

Attention! Is Recycling Artificial Neural Network Effective for Maintaining Renewable Energy Efficiency?

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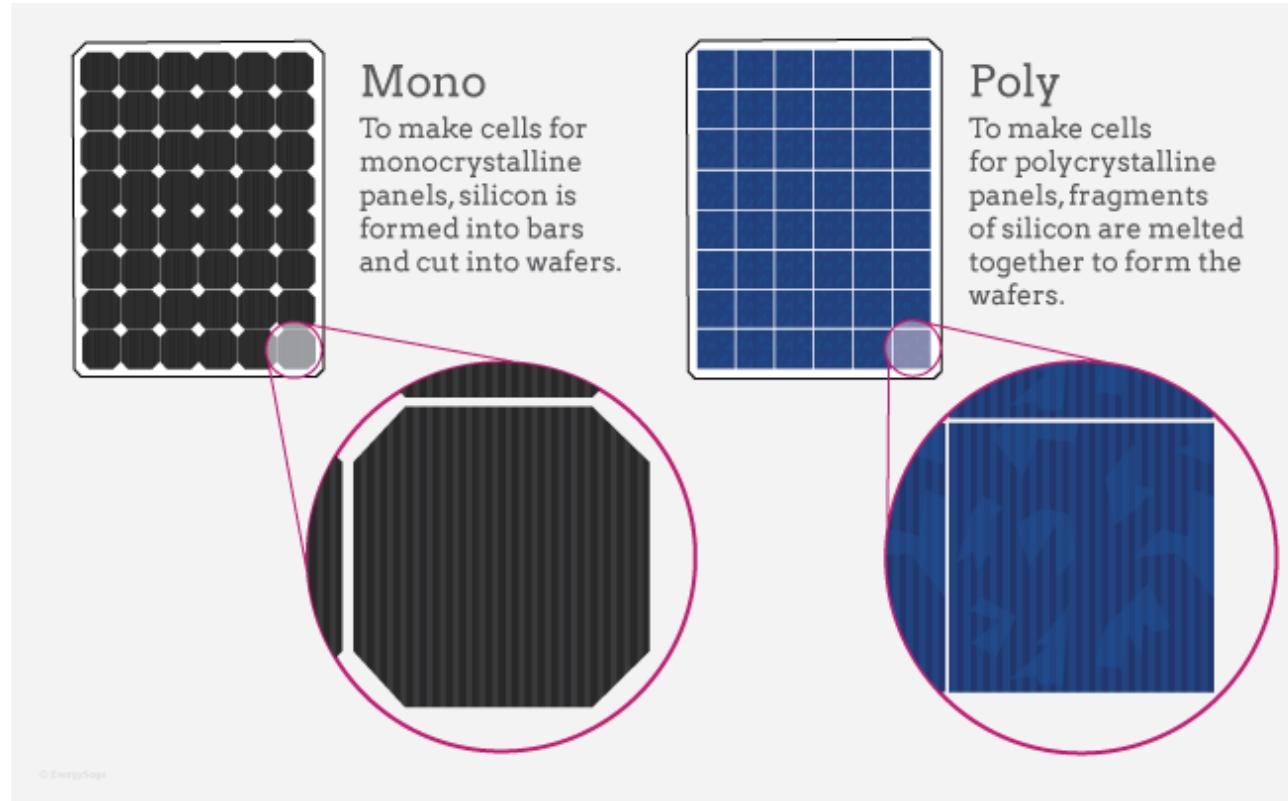
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Introduction

Renewable Energy



Type of solar panels



Monocrystalline

- Single pure silicon crystal
- Uniform dark squares
- 15~20% of conversion efficiency
- 40 years of lifespan
- More expensive

Polycrystalline

- Different Silicon Fragments
- Irregular blue squares dark squares
- 13~16% of conversion efficiency
- 35 years of lifespan
- Less expensive

Efficiency of photovoltaic system



FIGURE 2: Photograph of apparatus.

