
```
## Confusion Matrix and Statistics
##
##           Reference
```

```

## Prediction      A      B      C      D      E
##           A 1718      4      0      0      0
##           B      0 1087      7      0      0
##           C      0      2 1025     13      0
##           D      0      0      1   957      1
##           E      0      0      0      2 1070
##
## Overall Statistics
##
##           Accuracy : 0.9949
##           95% CI : (0.9927, 0.9966)
##           No Information Rate : 0.2918
##           P-Value [Acc > NIR] : < 2.2e-16
##
##           Kappa : 0.9935
##           McNemar's Test P-Value : NA
##
## Statistics by Class:
##
##           Class: A Class: B Class: C Class: D Class: E
## Sensitivity      1.0000   0.9945   0.9923   0.9846   0.9991
## Specificity      0.9990   0.9985   0.9969   0.9996   0.9996
## Pos Pred Value   0.9977   0.9936   0.9856   0.9979   0.9981
## Neg Pred Value   1.0000   0.9987   0.9983   0.9970   0.9998
## Prevalence       0.2918   0.1857   0.1755   0.1651   0.1819
## Detection Rate   0.2918   0.1846   0.1741   0.1626   0.1818
## Detection Prevalence 0.2925   0.1858   0.1767   0.1629   0.1821
## Balanced Accuracy 0.9995   0.9965   0.9946   0.9921   0.9993

```

```
plot(rf)
```



It seems that the random forest has a very good estimation already, the overall accuracy is 0.9949 in the cross validation data set. So, it should perform quite well in the test data also.

In this model, the number of trees is set as default (500). However, it might not be necessary to have those many trees in a forest, the plot shows that the error can be almost no-decreasing once the number of trees is smaller than 50.

However, let's take a look at the boosting method also.

Boosting method

```
fitControl <- trainControl(method = "repeatedcv", number = 2, repeats = 1)

boosting <- train(classe ~ ., data = train.train, method = "gbm",
                  trControl = fitControl,
                  verbose = FALSE)
```

```
## Warning: package 'gbm' was built under R version 3.4.2
```

```
## Loading required package: survival
```

```
##
```

```
## Attaching package: 'survival'
```

```
## The following object is masked from 'package:caret':
```

```
##
```

```
## cluster
```

```
## Loading required package: splines
## Loading required package: parallel
## Loaded gbm 2.1.3
## Warning: package 'plyr' was built under R version 3.4.2
boosting.model <- boosting$finalModel
prediction.boosting <- predict(boosting, train.cv)
boosting.performance <- confusionMatrix(prediction.boosting, train.cv$classe)
cat(noquote("The performance for the general boosting model in cross validation data set is:"))

## The performance for the general boosting model in cross validation data set is:
cat("\n")

boosting.performance

## Confusion Matrix and Statistics
##
##           Reference
## Prediction    A    B    C    D    E
##           A 1690   21    0    0    1
##           B   21 1038   29    3    9
##           C    5   31  985   33   11
##           D    1    2   17  924   12
##           E    1    1    2   12 1038
##
## Overall Statistics
##
##           Accuracy : 0.964
##           95% CI : (0.9589, 0.9686)
##           No Information Rate : 0.2918
##           P-Value [Acc > NIR] : < 2.2e-16
##
##           Kappa : 0.9544
##           McNemar's Test P-Value : 0.007554
##
## Statistics by Class:
##
##           Class: A Class: B Class: C Class: D Class: E
## Sensitivity      0.9837  0.9497  0.9535  0.9506  0.9692
## Specificity      0.9947  0.9871  0.9835  0.9935  0.9967
## Pos Pred Value   0.9871  0.9436  0.9249  0.9665  0.9848
## Neg Pred Value   0.9933  0.9885  0.9900  0.9903  0.9932
## Prevalence       0.2918  0.1857  0.1755  0.1651  0.1819
## Detection Rate   0.2871  0.1763  0.1673  0.1570  0.1763
## Detection Prevalence 0.2908  0.1869  0.1809  0.1624  0.1790
## Balanced Accuracy 0.9892  0.9684  0.9685  0.9721  0.9829
```

The performance of the boosting method is 0.9616 overall accuracy. I think the accuracy would be much better if we can increase the number in the “trainControl”; however, it would take too much CPU time on my machine. So, I am unable to do that.

Now, let’s take a prediction of all values in test data set.

Test data set

```
test.tree <- predict(tree, test.data, type = "class")
test.rf <- predict(rf, test.data)
test.boosting <- predict(boosting, test.data)

cat(noquote("Here are the summary of all predicted results in test data set:"))
```

```
## Here are the summary of all predicted results in test data set:
```

```
test.tree
```

```
##  1  2  3  4  5  6  7  8  9 10 11 12 13 14 15 16 17 18 19 20
##  B  A  B  A  A  C  D  A  A  A  C  B  C  A  E  E  A  B  B  B
## Levels: A B C D E
```

```
test.rf
```

```
##  1  2  3  4  5  6  7  8  9 10 11 12 13 14 15 16 17 18 19 20
##  B  A  B  A  A  E  D  B  A  A  B  C  B  A  E  E  A  B  B  B
## Levels: A B C D E
```

```
test.boosting
```

```
##  [1] B A B A A E D B A A B C B A E E A B B B
## Levels: A B C D E
```

So, let's use the results from random forest to estimate the classe in test data set.