

Introduction to Genetic Algorithms

A Tutorial by Erik D. Goodman

Professor, Electrical and Computer Engineering

Professor, Mechanical Engineering

Co-Director, Genetic Algorithms Research and Applications Group (GARAGe)

Michigan State University

goodman@egr.msu.edu

Executive Committee Member, ACM SIGEVO

Vice President, Technology

Red Cedar Technology, Inc.

**2009 World Summit on Genetic and Evolutionary Computation
Shanghai, China**

GEC Summit, Shanghai, June, 2009

Thanks to:

Much of this material is based on:

- ◆ **David Goldberg, *Genetic Algorithms in Search, Optimization, and Machine Learning*, Addison-Wesley, 1989** (still one of the best introductions!)
- ◆ **Darrell Whitley, “Genetic Algorithm Tutorial” – on the web at**
www.cs.colostate.edu/~genitor/MiscPubs/tutorial.pdf

Overview of Tutorial

- ◆ **Quick intro – What IS a genetic algorithm?**
 - **Classical, binary chromosome**
- ◆ **Where used, & when better to use something else**
- ◆ **A little theory – why a GA works**
- ◆ **GA in Practice -- some modern variants**

Genetic Algorithms:

- ◆ Are a method of search, often applied to optimization or learning
- ◆ Are stochastic – but are *not* random search
- ◆ Use an evolutionary analogy, “survival of fittest”
- ◆ Not *fast* in some sense; but sometimes more robust; scale relatively well, so can be useful
- ◆ Have extensions including Genetic Programming (GP) (LISP-like function trees), learning classifier systems (evolving rules), linear GP (evolving “ordinary” programs), many others

The Canonical or Classical GA

- ◆ Maintains a set or “population” of strings at each stage
- ◆ Each string is called a chromosome, and encodes a “candidate solution”–
CLASSICALLY, encodes as a *binary string* (but now in almost any conceivable representation)

Criterion for Search

- ◆ **Goodness (“fitness”) or optimality of a string’s solution determines its FUTURE influence on search process -- survival of the fittest**
- ◆ **Solutions which are good are used to generate other, similar solutions which may also be good (even better)**
- ◆ **The POPULATION at any time stores ALL we have learned about the solution, at any point**
- ◆ **Robustness (efficiency in finding good solutions in difficult searches) is key to GA success**

Classical GA: The Representation

1011101010 – a possible 10-bit string
 (“CHROMOSOME”) representing a possible solution to
 a problem

Bits or subsets of bits might represent choice of some feature,
 for example. Let’s represent choice of shipping container for
 some object:

<u>bit position</u>	<u>meaning</u>
1-2	steel, aluminum, wood or cardboard
3-5	thickness (1mm-8mm)
6-7	fastening (tape, glue, rope, plastic wrap)
8	stuffing (paper or plastic “peanuts”)
9	corner reinforcement (yes, no)
10	handles (yes, no)

Terminology

Each position (or each set of positions that encodes some feature) is called a LOCUS (plural LOCI)

Each possible value at a locus is called an ALLELE

We need a simulator, or evaluator program, that can tell us the (probable) outcome of shipping a given object in any particular type of container

- ◆ **may be a COST (including losses from damage) (for example, maybe 1.4 means very low cost, 8.3 is very bad on a scale of 0-10.0), or**
- ◆ **may be a FITNESS, or a number that is larger if the result is BETTER**

How Does a GA Operate?

- ◆ For ANY chromosome, must be able to determine a **FITNESS** (measure of performance toward an objective) using a simulator or analysis tool, etc.
- ◆ Objective may be maximized or minimized; usually say *fitness* is to be maximized, and if objective is to be minimized, define fitness from it as something to maximize

GA Operators: Classical Mutation

- ◆ Operates on ONE “parent” chromosome
- ◆ Produces an “offspring” with changes.
- ◆ Classically, toggles one bit in a binary representation
- ◆ So, for example: 1101000110 could
mutate to: 11**1**1000110
- ◆ Each bit has same probability of mutating



Classical Crossover

- ◆ Operates on two parent chromosomes
- ◆ Produces one or two children or offspring
- ◆ Classical crossover occurs at 1 or 2 points:
- ◆ For example: (1-point) (2-point)


	1111111111	or	1111111111
x	0000000000		0000000000
	<hr/>		<hr/>
	1110000000		1110000011
and	0001111111		0001111100

Selection

- ◆ ***Traditionally*, parents are chosen to mate with probability proportional to their fitness: *proportional selection***
- ◆ **Traditionally, children replace their parents**
- ◆ **Many other variations now more commonly used (we'll come back to this)**
- ◆ **Overall principle: survival of the fittest**



Synergy – the KEY



Clearly, selection alone is no good ...

