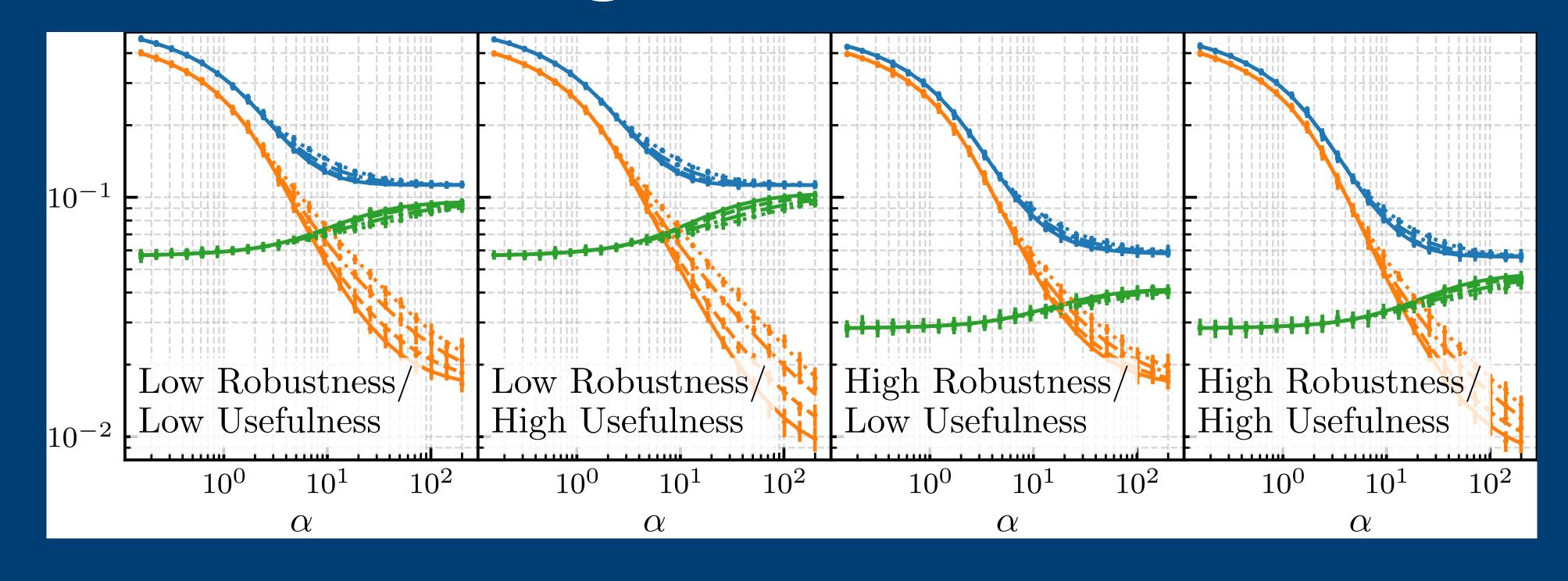
# A rigorous, closed-form characterisation of adversarial generalisation errors.



## A High Dimensional Statistical Model for Adversarial Training: Geometry and Trade-Offs

## **Problem Setup**

#### **Binary Classification Setting:**

- Training data  $\mathcal{D} = \{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^n \in \mathbb{R}^d \times \{-1, +1\}$
- Probit model with noise parameter  $\tau > 0$
- High-dimensional limit:  $d, n \to \infty$  with fixed  $\alpha = n/d$
- Structured data with block features: covariance matrices  $\Sigma_x$ ,  $\Sigma_{\delta}$ ,  $\Sigma_{v}$ ,  $\Sigma_{\theta}$  are block diagonal with k blocks of sizes  $d_1, \ldots, d_k$

#### **Metrics of Interest:**

- Generalisation Error:  $E_{gen} = \mathbb{E}_{y,x} \big[ \mathbb{1}(y \neq \hat{y}(\hat{\boldsymbol{\theta}}, \boldsymbol{x})) \big]$
- Adversarial Generalisation Error:  $E_{adv} = \mathbb{E}_{y,x} \left| \max_{\|\boldsymbol{\delta}\|_{\Sigma_{ol}^{-1}} \leq \varepsilon_g} \mathbb{1}(y) \right|$
- Boundary Error:  $E_{adv} = E_{gen} + E_{bnd}$  where  $E_{bnd}$  are the attackable samples.
- Usefulness and Robustness:

$$\mathcal{U}_{\boldsymbol{\theta}_0} = \frac{1}{\sqrt{d}} \mathbb{E}_{\boldsymbol{x}, y} [y \boldsymbol{\theta}_0^\top \boldsymbol{x}] , \qquad (1)$$

