

Reproducing Kernel Hilbert Spaces in Machine Learning

Arthur Gretton, Gatsby Unit, CSML, UCL

October 25, 2017

Course overview (kernels part)

- 1 Construction of RKHS,
- 2 Simple linear algorithms in RKHS (e.g. PCA, ridge regression)
- 3 Kernel methods for hypothesis testing (two-sample, independence)
- 4 Further applications of kernels (feature selection, clustering, ICA)
- 5 Support vector machines for classification, regression
- 6 Theory of reproducing kernel Hilbert spaces (optional, not assessed)

Lecture notes will be put online at:

<http://www.gatsby.ucl.ac.uk/~gretton/rkhscourse.html>

Assessment and locations

The course has the following assessment components:

- Written Examination (2.5 hours, 50%)
- Coursework (50%)

To pass this course, you must pass *both* the exam and the coursework

Course times, locations

Lectures will be at the Ground Floor Lecture Theatre, Sainsbury Wellcome Centre (with a couple of exceptions late in the term)

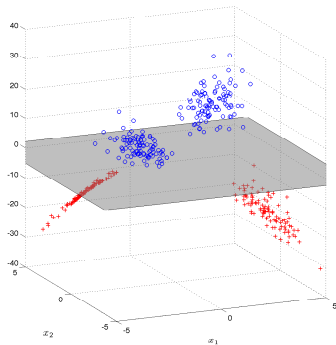
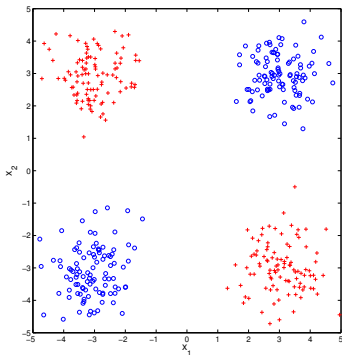
- Kernel lectures are Wednesday, 11:30 -13:00,
- Theory lectures are Friday 14:00 -15:30

(with a couple of exceptions!)

There will be lectures during reading week, due to clash with NIPS conference.

The tutor for the kernels part is Michael Arbel.

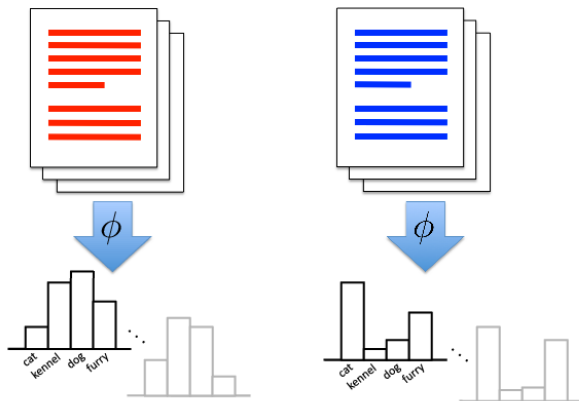
Why kernel methods (1): XOR example



- No linear classifier separates red from blue
- Map points to **higher dimensional feature space**:

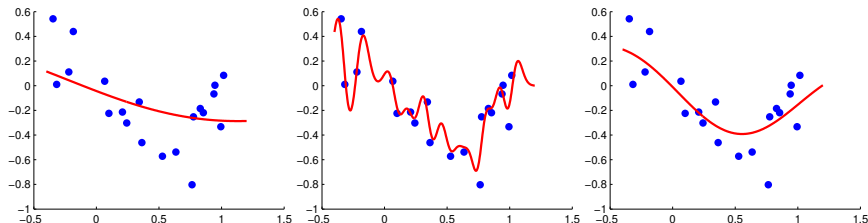
$$\phi(x) = \begin{bmatrix} x_1 & x_2 & x_1 x_2 \end{bmatrix} \in \mathbb{R}^3$$

Why kernel methods (2): document classification



Kernels let us compare **objects** on the basis of **features**

Why kernel methods(3): smoothing



Kernel methods can control **smoothness** and **avoid overfitting/underfitting**.

Basics of reproducing kernel Hilbert spaces

Outline: reproducing kernel Hilbert space

We will describe in order:

- 1 Hilbert space (very simple)
- 2 Kernel (lots of examples: e.g. you can build kernels from simpler kernels)
- 3 Reproducing property

Hilbert space

Definition (Inner product)

Let \mathcal{H} be a vector space over \mathbb{R} . A function $\langle \cdot, \cdot \rangle_{\mathcal{H}} : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}$ is an **inner product** on \mathcal{H} if

- 1 Linear: $\langle \alpha_1 f_1 + \alpha_2 f_2, g \rangle_{\mathcal{H}} = \alpha_1 \langle f_1, g \rangle_{\mathcal{H}} + \alpha_2 \langle f_2, g \rangle_{\mathcal{H}}$
- 2 Symmetric: $\langle f, g \rangle_{\mathcal{H}} = \langle g, f \rangle_{\mathcal{H}}$
- 3 $\langle f, f \rangle_{\mathcal{H}} \geq 0$ and $\langle f, f \rangle_{\mathcal{H}} = 0$ if and only if $f = 0$.

Norm induced by the inner product: $\|f\|_{\mathcal{H}} := \sqrt{\langle f, f \rangle_{\mathcal{H}}}$

Definition (Hilbert space)

Inner product space containing Cauchy sequence limits.

Hilbert space

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Kernel

Definition

Let \mathcal{X} be a non-empty set. A function $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is a **kernel** if there exists an \mathbb{R} -Hilbert space and a **feature** map $\phi : \mathcal{X} \rightarrow \mathcal{H}$ such that $\forall x, x' \in \mathcal{X}$,

$$k(x, x') := \langle \phi(x), \phi(x') \rangle_{\mathcal{H}}.$$

- Almost no conditions on \mathcal{X} (eg, \mathcal{X} itself doesn't need an inner product, eg. documents).
- A single kernel can correspond to several possible feature maps. A trivial example for $\mathcal{X} := \mathbb{R}$:

$$\phi_1(x) = x \quad \text{and} \quad \phi_2(x) = \begin{bmatrix} x/\sqrt{2} \\ x/\sqrt{2} \end{bmatrix}$$

New kernels from old: sums, transformations

Theorem (Sums of kernels are kernels)

Given $\alpha > 0$ and k , k_1 and k_2 all kernels on \mathcal{X} , then αk and $k_1 + k_2$ are kernels on \mathcal{X} .

(Proof via positive definiteness: later!) A difference of kernels may not be a kernel (**why?**)

Theorem (Mappings between spaces)

Let \mathcal{X} and $\tilde{\mathcal{X}}$ be sets, and define a map $A : \mathcal{X} \rightarrow \tilde{\mathcal{X}}$. Define the kernel k on $\tilde{\mathcal{X}}$. Then the kernel $k(A(x), A(x'))$ is a kernel on \mathcal{X} .

Example: $k(x, x') = x^2 (x')^2$.

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New kernels from old: products

Theorem (Products of kernels are kernels)

*Given k_1 on \mathcal{X}_1 and k_2 on \mathcal{X}_2 , then $k_1 \times k_2$ is a kernel on $\mathcal{X}_1 \times \mathcal{X}_2$.
 If $\mathcal{X}_1 = \mathcal{X}_2 = \mathcal{X}$, then $k := k_1 \times k_2$ is a kernel on \mathcal{X} .*

Proof: Main idea only!

k_1 is a kernel between **shapes**,

$$\phi_1(x) = \begin{bmatrix} \mathbb{I}_{\square} \\ \mathbb{I}_{\triangle} \end{bmatrix} \quad \phi_1(\square) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad k_1(\square, \triangle) = 0.$$

k_2 is a kernel between **colors**,

$$\phi_2(x) = \begin{bmatrix} \mathbb{I}_{\bullet} \\ \mathbb{I}_{\circ} \end{bmatrix} \quad \phi_2(\bullet) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad k_2(\bullet, \bullet) = 1.$$

New kernels from old: products

“Natural” feature space for **colored shapes**:

$$\Phi(x) = \begin{bmatrix} \mathbb{I}_{\square} & \mathbb{I}_{\triangle} \\ \mathbb{I}_{\square} & \mathbb{I}_{\triangle} \end{bmatrix} = \begin{bmatrix} \mathbb{I} \\ \mathbb{I} \end{bmatrix} \begin{bmatrix} \mathbb{I}_{\square} & \mathbb{I}_{\triangle} \end{bmatrix} = \phi_2(x)\phi_1^\top(x)$$

Kernel is:

$$\begin{aligned} k(x, x') &= \sum_{i \in \{\color{red}\bullet, \color{blue}\bullet\}} \sum_{j \in \{\square, \triangle\}} \Phi_{ij}(x) \Phi_{ij}(x') = \text{tr} \left(\phi_1(x) \underbrace{\phi_2^\top(x) \phi_2(x')}_{k_2(x, x')} \phi_1^\top(x') \right) \\ &= \text{tr} \left(\underbrace{\phi_1^\top(x') \phi_1(x)}_{k_1(x, x')} k_2(x, x') \right) = k_1(x, x') k_2(x, x') \end{aligned}$$

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Sums and products \implies polynomials

Theorem (Polynomial kernels)

Let $x, x' \in \mathbb{R}^d$ for $d \geq 1$, and let $m \geq 1$ be an integer and $c \geq 0$ be a positive real. Then

$$k(x, x') := (\langle x, x' \rangle + c)^m$$

is a valid kernel.

To prove: expand into a sum (with non-negative scalars) of kernels $\langle x, x' \rangle$ raised to integer powers. These individual terms are valid kernels by the product rule.

