3. I. full code in q-3.py \* data set is candomized with set seed before execution \*

```
knn(num_neighbour, metric, training_set, validation_set, test_set, sklearn = False):
validation_set, validation_class = np.hsplit(validation_set, np.array([3]))
validation_class = validation_class.reshape(-1)
training_set, training_class = np.hsplit(training_set, np.array([3]))
training_class = training_class.reshape(-1)
test_set, test_class = np.hsplit(test_set, np.array([3]))
test_class = test_class.reshape(-1)
# use sklearn if metric is None
if sklearn:
      neigh = KNeighborsClassifier(n_neighbors=num_neighbour, metric=metric)
      neigh.fit(training_set, training_class)
# calculate error in validation set
for i, x in enumerate(validation_set):
           class_sum = 1
     else:
k_neighbours = []
             # add distances of between validation point and all training poi
for j, y in enumerate(training_set):
    distance = metric(x, y)
    heapq.heappush(k_neighbours, (distance, training_class[j]))
                  rs__sum = 0

k in range(num_neighbour):
distance, classification = heapq.heappop(k_neighbours)
                  \label{prop:continuous} \textit{\# class\_sum finds if majority of neighbours will belong to the correct validation class \\ \textit{if classification} == \textit{validation\_class[i]:} \\
                   class_sum -= 1
            if neigh.predict(x.reshape(1, -1))[0] != test_class[i]:
                  class sum = 1
             k_neighbours = []
            k_merginuours = for j, y in enumerate(training_set):
    distance = metric(x, y)
    heapq.heappush(k_neighbours, (distance, training_class[j]))
                ass_sum = 0
rx k in range(num_neighbour):
    distance, classification = heapq.heappop(k_neighbours)
    if classification == test_class[i]:
                        class sum += 1
      if class_sum < 0:
    test_error += 1</pre>
return validation_error, test_error
```

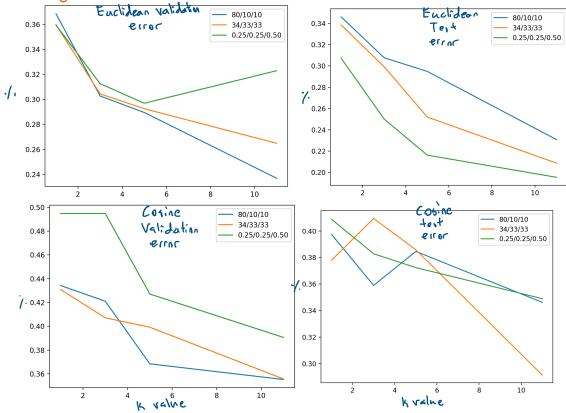
```
def euclid_dist(x, y):
    res = 0
    for i in range(x.shape[0]):
        res += pow((x[i] - y[i]), 2)
    return math.sqrt(res)
```

```
def cosine_sim(x, y):
    # subtract 1 for distance
    return 1 - (dot(x, y) / (norm(x) * norm(y)))
```

```
COI
                Validation Error
                                                 # of emm
      Endidian #: 28 cate:36.84.1.
                                    Error rate = # in validation set
                         43.42%
 SKL Eudidian
                21
                        36.84.1.
                         43.42%
 Shl Cosine
               Validation Error
   b)
      Endidian #: 91
                    rate: 35.971.
      Cosine
                        43.08%
  SKL Enclidian 91
                        35.97.1.
  SKL Cosine
                        43.08%
               Validation Error
   c)
      Endidian #:69
                    rate: 35,94%.
                       49.48./
      Cosine
   SKL Enclidion 69
                       35.941
   SKL Corine
                       49.48/
```

d) The combination of the split 25/25/50 and Enclidian distance as the metric works the best since it has the lowest error rate out of all the combination. Although it might be thought that a split of 80/10/10 would do the best, the results might be due to the number of neighbour only being I. Any single data point heavily infuences the prediction, so the number of data points in the training set matters loss.





The combination of k = 11, split = 80/10/10 and metrics = exclident distance results in the best model. It's validation is the lowest amongs models at  $\approx 244$ , and has fairly low test error rate. This is expected as with the number of neighbours increasing, singular datapoints have less of an impact, which gives the model with the higher amount of training data the advantage. This fact is reflected on the graphs above, as all errors decreased with increasing number of neighbours.