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$$\mathcal{R}_{\boldsymbol{\theta}_{0}} = \frac{1}{\sqrt{d}} \mathbb{E}_{\boldsymbol{x},y} \left[ \inf_{\|\boldsymbol{\delta}\|_{\boldsymbol{\Sigma}_{\boldsymbol{v}}^{-1}} \leq \varepsilon_{g}} y \boldsymbol{\theta}_{0}^{\top} (\boldsymbol{x} + \boldsymbol{\delta}) \right]. \qquad (2)$$

#### **Adversarial ERM:**

$$\sum_{i=1}^{n} g \left( y_{i} \frac{\boldsymbol{\theta}^{\top} \boldsymbol{x}_{i}}{\sqrt{d}} - \varepsilon_{t} \frac{\sqrt{\boldsymbol{\theta}^{\top} \boldsymbol{\Sigma}_{\delta} \boldsymbol{\theta}}}{\sqrt{d}} \right) + r(\boldsymbol{\theta}).$$
 (3)

#### Main Result

**Theorem:** Adversarial generalization errors are provably characterized by a system of 8 order parameters  $(m, q, V, P, \hat{m}, \hat{q}, \hat{V}, \hat{P})$  and an additional parameter A through:

$$E_{\mathrm{gen}} = \frac{1}{\pi} \arccos\left(m/\sqrt{(
ho + au^2)q}\right)$$
 , (4)

$$E_{\text{bnd}} = \int_0^{\varepsilon_g \frac{\sqrt{A}}{\sqrt{q}}} \operatorname{erfc}\left(\frac{-\frac{m}{\sqrt{q}}\nu}{\sqrt{2(\rho + \tau^2 - m^2/q)}}\right) \frac{e^{-\frac{\nu^2}{2}}}{\sqrt{2\pi}} \,\mathrm{d}\nu , \qquad (5)$$

## **Implications**

#### Trade-off between Usefulness Robustness:

- Usefulness relates to generalisation error.
- Robustness relates to boundary error.
- Trade-off emerges when protecting useful but non-robust features.

#### **Key Bounds:**

$$E_{\rm gen} \geq \frac{1}{\pi} \arccos\left(\sqrt{\frac{\pi}{2\rho}} \mathcal{U}_{\boldsymbol{\theta}_0}\right)$$
 (6)

$$E_{\text{bnd}} \leq 2\mathsf{T}\left(\varepsilon_{g}\mathcal{A}\mathcal{B}, \mathcal{A}^{-1}\right) - \frac{1}{\pi}\arctan(\mathcal{A}^{-1})$$

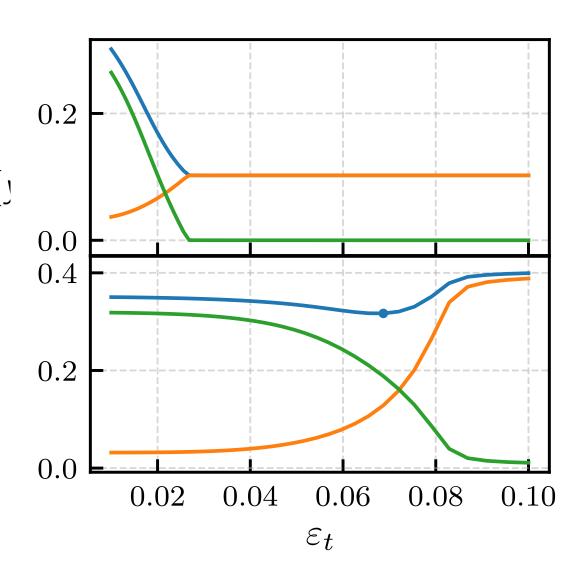
$$-\frac{1}{\pi}\operatorname{erf}\left(\frac{\varepsilon_{g}\mathcal{B}}{\sqrt{2}}\right)\operatorname{erfc}\left(\frac{\varepsilon_{g}\mathcal{A}\mathcal{B}}{\sqrt{2}}\right), \tag{7}$$

#### Directional Defences and structured data

**Key Finding:** The choice of defense strategy significantly impacts adversarial performance:

## Impact of different defense strategies on generalization ( $E_{gen}$ ) and boundary ( $E_{bnd}$ ) errors

- Defending robust features: Low  $E_{gen}$  but high  $E_{bnd}$
- Uniform defense: Better balance, improves overall  $E_{adv}$
- Defending non-robust features: Increases  $E_{qen}$  while decreasing  $E_{bnd}$



