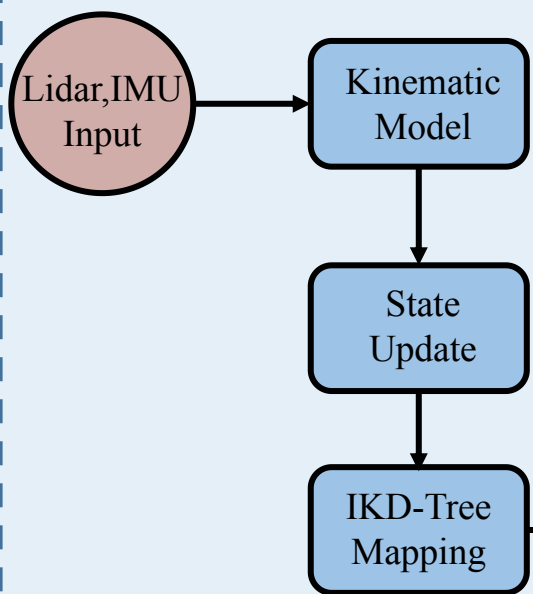
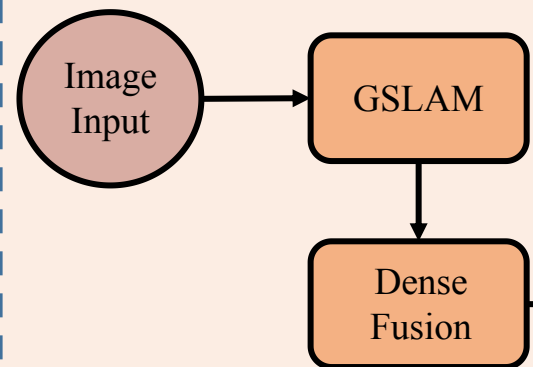


### A: Vision-Based SLAM



### B: Lidar-Based SLAM

### C: Cross-Source Registration