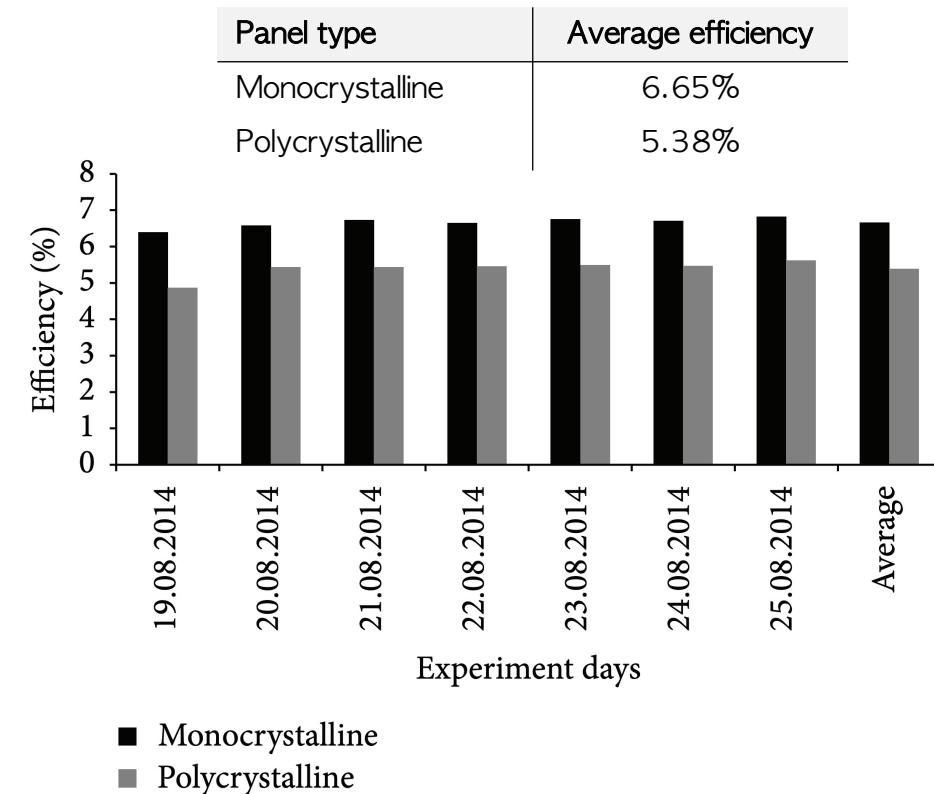
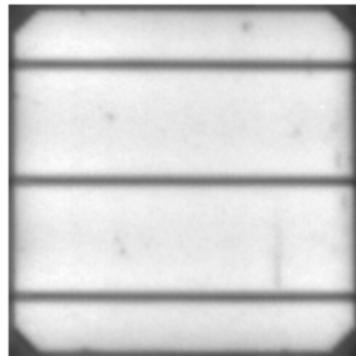
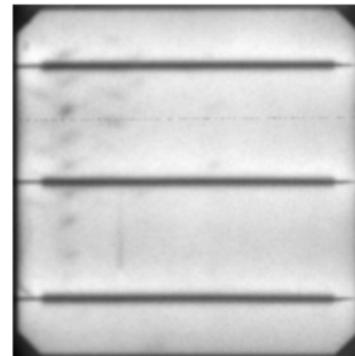


FIGURE 7: Panels efficiencies ratio.

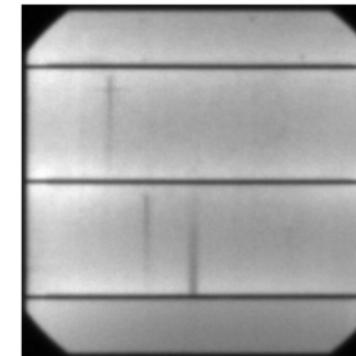
Solar Panels



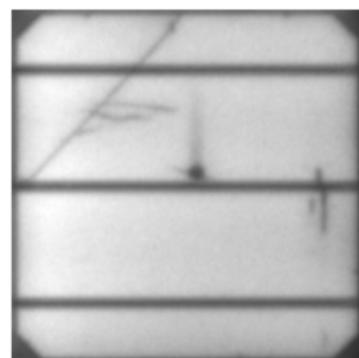
Non-defective



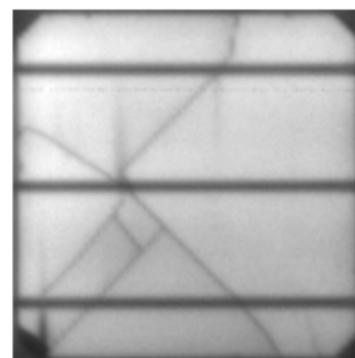
Defective
(1/3-level)



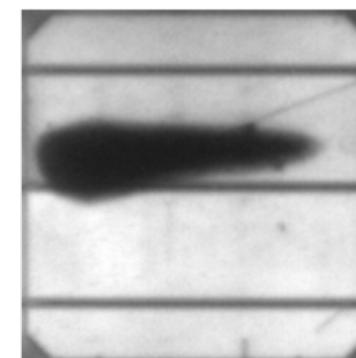
Defective
(2/3-level)



Complete Defective
(Crack)



Complete Defective
(Crack)



Complete Defective
(Contamination)

Problem and goal

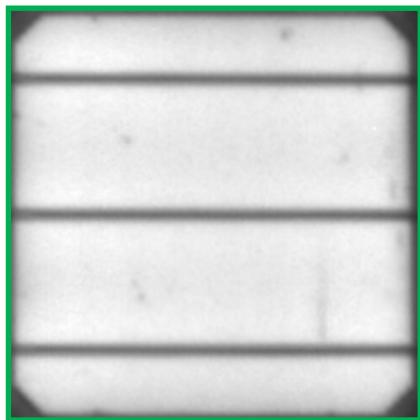
- Cause of the **decrease** in efficiency
 - Cracks
 - Contaminations
 - No/slow response to fix the above states
- For **maximizing** the efficiency
 - Detect the defectives
 - Fix defectives as soon as possible

Approach

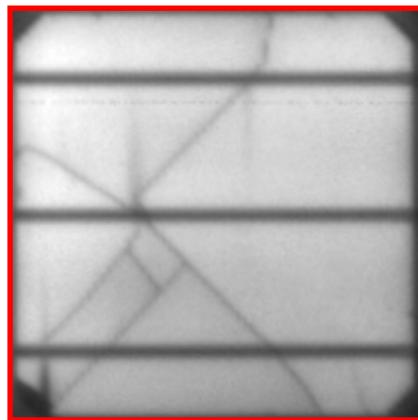
Limitations of the conventional methods

- Deep learning-based Classification method (supervised)
 - Needs one-to-one class label
 - High complexity, high power consumption
- Segmentation method
 - Needs one-to-one segmentation mask
 - Marking the defective area is unnecessary

