Yiming Luo, Ph.D.

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Employment History

Sep/2019 - Present..

- Research Assistant X-CHI Lab (Leader: Prof. Hai-Ning Liang), Xi'an Jiao-tong Liverpool University, Suzhou, China.
- **Teaching Assistant** Department of Computer Science, Xi'an Jiao-tong Liverpool University, Suzhou, China.

Jul/2017 - Sep/2017

Intern Department of Engine, SAIC Motor Corporation Limited, Shanghai, China.

Education

Sep/2019 - Present..

Ph.D., University of Liverpool in Computer Science & Software Engineering. Thesis title: *Teleoperation of Mobile Unmanned Robots in Virtual Reality* Supervisor: Hai-Ning Liang, Professor, Xi'an Jiaotong-Liverpool University, Suzhou, China

Second Supervisor: Shan Luo, Associate Professor, King's College London, London, UK

Sep/2017 - Sep/2018

■ M.Sc., University of Southampton in Systems, Control & Signal Processing. Thesis title: Sensors for measurement of object gripping.

Sep/2015 - Jun/2017

B.Eng., University of Liverpool in Electrical & Electronics Engineering. Thesis title: *Control of a wind turbine for supporting power grid frequency*

Sep/2013 - Jun/2015

Y1 - Y2, Xi'an Jiaotong Liverpool University in Electrical & Electronics Engineering.

Project Work

Mar/2022 - Present..

Dynamic edges enhancement: A telepresence method based on two binocular depth cameras (Team)

Lead a team of postgraduates to enable dynamic edge enhancement of binocular images in UGV telepresence using depth information from two depth cameras.

Sep/2021 - Mar/2022

World-in-Miniature (WiM) technology in UGV teleoperation (Team) Lead a team of Ph.D. to investigate a remote manipulation method based on the visualization of the miniature virtual world and the grasping interaction of the miniature virtual surrogate of UGV.

Mar/2021 - Sep/2021

■ Complementary colors edge enhancement: an edge enhancement-based teleoperation method (Team)

Lead a team of postgraduates to investigate an edge enhancement for telepresence based on the theory of highlighting related to complementary colors.

Project Work (continued)

Sep/2020 – Mar/2021	AirNeck: a prototype for wind haptic feedback around human neck (Team)
	Lead a team of undergraduates to realize real-time wind haptic feedback on the human neck to simulate natural wind resistance during UGV teleoperation.
Mar/2020 – Sep/2020	Stereoscopic film: a binocular camera-based telepresence method (Team) Lead a team of undergraduates to realize real-time image transmission using a binocular camera and provide a perspective similar to a stereoscopic movie in a VR environment for UGV telepresence.
Sep/2019 – Mar/2020	Haptic on HMD: A distance perception method (Individual) Complete all software and hardware programming, constructions, and experimental site settings individually. Realize real-time distance perception using in-HMD vibro-tactile feedback during UGV teleoperation.
Mar/2018 – Sep/2018	Sensors for measurement of object gripping (Individual) Investigate the data visualization of measurement of object gripping with inertial measurement units (IMUs).
Mar/2017 – Sep/2017	Control of a wind turbine for supporting power grid frequency (Individual) Investigate the control of wind turbines to provide operations to achieve the maximum wind power extraction and provide constant power above the rated wind speed.
Sep/2015 – Sep/2016	Autonomous on-water vehicle for searching and mapping (Team) Lead a team and be responsible for the assembly and programming of the hardware and the setup of the experimental site. Implement automatic drawing and

Research Publications

Journal Articles

Luo, Y., Wang, J., Shi, R., Liang, H.-N., & Luo, S. (2022). In-device feedback in immersive head-mounted displays for distance perception during teleoperation of unmanned ground vehicles. *IEEE Transactions on Haptics*, 15(1), 79–84. **Ø** doi:10.1109/TOH.2021.3138590

visualization of real-time obstacle map.

Conference Proceedings

- Li, Z., Luo, Y., Wang, J., Pan, Y., Yu, L., & Liang, H.-N. (2022). Collaborative remote control of unmanned ground vehicles in virtual reality. In 2022 2nd international conference on interactive media, smart systems and emerging technologies (imet).
- **Luo, Y.,** Wang, J., Pan, Y., Luo, S., Irani, P., & Liang, H.-N. (2022). Teleoperation of a fast omnidirectional unmanned ground vehicle in the cyber-physical world via a vr interface. In *The 18th acm siggraph lnternational conference onvirtual-reality continuum and its applications in industry (vrcai 2022).*
- Liu, Y., Lin, Y., Shi, R., **Luo, Y.**, & Liang, H.-N. (2021). Relicvr: A virtual reality game for active exploration of archaeological relics. In *Extended abstracts of the 2021 annual symposium on computer-human interaction in play* (pp. 326–332). **6** doi:10.1145/3450337.3483507
- **Luo, Y.,** Wang, J., Liang, H.-N., Luo, S., & Lim, E. G. (2021). Monoscopic vs. stereoscopic views and display types in the teleoperation of unmanned ground vehicles for object avoidance. In 2021 30th ieee international conference on robot & human interactive communication (ro-man) (pp. 418–425). **6** doi:10.1109/RO-MAN50785.2021.9515455

In-Progress Papers

Under Review

Augmenting Performance of VR-mediated Teleoperation of Unmanned-Ground Vehicles Using Edge Detection

Preparing

- Supporting Awareness in the Virtual Environment: A Comprehensive Review Teleoperation of Mobile Unmanned Robots in Virtual Reality
- A Telepresence Method to Enhance Dynamic Edges Based on Binocular Depth Cameras
- Edge Enhancement for Improved Teleoperation of Unmanned Ground Vehicles Using Virtual Reality

Skills

Misc.

Tools ■ Unity3D, SPSS, MS, PS, LaTeX, Matlab, VICON···.

Academic research, teaching, training, consultation, LeTeX typesetting and publishing; Working out, playing and developing games...