USDHKD volatility surface build

Given market inputs:

• Spot: S_0

• Forward: F

• ATM Call price at strike K = F : $C_{
m mkt}$

• ATM Put price at strike K = F : $P_{\rm mkt}$

We want to solve for jump model parameters:

- p: probability of no jump
- q: probability of jump down -d
- d: log-jump size (assume symmetric, so +d and -d only

Model Assumptions

- ullet $U\sim \mathrm{Unif}[a,b]$, e.g. [7.75,7.85]
- Spot return:

$$S_T = e^{R_{ ext{jump}}} \cdot U$$

• Three-point jump:

$$R_{
m jump} = egin{cases} -d & ext{with prob } q \ 0 & ext{with prob } p \ +d & ext{with prob } 1-p-q \end{cases}$$

Step 1: Forward Constraint

From risk-neutral pricing:

$$F = \mathbb{E}[S_T] = \mu \cdot (qe^{-d} + p + (1-p-q)e^d) \quad ext{where } \mu = rac{a+b}{2}$$
 (1)

Step 2: ATM Call Pricing

$$C_{\text{mkt}} = q \cdot \Phi_{\text{call}}(F; -d) + p \cdot \Phi_{\text{call}}(F; 0) + (1 - p - q) \cdot \Phi_{\text{call}}(F; d)$$
 (2)

Step 3: ATM Put Pricing

$$P_{\text{mkt}} = q \cdot \Phi_{\text{put}}(F; -d) + p \cdot \Phi_{\text{put}}(F; 0) + (1 - p - q) \cdot \Phi_{\text{put}}(F; d)$$
(3)

Definitions of $\Phi_{\mathrm{call}}(K;x)$ and $\Phi_{\mathrm{put}}(K;x)$

Let
$$a_x=ae^x$$
 , $b_x=be^x$, $\Delta_x=b_x-a_x=\Delta e^x$:

$$\Phi_{
m call}(K;x) = egin{cases} rac{a_x + b_x}{2} - K, & K \leq a_x \ rac{(b_x - K)^2}{2\Delta_x}, & a_x < K < b_x \ 0, & K \geq b_x \end{cases} \ \Phi_{
m put}(K;x) = egin{cases} 0, & K \leq a_x \ rac{(K - a_x)^2}{2\Delta_x}, & a_x < K < b_x \ K - rac{a_x + b_x}{2}, & K \geq b_x \end{cases}$$

Calibration Strategy

Option A: Fix p=0

Then:

• From (1):

$$q = \frac{e^d - \frac{F}{\mu}}{e^d - e^{-d}} \tag{4}$$

• Plug into (2), (3) \rightarrow only unknown is d

Use root solver (Brent / Newton) to solve for d

Option B: General case (solve p, q, d)

1. Use (1) to eliminate p:

$$p=\frac{F}{\mu}-qe^{-d}-(1-p-q)e^d$$

2. Plug into (2), (3) \rightarrow Two equations, two unknowns: q, d

Use root finder / system solver (e.g. scipy.optimize.root)

Final Output

Once you solve for (p, q, d), you can:

- · Build full risk-neutral PDF
- · Price any vanilla option with closed-form
- · Generate implied vol surface
- Derive 25Δ RR, Fly, and Greeks

4. Case-by-Case Pricing Formula (7 Cases)

Let
$$a_{-d}=ae^{-d}$$
 , $b_{-d}=be^{-d}$, $a_0=a$, $b_0=b$, $a_d=ae^d$, $b_d=be^d$

Case 1: $K < ae^{-d}$

$$C(K)=q\left(rac{a_{-d}+b_{-d}}{2}-K
ight)+p\left(rac{a_0+b_0}{2}-K
ight)+(1-p-q)\left(rac{a_d+b_d}{2}-K
ight)$$

Case 2: $ae^{-d} \leq K < be^{-d}$

$$C(K) = q \cdot rac{(b_{-d} - K)^2}{2\Delta_{-d}} + p\left(rac{a_0 + b_0}{2} - K
ight) + (1 - p - q)\left(rac{a_d + b_d}{2} - K
ight)$$