Infinite sequences

The kernels we've seen so far are dot products between finitely many features. E.g.

$$k(x, y) = \begin{bmatrix} \sin(x) & x^3 & \log x \end{bmatrix}^\top \begin{bmatrix} \sin(y) & y^3 & \log y \end{bmatrix}$$

where $\phi(x) = \begin{bmatrix} \sin(x) & x^3 & \log x \end{bmatrix}$

Can a kernel be a dot product between **infinitely many features**?

Infinite sequences

Definition

The space ℓ_2 (**square** summable sequences) comprises all sequences $(a_i)_{i \geq 1}$ for which

$$\sum_{i=1}^{\infty} a_i^2 < \infty.$$

Theorem

Given sequence of functions $(\phi_i(x))_{i \geq 1}$ in ℓ_2 where $\phi_i : \mathcal{X} \rightarrow \mathbb{R}$ is the i th coordinate of $\phi(x)$. A well-defined kernel k on \mathcal{X} is

$$k(x, x') := \sum_{i=1}^{\infty} \phi_i(x) \phi_i(x'). \quad (1)$$

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Infinite sequences (proof)

Proof: We just need to check that inner product remains finite.
Norm $\|a\|_{\ell_2}$ associated with inner product (1)

$$\|a\|_{\ell_2} := \sqrt{\sum_{i=1}^{\infty} a_i^2},$$

where a represents sequence with terms a_i . Via Cauchy-Schwarz,

$$\left| \sum_{i=1}^{\infty} \phi_i(x) \phi_i(x') \right| \leq \|\phi_i(x)\|_{\ell_2} \|\phi_i(x')\|_{\ell_2},$$

so the sequence defining the inner product converges for all
 $x, x' \in \mathcal{X}$

Taylor series kernels

Definition (Taylor series kernel)

For $r \in (0, \infty]$, with $a_n \geq 0$ for all $n \geq 0$

$$f(z) = \sum_{n=0}^{\infty} a_n z^n \quad |z| < r, \quad z \in \mathbb{R},$$

Define \mathcal{X} to be the \sqrt{r} -ball in \mathbb{R}^d , so $\|x\| < \sqrt{r}$,

$$k(x, x') = f(\langle x, x' \rangle) = \sum_{n=0}^{\infty} a_n \langle x, x' \rangle^n.$$

Example (Exponential kernel)

$$k(x, x') := \exp(\langle x, x' \rangle).$$

Taylor series kernel (proof)

Proof: Non-negative weighted sums of kernels are kernels, and products of kernels are kernels, so the following is a kernel **if it converges**:

$$k(x, x') = \sum_{n=0}^{\infty} a_n (\langle x, x' \rangle)^n$$

By Cauchy-Schwarz,

$$|\langle x, x' \rangle| \leq \|x\| \|x'\| < r,$$

so the sum converges.

Exponentiated quadratic kernel

Example (Exponentiated quadratic kernel)

This kernel on \mathbb{R}^d is defined as

$$k(x, x') := \exp \left(-\gamma^{-2} \|x - x'\|^2 \right).$$

Proof: an exercise! Use product rule, mapping rule, exponential kernel.

Positive definite functions

If we are given a function of two arguments, $k(x, x')$, how can we determine if it is a valid kernel?

- ① Find a feature map?
 - ① Sometimes this is not obvious (eg if the feature vector is infinite dimensional, like the exponentiated quadratic kernel in the last slide)
 - ② The feature map is not unique.
- ② A direct property of the function: **positive definiteness**.

Positive definite functions

Definition (Positive definite functions)

A symmetric function $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is **positive definite** if $\forall n \geq 1, \forall (a_1, \dots, a_n) \in \mathbb{R}^n, \forall (x_1, \dots, x_n) \in \mathcal{X}^n,$

$$\sum_{i=1}^n \sum_{j=1}^n a_i a_j k(x_i, x_j) \geq 0.$$

The function $k(\cdot, \cdot)$ is **strictly positive definite** if for mutually distinct x_i , the equality holds only when all the a_i are zero.

Kernels are positive definite

Theorem

Let \mathcal{H} be a Hilbert space, \mathcal{X} a non-empty set and $\phi : \mathcal{X} \rightarrow \mathcal{H}$.
Then $\langle \phi(x), \phi(y) \rangle_{\mathcal{H}} =: k(x, y)$ is positive definite.

Proof.

$$\begin{aligned} \sum_{i=1}^n \sum_{j=1}^n a_i a_j k(x_i, x_j) &= \sum_{i=1}^n \sum_{j=1}^n \langle a_i \phi(x_i), a_j \phi(x_j) \rangle_{\mathcal{H}} \\ &= \left\| \sum_{i=1}^n a_i \phi(x_i) \right\|_{\mathcal{H}}^2 \geq 0. \end{aligned}$$

Reverse also holds: positive definite $k(x, x')$ is inner product in \mathcal{H} between $\phi(x)$ and $\phi(x')$. □

Sum of kernels is a kernel

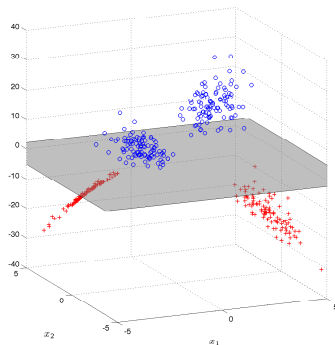
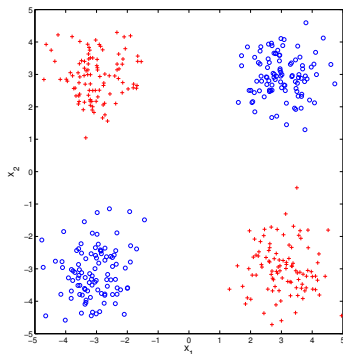
Consider two kernels $k_1(x, x')$ and $k_2(x, x')$. Then

$$\begin{aligned} & \sum_{i=1}^n \sum_{j=1}^n a_i a_j [k_1(x_i, x_j) + k_2(x_i, x_j)] \\ &= \sum_{i=1}^n \sum_{j=1}^n a_i a_j k_1(x_i, x_j) + \sum_{i=1}^n \sum_{j=1}^n a_i a_j k_2(x_i, x_j) \\ &\geq 0 \end{aligned}$$

The reproducing kernel Hilbert space

First example: finite space, polynomial features

Reminder: XOR example:



First example: finite space, polynomial features

Reminder: Feature space from XOR motivating example:

$$\phi : \mathbb{R}^2 \rightarrow \mathbb{R}^3$$
$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \phi(x) = \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix},$$

with kernel

$$k(x, y) = \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix}^\top \begin{bmatrix} y_1 \\ y_2 \\ y_1 y_2 \end{bmatrix}$$

(the standard inner product in \mathbb{R}^3 between features). Denote this feature space by \mathcal{H} .

First example: finite space, polynomial features

Define a **linear function** of the inputs x_1, x_2 , and their product x_1x_2 ,

$$f(x) = f_1x_1 + f_2x_2 + f_3x_1x_2.$$

f in a space of functions mapping from $\mathcal{X} = \mathbb{R}^2$ to \mathbb{R} . Equivalent representation for f ,

$$f(\cdot) = \begin{bmatrix} f_1 & f_2 & f_3 \end{bmatrix}^\top.$$

$f(\cdot)$ refers to the function as an object (here as a **vector** in \mathbb{R}^3)
 $f(x) \in \mathbb{R}$ is function evaluated at a point (a **real number**).

$$f(x) = f(\cdot)^\top \phi(x) = \langle f(\cdot), \phi(x) \rangle_{\mathcal{H}}$$

Evaluation of f at x is an **inner product in feature space** (here standard inner product in \mathbb{R}^3)

\mathcal{H} is a space of functions mapping \mathbb{R}^2 to \mathbb{R} .

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What if we have infinitely many features?

Exponentiated quadratic kernel,

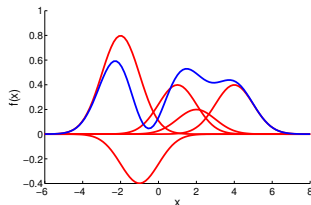
$$k(x, y) = \exp\left(-\frac{\|x - y\|^2}{2\sigma^2}\right) = \sum_{i=1}^{\infty} \phi_i(x)\phi_i(y)$$

$$f(x) = \sum_{i=1}^{\infty} f_i \phi_i(x) \quad \sum_{i=1}^{\infty} f_i^2 < \infty.$$

What if we have infinitely many features?

Function with **exponentiated quadratic kernel**:

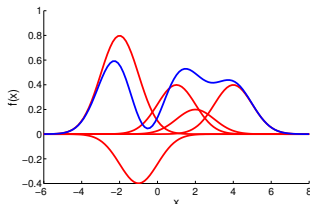
$$\begin{aligned} f(x) &= \sum_{i=1}^m \alpha_i k(x_i, x) \\ &= \sum_{i=1}^m \alpha_i \langle \phi(x_i), \phi(x) \rangle_{\mathcal{H}} \\ &= \left\langle \sum_{i=1}^m \alpha_i \phi(x_i), \phi(x) \right\rangle_{\mathcal{H}} \end{aligned}$$



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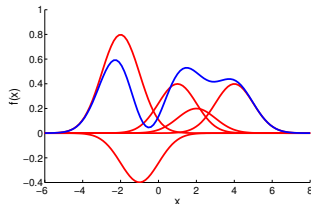
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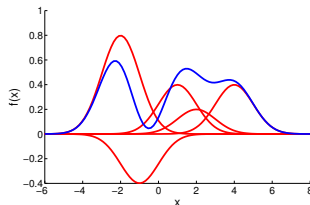
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 \end{aligned}$$



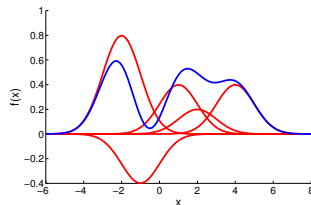
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Possible to write functions of **infinitely many features**!