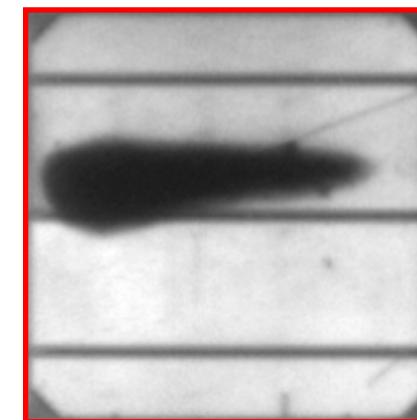
Easy to understand



Non-defective



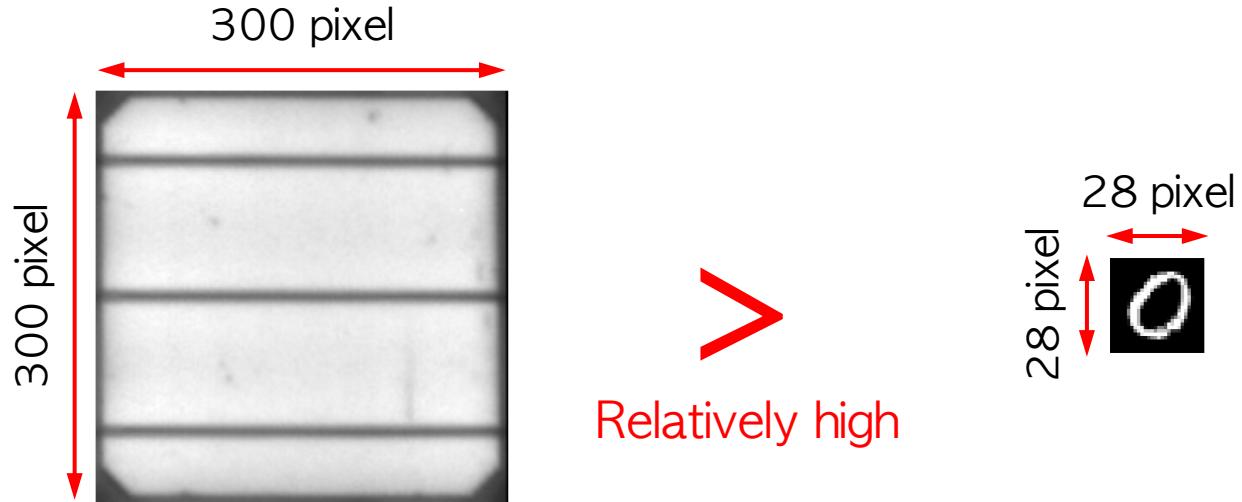
Defective
(Crack)



Defective
(Contamination)

- Is the given information sufficient? → Yes
- Do we need high-complex model? → Probably not

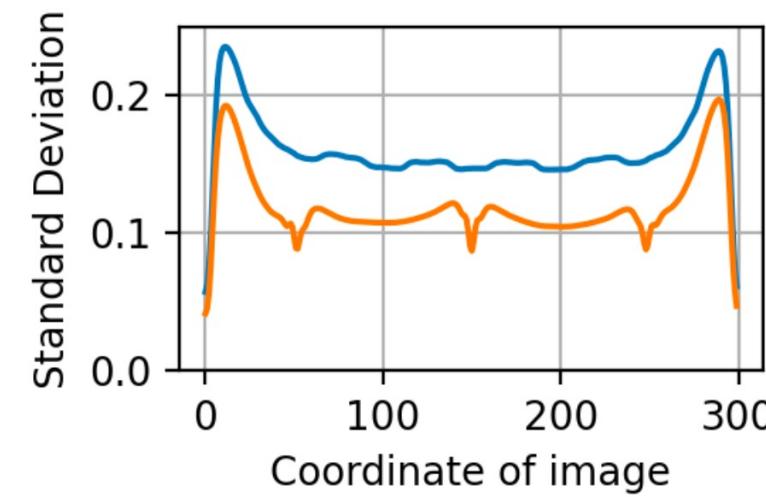
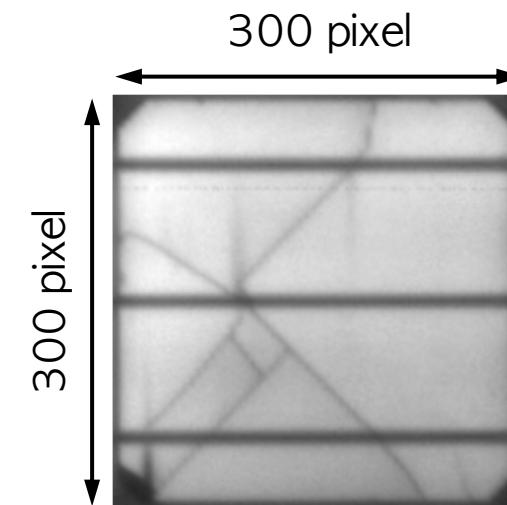
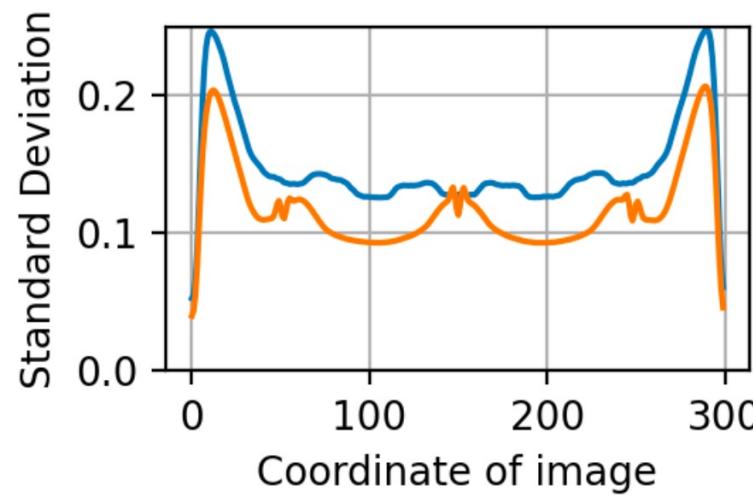
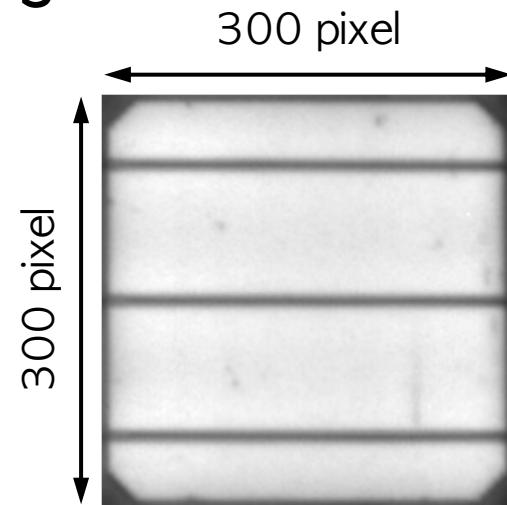
Need to reduce the computational cost



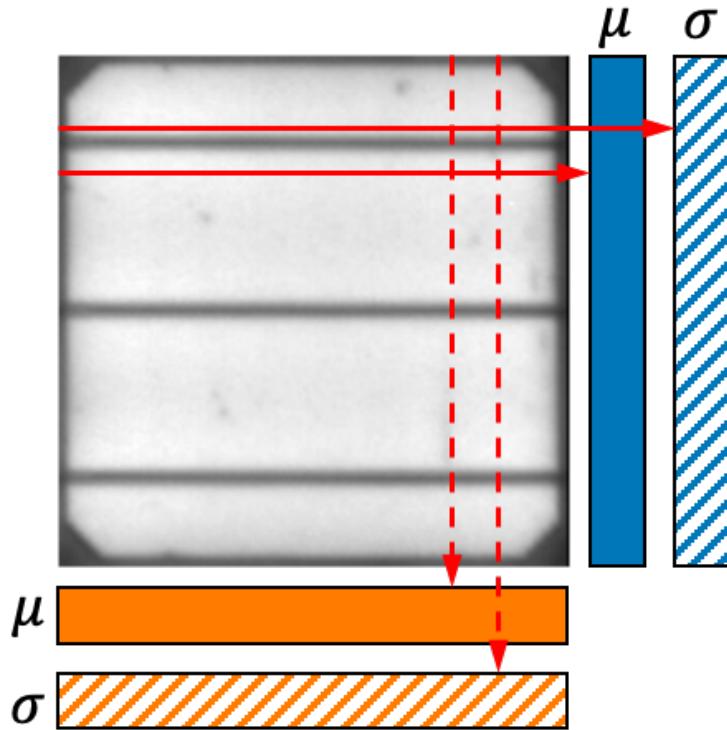
- Training for the high-resolution image requires large computing power.
- Large / high-performance computing is at odds with the concept of renewable energy.

- Blue line: height-axis
- Orange line: width-axis

Easy to distinguish



Feature Extraction



Feature	Description
μ_{image}	Mean of whole pixel values
σ_{image}	Standard deviation (SD) of whole pixel values
R	Outlier rate that deviate from the threshold, $\mu \pm 1.5\sigma$, among image
S	Skewness of whole pixel values
$S(\mu_{height})$	Skewness of the pixel mean along the height axis
$S(\mu_{width})$	Skewness of the pixel mean along the width axis
$S(\sigma_{height})$	Skewness of the pixel SD along the height axis
$S(\sigma_{width})$	Skewness of the pixel SD along the width axis
K	Kurtosis of whole pixel values
$K(\mu_{height})$	Kurtosis of the pixel mean along the height axis
$K(\mu_{width})$	Kurtosis of the pixel mean along the width axis
$K(\sigma_{height})$	Kurtosis of the pixel SD along the height axis
$K(\sigma_{width})$	Kurtosis of the pixel SD along the width axis

