

Optimization of Submodular Functions

Tutorial - lecture II

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Lecture I:

- 1 Submodular functions: what and why?
- 2 Convex aspects: Submodular minimization
- 3 Concave aspects: Submodular maximization

Lecture II:

- 1 Hardness of constrained submodular minimization
- 2 Unconstrained submodular maximization
- 3 Hardness more generally: the symmetry gap

Hardness of constrained submodular minimization

We saw:

- Submodular minimization is in P
(without constraints, and also under "parity type" constraints).

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- **Submodular minimization** is in P
(without constraints, and also under "parity type" constraints).

However: minimization is brittle and can become very hard to approximate under simple constraints.

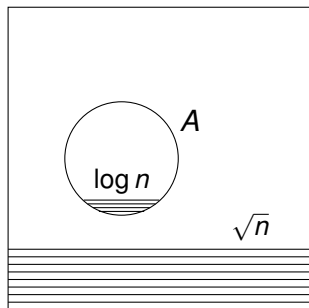
- $\sqrt{\frac{n}{\log n}}$ -**hardness** for $\min\{f(S) : |S| \geq k\}$, Submodular Load Balancing, Submodular Sparsest Cut [Svitkina, Fleischer '09]
- $n^{\Omega(1)}$ -**hardness** for Submodular Spanning Tree, Submodular Perfect Matching, Submodular Shortest Path [Goel, Karande, Tripathi, Wang '09]

These hardness results assume the **value oracle model**: the only access to f is through **value queries**, $f(S) = ?$

Superconstant hardness for submodular minimization

Problem: $\min\{f(S) : |S| \geq k\}$.

Construction of [Goemans,Harvey,Iwata,Mirrokní '09]:



$A = \text{random (hidden) set of size } k = \sqrt{n}$

$$f(S) = \min\{\sqrt{n}, |S \setminus A| + \min\{\log n, |S \cap A|\}\}$$

Analysis: with high probability, a value query does not give any information about $A \Rightarrow$ an algorithm will return a set of value \sqrt{n} , while the optimum is $\log n$.

CONSTRAINED SUBMODULAR MINIMIZATION

Constraint	Approximation	Hardness	hardness ref
Vertex cover	2	2 _[UGC]	Khot,Regev '03
k -unif. hitting set	k	k _[UGC]	Khot,Regev '03
k -way partition	$2 - 2/k$	$2 - 2/k$	Ene,V.,Wu '12
Facility location	$\log n$	$\log n$	Svitkina,Tardos '07
Set cover	n	$n/\log^2 n$	Iwata,Nagano '09
$ S \geq k$	$\tilde{O}(\sqrt{n})$	$\tilde{\Omega}(\sqrt{n})$	Svitkina,Fleischer '09
Sparsest Cut	$\tilde{O}(\sqrt{n})$	$\tilde{\Omega}(\sqrt{n})$	Svitkina,Fleischer '09
Load Balancing	$\tilde{O}(\sqrt{n})$	$\tilde{\Omega}(\sqrt{n})$	Svitkina,Fleischer '09
Shortest path	$O(n^{2/3})$	$\Omega(n^{2/3})$	GKTW '09
Spanning tree	$O(n)$	$\Omega(n)$	GKTW '09

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Maximization of a nonnegative submodular function

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- Maximizing a submodular function is NP-hard (Max Cut).

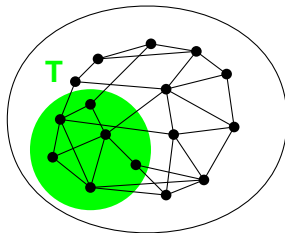
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Unconstrained submodular maximization: *Given a submodular function $f : 2^N \rightarrow \mathbb{R}_+$, how well can we approximate the maximum?*

Special case - Max Cut:



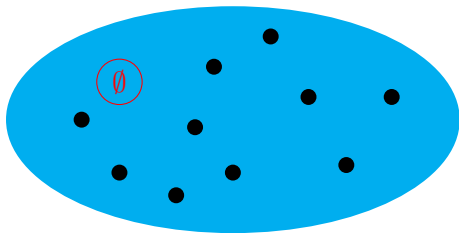
polynomial-time **0.878-approximation** [Goemans-Williamson '95],
best possible assuming the Unique Games Conjecture [Khot,Kindler,
Mossel,O'Donnell '04, Mossel,O'Donnell,Oleszkiewicz '05]