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Possible to write functions of **infinitely many features**!

The feature map is *also* a function

On previous page,

$$f(x) := \sum_{i=1}^m \alpha_i k(x_i, x) = \langle f(\cdot), \phi(x) \rangle_{\mathcal{H}} \quad \text{where} \quad f(\cdot) = \sum_{i=1}^m \alpha_i \phi(x_i).$$

What if $m = 1$ and $\alpha_1 = 1$?

Then

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....so the feature map is a (very simple) function!

We can write without ambiguity

$$k(x, y) = \langle k(\cdot, x), k(\cdot, y) \rangle_{\mathcal{H}}.$$

The feature map is *also* a function

On previous page,

$$f(x) := \sum_{i=1}^m \alpha_i k(x_i, x) = \langle f(\cdot), \phi(x) \rangle_{\mathcal{H}} \quad \text{where} \quad f(\cdot) = \sum_{i=1}^m \alpha_i \phi_{\ell}(x_i).$$

What if $m = 1$ and $\alpha_1 = 1$?

Then

$$\begin{aligned} f(x) = k(\mathbf{x}_1, \mathbf{x}) &= \left\langle \underbrace{k(\mathbf{x}_1, \cdot)}_{=f(\cdot)=\phi(\mathbf{x}_1)}, \phi(\mathbf{x}) \right\rangle_{\mathcal{H}} \\ &= \langle k(\mathbf{x}, \cdot), \phi(\mathbf{x}_1) \rangle_{\mathcal{H}} \end{aligned}$$

....so the feature map is a (very simple) function!

We can write without ambiguity

$$k(x, y) = \langle k(\cdot, x), k(\cdot, y) \rangle_{\mathcal{H}}.$$

The reproducing property

This example illustrates the two defining features of an RKHS:

- **The reproducing property:**

$$\forall x \in \mathcal{X}, \forall f(\cdot) \in \mathcal{H}, \quad \langle f(\cdot), k(\cdot, x) \rangle_{\mathcal{H}} = f(x)$$

...or use shorter notation $\langle f, \phi(x) \rangle_{\mathcal{H}}$.

- In particular, for any $x, y \in \mathcal{X}$,

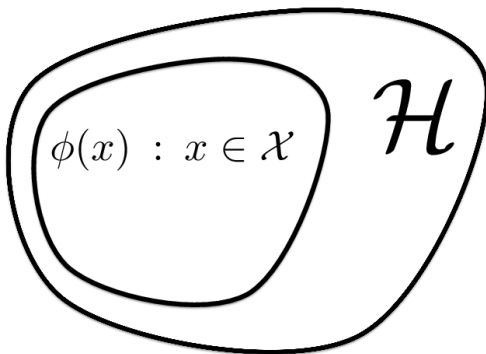
$$k(x, y) = \langle k(\cdot, x), k(\cdot, y) \rangle_{\mathcal{H}}.$$

Note: the feature map of every point is in the feature space:

$$\forall x \in \mathcal{X}, \quad k(\cdot, x) = \phi(x) \in \mathcal{H},$$

First example: finite space, polynomial features

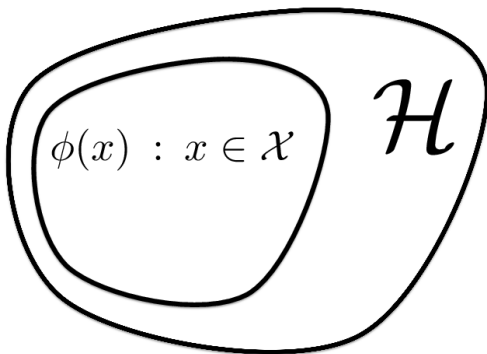
Another, more subtle point: \mathcal{H} can be larger than all $\phi(x)$.



E.g. $f = [1 \ 1 \ -1] \in \mathcal{H}$ cannot be obtained by $\phi(x) = [x_1 \ x_2 \ (x_1 x_2)]$.

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Second (infinite) example: fourier series

Function on the interval $[-\pi, \pi]$ with periodic boundary. **Fourier series:**

$$f(x) = \sum_{\ell=-\infty}^{\infty} \hat{f}_{\ell} \exp(i\ell x) = \sum_{\ell=-\infty}^{\infty} \hat{f}_{\ell} (\cos(\ell x) + i \sin(\ell x)).$$

using the orthonormal basis on $[-\pi, \pi]$,

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \exp(i\ell x) \overline{\exp(imx)} dx = \begin{cases} 1 & \ell = m, \\ 0 & \ell \neq m. \end{cases}$$

Example: “top hat” function,

$$f(x) = \begin{cases} 1 & |x| < T, \\ 0 & T \leq |x| < \pi. \end{cases}$$

$$\hat{f}_{\ell} := \frac{\sin(\ell T)}{\ell\pi} \quad f(x) = \sum_{\ell=0}^{\infty} 2\hat{f}_{\ell} \cos(\ell x).$$

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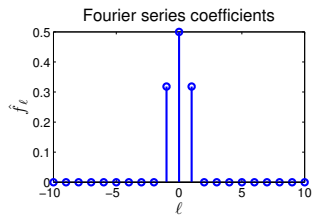
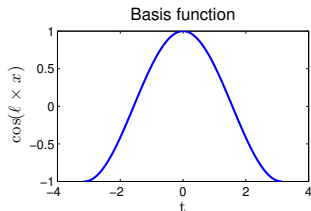
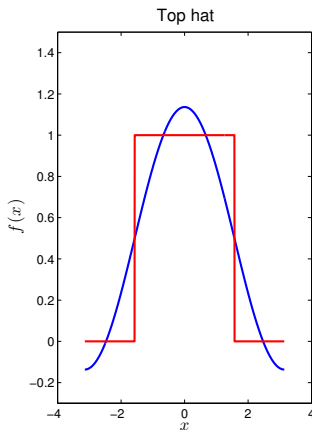
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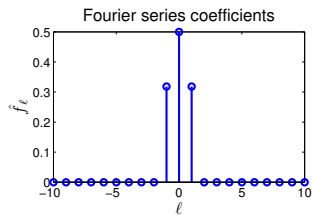
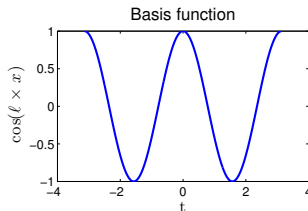
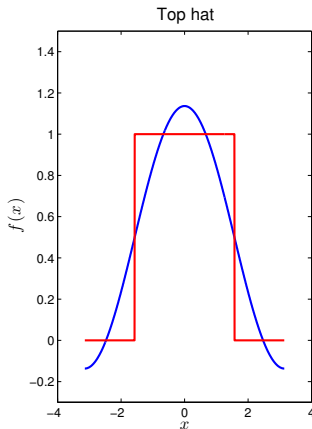
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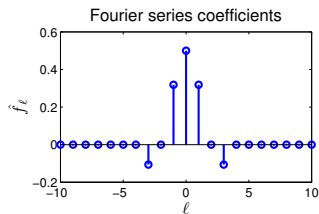
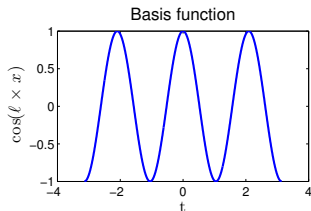
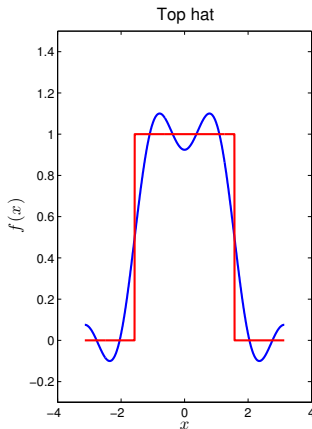
Fourier series for top hat function