Case 3: $be^{-d} \leq K < a$

$$C(K) = p\left(rac{a_0+b_0}{2}-K
ight) + (1-p-q)\left(rac{a_d+b_d}{2}-K
ight)$$

Case 4: $a \le K < b$

$$C(K) = p \cdot rac{(b_0-K)^2}{2\Delta_0} + (1-p-q)\left(rac{a_d+b_d}{2} - K
ight)$$

Case 5: $b \le K < ae^d$

$$C(K) = (1-p-q)\left(rac{a_d+b_d}{2}-K
ight)$$

Case 6: $ae^d \leq K < be^d$

$$C(K) = (1-p-q) \cdot rac{(b_d-K)^2}{2\Delta_d}$$

Case 7: $K \geq be^d$

$$C(K) = 0$$

Put cases follow symmetric logic using $\Phi_{\mathrm{put}}.$

5. Third Equation: Forward Constraint

The forward price (risk-neutral expectation of S_T):

$$F = \mathbb{E}[S_T] = q \cdot \mu e^{-d} + p \cdot \mu + (1-p-q) \cdot \mu e^d, \quad ext{where } \mu = rac{a+b}{2}$$

6. Calibration: Solve for (p, q, d)

Use three equations:

• Call price: $C_{
m mkt} = C(K=F)$

- Put price: $P_{\mathrm{mkt}} = P(K = F)$
- Forward equation above

General (p, q, d)

Minimize objective:

$$loss = (F_{model} - F)^2 + (C_{model} - C_{mkt})^2 + (P_{model} - P_{mkt})^2$$

Use scipy optimize minimize with constraints $p \geq 0$, $q \geq 0$, $p + q \leq 1$, d > 0