Unconstrained submodular maximization: $\max_{S \subseteq N} f(S)$
has been resolved recently:

- there is a (randomized) $1/2$ -approximation [Buchbinder, Feldman, Naor, Schwartz '12]
- $(1/2 + \epsilon)$ -approximation in the value oracle model would require exponentially many queries [Feige, Mirrokni, V. '07]
- $(1/2 + \epsilon)$ -approximation for certain explicitly represented submodular functions would imply $NP = RP$ [Dobzinski, V. '12]

$\frac{1}{2}$ -approximation for submodular maximization [Buchbinder, Feldman, Naor, Schwartz '12]

A double-greedy algorithm with two evolving solutions:

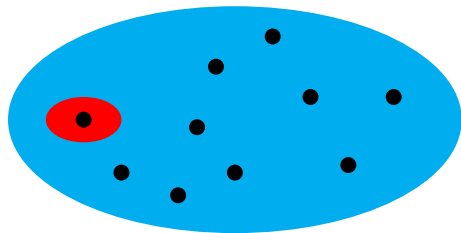


Initialize $A = \emptyset$, $B = \text{everything}$.
In each step, **grow** A or **shrink** B .
Invariant: $A \subseteq B$.

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While  $A \neq B$  {  
  Pick  $i \in B \setminus A$ ;  
  Let  $\alpha = \max\{f(A + i) - f(A), 0\}$ ,  $\beta = \max\{f(B - i) - f(B), 0\}$ ;  
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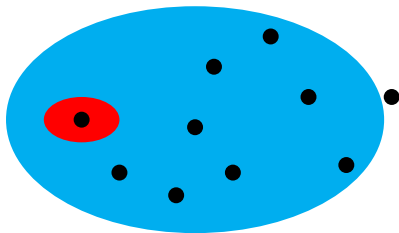


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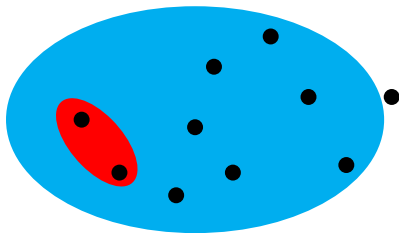


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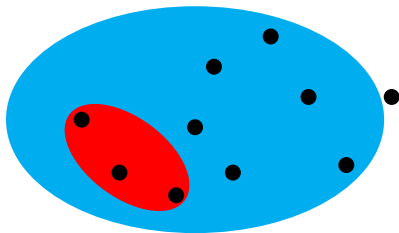


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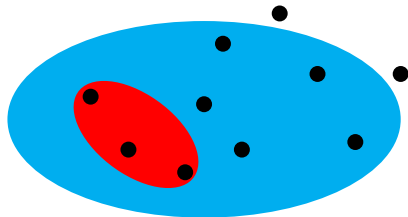


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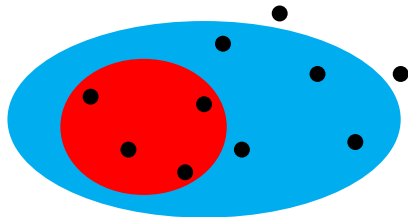


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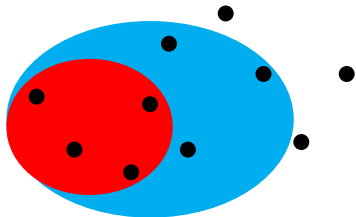


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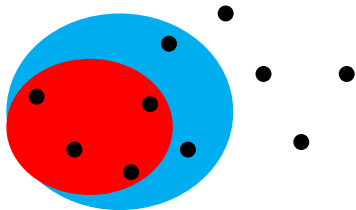


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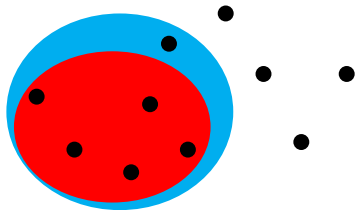


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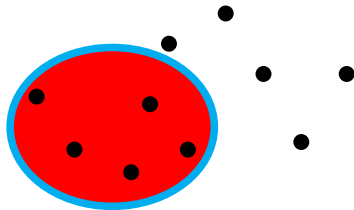


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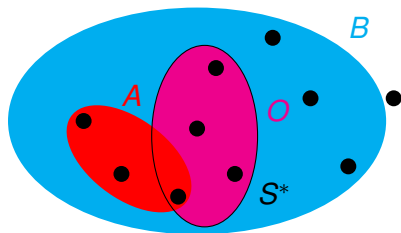
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Analysis of $\frac{1}{2}$ -approximation

Evolving optimum: $O = A \cup (B \cap S^*)$, where S^* is the optimum.