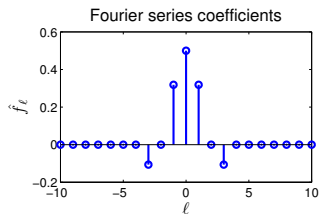
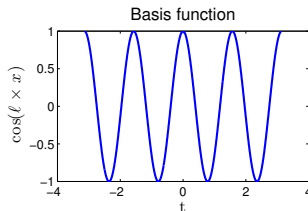
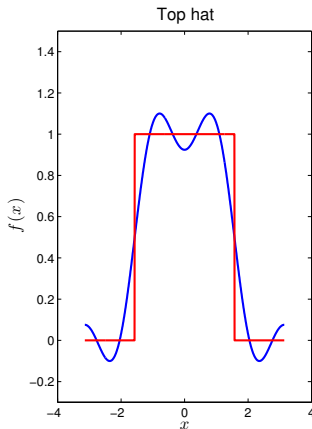
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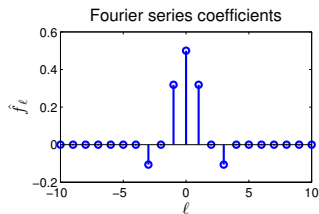
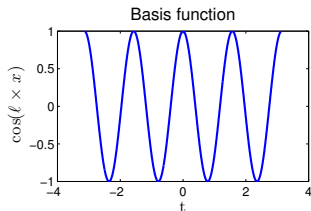
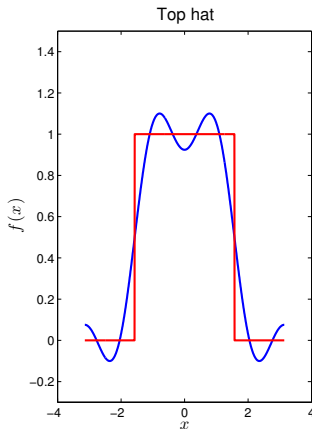
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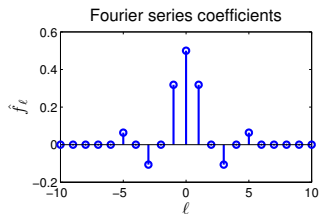
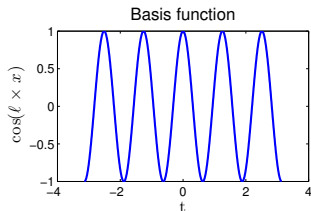
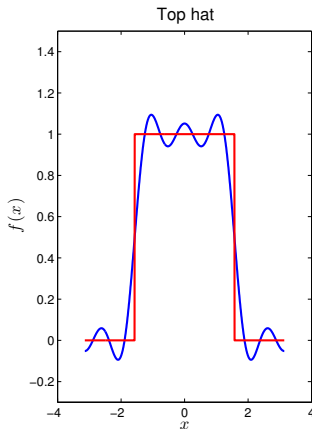
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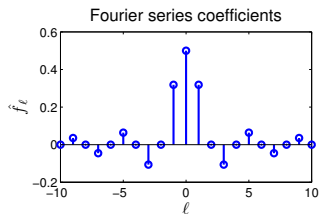
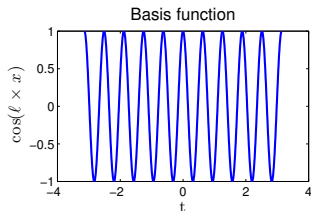
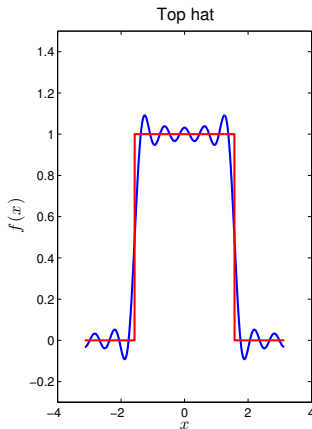
Fourier series for top hat function



Fourier series for top hat function



Fourier series for top hat function



Fourier series for kernel function

Kernel takes a single argument,

$$k(x, y) = k(x - y),$$

Define the Fourier series representation of k

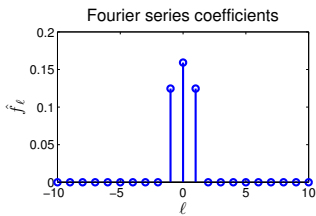
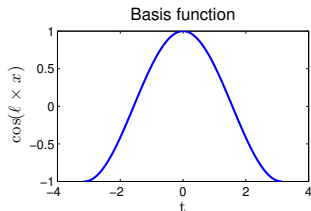
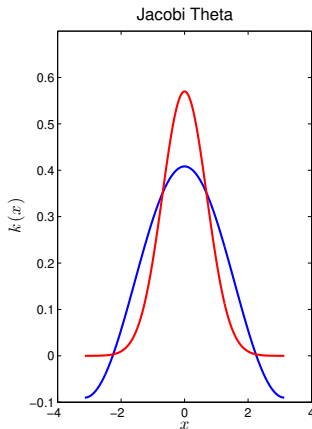
$$k(x) = \sum_{\ell=-\infty}^{\infty} \hat{k}_{\ell} \exp(i\ell x),$$

k and its Fourier transform are **real and symmetric**. For example,

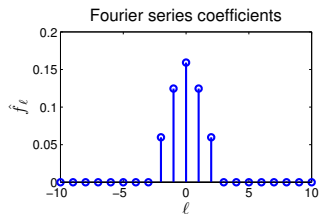
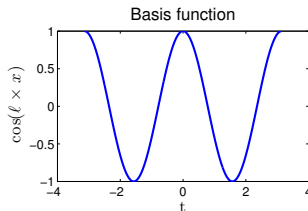
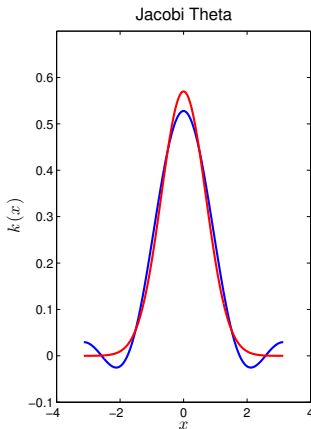
$$k(x) = \frac{1}{2\pi} \vartheta\left(\frac{x}{2\pi}, \frac{i\sigma^2}{2\pi}\right), \quad \hat{k}_{\ell} = \frac{1}{2\pi} \exp\left(\frac{-\sigma^2 \ell^2}{2}\right).$$

ϑ is the Jacobi theta function, close to exponentiated quadratic when σ^2 sufficiently narrower than $[-\pi, \pi]$.

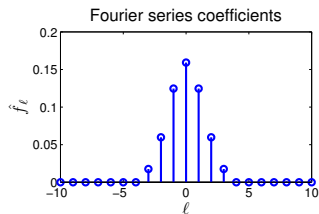
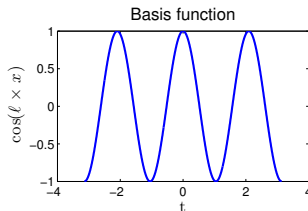
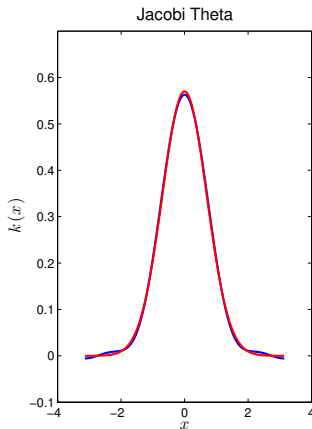
Fourier series for “Gaussian spectrum” kernel



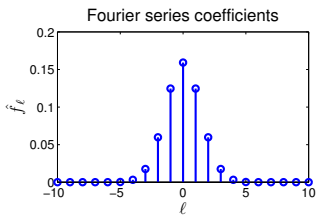
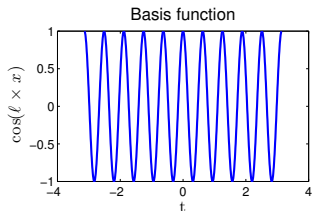
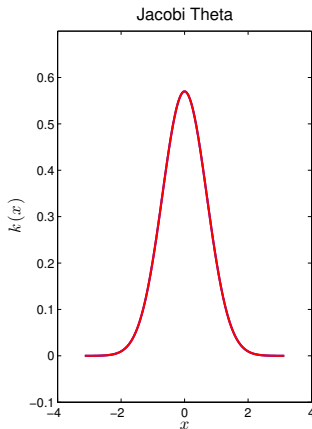
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Fourier series for “Gaussian spectrum” kernel



RKHS via fourier series

Recall **standard dot product** in L_2 :

$$\begin{aligned}\langle f, g \rangle_{L_2} &= \left\langle \sum_{\ell=-\infty}^{\infty} \hat{f}_{\ell} \exp(i\ell x), \sum_{m=-\infty}^{\infty} \overline{\hat{g}_m \exp(imx)} \right\rangle_{L_2} \\ &= \sum_{\ell=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \hat{f}_{\ell} \overline{\hat{g}_m} \langle \exp(i\ell x), \exp(-imx) \rangle_{L_2} \\ &= \sum_{\ell=-\infty}^{\infty} \hat{f}_{\ell} \overline{\hat{g}_{\ell}}.\end{aligned}$$

Define the **dot product** in \mathcal{H} to have a *roughness penalty*,

$$\langle f, g \rangle_{\mathcal{H}} = \sum_{\ell=-\infty}^{\infty} \frac{\hat{f}_{\ell} \overline{\hat{g}_{\ell}}}{\hat{k}_{\ell}}.$$

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Roughness penalty explained

The squared norm of a function f in \mathcal{H} enforces smoothness:

$$\|f\|_{\mathcal{H}}^2 = \langle f, f \rangle_{\mathcal{H}} = \sum_{l=-\infty}^{\infty} \frac{\hat{f}_l \bar{\hat{f}}_l}{\hat{k}_l} = \sum_{l=-\infty}^{\infty} \frac{|\hat{f}_l|^2}{\hat{k}_l}.$$

If \hat{k}_l decays fast, then so must \hat{f}_l if we want $\|f\|_{\mathcal{H}}^2 < \infty$.

Recall $f(x) = \sum_{l=-\infty}^{\infty} \hat{f}_l (\cos(lx) + i \sin(lx))$.

Question: is the top hat function in the “Gaussian spectrum” RKHS?

Warning: need stronger conditions on kernel than L_2 convergence: Mercer’s theorem (later).