Output

- Exact analytical expressions for call/put across all strikes
- Can be used to compute:
 - Implied volatility surface
 - 25∆ Risk Reversal and Butterfly
 - Greeks: Delta, Vega, etc.

```
In [2]:
         import matplotlib.pyplot as plt
         from scipy.optimize import minimize
         # Define \Phi_call and \Phi_put for vectorized strike K and fixed x
         def phi call vector(K, x):
             ax = a * np.exp(x)
             bx = b * np.exp(x)
             Dx = bx - ax
             result = np.piecewise(K,
                                     [K \le ax, (K > ax) \& (K < bx), K >= bx],
                                    [lambda K: (ax + bx) / 2 - K,
                                     lambda K: (bx - K) ** 2 / (2 * Dx),
                                     0.0])
             return result
         def phi_put_vector(K, x):
             ax = a * np.exp(x)
             bx = b * np.exp(x)
             Dx = bx - ax
             result = np.piecewise(K,
                                    [K \le ax, (K > ax) \& (K < bx), K >= bx],
                                     lambda K: (K - ax) ** 2 / (2 * Dx),
                                     lambda K: K - (ax + bx) / 2])
             return result
         # Full 3-variable calibration: objective function
         def calibration_objective(x):
             p, q, d = x
             if p < 0 or q < 0 or (p + q > 1) or d \le 0:
                 return 1e6 # infeasible
             w0 = p
             w1 = q
             w2 = 1 - p - q
             f_{model} = mu * (w1 * np.exp(-d) + w0 + w2 * np.exp(d))
             c_{model} = w1 * phi_{call}(F, -d) + w0 * phi_{call}(F, 0) + w2 * phi_{call}(F, d)
             p_{model} = w1 * phi_put(F, -d) + w0 * phi_put(F, 0) + w2 * phi_put(F, d)
             return (f_model - F) ** 2 + (c_model - C_mkt) ** 2 + (p_model - P_mkt) **
```

```
# Initial guess: p, q, d
x0 = [0.5, 0.25, 0.01]
bounds = [(0, 1), (0, 1), (0.001, 1.0)]
res_full = minimize(calibration_objective, x0=x0, bounds=bounds)
p fit, q fit, d fit = res full.x
# Evaluate PDF over K for plotting
K_{vals} = np.linspace(7.70, 7.90, 200)
pdf vals = (
             q_fit / (b * np.exp(-d_fit) - a * np.exp(-d_fit)) * ((K_vals >= a * np.e
              p_{fit} / (b - a) * ((K_vals >= a) & (K_vals <= b)) +
              (1 - p_fit - q_fit) / (b * np.exp(d_fit) - a * np.exp(d_fit)) * ((K_vals))
# Plot the calibrated PDF
plt.figure(figsize=(8, 4))
plt.plot(K_vals, pdf_vals, label="Calibrated Risk-Neutral PDF")
plt.axvline(F, color='gray', linestyle='--', label='Forward (ATM strike)')
plt.title("Risk-Neutral Density for USD/HKD with Jump Model")
plt.xlabel("Strike K")
plt.ylabel("Density")
plt.legend()
plt.grid(True)
plt.tight_layout()
plt.show()
(p_fit, q_fit, d_fit)
```

```
NameError
                                           Traceback (most recent call last)
Cell In[2], line 44
     41 \times 0 = [0.5, 0.25, 0.01]
     42 bounds = [(0, 1), (0, 1), (0.001, 1.0)]
---> 44 res_full = minimize(calibration_objective, x0=x0, bounds=bounds)
     45 p_fit, q_fit, d_fit = res_full.x
     47 # Evaluate PDF over K for plotting
File ~/opt/anaconda3/envs/myenv/lib/python3.10/site-packages/scipy/optimize/
minimize.py:713, in minimize(fun, x0, args, method, jac, hess, hessp, bounds,
constraints, tol, callback, options)
            res = _minimize_newtoncg(fun, x0, args, jac, hess, hessp, callbac
k,
    711
                                     **options)
    712 elif meth == 'l-bfqs-b':
            res = _minimize_lbfgsb(fun, x0, args, jac, bounds,
--> 713
                                   callback=callback, **options)
    715 elif meth == 'tnc':
    716
            res = _minimize_tnc(fun, x0, args, jac, bounds, callback=callbac
k,
    717
                                **options)
File ~/opt/anaconda3/envs/myenv/lib/python3.10/site-packages/scipy/optimize/_
lbfgsb_py.py:309, in _minimize_lbfgsb(fun, x0, args, jac, bounds, disp, maxco
r, ftol, gtol, eps, maxfun, maxiter, iprint, callback, maxls, finite_diff_rel
_step, **unknown_options)
                iprint = disp
    308 # _prepare_scalar_function can use bounds=None to represent no bounds
--> 309 sf = _prepare_scalar_function(fun, x0, jac=jac, args=args, epsilon=ep
s,
    310
                                       bounds=bounds,
    311
                                       finite_diff_rel_step=finite_diff_rel_st
ep)
    313 func_and_grad = sf.fun_and_grad
    315 fortran_int = _lbfgsb.types.intvar.dtype
```

```
optimize.py:402, in _prepare_scalar_function(fun, x0, jac, args, bounds, epsi
        lon, finite_diff_rel_step, hess)
            398
                    bounds = (-np.inf, np.inf)
            400 # ScalarFunction caches. Reuse of fun(x) during grad
            401 # calculation reduces overall function evaluations.
         403