We track the quantity $f(A) + f(B) + 2f(O)$:



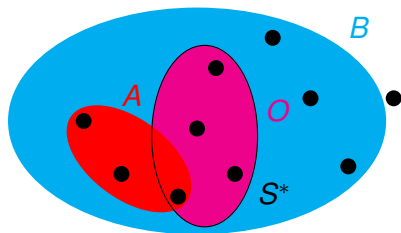
Initially: $A = \emptyset$, $B = N$, $O = S^*$.
 $f(A) + f(B) + 2f(O) \geq 2 \cdot OPT.$

At the end: $A = B = O = \text{output}$.
 $f(A) + f(B) + 2f(O) = 4 \cdot ALG.$

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Claim: $\mathbb{E}[f(A) + f(B) + 2f(O)]$ never decreases in the process.

Proof: Expected change in $f(A) + f(B) + 2f(O)$ is

$$\frac{\alpha}{\alpha + \beta} \cdot \alpha + \frac{\beta}{\alpha + \beta} \cdot \beta - \frac{2\alpha\beta}{\alpha + \beta} = \frac{(\alpha - \beta)^2}{\alpha + \beta} \geq 0.$$

Optimality of $1/2$ for submodular maximization

How do we prove that $1/2$ is optimal? [Feige, Mirrokni, V. '07]

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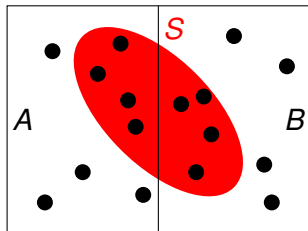
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Again, the **value oracle model**: the only access to f is through **value queries**, $f(S) = ?$, polynomially many times.

Idea: Construct an instance of optimum $f(S^*) = 1 - \epsilon$, so that all the sets an algorithm will ever see have value $f(S) \leq 1/2$.



$$f(S) = \psi\left(\frac{|S \cap A|}{|A|}, \frac{|S \cap B|}{|B|}\right)$$

A, B are the intended optimal solutions, but the partition (A, B) is *hard to find*.

Constructing the hard instance

Continuous submodularity:

If $\frac{\partial^2 \psi}{\partial x \partial y} \leq 0$, then $f(S) = \psi\left(\frac{|S \cap A|}{|A|}, \frac{|S \cap B|}{|B|}\right)$ is submodular.

(non-increasing partial derivatives \simeq non-increasing marginal values)

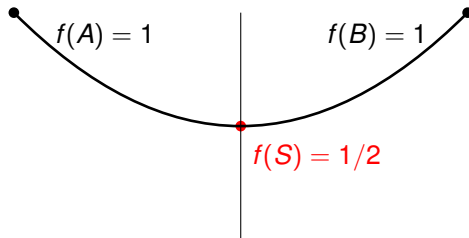
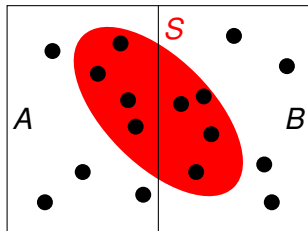
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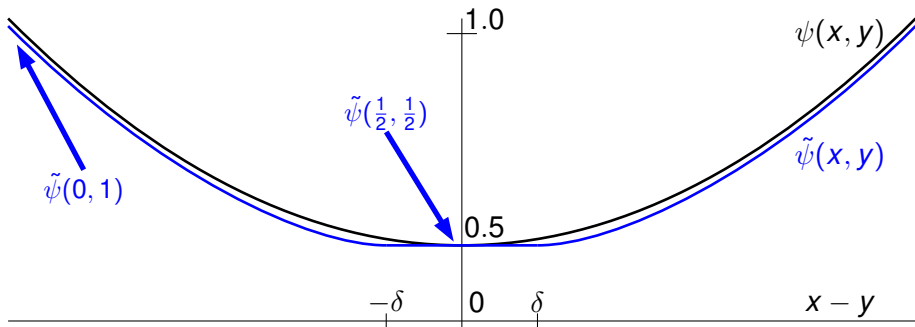
The function will be "roughly": $\psi(x, y) = x(1 - y) + (1 - x)y$.