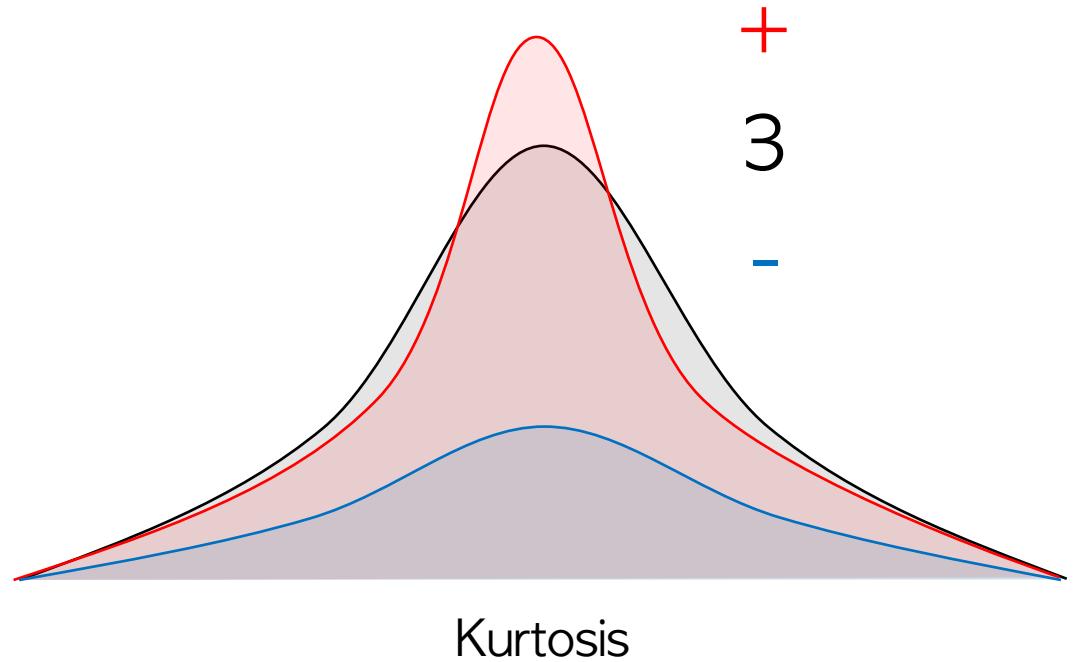
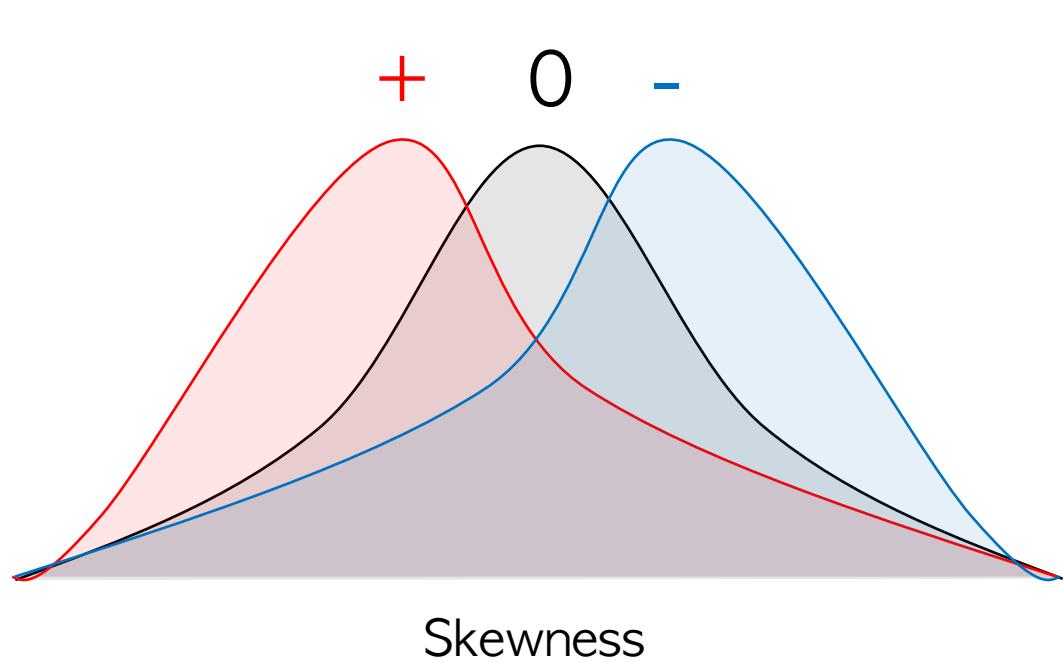
300 x 300 pixel values → 13 statistical features

Computational cost is reduced by 0.014%-level.

- Black: Reference
- Blue: Negative (or small)
- Red: Positive (or large)

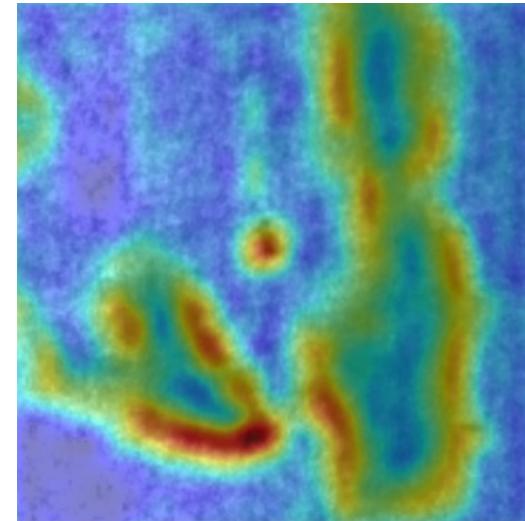
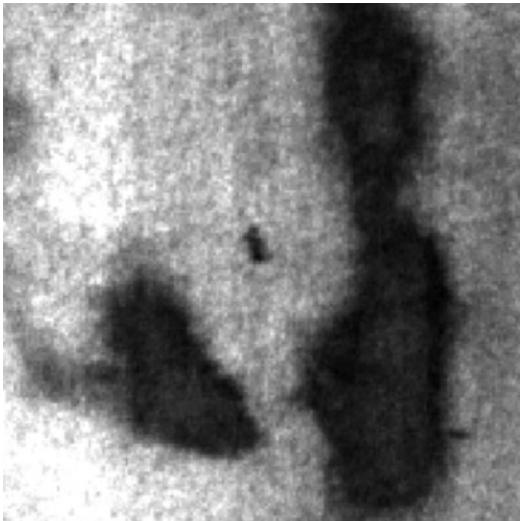
Skewness and Kurtosis

