

Part2

a) let V_t of Adam equal to V_t of RMSprop
that is

$$\beta_2 V_{t-1} + (1 - \beta_2) g_t^2 = \gamma V_{t-1} + (1 - \gamma) g_t^2$$

so $\beta_2 = \gamma$

let Θ_t of Adam equal to Θ_t of RMSprop
then that is

$$\Theta_{t+1} - \alpha_A m_t / (\sqrt{V_t} + \epsilon_A) = \Theta_{t+1} - \alpha_R g_t / (\sqrt{V_t} + \epsilon_R)$$

so $m_t = g_t$, $\epsilon_A = \epsilon_R$, $\alpha_A = \alpha_R$,

By Adam, we know

$$m_t \leftarrow \beta_1 m_{t-1} + (1 - \beta_1) g_t$$

to make $m_t = g_t$, we need

$$\beta_1 = 0,$$

then we get hyperparameters $(\alpha_R, 0, \gamma, \epsilon_R)$

that matches $(\alpha_A, \beta_1, \beta_2, \epsilon_A)$

B) We want to make Adam approximately equivalent to momentum SGD, we need to find a set of $(\alpha, \beta_1, \beta_2, \epsilon_1)$ such that

$$\theta_t = \alpha m_t / (\sqrt{v_t} + \epsilon_1) \approx \theta_{t-1} + \alpha s P_t$$

then let $\alpha_s = \alpha$, we get

$$m_t / (\sqrt{v_t} + \epsilon_1) \approx P_t$$

According to the algorithms; we can get

$$(\beta_1 m_{t-1} + (1 - \beta_1) g_t) / \sqrt{\beta_2 v_{t-1} + (1 - \beta_2) g_t^2} + \epsilon_1 \approx - (M P_{t-1} - (1 - M) \nabla J(\theta_{t-1}))$$

let $\beta_2 = 1, \epsilon_1 = 1$ we can get

$$\frac{\beta_1 m_{t-1} + (1 - \beta_1) g_t}{\sqrt{v_{t-1}} + 1} \quad \text{where } v_{t-1} = v_t$$

By Adam, $v_0 = 0$, v_t will be 0 on all iterations.
then $\sqrt{v_{t-1}} + 1 = 1$

then we get

$$\underbrace{\beta_1 m_{t-1}}_{m_t} + (1 - \beta_1) g_t \approx - \underbrace{M P_{t-1}}_{-P_t} + (1 - M) g_t$$

let $\beta_1 = M$, if M is small enough, then they will be closer

Then we can find hyperparameters

$$(\alpha_s, M, 1, 1) \text{ where } M \rightarrow 0.$$

c) According to the question, we can denote the quantities as $\tilde{g}_t, \tilde{m}_t, \tilde{v}_t, \tilde{\theta}_t$
WTS for $E_A = 0$, Adam is invariant to rescaling.
that is $\tilde{\theta}_t = \theta_t$ for $\forall t \in \mathbb{N}$, by hint we can use induction.

Base case:

$$\text{let } m_0 = \tilde{m}_0 = v_0 = \tilde{v}_0 = 0, \tilde{\theta}_0 = \theta_0$$

$$\text{WTS } \tilde{\theta}_1 = \theta_1$$

$$\text{We know } \tilde{g}_1 = C \nabla J(\tilde{\theta}_0)$$

$$\text{then } = C \nabla J(\theta_0) \text{ since } \tilde{\theta}_0 = \theta_0$$

$$= C g_1$$

$$\tilde{m}_1 = \beta_1 \tilde{m}_0 + (1 - \beta_1) \tilde{g}_1 \quad (\tilde{m}_0 = 0)$$

$$= (1 - \beta_1) C g_1$$

$$m_1 = \beta_1 m_0 + (1 - \beta_1) g_1$$

$$= (1 - \beta_1) g_1$$

$$\text{then } \tilde{m}_1 = C m_1$$

$$\tilde{v}_1 = \beta_2 \tilde{v}_0 + (1 - \beta_2) \tilde{g}_1^2$$

$$= (1 - \beta_2) C^2 g_1^2 \quad (\tilde{v}_0 = 0)$$

$$v_1 = \beta_2 v_0 + (1 - \beta_2) g_1^2$$

$$= (1 - \beta_2) g_1^2$$

$$\text{then } \tilde{v}_1 = C^2 v_1$$

$$\tilde{\theta}_1 = \tilde{\theta}_0 - \alpha_A \tilde{m}_1 / (\sqrt{\tilde{v}_1} + E_A) \quad (E_A = 0)$$

$$= \theta_0 - \alpha_A m_1 / \sqrt{v_1} \quad (\text{By above})$$

$$= \theta_0 - \alpha_A m_1 / \sqrt{v_1}$$

$$= \theta_0 - \alpha_A m_1 / (\sqrt{v_1} + E_A) = \theta_1$$

I.S.

$$I.H. \quad \tilde{\theta}_{t+1} = \theta_t, \quad \tilde{m}_{t+1} = C m_{t+1}, \quad \tilde{v}_{t+1} = C^2 v_{t+1}$$

$$\text{WIS: } \theta_t = \theta_t$$

$$\text{we get } g_t = C \nabla J(\tilde{\theta}_{t+1}) \quad (\tilde{\theta}_{t+1} = \theta_t)$$

$$= C \nabla J(\theta_t)$$

$$= C g_t$$

$$\tilde{m}_t = \beta_1 \tilde{m}_{t-1} + (1 - \beta_1) \tilde{g}_t$$

$$= \beta_1 C m_{t-1} + (1 - \beta_1) C g_t \quad (\text{By I.H.})$$

$$= C (\beta_1 m_{t-1} + (1 - \beta_1) g_t)$$

$$= C m_t$$

$$\tilde{v}_t = \beta_2 \tilde{v}_{t-1} + (1 - \beta_2) \tilde{g}_t^2$$

$$= \beta_2 C^2 v_{t-1} + (1 - \beta_2) C^2 g_t^2 \quad (\text{By I.H.})$$

$$= C^2 (\beta_2 v_{t-1} + (1 - \beta_2) g_t^2)$$

$$= C^2 v_t$$

$$\text{then } \tilde{\theta}_t = \theta_{t-1} - \alpha_A \tilde{m}_t / (C \sqrt{v_t} + \epsilon_A) \quad (\epsilon_A = 0)$$

$$= \theta_{t-1} - \alpha_A C m_t / \sqrt{v_t}$$

$$= \theta_{t-1} - \alpha_A m_t / (\sqrt{v_t} + \epsilon_A)$$

$$= \theta_t$$

then we get Adam is invariant
to this rescaling 