However, it should be hard to find the partition (A, B) !

The perturbation trick

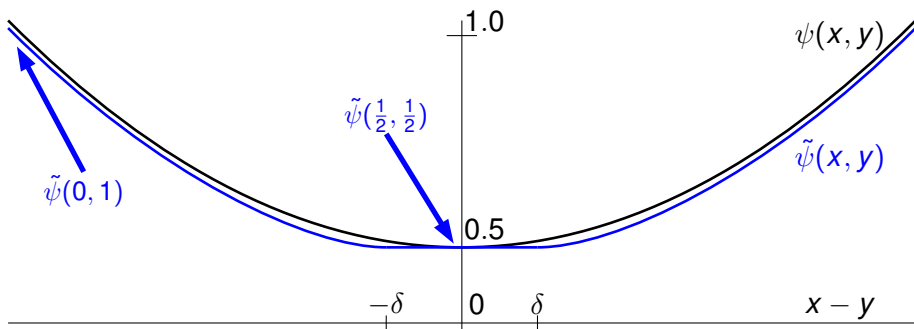
We modify $\psi(x, y)$ as follows:
(graph restricted to $x + y = 1$)



- The function for $|x - y| < \delta$ is **flattened** so it depends only on $x + y$.

The perturbation trick

We modify $\psi(x, y)$ as follows:
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- The function for $|x - y| < \delta$ is **flattened** so it depends only on $x + y$.
- If the partition (A, B) is random, $x = \frac{|S \cap A|}{|A|}$ and $y = \frac{|S \cap B|}{|B|}$ are random variables, with high probability satisfying $|x - y| < \delta$.
- Hence, an algorithm will never learn any information about (A, B) .

Conclusion: for unconstrained submodular maximization,

- The optimum is $f(A) = f(B) = 1 - \epsilon$.
- An algorithm can only find solutions symmetrically split between A, B : $|S \cap A| \simeq |S \cap B|$.
- The value of such solutions is at most $1/2$.

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More general view:

- The difficulty here is in distinguishing between **symmetric** and **asymmetric** solutions.
- Submodularity is flexible enough that we can hide the **asymmetric** solutions and force an algorithm to find only **symmetric** ones.

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Symmetric instances

Symmetric instance: $\max\{f(S) : S \in \mathcal{F}\}$ on a ground set X is symmetric under a group of permutations $\mathcal{G} \subset \mathbb{S}(X)$, if for any $\sigma \in \mathcal{G}$,

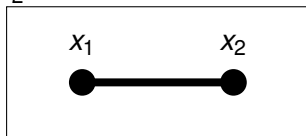
- $f(S) = f(\sigma(S))$
- $S \in \mathcal{F} \Leftrightarrow S' \in \mathcal{F}$ whenever $\overline{\mathbf{1}_S} = \overline{\mathbf{1}_{S'}}$, where
- $\bar{x} = \mathbb{E}_{\sigma \in \mathcal{G}}[\sigma(x)]$ (*symmetrization operation*)

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Example: Max Cut on K_2



- $X = \{1, 2\}$, $\mathcal{F} = 2^X$, $P(\mathcal{F}) = [0, 1]^2$.
- $f(S) = 1$ if $|S| = 1$, otherwise 0.
- Symmetric under $\mathcal{G} = \mathbb{S}_2$, all permutations of 2 elements.
- For $x = (x_1, x_2)$, $\bar{x} = (\frac{x_1 + x_2}{2}, \frac{x_1 + x_2}{2})$.

Symmetry gap

Symmetry gap:

$$\gamma = \frac{\overline{OPT}}{OPT}$$

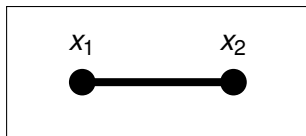
where

$$OPT = \max\{F(x) : x \in P(\mathcal{F})\}$$

$$\overline{OPT} = \max\{F(\bar{x}) : x \in P(\mathcal{F})\}$$

where $F(x)$ is the multilinear extension of f .

Example:



- $OPT = \max\{F(x) : x \in P(\mathcal{F})\} = F(1, 0) = 1.$
- $\overline{OPT} = \max\{F(\bar{x}) : x \in P(\mathcal{F})\} = F(\frac{1}{2}, \frac{1}{2}) = 1/2.$

Symmetry gap \Rightarrow hardness

Oracle hardness [V. '09]:

For any instance \mathcal{I} of submodular maximization with symmetry gap γ , and any $\epsilon > 0$, $(\gamma + \epsilon)$ -approximation for a class of instances produced by "blowing up" \mathcal{I} would require exponentially many value queries.

Computational hardness [Dobzinski, V. '12]:

There is no $(\gamma + \epsilon)$ -approximation for a certain explicit representation of these instances, unless $NP = RP$.

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For any instance \mathcal{I} of submodular maximization with symmetry gap γ , and any $\epsilon > 0$, $(\gamma + \epsilon)$ -approximation for a class of instances produced by "blowing up" \mathcal{I} would require exponentially many value queries.

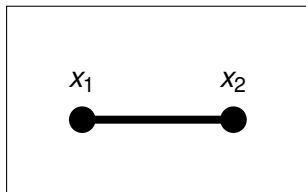
Computational hardness [Dobzinski, V. '12]:

There is no $(\gamma + \epsilon)$ -approximation for a certain explicit representation of these instances, unless $NP = RP$.

Notes:

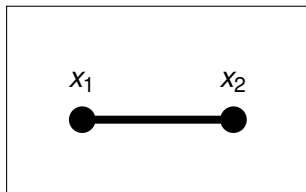
- "Blow-up" means expanding the ground set, replacing the objective function by the perturbed one, and extending the feasibility constraint in a natural way.
- Example: $\max\{f(S) : |S| \leq 1\}$ on a ground set $[k]$
 $\longrightarrow \max\{f(S) : |S| \leq n/k\}$ on a ground set $[n]$.

Application 1: nonnegative submodular maximization



- $\max\{f(S) : S \subseteq \{1, 2\}\}$: symmetric under \mathbb{S}_2 .
- Symmetry gap is $\gamma = 1/2$.
- Refined instances are instances of unconstrained (non-monotone) submodular maximization.

Application 1: nonnegative submodular maximization



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- Symmetry gap is $\gamma = 1/2$.
- Refined instances are instances of unconstrained (non-monotone) submodular maximization.
- Theorem implies that **a better than 1/2-approximation is impossible** (previously known [FMV '07]).

Application 2: submodular welfare maximization



- k items, k players; each player has a valuation function $f(S) = \min\{|S|, 1\}$, symmetric under \mathbb{S}_k .

Application 2: submodular welfare maximization



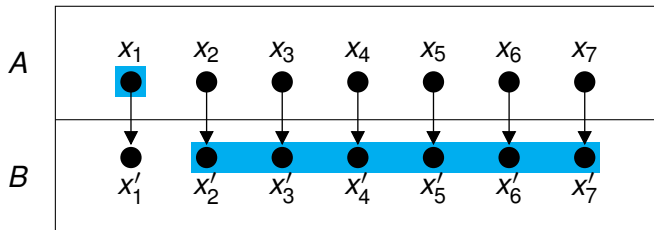
- k items, k players; each player has a valuation function $f(S) = \min\{|S|, 1\}$, symmetric under \mathbb{S}_k .
- Optimum allocates 1 item to each player, $OPT = k$.
- $\overline{OPT} = k \cdot F(\frac{1}{k}, \frac{1}{k}, \dots, \frac{1}{k}) = k(1 - (1 - \frac{1}{k})^k)$.

Application 2: submodular welfare maximization



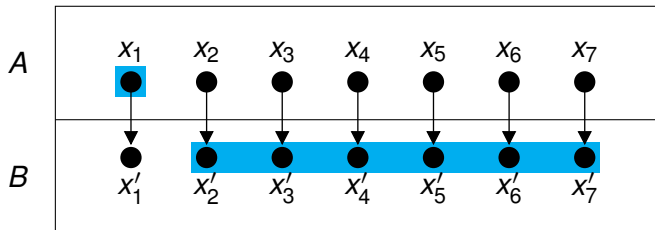
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- \Rightarrow **hardness of $(1 - (1 - 1/k)^k + \epsilon)$ -approximation** for k players [Mirrokni, Schapira, V. '08]
- $(1 - (1 - 1/k)^k)$ -approximation can be achieved [Feldman, Naor, Schwartz '11]

Application 3: non-monotone submodular over bases



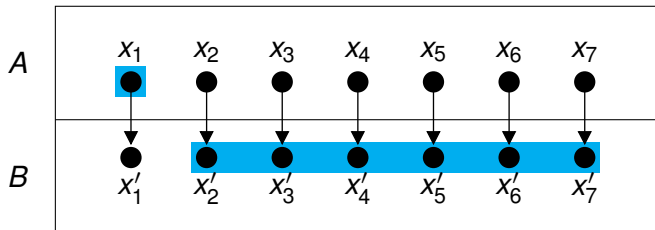
- $X = A \cup B, |A| = |B| = k,$
 $\mathcal{F} = \{S \subseteq X : |S \cap A| = 1, |S \cap B| = k - 1\}.$
- $f(S)$ = number of arcs leaving S ; symmetric under \mathbb{S}_k .

Application 3: non-monotone submodular over bases



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- $OPT = F(1, 0, \dots, 0; 0, 1, \dots, 1) = 1$.
- $\overline{OPT} = F(\frac{1}{k}, \dots, \frac{1}{k}; 1 - \frac{1}{k}, \dots, 1 - \frac{1}{k}) = \frac{1}{k}$.

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- $\overline{OPT} = F(\frac{1}{k}, \dots, \frac{1}{k}; 1 - \frac{1}{k}, \dots, 1 - \frac{1}{k}) = \frac{1}{k}$.
- Refined instances: non-monotone submodular maximization over matroid bases, with base packing number $\nu = k/(k - 1)$.
- Theorem implies that **a better than $\frac{1}{k}$ -approximation is impossible**.

Symmetry gap \leftrightarrow Integrality gap

In fact: [Ene,V.,Wu '12]

- **Symmetry gap** is equal to the **integrality gap** of a related LP.
- In some cases, LP gap gives a matching UG-hardness result.

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- In some cases, LP gap gives a matching UG-hardness result.

Example: both gaps are $2 - 2/k$ for Node-weighted k -way Cut.

- \Rightarrow No $(2 - 2/k + \epsilon)$ -approximation for Node-weighted k -way Cut (assuming UGC).
- \Rightarrow No $(2 - 2/k + \epsilon)$ -approximation for Submodular k -way Partition (in the value oracle model)
- $(2 - 2/k)$ -approximation can be achieved for both.

Hardness results from symmetry gap (in red)

MONOTONE MAXIMIZATION

Constraint	Approximation	Hardness	hardness ref
$ S \leq k$, matroid	$1 - 1/e$	$1 - 1/e$	Nemhauser, Wolsey '78
k -player welfare	$1 - (1 - \frac{1}{k})^k$	$1 - (1 - \frac{1}{k})^k$	Mirrokní, Schapira, V. '08
k matroids	$k + \epsilon$	$\Omega(k/\log k)$	Hazan, Safra, Schwartz '03

NON-MONOTONE MAXIMIZATION

Constraint	Approximation	Hardness	hardness ref
unconstrained	$1/2$	$1/2$	Feige, Mirrokní, V. '07
$ S \leq k$	$1/e$	0.49	Oveis-Gharan, V. '11
matroid	$1/e$	0.48	Oveis-Gharan, V. '11
matroid base	$\frac{1}{2}(1 - \frac{1}{\nu})$	$1 - \frac{1}{\nu}$	V. '09
k matroids	$k + O(1)$	$\Omega(k/\log k)$	Hazan, Safra, Schwartz '03

Where to go next?

Many questions unanswered: optimal approximations, online algorithms, stochastic models, incentive-compatible mechanisms, more powerful oracle models,...

Two meta-questions:

- Is there a maximization problem which is significantly more difficult for monotone submodular functions than for linear functions?
- Can the symmetry gap ratio be always achieved, for problems where the multilinear relaxation can be rounded without loss?