Clearly, mutation alone is no good ...

Clearly, crossover alone is no good ...

**Fortunately, using all three simultaneously
is sometimes spectacular!**

Contrast with Other Search Methods

- ◆ “indirect” -- setting derivatives to 0
- ◆ “direct” -- hill climber
- ◆ enumerative – search ‘em all
- ◆ random – just keep trying, or can avoid resampling
- ◆ simulated annealing – single-point method, reals, changes all loci randomly by decreasing amounts, mostly keeps the better answer, ...
- ◆ Tabu (another common method)

BEWARE of Claims about ANY Algorithm's Asymptotic Behavior – “Eventually” is a LONG Time

- ◆ **LOTS of methods can guarantee to find the best solution, with probability 1, eventually...**
 - Enumeration
 - Random search (better without resampling)
 - SA (properly configured)
 - Any GA that avoids “absorbing states” in a Markov chain
- ◆ **The POINT: you can't afford to wait that long, if the problem is anything interesting!!!**

When Might a GA Be Any Good?

- ◆ **Highly multimodal functions**
- ◆ **Discrete or discontinuous functions**
- ◆ **High-dimensionality functions, including many combinatorial ones**
- ◆ **Nonlinear dependencies on parameters (interactions among parameters) -- “epistasis” makes it hard for others**
- ◆ **Often used for approximating solutions to NP-complete combinatorial problems**
- ◆ **DON'T USE if a hill-climber, etc., will work well**

The Limits to Search

- ◆ No search method is best for all problems – per the No Free Lunch Theorem
- ◆ Don't let anyone tell you a GA (or THEIR favorite method) is best for all problems!!!
- ◆ Needle-in-a-haystack is just *hard*, in practice
- ◆ Efficient search must be able to EXPLOIT correlations in the search space, or it's no better than random search or enumeration
- ◆ Must balance with EXPLORATION, so don't just find nearest local optimum

Examples of Successful Real-World GA Application

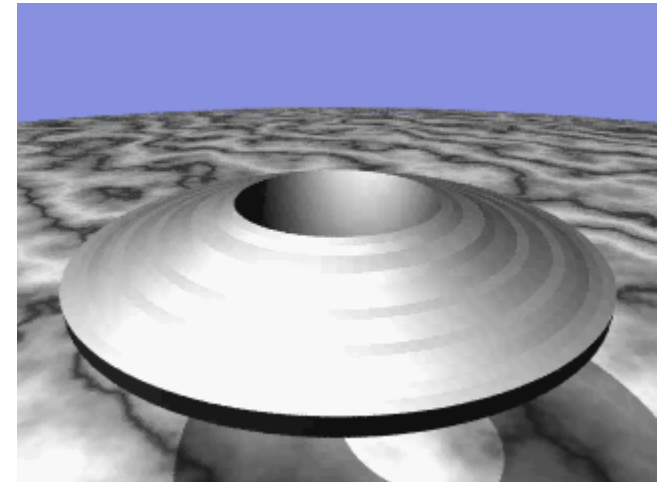
- ◆ Antenna design
- ◆ Drug design
- ◆ Chemical classification
- ◆ Electronic circuits (Koza)
- ◆ Factory floor scheduling (Volvo, Deere, others)
- ◆ Turbine engine design (GE)
- ◆ Crashworthy car design (GM/Red Cedar)
- ◆ Protein folding
- ◆ Network design
- ◆ Control systems design
- ◆ Production parameter choice
- ◆ Satellite design
- ◆ Stock/commodity analysis/trading
- ◆ VLSI partitioning/ placement/routing
- ◆ Cell phone factory tuning
- ◆ Data Mining

EXAMPLE!!!

Let's Design a Flywheel

GOAL: To store as much energy as possible (for a given diameter flywheel) without breaking apart

- ◆ On the chromosome, a number specifies the thickness (height) of the “ring” at each given radius
- ◆ Center “hole” for a bearing is fixed
- ◆ To evaluate: simulate spinning it faster and faster until it breaks; calculate how much energy is stored just before it breaks



Flywheel Example

So if we use 8 rings, the chromosome might look like:

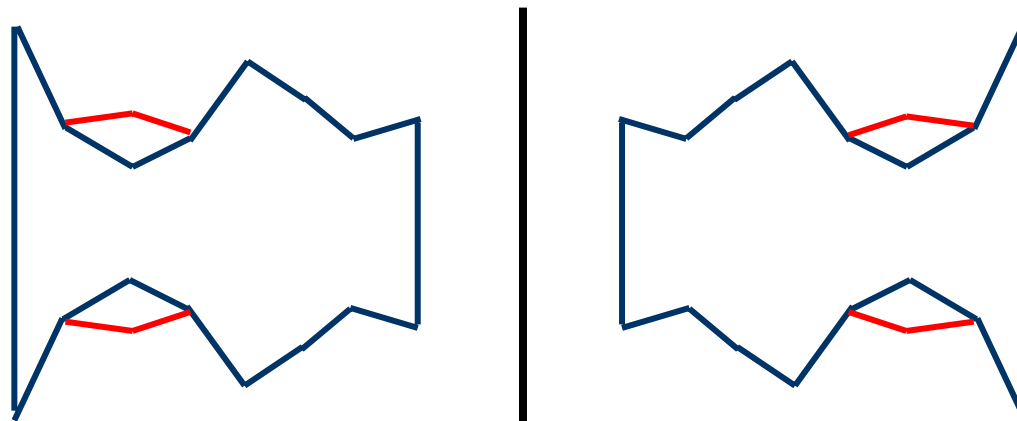
6.3 3.7 2.5 3.5 5.6 4.5 3.6 4.1



If we **mutate** HERE, we might get:


6.3 3.7 **4.1** 3.5 5.6 4.5 3.6 4.1

And that might look like (from the side):



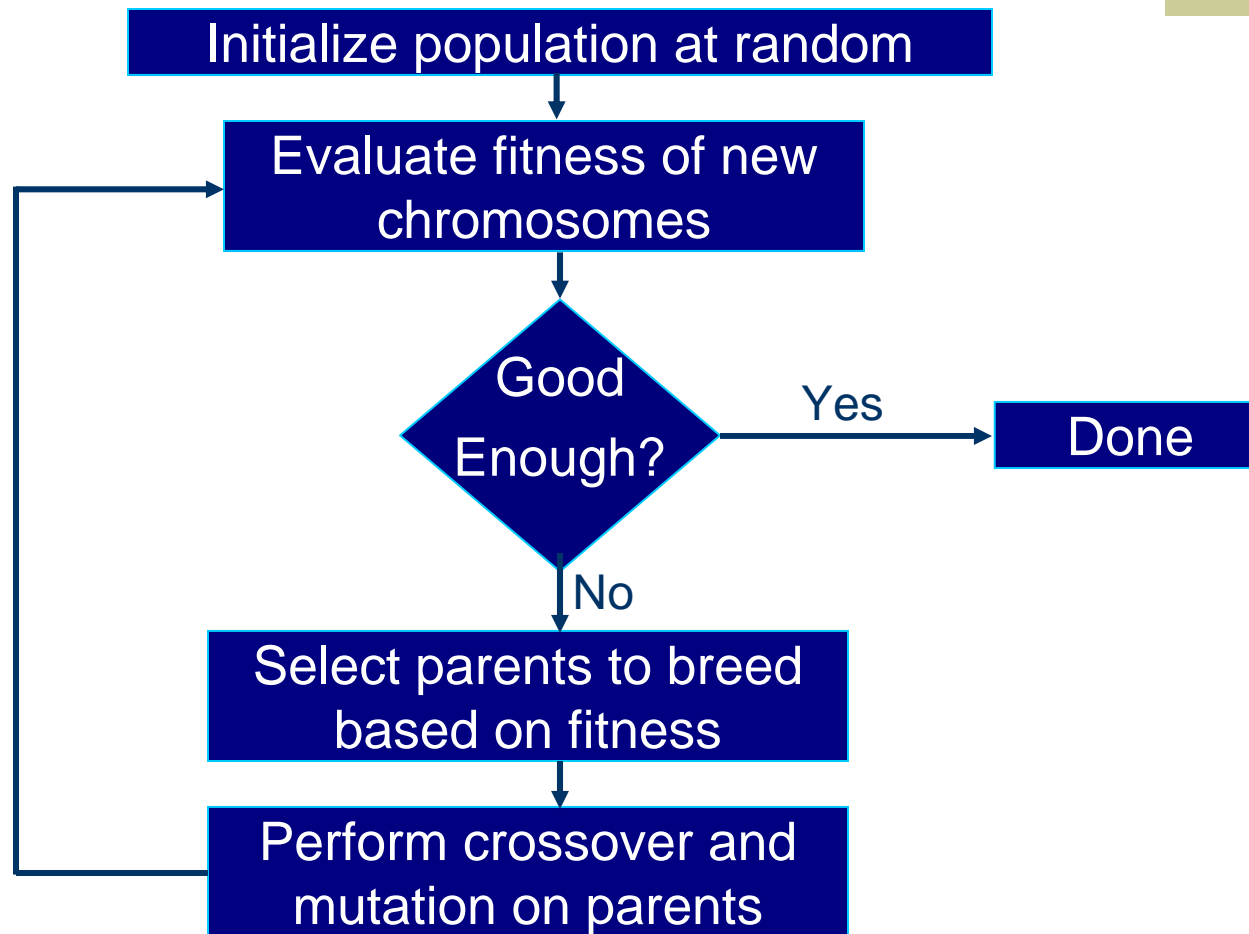
Recombination (“Crossover”)

If we **recombine** two designs, we might get:

6.3	3.7	2.5	3.5	5.6	4.5	3.6	4.1
				x			
3.6	5.1	3.2	4.3	4.4	6.2	2.3	3.4
							
3.6	5.1	3.2	3.5	5.6	4.5	3.6	4.1

This new design might be BETTER or WORSE!

Typical GA Operation -- Overview



A GA Evolves the Flywheel:

**One
Material**



**Choice of
Materials**



**Choice
(side view)**



“Genetic Algorithm” -- Meaning?

- ◆ **“classical or canonical” GA -- Holland (taught in ‘60’s, book in ‘75) -- binary chromosome, population, selection, crossover (recombination), low rate of mutation**
- ◆ **More general GA: population, selection, (+ recombination) (+ mutation) -- may be hybridized with LOTS of other stuff**

Representation Terminology

- ◆ Classically, binary string: individual or chromosome
- ◆ What's on the chromosome is **GENOTYPE**
- ◆ What it *means* in the problem context is the **PHENOTYPE** (e.g., binary sequence may map to integers or reals, or order of execution, or inputs to a simulator, etc.)
- ◆ Genotype and problem environment determine phenotype, but phenotype may *look* very different

In PRACTICE – GAs Do a JOB

- ◆ DOESN'T mean necessarily finding *global optimum*
- ◆ DOES mean *trying* to find *better* approximate answers than other methods do, within the time available!
- ◆ People use any “dirty tricks” that work:
 - Hybridize with local search operations
 - Use multiple populations/multiple restarts, etc.
 - Use problem-specific representations and operators
- ◆ The GOALS:
 - Minimize # of function evaluations needed
 - Balance exploration/exploitation so get best answer can during time available (AVOIDING *premature convergence*)

Other Forms of GA

Generational vs. “Steady-State”

- ◆ “Generation gap”: 1.0 means replace ALL by newly generated “children”
- ◆ at lower extreme, generate 1 (or 2) offspring per generation (called “steady-state”) – no real “generations” – children ready to become parents on next operation

More Forms of GA

Replacement Policy:

- 1. Offspring replace parents**
- 2. K offspring replace K worst ones**
- 3. Offspring replace random individuals in intermediate population**
- 4. Offspring are “crowded” in**
- 5. “Elitism” – always keep best K**

How Do GAs Go Bad?

- ◆ Premature convergence
- ◆ Unable to overcome deception
- ◆ Need more evaluations than time permits
- ◆ Bad match of representation/mutation/crossover, making operators destructive
- ◆ Biased or incomplete representation
- ◆ Problem too hard
- ◆ (Problem too easy, makes GA *look* bad)

So, in Conclusion...

- ◆ **GAs can be easy to use, but not necessarily easy to use WELL**
- ◆ **Don't use them if something else will work – it will probably be faster**
- ◆ **GAs can't solve every problem, either...**
- ◆ **GAs are only one of several strongly related “branches” of evolutionary computation – and they all commonly get hybridized**
- ◆ **There's lots of expertise at GECCO – talk to people for ideas about how to address YOUR problem using evolutionary computation**