FB1 - <offline>

"Program_Control"

SIMATIC

Name: Family:
Author: Yetkin Version: 0.1
Block version: 2
Time stamp Code: 01/03/2022 02:57:17 PM

Interface: 07/20/2017 05:12:40 PM

Lengths (block/logic/data): 00700 00486 00000

Name	Data Type	Address	Initial Value	Comment
IN		0.0		
Stage_1	Bool	0.0	FALSE	
Stage_2	Bool	0.1	FALSE	
Stage_3	Bool	0.2	FALSE	
Stage_4	Bool	0.3	FALSE	
Emergency_Stop	Bool	0.4	FALSE	
Motor_Healthy	Bool	0.5	FALSE	
Prox_sensor_1	Bool	0.6	FALSE	
Prox_sensor_2	Bool	0.7	FALSE	
OUT		0.0		
Stage_1_lamp	Bool	2.0	FALSE	
Stage_2_lamp	Bool	2.1	FALSE	
Stage_3_lamp	Bool	2.2	FALSE	
Stage_4_lamp	Bool	2.3	FALSE	
Error_lamp	Bool	2.4	FALSE	
Motor_fault	Bool	2.5	FALSE	
Speed_1_Fast	Bool	2.6	FALSE	
Speed_2_Slow	Bool	2.7	FALSE	
Move_forward	Bool	3.0	FALSE	
Move_backward	Bool	3.1	FALSE	
Brake	Bool	3.2	FALSE	
IN_OUT		0.0		
STAT		0.0		
Actual_Stage	Int	4.0	0	
Requested_Stage	Int	6.0	0	
Countup_FP	Bool	8.0	FALSE	
Countdown_FP	Bool	8.1	FALSE	
TEMP		0.0		

Block: FB1

Sample project for a segment car control

Network: 1

U #Stage_1 #Stage_1 SPB _012 U #Stage_2 #Stage_2 SPB _013 U #Stage_3 #Stage_3 SPB _014 SIMATIC 300(1)\CPU 313C-2 DP\...\FB1 - <offline>

```
ŢŢ
            #Stage_4
                               #Stage_4
      SPB
            _015
      SPA
            end6
_012: L
      Т
            #Requested_Stage #Requested_Stage
      SPA
            end6
_013: L
            #Requested_Stage #Requested_Stage
      Т
      SPA
            end6
_014: L
      т
            #Requested_Stage #Requested_Stage
      SPA
_015: L
            #Requested_Stage #Requested_Stage
      Т
end6: NOP
Network: 2
                 Forward - Backward
      0
            #Emergency_Stop
                               #Emergency_Stop
      ON
            #Motor_Healthy
                               #Motor_Healthy
      SPB
             _003
            #Actual_Stage
                               #Actual_Stage
      L
      _{\rm L}
            #Requested_Stage
                               #Requested_Stage
      <I
            _001
      SPB
      >I
            _002
      SPB
      ==I
      SPB
            _003
      SPA
            end1
_001: R
            #Brake
                               #Brake
                               #Move_forward
      S
            #Move_forward
            #Speed_1_Fast
                               #Speed_1_Fast
      S
      SPA
            end1
002: R
            #Brake
                               #Brake
      S
            #Move_backward
                               #Move_backward
      S
                               #Speed_1_Fast
            #Speed_1_Fast
            end1
      SPA
_003: R
            #Move_forward
                               #Move_forward
      R
            #Move_backward
                               #Move_backward
            #Speed_1_Fast
                               #Speed_1_Fast
      R
      R
            #Speed_2_Slow
                               #Speed_2_Slow
      S
            #Brake
                               #Brake
end1: NOP
Network: 3
                 Check motor health
      ON
            #Motor_Healthy
                             #Motor_Healthy
            #Motor_fault
      S
                             #Motor_fault
      0
            #Motor_Healthy
                             #Motor_Healthy
      R
            #Motor_fault
                             #Motor_fault
Network: 4
                 Stage count & actual stage
      U
            #Move_forward
                             #Move_forward
                             #Prox_sensor_2
      TT
            #Prox_sensor_2
      FΡ
            #Countup_FP
                             #Countup_FP
      SPB
             004
            #Move_backward
                             #Move_backward
      ŢŢ
      U
            #Prox_sensor_1
                             #Prox_sensor_1
            #Countdown_FP
      FP
                             #Countdown_FP
      SPB
             _005
            end2
      SPA
_004: L
            #Actual_Stage
                             #Actual_Stage
      INC
            #Actual_Stage
      т
                             #Actual_Stage
      SPA
            end2
```

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```
_005: L
            #Actual_Stage
                             #Actual_Stage
      DEC
      Т
            #Actual_Stage
                             #Actual_Stage
end2: NOP
            0
Network: 5
                 Automatic speed regulation (Closing to station)
      L
            #Requested_Stage
                               #Requested_Stage
                               #Actual_Stage
            #Actual_Stage
      L
      - T
      L
      ==I
      IJ
            #Move_forward
                               #Move_forward
      U
            #Prox_sensor_1
                               #Prox_sensor_1
      SPB
            _006
      L
            #Actual_Stage
                               #Actual_Stage
      L
            #Requested_Stage
                               #Requested_Stage
      -I
      L
      ==I
      TT
            #Move_backward
                               #Move_backward
      U
            #Prox_sensor_2
                               #Prox_sensor_2
      SPB
            _007
      SPA
            end3
_006: R
            #Speed_1_Fast
                               #Speed_1_Fast
            #Speed_2_Slow
      S
                               #Speed_2_Slow
      SPA
            end3
_007: R
            #Speed_1_Fast
                               #Speed_1_Fast
      S
            #Speed_2_Slow
                               #Speed_2_Slow
end3: NOP
            0
Network: 6
                 Speed regulation
      U
            #Speed_2_Slow #Speed_2_Slow
      R
            #Speed_1_Fast #Speed_1_Fast
Network: 7
                 Current stage
            #Actual_Stage #Actual_Stage
      L
      L
      ==I
      SPB
            008
      L
            #Actual_Stage
                          #Actual_Stage
      L
      ==I
      SPB
            #Actual_Stage
      L
                            #Actual_Stage
      L
      ==I
      SPB
             010
      L
            #Actual_Stage #Actual_Stage
      L
      ==I
      SPB
            _011
            end4
      SPA
_008: s
            #Stage_1_lamp
                            #Stage_1_lamp
            #Stage_2_lamp
                            #Stage_2_lamp
      R
      R
            #Stage_3_lamp
                            #Stage_3_lamp
      R
            #Stage_4_lamp
                           #Stage_4_lamp
      SPA
            end4
_009: R
            #Stage_1_lamp
                            #Stage_1_lamp
                            #Stage_2_lamp
      S
            #Stage_2_lamp
      R
            #Stage_3_lamp
                            #Stage_3_lamp
            #Stage_4_lamp
                            #Stage_4_lamp
      R
      SPA
            end4
_010: R
            #Stage_1_lamp
                            #Stage_1_lamp
```

R

S

#Stage_2_lamp

#Stage_3_lamp

#Stage_2_lamp
#Stage_3_lamp

R #Stage_4_lamp #Stage_4_lamp sPA end4

_011: R #Stage_1_lamp #Stage_1_lamp R #Stage_2_lamp R #Stage_3_lamp S #Stage_4_lamp #Stage_4_lamp end4: NOP 0

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