                                    finite diff rel step, bounds, epsilon=epsilon)
            405 return sf
        File ~/opt/anaconda3/envs/myenv/lib/python3.10/site-packages/scipy/optimize/_
        differentiable_functions.py:166, in ScalarFunction.__init__(self, fun, x0, ar
        gs, grad, hess, finite_diff_rel_step, finite_diff_bounds, epsilon)
                    self.f = fun_wrapped(self.x)
            165 self._update_fun_impl = update_fun
         --> 166 self._update_fun()
            168 # Gradient evaluation
            169 if callable(grad):
        File ~/opt/anaconda3/envs/myenv/lib/python3.10/site-packages/scipy/optimize/
        differentiable functions.py:262, in ScalarFunction. update fun(self)
            260 def _update_fun(self):
                    if not self.f_updated:
            261
         --> 262
                        self._update_fun_impl()
            263
                        self.f updated = True
        File ~/opt/anaconda3/envs/myenv/lib/python3.10/site-packages/scipy/optimize/
        differentiable_functions.py:163, in ScalarFunction.__init__.<locals>.update_f
        un()
            162 def update_fun():
         --> 163
                    self.f = fun_wrapped(self.x)
        File ~/opt/anaconda3/envs/myenv/lib/python3.10/site-packages/scipy/optimize/_
        differentiable_functions.py:145, in ScalarFunction.__init__.<locals>.fun_wrap
        ped(x)
            141 self_nfev += 1
            142 # Send a copy because the user may overwrite it.
            143 # Overwriting results in undefined behaviour because
            144 # fun(self.x) will change self.x, with the two no longer linked.
        --> 145 fx = fun(np.copy(x), *args)
            146 # Make sure the function returns a true scalar
            147 if not np.isscalar(fx):
        Cell In[2], line 35, in calibration_objective(x)
             33 \text{ w1} = q
             34 \text{ w2} = 1 - p - q
          -> 35 f_model = mu * (w1 * np.exp(-d) + w0 + w2 * np.exp(d))
             36 c_model = w1 * phi_call(F, -d) + w0 * phi_call(F, 0) + w2 * phi_call
        (F, d)
             37 p_{model} = w1 * phi_put(F, -d) + w0 * phi_put(F, 0) + w2 * phi_put(F, 0)
        d)
        NameError: name 'mu' is not defined
        # Consolidate all required functions and run global calibration again
In [3]:
         import numpy as np
         from scipy.optimize import minimize
         # Constants (based on prior session)
         a, b = 7.75, 7.85
         mu = 0.5 * (a + b)
         F = mu # Approximate ATM forward
         C_mkt = 0.025 # Example market ATM call price
         P_mkt = 0.020 # Example market ATM put price
         # Define elementary phi functions
         def phi_call(K, x):
             ax, bx = a * np.exp(x), b * np.exp(x)
```

```
Dx = bx - ax
    if K <= ax:
        return (ax + bx) / 2 - K
    elif ax < K < bx:</pre>
        return (bx - K)**2 / (2 * Dx)
    else:
        return 0.0
def phi_put(K, x):
    ax, bx = a * np.exp(x), b * np.exp(x)
    Dx = bx - ax
    if K <= ax:</pre>
        return 0.0
    elif ax < K < bx:</pre>
        return (K - ax)**2 / (2 * Dx)
        return K - (ax + bx) / 2
# Call price by region
def call_price_7case_with_label(K, p, q, d):
    components = []
    for x, label in zip([-d, 0.0, d], ['-d', '0', '+d']):
        ax, bx = a * np.exp(x), b * np.exp(x)
        Dx = bx - ax
        if K <= ax:
            value, region = (ax + bx) / 2 - K, "linear"
        elif ax < K < bx:</pre>
             value, region = (bx - K)**2 / (2 * Dx), "quadratic"
             value, region = 0.0, "zero"
        weight = q if label == '-d' else p if label == '0' else 1 - p - q
        components.append({
            "jump": label,
            "support": (ax, bx),
            "type": region,
            "weight": weight,
            "contrib": weight * value
        })
    total_price = sum(c["contrib"] for c in components)
    return total_price, components
# Generate 7 sample Ks across regions
def generate_strike_examples(d):
    return [
        a * np.exp(-d) - 0.01,
        (a * np.exp(-d) + b * np.exp(-d)) / 2,
        b * np.exp(-d) + 0.001,
        (a + b) / 2,
        b + 0.001,
        (a * np.exp(d) + b * np.exp(d)) / 2,
        b * np.exp(d) + 0.01
    ]
# Global calibration objective across all Ks
def global_calibration_loss(x, Ks, market_prices):
    p, q, d = x
    if not (0 \le p \le 1 \text{ and } 0 \le q \le 1 \text{ and } 0 \le p + q \le 1 \text{ and } d > 0):
        return 1e6
    total loss = 0
    for K, market_price in zip(Ks, market_prices):
        model_price, _ = call_price_7case_with_label(K, p, q, d)
        total_loss += (model_price - market_price)**2
    return total_loss
```

Out[3]: (0.05794801727223921, 0.0, 0.9420519827277608, 0.0028792238937540887)

In []: