Yeonju Kim

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EDUCATION

University of Illinois at Urbana-Champaign

Illinois, US

Master of Science in Mechanical Engineering (GPA 3.86/4.0)

Sep. 2019 - June 2021

Coursework include: Control System Theory and Design, Computational Photography, Machine Learning, Markov Decision Processes and Reinforcement Learning, Special Topics in Learning-based Robotics, Analysis of Nonlinear Systems

Seoul National University

Seoul, South Korea

Bachelor of Science in Mechanical Engineering and Aerospace Engineering (GPA 3.73/4.3)

Mar. 2014 - Feb. 2019

TECHNICAL SKILLS

Programming: Python, C++, MATLAB, PyTorch, OpenCV, ROS

3-D Modeling: SOLIDWORKS, Fusion360, 3D-MAX

Other Software: Unreal Engine, Adobe Photoshop, Adobe Illustrator

Publication

Y.Kim, Z.Pan, and K.Hauser. MO-BBO: Multi-Objective Bilevel Bayesian Optimization for Robot and Behavior Co-Design., IEEE International Conference on Robotics and Automation (ICRA), May 2021

EXPERIENCE

Animation Tech Team, NC SOFT Corporation

Seongnam, South Korea

Animation Programmer

July 2021 - Present

- Investigated Iterative Inverse Kinematics Solver for 3d Animation.
- Developed Joint Constraints (Hinge and Cone Constraint) used in Inverse Kinematics Solver. Evaluated the Constraints using Humanoid model.

Intelligent Motion Laboratory, University of Illinois at Urbana-Champaign

Illinois, US

Graduate Researcher

Sep. 2019 - June 2021

- · Developed a co-optimization method for robot design and behaviors, which helps designers effectively explore the design space.
- Evaluated the method by applying it to grasping gripper design and arm placement for a bimanual mobile manipulator.
- Work on the optimization of robot arm placement for the Tele-Robotic Intelligent Nursing Assistant (TRINA) considering human-likeness.

Bear Robotics Seoul, South Korea

Software Engineering Intern

Jan. 2019 - June 2019

- Developed web-based ROS data visualization using ROS Javascript libraries and React.
- Investigated Seq2Seq model and Transformer model to implement Korean Chatbot.

NC SOFT Corporation

Seongnam, South Korea

Game Development Intern

July 2018 - August 2018

- Developed Turn-Based 3-D Tank Game using Unreal Engine 4 with C++.
- Developed Online Multiplayer Tank Game based on the Client-Server architecture.

Biorobotics Laboratory, Seoul National University

Seoul, South Korea

Undergraduate Researcher

Mar. 2017 - June 2018

- Fabricated soft robotic modules with 3-D printer.
- Analyzed soft module movement using Pseudo Rigid Body modeling method.
- Developed a bending angle prediction method as a design guide for users to attain desired motions.

Disney Research Zurich and Autonomous Systems Laboratory, ETH Zurich

Zurich, Switzerland

Undergraduate Researcher

Sep. 2017 - Feb. 2018

• Designed and fabricated two different designs minimizing the adverse effect on servomotor caused by undesirable rake's motions.

HONORS AND AWARDS

Korean Government Scholarship for Overseas Study Awarded 40 K USD annually for 2 years	2019 - 2021
National Scholarship for Science and Engineering Awarded 6K USD annually for 2 years (full tuition)	2016 - 2017
Eminence Scholarship, Seoul National University Awarded 3K USD (full tuition)	Sep. 2015
Gold Prize, The 7th Creative Design Challenge for 90 Percent Alienated	May 2015
SNU Development Fund Scholarship, Sangjin Foundation Awarded 2K USD	March 2015
Merit-based Scholarship, Seoul National University Awarded 1.5K USD	Sep. 2014

EXTRACURRICULAR ACTIVITIES

SNU Tomorrow's Engineers Membership(STEM), Seoul National University

Mar. 2016 - August 2017

- The only honor society in College of Engineering, Seoul National University
- Shared my vision and experiences with over 300 high school students to encourage them to study engineering.