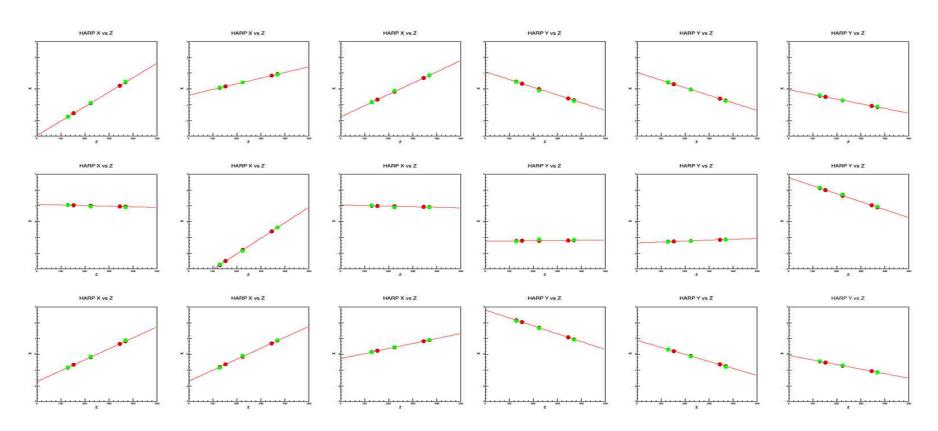
# **BPM Calibration Update**

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August 9, 2018

# Sanity Checks for Internal Consistency



### Gains and Offsets

- Projected X/Y Position = slope \* Raw EPICS BPM X/Y Position + offset
- A calibration script now exists in

## Beam Position at Target (z = 0)

$$X(z) = m_x^*z + b_x$$
 and  $Y(z) - m_y^*z + b_y$ 

Calculate slopes from A and C BPM's (longest lever arm):  $m_x = (A_x - C_x)/(A_z - C_z)$  and  $m_v = (A_v - C_v)/(A_z - C_z)$ 

Then calculate b<sub>x</sub> and b<sub>y</sub> (positions at taCaynxz\* Adduyt)

#### EPICS data in detector classes

- The previous algorithm requires the BPM information event by event by event).
- The Raster class

#### THcRaster.h

N.B. Need to be careful with units!!! BPM calibrations are in mm, raster is in cm currently!!