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Feature map and reproducing property

Reproducing property: define a function

$$g(x) := k(x - z) = \sum_{\ell=-\infty}^{\infty} \exp(i\ell x) \underbrace{\hat{k}_{\ell} \exp(-i\ell z)}_{\hat{g}_{\ell}}$$

Then for a function $f(\cdot) \in \mathcal{H}$,

$$\begin{aligned} \langle f(\cdot), k(\cdot, z) \rangle_{\mathcal{H}} &= \langle f(\cdot), g(\cdot) \rangle_{\mathcal{H}} \\ &= \sum_{\ell=-\infty}^{\infty} \frac{\hat{f}_{\ell} \left(\overline{\hat{k}_{\ell} \exp(-i\ell z)} \right)}{\hat{k}_{\ell}} \\ &= \sum_{\ell=-\infty}^{\infty} \hat{f}_{\ell} \exp(i\ell z) = f(z). \end{aligned}$$

Feature map and reproducing property

Reproducing property for the kernel:

Recall kernel definition:

$$k(x - y) = \sum_{\ell=-\infty}^{\infty} \hat{k}_{\ell} \exp(i\ell(x - y)) = \sum_{\ell=-\infty}^{\infty} \hat{k}_{\ell} \exp(i\ell x) \exp(-i\ell y)$$

Define two functions

$$\begin{aligned} f(x) &:= k(x - y) = \sum_{\ell=-\infty}^{\infty} \hat{k}_{\ell} \exp(i\ell(x - y)) \\ &= \sum_{\ell=-\infty}^{\infty} \exp(i\ell x) \underbrace{\hat{k}_{\ell} \exp(-i\ell y)}_{\hat{f}_{\ell}} \\ g(x) &:= k(x - z) = \sum_{\ell=-\infty}^{\infty} \exp(i\ell x) \underbrace{\hat{k}_{\ell} \exp(-i\ell z)}_{\hat{g}_{\ell}} \end{aligned}$$

Feature map and reproducing property

Check the **reproducing property**:

$$\begin{aligned}
 \langle k(\cdot, y), k(\cdot, z) \rangle_{\mathcal{H}} &= \langle f(\cdot), g(\cdot) \rangle_{\mathcal{H}} \\
 &= \sum_{\ell=-\infty}^{\infty} \frac{\hat{f}_{\ell} \overline{\hat{g}_{\ell}}}{\hat{k}_{\ell}} \\
 &= \sum_{\ell=-\infty}^{\infty} \frac{\left(\hat{k}_{\ell} \exp(-\imath \ell y) \right) \left(\overline{\hat{k}_{\ell} \exp(-\imath \ell z)} \right)}{\hat{k}_{\ell}} \\
 &= \sum_{\ell=-\infty}^{\infty} \hat{k}_{\ell} \exp(\imath \ell (z - y)) = k(z - y).
 \end{aligned}$$

Link back to original RKHS definition

Original form of a function in the RKHS was (detail: sum now from $-\infty$ to ∞ , complex conjugate)

$$f(x) = \sum_{\ell=-\infty}^{\infty} f_{\ell} \overline{\phi_{\ell}(x)} = \langle f(\cdot), \phi(x) \rangle_{\mathcal{H}}.$$

We've defined the RKHS dot product as

$$\langle f, g \rangle_{\mathcal{H}} = \sum_{l=-\infty}^{\infty} \frac{\hat{f}_l \overline{\hat{g}_l}}{\hat{k}_l} \qquad \langle f(\cdot), k(\cdot, z) \rangle_{\mathcal{H}} = \sum_{\ell=-\infty}^{\infty} \frac{\hat{f}_{\ell} \left(\overline{\hat{k}_{\ell} \exp(-\imath \ell z)} \right)}{\hat{k}_{\ell}}$$

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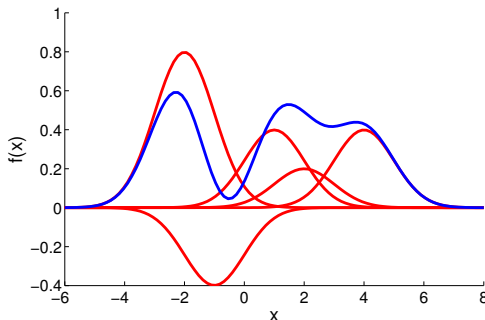
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By inspection

$$f_{\ell} = \hat{f}_{\ell} / \sqrt{\hat{k}_{\ell}} \quad \phi_{\ell}(x) = \sqrt{\hat{k}_{\ell}} \exp(-\imath \ell x).$$

Third example: infinite feature space on \mathbb{R}

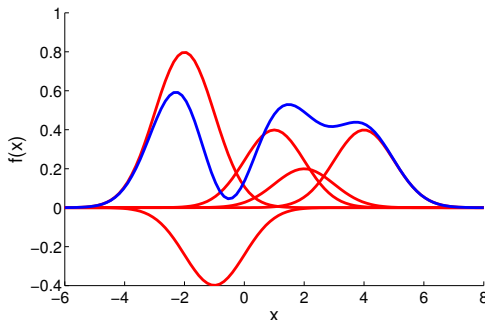
Reproducing property for function with exponentiated quadratic kernel on \mathbb{R} : $f(x) := \sum_{i=1}^m \alpha_i k(x_i, x) = \langle \sum_{i=1}^m \alpha_i \phi(x_i), \phi(x) \rangle_{\mathcal{H}}$.



- What do the features $\phi(x)$ look like (there are infinitely many of them!)
- What do these features have to do with smoothness?

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Third example: infinite feature space on \mathbb{R}

Define a probability measure on $\mathcal{X} := \mathbb{R}$. We'll use the Gaussian density,

$$d\mu(x) = \frac{1}{\sqrt{2\pi}} \exp(-x^2) dx$$

Define the eigenexpansion of $k(x, x')$ wrt this measure:

$$\lambda_i e_i(x) = \int k(x, x') e_i(x') d\mu(x'), \quad \int_{L_2(\mu)} e_i(x) e_j(x) d\mu(x) = \begin{cases} 1 & i = j \\ 0 & i \neq j. \end{cases}$$

We can write

$$k(x, x') = \sum_{\ell=1}^{\infty} \lambda_{\ell} e_{\ell}(x) e_{\ell}(x'),$$

which converges in $L_2(\mu)$.

Warning: again, need stronger conditions on kernel than L_2 convergence.

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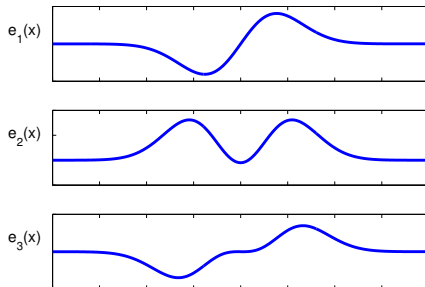
Third example: infinite feature space on \mathbb{R}

Exponentiated quadratic kernel, $k(x, y) = \exp\left(-\frac{\|x-y\|^2}{2\sigma^2}\right)$, and Gaussian μ , yield

$$\lambda_k \propto b^k \quad b < 1$$

$$e_k(x) \propto \exp(-(c-a)x^2) H_k(x\sqrt{2c}),$$

a, b, c are functions of σ , and H_k is k th order Hermite polynomial.



$$k(x, x') = \sum_{i=1}^{\infty} \lambda_i e_i(x) e_i(x')$$

Result from Rasmussen and Williams (2006, Section 4.3)

Third example: infinite feature space

Reminder: for two functions f, g in $L_2(\mu)$,

$$f(x) = \sum_{\ell=1}^{\infty} \hat{f}_{\ell} e_{\ell}(x) \quad g(x) = \sum_{\ell=1}^{\infty} \hat{g}_{\ell} e_{\ell}(x),$$

dot product is

$$\begin{aligned} \langle f, g \rangle_{L_2(\mu)} &= \left\langle \sum_{\ell=1}^{\infty} \hat{f}_{\ell} e_{\ell}(x), \sum_{\ell=1}^{\infty} \hat{g}_{\ell} e_{\ell}(x) \right\rangle_{L_2(\mu)} \\ &= \sum_{\ell=1}^{\infty} \hat{f}_{\ell} \hat{g}_{\ell}. \end{aligned}$$

Define the dot product in \mathcal{H} to have a *roughness penalty*,

$$\langle f, g \rangle_{\mathcal{H}} = \sum_{\ell=1}^{\infty} \frac{\hat{f}_{\ell} \hat{g}_{\ell}}{\lambda_{\ell}} \quad \|f\|_{\mathcal{H}}^2 = \sum_{\ell=1}^{\infty} \frac{\hat{f}_{\ell}^2}{\lambda_{\ell}}.$$

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Link back to the original RKHS definition

Original form of a function in the RKHS was

$$f(x) = \sum_{\ell=1}^{\infty} f_{\ell} \phi_{\ell}(x) = \langle f(\cdot), \phi(x) \rangle_{\mathcal{H}}$$

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$$\langle f, g \rangle_{\mathcal{H}} = \sum_{l=1}^{\infty} \frac{\hat{f}_l \hat{g}_l}{\lambda_l} \quad g(z) = k(x, z) = \sum_{\ell=1}^{\infty} \underbrace{\lambda_{\ell} e_{\ell}(z)}_{\hat{g}_{\ell}} e_{\ell}(x)$$

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By inspection

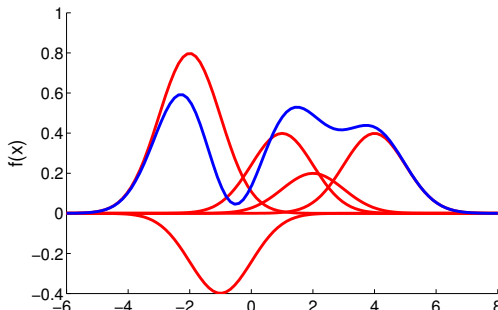
$$f_{\ell} = \hat{f}_{\ell} / \sqrt{\lambda_{\ell}} \qquad \phi_{\ell}(x) = \sqrt{\lambda_{\ell}} e_{\ell}(x).$$

Writing RKHS functions without explicit features

Example RKHS function from earlier:

$$f(x) := \sum_{i=1}^m \alpha_i k(x_i, x) = \sum_{i=1}^m \alpha_i \left[\sum_{j=1}^{\infty} \lambda_j e_j(x_i) e_j(x) \right] = \sum_{j=1}^{\infty} f_j \underbrace{\left[\sqrt{\lambda_j} e_j(x) \right]}_{\phi_j(x)}$$

where $f_j = \sum_{i=1}^m \alpha_i \sqrt{\lambda_j} e_j(x_i)$.