**Optimal defense** 

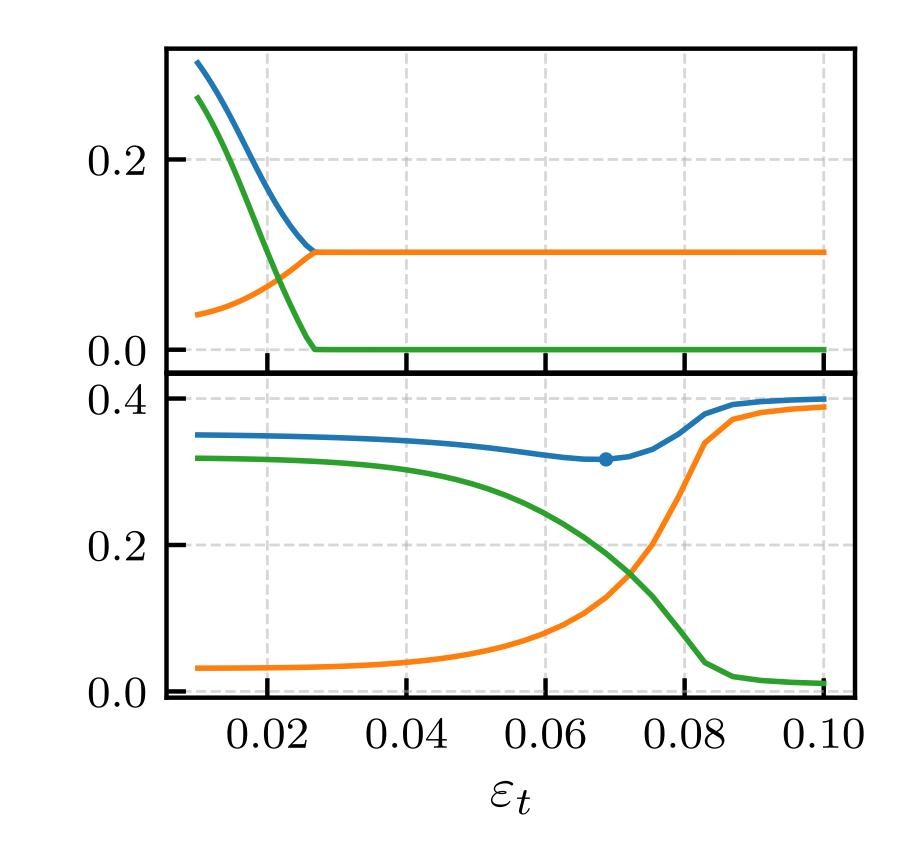
#### strategy depends on feature geometry

Analytical Result: For structured data with two feature blocks, we prove that protecting non-robust features:

- Always increases  $E_{gen}$  and decreases  $E_{bnd}$
- Can improve  $E_{adv}$  when attack size is small enough

#### Tradeoff directions and innocuous directions

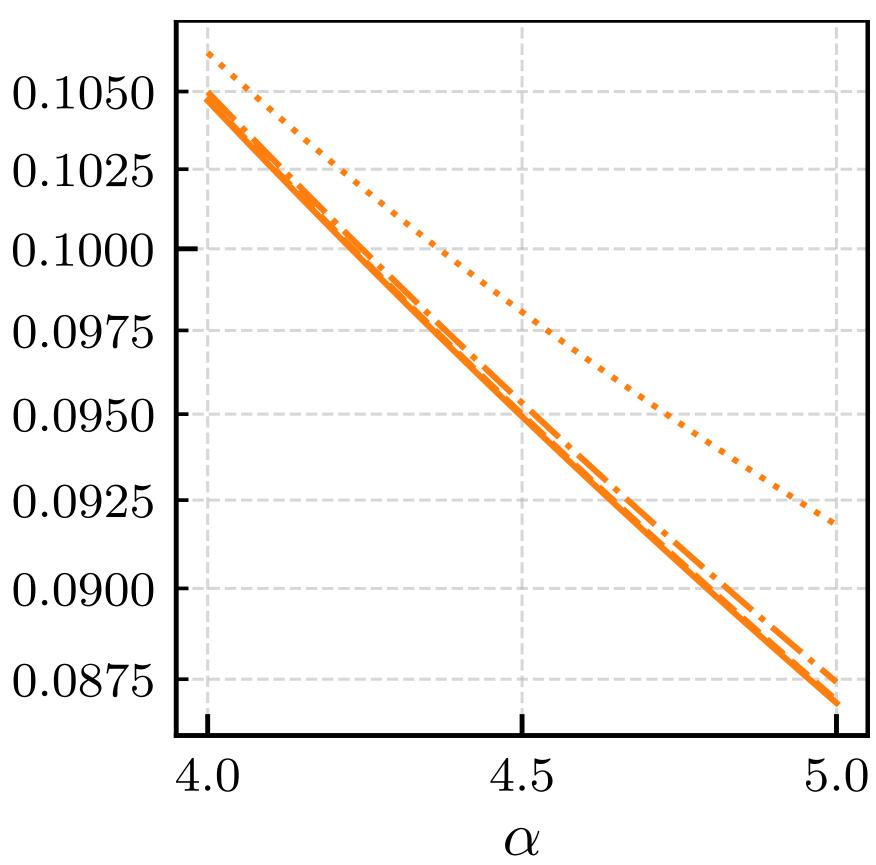
**Key Insight:** The geometry of features determines whether adversarial training leads to a trade-off:

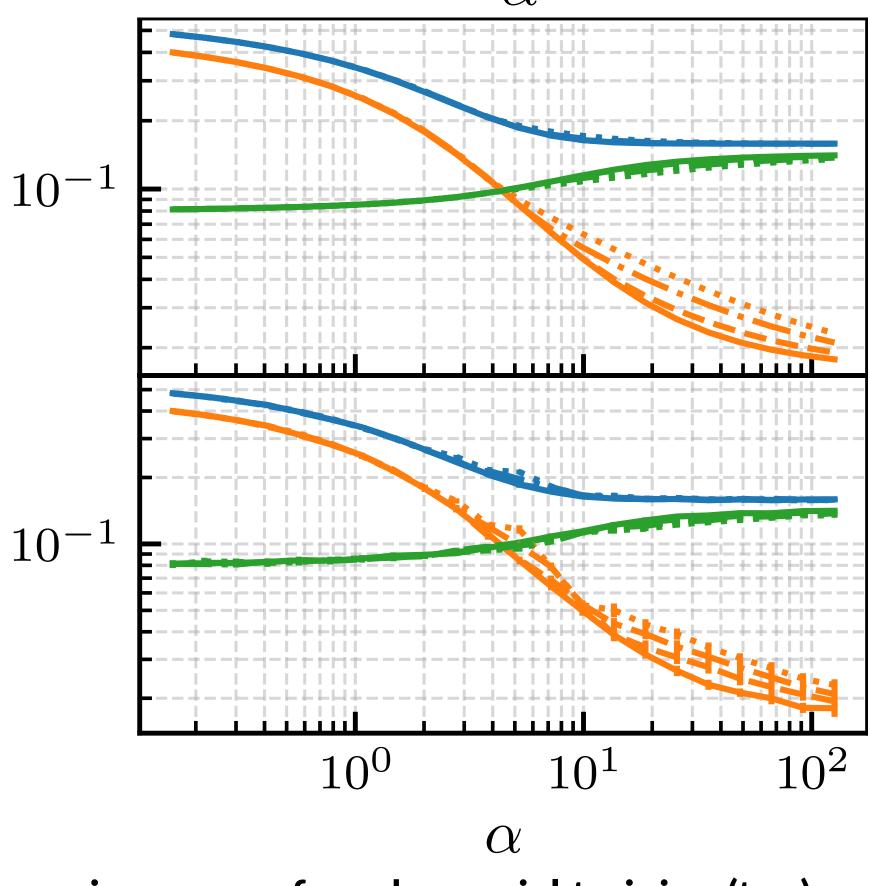


Impact of adversarial training on features with different geometries

#### **Two Distinct Cases:**

- Innocuous Features (orthogonal to teacher):
- Attack can be completely neutralized
- $E_{adv}$  →  $E_{gen}$  as  $\varepsilon_t$  increases





Learning curves for adversarial training (top) and its regularisation approximation (bottom)

#### **Approximate Loss:**

$$\sum_{i=1}^{n} g\left(y_{i} \frac{\boldsymbol{\theta}^{\top} \boldsymbol{x}_{i}}{\sqrt{d}}\right) + \tilde{\lambda}_{1} \sqrt{\boldsymbol{\theta}^{\top} \boldsymbol{\Sigma}_{\delta} \boldsymbol{\theta}} + \tilde{\lambda}_{2} \boldsymbol{\theta}^{\top} \boldsymbol{\Sigma}_{\delta} \boldsymbol{\theta}$$
(8)

#### **Key Properties:**

- Not just  $\ell_2$ : Performance depends on  $\varepsilon_t$  even with optimal  $\lambda$
- Effective Regularisation: is a directional  $\sqrt{\ell_2} + \ell_2$ regularisation.
- Non-sparse:  $\sqrt{\ell_2}$  term provides linear scaling in the norm of the student vector without sparsity

### Acknowledgements

Bruno Loureiro acknowledges support from the Choose France - CNRS AI Rising Talents program, and Florent Krzakala from the Swiss National Science Foundation grant SNFS OperaGOST (grant number 200390).



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