Data
(Matrix / Vector) → Histogram
(Vector) → Skewness / Kurtosis
(Scalar)



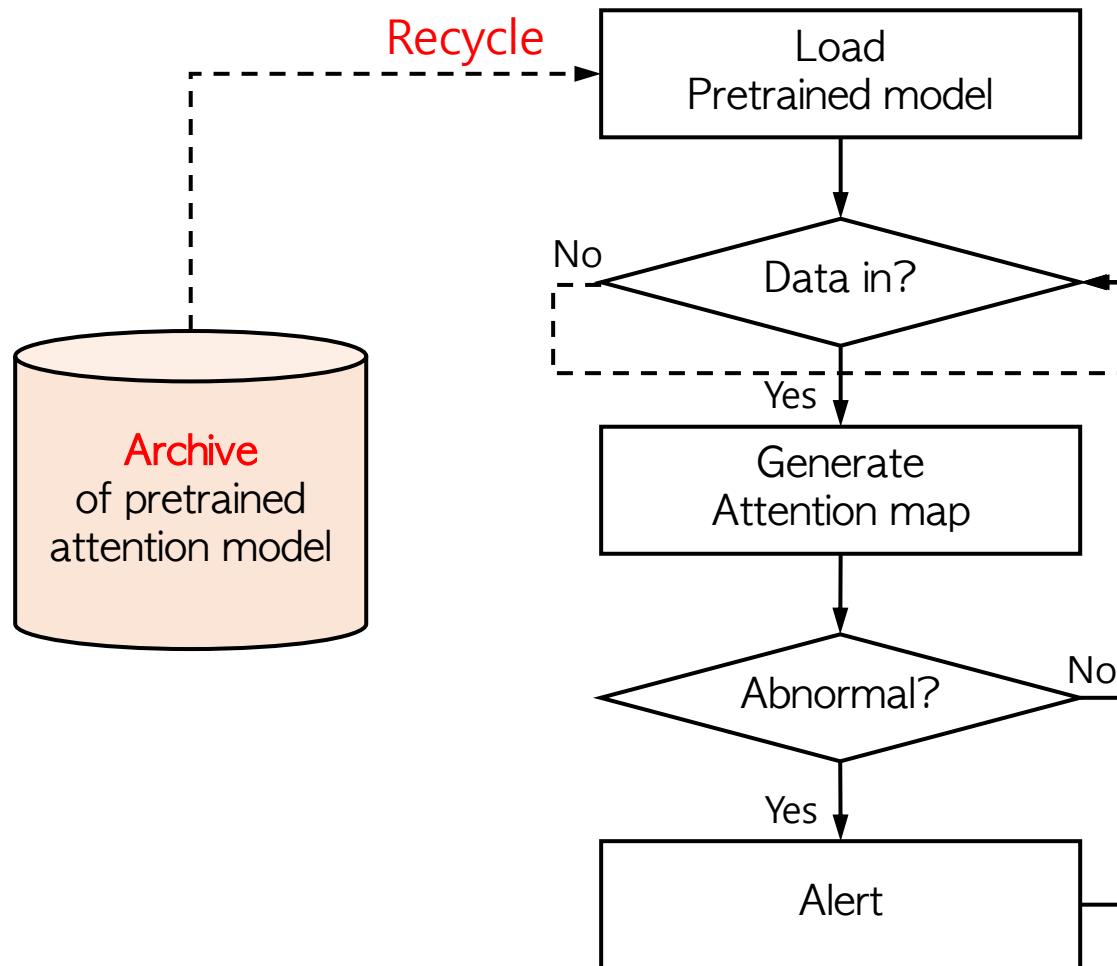
Information emphasizing will be helpful

Information Emphasizing!



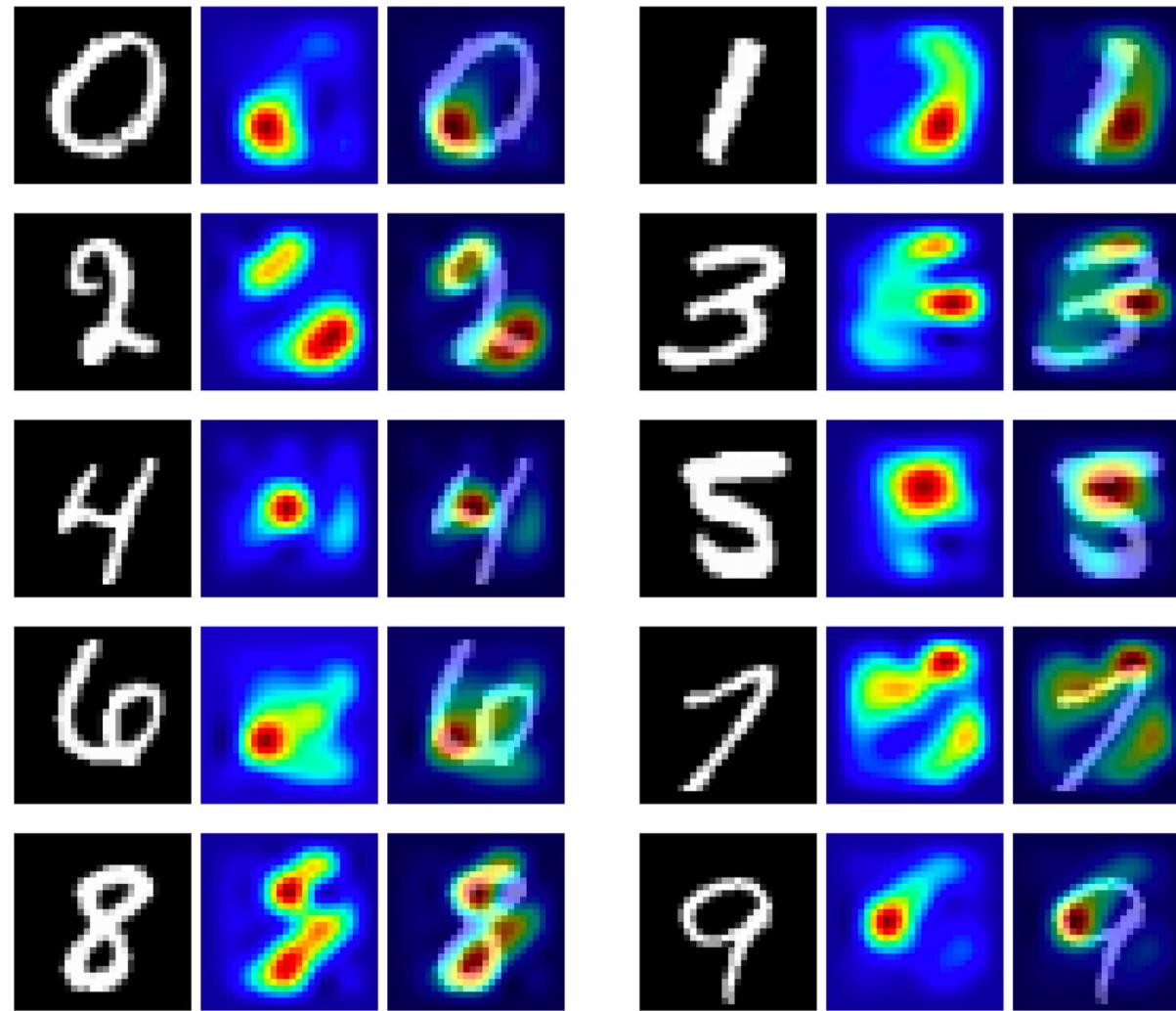
	Class Activation Map (CAM)	Attention Map (AM)
Task	Discrimination	Discrimination / Generation
Training Manner	Supervised	Supervised / Unsupervised
Label	Necessary	Optional

Overall flow

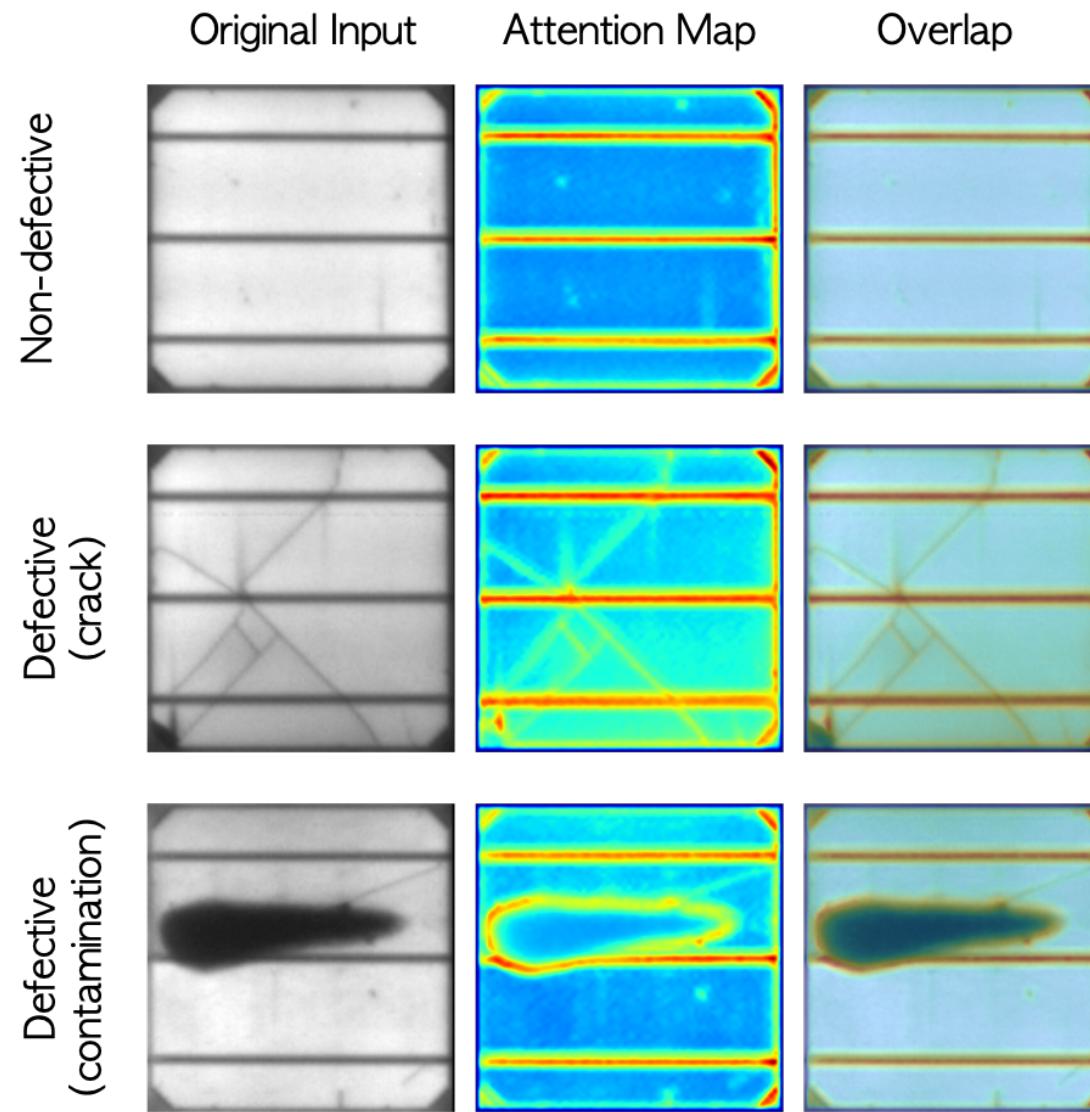


Experiments

Pretrained Attention Model



Attention Maps



Comparison - 1

Correlation coefficients between labels and extracted features

	Value	Original	Attention
Sign	Min	-0.937	-0.948
	Max	0.889	0.815
	Avg	0.403	0.447
	SD	0.288	0.280
Absolute	Min	0.010	0.014
	Max	0.937	0.948
	Avg	0.027	0.023
	SD	0.494	0.527

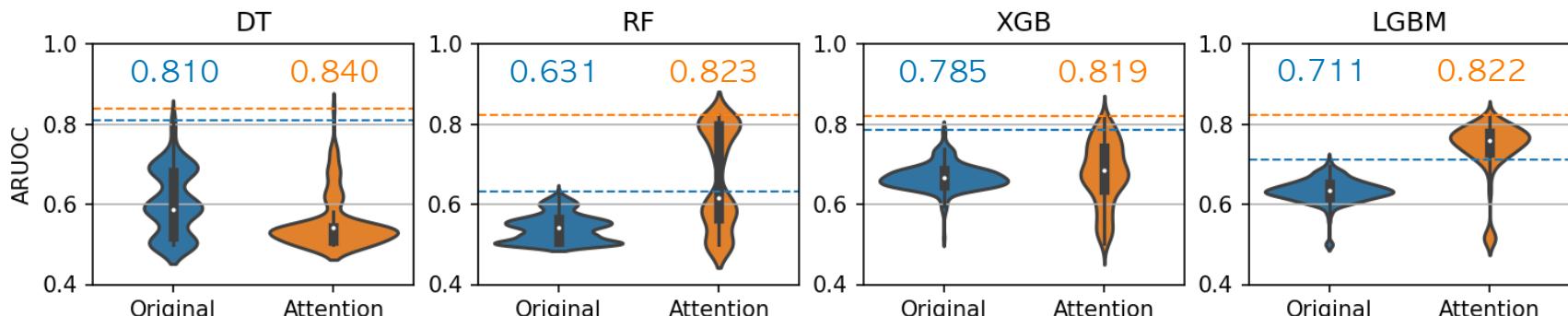
High maximum coefficient → Setting the threshold to determine defective or not is easier.

Low average coefficient → Each feature value is independent and meaningful info.

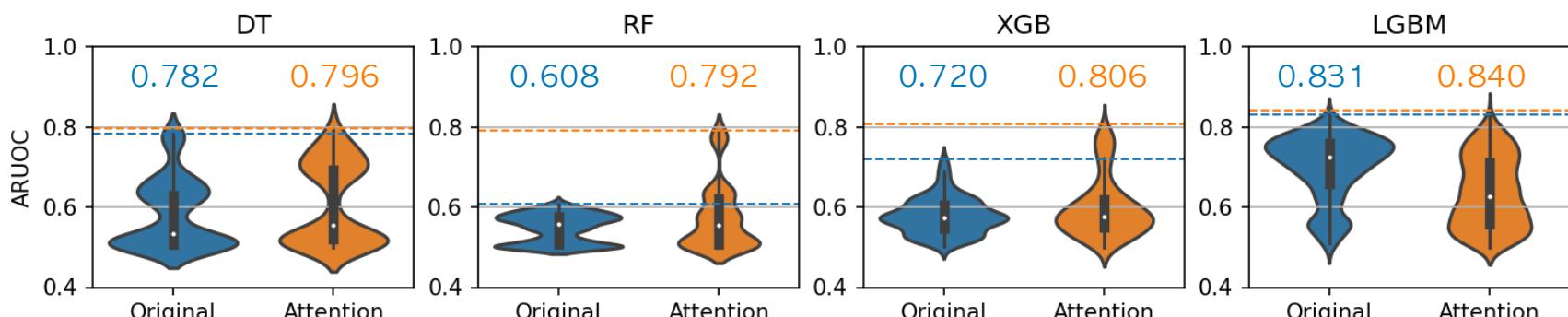
Comparison - 2

- DT: decision tree
- RF: random forest
- XGB: extreme gradient boosting
- LGBM: light gradient boosting machine

Clear non-defective
VS
Complete defective



Complete non-defective
VS
Various defectives
(including small defective)



- Control variable
 - Feature extraction method: 13 statistical features
- Independence variable
 - Input type: original image or attention map
 - Model: decision tree, random forest, or other lightweight machine learning models

Conclusion

Conclusion

- We highly **reduce the computational cost**.
 - Through the proposed feature extraction method.
 - 300 x 300 pixel values → 13 statistical features
- We propose an **attention map utilization** for information emphasis.
- We **eliminated the cost of training a new attention model** by recycling the model trained on public datasets.
 - This approach is very meaningful in the context of maximizing renewable energy efficiency.

Thank you!