NOTE that this
 enforces
 smoothing:

λ_j decay as e_j
 become rougher,
 f_j decay since
 $\sum_j f_j^2 < \infty$.

Explicit feature space as element of ℓ_2

Does this work? Is $f(x) < \infty$ despite the infinite feature space?

Finiteness of $f(x) = \langle f, \phi(x) \rangle_{\mathcal{H}}$ obtained by Cauchy-Schwarz,

$$\begin{aligned} |\langle f, \phi(x) \rangle_{\mathcal{H}}| &= \left| \sum_{i=1}^{\infty} f_i \sqrt{\lambda_i} e_i(x) \right| \leq \left(\sum_{i=1}^{\infty} f_i^2 \right)^{1/2} \left(\sum_{i=1}^{\infty} \lambda_i e_i^2(x) \right)^{1/2} \\ &= \|f\|_{\ell_2} \sqrt{k(x, x)}. \end{aligned}$$

and by triangle inequality,

$$\begin{aligned} \|f\|_{\ell_2} &= \left\| \sum_{i=1}^m \alpha_i \phi(x_i) \right\| \\ &\leq \sum_{i=1}^m |\alpha_i| \|\phi(x_i)\| < \infty. \end{aligned}$$

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Some reproducing kernel Hilbert space theory

Reproducing kernel Hilbert space (1)

Definition

\mathcal{H} a Hilbert space of \mathbb{R} -valued functions on non-empty set \mathcal{X} . A function $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is a **reproducing kernel** of \mathcal{H} , and \mathcal{H} is a **reproducing kernel Hilbert space**, if

- $\forall x \in \mathcal{X}, k(\cdot, x) \in \mathcal{H}$,
- $\forall x \in \mathcal{X}, \forall f \in \mathcal{H}, \langle f(\cdot), k(\cdot, x) \rangle_{\mathcal{H}} = f(x)$ (the reproducing property).

In particular, for any $x, y \in \mathcal{X}$,

$$k(x, y) = \langle k(\cdot, x), k(\cdot, y) \rangle_{\mathcal{H}}. \quad (2)$$

Original definition: kernel an inner product between feature maps.
Then $\phi(x) = k(\cdot, x)$ a valid feature map.

Reproducing kernel Hilbert space (2)

Another RKHS definition:

Define δ_x to be the operator of evaluation at x , i.e.

$$\delta_x f = f(x) \quad \forall f \in \mathcal{H}, x \in \mathcal{X}.$$

Definition (Reproducing kernel Hilbert space)

\mathcal{H} is an RKHS if the evaluation operator δ_x is **bounded**: $\forall x \in \mathcal{X}$ there exists $\lambda_x \geq 0$ such that for all $f \in \mathcal{H}$,

$$|f(x)| = |\delta_x f| \leq \lambda_x \|f\|_{\mathcal{H}}$$

\implies two functions identical in RKHS norm agree at every point:

$$|f(x) - g(x)| = |\delta_x(f - g)| \leq \lambda_x \|f - g\|_{\mathcal{H}} \quad \forall f, g \in \mathcal{H}.$$

RKHS definitions equivalent

Theorem (Reproducing kernel equivalent to bounded δ_x)

\mathcal{H} is a reproducing kernel Hilbert space (i.e., its evaluation operators δ_x are bounded linear operators), if and only if \mathcal{H} has a reproducing kernel.

Proof: If \mathcal{H} has a reproducing kernel $\implies \delta_x$ bounded

$$\begin{aligned} |\delta_x[f]| &= |f(x)| \\ &= |\langle f, k(\cdot, x) \rangle_{\mathcal{H}}| \\ &\leq \|k(\cdot, x)\|_{\mathcal{H}} \|f\|_{\mathcal{H}} \\ &= \langle k(\cdot, x), k(\cdot, x) \rangle_{\mathcal{H}}^{1/2} \|f\|_{\mathcal{H}} \\ &= k(x, x)^{1/2} \|f\|_{\mathcal{H}} \end{aligned}$$

Cauchy-Schwarz in 3rd line . Consequently, $\delta_x : \mathcal{F} \rightarrow \mathbb{R}$ bounded with $\lambda_x = k(x, x)^{1/2}$ (**other direction**: Riesz theorem).

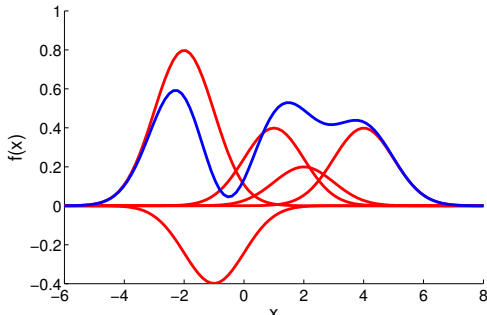
Moore-Aronszajn

Theorem (Moore-Aronszajn)

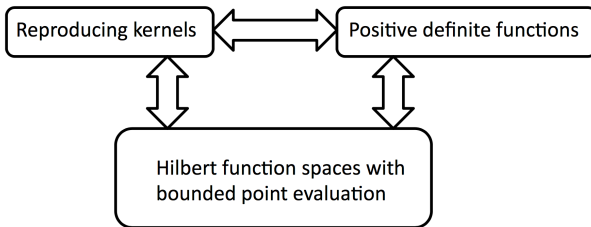
Every positive definite kernel k uniquely associated with RKHS \mathcal{H} .

Recall feature map is *not* unique (as we saw earlier): **only kernel is**.
Example RKHS function, exponentiated quadratic kernel:

$$f(\cdot) := \sum_{i=1}^m \alpha_i k(x_i, \cdot).$$



Correspondence



Simple Kernel Algorithms

Distance between means (1)

Sample $(x_i)_{i=1}^m$ from p and $(y_i)_{i=1}^m$ from q . What is the distance between their means *in feature space*?

$$\begin{aligned}
 & \left\| \frac{1}{m} \sum_{i=1}^m \phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(y_j) \right\|_{\mathcal{H}}^2 \\
 &= \left\langle \frac{1}{m} \sum_{i=1}^m \phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(y_j), \frac{1}{m} \sum_{i=1}^m \phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(y_j) \right\rangle_{\mathcal{H}} \\
 &= \frac{1}{m^2} \left\langle \sum_{i=1}^m \phi(x_i), \sum_{i=1}^m \phi(x_i) \right\rangle + \dots \\
 &= \frac{1}{m^2} \sum_{i=1}^m \sum_{j=1}^m k(x_i, x_j) + \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n k(y_i, y_j) - \frac{2}{mn} \sum_{i=1}^m \sum_{j=1}^n k(x_i, y_j).
 \end{aligned}$$

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 &= \frac{1}{m^2} \left\langle \sum_{i=1}^m \phi(x_i), \sum_{i=1}^m \phi(x_i) \right\rangle + \dots \\
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 \end{aligned}$$

Distance between means (2)

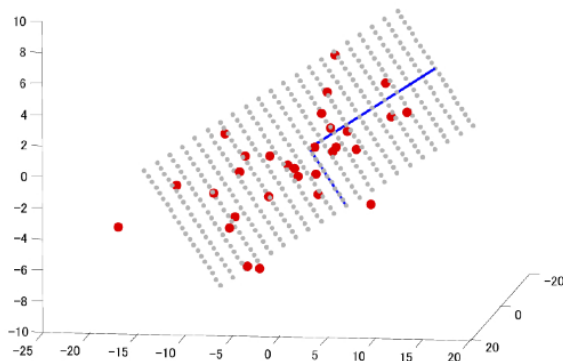
Sample $(x_i)_{i=1}^m$ from p and $(y_i)_{i=1}^m$ from q . What is the distance between their means *in feature space*?

$$\left\| \frac{1}{m} \sum_{i=1}^m \phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(y_j) \right\|_{\mathcal{H}}^2$$

- When $\phi(x) = x$, distinguish means. When $\phi(x) = [x \ x^2]$, distinguish means and variances.
- There are kernels that can distinguish *any* two distributions

PCA (1)

Goal of classical PCA: to find a d -dimensional subspace of a higher dimensional space (D -dimensional, \mathbb{R}^D) containing the directions of maximum variance.



(Figure by K. Fukumizu)

Application of kPCA: image denoising

What is the purpose of kernel PCA?

We consider the problem of **denoising** hand-written digits.

We are given a noisy digit x^* .

$$P_d \phi(x^*) = P_{f_1} \phi(x^*) + \dots + P_{f_d} \phi(x^*)$$

is the projection of $\phi(x^*)$ onto one of the first d eigenvectors $\{f_\ell\}_{\ell=1}^d$ from kernel PCA (these are orthogonal).

Define the nearest point $y^* \in \mathcal{X}$ to this feature space projection as

$$y^* = \arg \min_{y \in \mathcal{X}} \|\phi(y) - P_d \phi(x^*)\|_{\mathcal{H}}^2.$$

In many cases, not possible to reduce the squared error to zero, as no single y^* corresponds to exact solution.

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Application of kPCA: image denoising

Projection onto PCA subspace for denoising. **kPCA**: data may not be Gaussian distributed, but can lie in a submanifold in input space.

USPS hand-written digits data:

7191 images of hand-written digits of 16×16 pixels.



Sample of original images (not used for experiments)



Sample of noisy images



Sample of denoised images (linear PCA)



Sample of denoised images (**kernel PCA, Gaussian kernel**)

Generated by Matlab Stprtool (by V. Franc). (Figure: K.

What is PCA? (reminder)

First principal component (max. variance)

$$\begin{aligned} u_1 &= \arg \max_{\|u\| \leq 1} \frac{1}{n} \sum_{i=1}^n \left(u^\top \left(x_i - \frac{1}{n} \sum_{j=1}^n x_j \right) \right)^2 \\ &= \arg \max_{\|u\| \leq 1} u^\top C u \end{aligned}$$

where

$$C = \frac{1}{n} \sum_{i=1}^n \left(x_i - \frac{1}{n} \sum_{j=1}^n x_j \right) \left(x_i - \frac{1}{n} \sum_{j=1}^n x_j \right)^\top = \frac{1}{n} X H X^\top,$$

$X = \begin{bmatrix} x_1 & \dots & x_n \end{bmatrix}$, $H = I - n^{-1} \mathbf{1}_{n \times n}$, $\mathbf{1}_{n \times n}$ a matrix of ones.

Definition (Principal components)

The pairs (λ_i, u_i) are the eigensystem of $n\lambda_i u_i = C u_i$.

PCA in feature space

Kernel version, first principal component:

$$\begin{aligned} f_1 &= \arg \max_{\|f\|_{\mathcal{H}} \leq 1} \frac{1}{n} \sum_{i=1}^n \left(\left\langle f, \phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(x_j) \right\rangle_{\mathcal{H}} \right)^2 \\ &= \arg \max_{\|f\|_{\mathcal{H}} \leq 1} \text{var}(f). \end{aligned}$$

We can write

$$f = \sum_{i=1}^n \alpha_i \left(\phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(x_j) \right) = \sum_{i=1}^n \alpha_i \tilde{\phi}(x_i),$$

since any component orthogonal to the span of $\tilde{\phi}(x_i) := \phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(x_j)$ vanishes.

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How to solve kernel PCA

We can also define an infinite dimensional analog of the covariance:

$$\begin{aligned} C &= \frac{1}{n} \sum_{i=1}^n \left(\phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(x_j) \right) \otimes \left(\phi(x_i) - \frac{1}{n} \sum_{j=1}^n \phi(x_j) \right), \\ &= \frac{1}{n} \sum_{i=1}^n \tilde{\phi}(x_i) \otimes \tilde{\phi}(x_i) \end{aligned}$$

where we use the definition

$$(a \otimes b)c := \langle b, c \rangle_{\mathcal{H}} a \quad (3)$$

this is analogous to the case of finite dimensional vectors,
 $(ab^{\top})c = (b^{\top}c)a$.

How to solve kernel PCA (1)

Eigenfunctions of kernel covariance:

$$\begin{aligned}
 f_\ell \lambda_\ell &= C f_\ell \\
 &= \left(\frac{1}{n} \sum_{i=1}^n \tilde{\phi}(x_i) \otimes \tilde{\phi}(x_i) \right) f_\ell \\
 &= \frac{1}{n} \sum_{i=1}^n \tilde{\phi}(x_i) \left\langle \tilde{\phi}(x_i), \sum_{j=1}^n \alpha_{\ell j} \tilde{\phi}(x_j) \right\rangle_{\mathcal{H}} \\
 &= \frac{1}{n} \sum_{i=1}^n \tilde{\phi}(x_i) \left(\sum_{j=1}^n \alpha_{\ell j} \tilde{k}(x_i, x_j) \right)
 \end{aligned}$$

$\tilde{k}(x_i, x_j)$ is the (i, j) th entry of the matrix $\tilde{K} := HKH$ (exercise!).

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$\tilde{k}(x_i, x_j)$ is the (i, j) th entry of the matrix $\tilde{K} := HKH$ (exercise!).

How to solve kernel PCA (2)

We can now project both sides of

$$f_\ell \lambda_\ell = C f_\ell$$

onto all of the $\tilde{\phi}(x_q)$:

$$\langle \tilde{\phi}(x_q), \text{LHS} \rangle_{\mathcal{H}} = \lambda_\ell \langle \tilde{\phi}(x_q), f_\ell \rangle_{\mathcal{H}} = \lambda_\ell \sum_{i=1}^n \alpha_{\ell i} \tilde{k}(x_q, x_i) \quad \forall q \in \{1 \dots n\}$$

$$\langle \tilde{\phi}(x_q), \text{RHS} \rangle_{\mathcal{H}} = \langle \tilde{\phi}(x_q), C f_\ell \rangle_{\mathcal{H}} = \frac{1}{n} \sum_{i=1}^n \tilde{k}(x_q, x_i) \left(\sum_{j=1}^n \alpha_{\ell j} \tilde{k}(x_i, x_j) \right)$$

Writing this as a matrix equation,

$$n \lambda_\ell \tilde{K} \alpha_\ell = \tilde{K}^2 \alpha_\ell \quad n \lambda_\ell \alpha_\ell = \tilde{K} \alpha_\ell.$$

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$$n \lambda_\ell \tilde{K} \alpha_\ell = \tilde{K}^2 \alpha_\ell \quad n \lambda_\ell \alpha_\ell = \tilde{K} \alpha_\ell.$$

Eigenfunctions f have unit norm in feature space?

$$\begin{aligned}\|f\|_{\mathcal{H}}^2 &= \left\langle \sum_{i=1}^n \alpha_i \tilde{\phi}(x_i), \sum_{i=1}^n \alpha_i \tilde{\phi}(x_i) \right\rangle_{\mathcal{H}} \\&= \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j \left\langle \tilde{\phi}(x_i), \tilde{\phi}(x_j) \right\rangle_{\mathcal{H}} \\&= \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j \tilde{k}(x_i, x_j) \\&= \alpha^\top \tilde{K} \alpha = n\lambda \alpha^\top \alpha = n\lambda \|\alpha\|^2.\end{aligned}$$

Thus $\alpha \leftarrow \alpha / \sqrt{n\lambda}$ (assumed: original eigenvector solution has $\|\alpha\| = 1$)

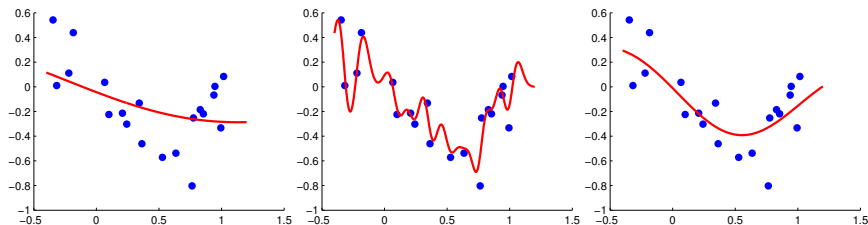
Projection onto kernel PC

How do you project a new point x^* onto the principal component f ?

Assuming $\|f\|_{\mathcal{H}} = 1$, the projection is

$$\begin{aligned} P_f \phi(x^*) &= \langle \phi(x^*), f \rangle_{\mathcal{H}} f \\ &= \sum_{i=1}^n \alpha_i \left(\sum_{j=1}^n \alpha_j \langle \phi(x^*), \tilde{\phi}(x_j) \rangle_{\mathcal{H}} \right) \tilde{\phi}(x_j) \\ &= \sum_{i=1}^n \alpha_i \left(\sum_{j=1}^n \alpha_j \left(k(x^*, x_j) - \frac{1}{n} \sum_{\ell=1}^n k(x^*, x_{\ell}) \right) \right) \tilde{\phi}(x_j). \end{aligned}$$

Kernel ridge regression



Very simple to implement, works well when no outliers.

Ridge regression: case of \mathbb{R}^D

We are given n training points in \mathbb{R}^D :

$$X = \begin{bmatrix} x_1 & \dots & x_n \end{bmatrix} \in \mathbb{R}^{D \times n} \quad y := \begin{bmatrix} y_1 & \dots & y_n \end{bmatrix}^\top$$

Define some $\lambda > 0$. Our goal is:

$$\begin{aligned} a^* &= \arg \min_{a \in \mathbb{R}^D} \left(\sum_{i=1}^n (y_i - x_i^\top a)^2 + \lambda \|a\|^2 \right) \\ &= \arg \min_{a \in \mathbb{R}^D} \left(\|y - X^\top a\|^2 + \lambda \|a\|^2 \right), \end{aligned}$$

The second term $\lambda \|a\|^2$ is chosen to avoid problems in high dimensional spaces (see below).

Ridge regression: solution (1)

Expanding out the above term, we get

$$\begin{aligned}\|y - X^\top a\|^2 + \lambda \|a\|^2 &= y^\top y - 2y^\top Xa + a^\top XX^\top a + \lambda a^\top a \\ &= y^\top y - 2y^\top X^\top a + a^\top (XX^\top + \lambda I) a = (*)\end{aligned}$$

- Define $b = (XX^\top + \lambda I)^{1/2} a$
- Square root defined since matrix positive definite
- XX^\top may not be invertible eg when $D > n$, adding λI means we can write $a = (XX^\top + \lambda I)^{-1/2} b$.

Ridge regression: solution (2)

Complete the square:

$$\begin{aligned}
 (*) &= y^\top y - 2y^\top X^\top (XX^\top + \lambda I)^{-1/2} b + b^\top b \\
 &= y^\top y + \left\| (XX^\top + \lambda I)^{-1/2} Xy - b \right\|^2 - \left\| y^\top X^\top (XX^\top + \lambda I)^{-1/2} \right\|^2
 \end{aligned}$$

This is minimized when

$$\begin{aligned}
 b^* &= (XX^\top + \lambda I)^{-1/2} Xy \quad \text{or} \\
 a^* &= (XX^\top + \lambda I)^{-1} Xy,
 \end{aligned}$$

which is the classic regularized least squares solution.

Ridge regression solution as sum of training points (1)

We may rewrite this expression in a way that is more informative, $a^* = \sum_{i=1}^n \alpha_i^* x_i$.

The solution is a linear combination of training points x_i .

Proof: Assume $D > n$ (in feature space case D can be very large or even infinite).

Perform an SVD on X , i.e.

$$X = USV^T,$$

where

$$U = [u_1 \quad \dots \quad u_D] \quad S = \begin{bmatrix} \tilde{S} & 0 \\ 0 & 0 \end{bmatrix} \quad V = [\tilde{V} \quad 0].$$

Here U is $D \times D$ and $U^T U = U U^T = I_D$ (subscript denotes unit matrix size), S is $D \times D$, where \tilde{S} has n non-zero entries, and V is $n \times D$, where $\tilde{V}^T \tilde{V} = \tilde{V} \tilde{V}^T = I_n$.

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Ridge regression solution as sum of training points (2)

Proof (continued):

$$\begin{aligned} a^* &= (XX^\top + \lambda I_D)^{-1} Xy \\ &= (US^2U^\top + \lambda I_D)^{-1} USV^\top y \\ &= U(S^2 + \lambda I_D)^{-1} U^\top USV^\top y \\ &= U(S^2 + \lambda I_D)^{-1} SV^\top y \\ &= US(S^2 + \lambda I_D)^{-1} V^\top y \\ &= \underbrace{USV^\top V}_{(a)} (S^2 + \lambda I_D)^{-1} V^\top y \\ &\stackrel{(b)}{=} X(X^\top X + \lambda I_n)^{-1} y \end{aligned} \tag{4}$$

Ridge regression solution as sum of training points (3)

Proof (continued):

(a): both S and $V^\top V$ are non-zero in same sized top-left block, and $V^\top V$ is I_n in that block.

(b): since

$$\begin{aligned}
 & V (S^2 + \lambda I_D)^{-1} V^\top \\
 &= \begin{bmatrix} \tilde{V} & 0 \end{bmatrix} \begin{bmatrix} (\tilde{S}^2 + \lambda I_n)^{-1} & 0 \\ 0 & (\lambda I_{D-n})^{-1} \end{bmatrix} \begin{bmatrix} \tilde{V}^\top \\ 0 \end{bmatrix} \\
 &= \tilde{V} (\tilde{S}^2 + \lambda I_n)^{-1} \tilde{V}^\top \\
 &= (X^\top X + \lambda I_n)^{-1}.
 \end{aligned}$$

Kernel ridge regression

Use features of $\phi(x_i)$ in the place of x_i :

$$a^* = \arg \min_{a \in \mathcal{H}} \left(\sum_{i=1}^n (y_i - \langle a, \phi(x_i) \rangle_{\mathcal{H}})^2 + \lambda \|a\|_{\mathcal{H}}^2 \right).$$

E.g. for finite dimensional feature spaces,

$$\phi_p(x) = \begin{bmatrix} x \\ x^2 \\ \vdots \\ x^\ell \end{bmatrix} \quad \phi_s(x) = \begin{bmatrix} \sin x \\ \cos x \\ \sin 2x \\ \vdots \\ \cos \ell x \end{bmatrix}$$

a is a vector of length ℓ giving weight to each of these features so as to find the mapping between x and y . Feature vectors can also have *infinite* length (more soon).

Kernel ridge regression: proof

Use previous proof!

$$X = \begin{bmatrix} \phi(x_1) & \dots & \phi(x_n) \end{bmatrix}.$$

All of the steps that led us to $a^* = X(X^\top X + \lambda I_n)^{-1}y$ follow.

$$XX^\top = \sum_{i=1}^n \phi(x_i) \otimes \phi(x_i)$$

(using tensor notation from kernel PCA), and

$$(X^\top X)_{ij} = \langle \phi(x_i), \phi(x_j) \rangle_{\mathcal{H}} = k(x_i, x_j).$$

Making these replacements, we get

$$\begin{aligned} a^* &= X(K + \lambda I_n)^{-1}y \\ &= \sum_{i=1}^n \alpha_i^* \phi(x_i) \quad \alpha^* = (K + \lambda I_n)^{-1}y. \end{aligned}$$

Kernel ridge regression: easier proof

We *begin* knowing a is a linear combination of feature space mappings of points (**representer theorem**: later in course)

$$a = \sum_{i=1}^n \alpha_i \phi(x_i).$$

Then

$$\begin{aligned} \sum_{i=1}^n (y_i - \langle a, \phi(x_i) \rangle_{\mathcal{H}})^2 + \lambda \|a\|_{\mathcal{H}}^2 &= \|y - K\alpha\|^2 + \lambda \alpha^\top K \alpha \\ &= y^\top y - 2y^\top K\alpha + \alpha^\top (K^2 + \lambda K) \alpha \end{aligned}$$

Differentiating wrt α and setting this to zero, we get

$$\alpha^* = (K + \lambda I_n)^{-1} y.$$

$$\text{Recall: } \frac{\partial \alpha^\top U \alpha}{\partial \alpha} = (U + U^\top) \alpha, \quad \frac{\partial v^\top \alpha}{\partial \alpha} = \frac{\partial \alpha^\top v}{\partial \alpha} = v$$

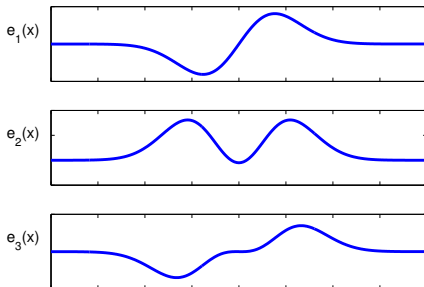
Reminder: smoothness

What does $\|a\|_{\mathcal{H}}$ have to do with smoothing?

Example 1: The exponentiated quadratic kernel. Recall

$$f(x) = \sum_{\ell=1}^{\infty} \hat{f}_{\ell} e_{\ell}(x), \quad \langle e_i, e_j \rangle_{L_2(\mu)} = \int_{\mathcal{X}} e_i(x) e_j(x) d\mu(x) = \begin{cases} 1 & i = j \\ 0 & i \neq j. \end{cases}$$

$$\|f\|_{\mathcal{H}}^2 = \sum_{\ell=1}^{\infty} \frac{\hat{f}_{\ell}^2}{\lambda_{\ell}}.$$



Reminder: smoothness

What does $\|a\|_{\mathcal{H}}$ have to do with smoothing?

Example 2: The Fourier series representation:

$$f(x) = \sum_{l=-\infty}^{\infty} \hat{f}_l \exp(\imath lx),$$

and

$$\langle f, g \rangle_{\mathcal{H}} = \sum_{l=-\infty}^{\infty} \frac{\hat{f}_l \overline{\hat{g}_l}}{\hat{k}_l}.$$

Thus,

$$\|f\|_{\mathcal{H}}^2 = \langle f, f \rangle_{\mathcal{H}} = \sum_{l=-\infty}^{\infty} \frac{|\hat{f}_l|^2}{\hat{k}_l}.$$

Parameter selection for KRR

Given the objective

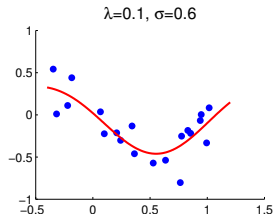
$$a^* = \arg \min_{a \in \mathcal{H}} \left(\sum_{i=1}^n (y_i - \langle a, \phi(x_i) \rangle_{\mathcal{H}})^2 + \lambda \|a\|_{\mathcal{H}}^2 \right).$$

How do we choose

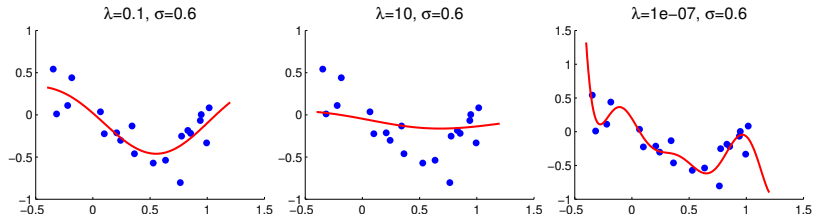
- The regularization parameter λ ?
- The kernel parameter: for exponentiated quadratic kernel, σ in

$$k(x, y) = \exp \left(\frac{-\|x - y\|^2}{\sigma} \right).$$

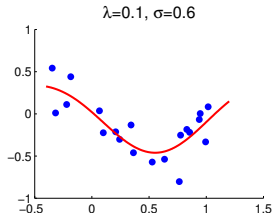
Choice of λ



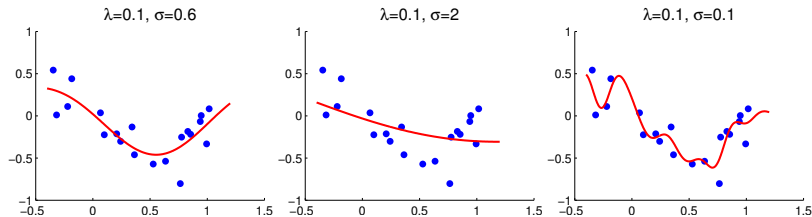
Choice of λ



Choice of σ



Choice of σ



Cross validation

- Split n data into training set size n_{tr} and **test set** size $n_{\text{te}} = n - n_{\text{tr}}$.
- Split training set into m equal chunks of size $n_{\text{val}} = n_{\text{tr}}/m$.
Call these $X_{\text{val},i}$, $Y_{\text{val},i}$ for $i \in \{1, \dots, m\}$
- For each λ, σ pair
 - For each $X_{\text{val},i}$, $Y_{\text{val},i}$
 - Train ridge regression on remaining training set data $X_{\text{tr}} \setminus X_{\text{val},i}$ and $Y_{\text{tr}} \setminus Y_{\text{val},i}$,
 - Evaluate its error on the validation data $X_{\text{val},i}$, $Y_{\text{val},i}$
 - Average the errors on the validation sets to get the average validation error for λ, σ .
- Choose λ^*, σ^* with the lowest average validation error
- Measure the performance on the test set X_{te} , Y_{te} .