1. b, 5*6 + 6 = 36

1. 0 0 0 for
$$l=2$$
, $S_{j}^{2} = \sum_{i=1}^{j} S_{k}^{2+i} W_{jk}^{2+i}$, $j=1,2,...6$

1. 0 0 0 0 $l=1$, $S_{j}^{2} = \sum_{k=1}^{j} S_{k}^{2+i} W_{jk}^{2+i}$ ton $h(S_{j}^{2})$, $j=1,2...5$

0 0 0 $l=1$, $S_{j}^{2} = \sum_{k=1}^{j} S_{k}^{2+i} W_{jk}^{2+i}$ ton $h(S_{j}^{2})$, $j=1,2...5$

0 0 $l=1$, $l=1$,

2. e, current max = 1219, dp program Ans: 2 layers, first 33, second 17.



Code:

```
import numpy as np
      DP = np.zeros((51,50))
      layers = np.zeros((51,50))
       def max_weight(hidden, first_layer):
          out_layer = 3
          if DP[hidden][first_layer] != 0:
               return DP[hidden][first_layer]
           tmp_max = (first_layer + 1) * (hidden - 1) + hidden * out_layer
          # print((hidden,first_layer,tmp_max))
          i = 1
          current_layer = 0
          while i < hidden:
              # print((hidden-2*i-2,i+1))
               dp = max_weight(hidden - i - 1, i) + (first_layer + 1) * i
               if dp > tmp_max:
                   tmp_max = dp
                   current_layer = i
               DP[hidden][first_layer] = tmp_max
20
              layers[hidden][first_layer] = current_layer
               i += 1
          return tmp_max
      <u>if name == ' main ':</u>
          print(_max_weight(50,19)_)
          layer = layers[50][19]
          print(layer+1)
          while layer != 1:
               if layers[int(50-int(layer)-1)][int(layer)] == 0:
                   print(50-layer-1)
                  break
               else:
                  layer = layers[int(50 - int(layer) - 1)][int(layer)]
                   print(layer)
36
```

$$evr(x,y) = -\frac{k}{\sum_{k=1}^{k}} v_k l_n \varrho_k, \quad \frac{\partial evr(x,y)}{\partial s_k^{\perp}} = \frac{\partial}{\partial s_k^{\perp}} v_k l_n \left(\frac{evps_k}{\sum_{k=1}^{k}}\right), \quad \text{other term will be}$$

$$\frac{\partial}{\partial s_k^{\perp}} evr = \frac{\partial}{\partial s_k^{\perp}} \left(l_n(evp(s_k)) - l_n \left(\frac{s_k^{\perp}}{\sum_{k=1}^{k}} evp(s_k^{\perp})\right)\right) v_k = \left(1 - \frac{evps_k}{\sum_{k=1}^{k}} evps_k^{\perp}\right) (v_k)$$

$$= -v_k + \varrho_k = \varrho_k - v_k$$

4. a, since the term is always multiplied by weight with 0, the answer is zero.

4.
$$x_0$$
 $x_0^{\frac{1}{2}}$ all neurons are zeros.

 $W_0^{\frac{1}{2}} = W_0^{\frac{1}{2}} - \eta x_0^{\frac{1}{2}} S_1^{\frac{1}{2}} = 0 - 1 \cdot 1 \cdot S_1^{\frac{1}{2}}$
 $S_1^{\frac{1}{2}} = \sum_{k=1}^{4} S_k^{\frac{1}{2}} W_{1k}^{\frac{1}{2}} t_{anh}^{\frac{1}{2}} (1 - \delta_0)$
 $W^{\frac{1}{2}}$
 $W^{\frac{1}{2}}$

5. e

5.
$$f(x) = \int_{W_{m}}^{\infty} \left(r_{nm} - \omega_{m}^{T} \nabla_{n} \right)^{2}, \quad \frac{\partial}{\partial W_{m}} \sum_{n} \left(r_{nm} - W_{m}^{T} \nabla_{n} \right)^{2} = 0, \quad \sum_{n} \left(r_{nm} - W_{m}^{T} \nabla_{n} \right) = 0$$

$$\sum_{n} r_{nm} = \sum_{n}^{\infty} W_{m}^{T} \nabla_{n} = \sum_{n}^{\infty} W_{m}^{T} \cdot 2 = 2n \cdot W_{m}^{T}, \quad \frac{1}{2} \frac{\sum_{n}^{\infty} r_{nm}}{n} = W_{m}^{T} \times \infty$$

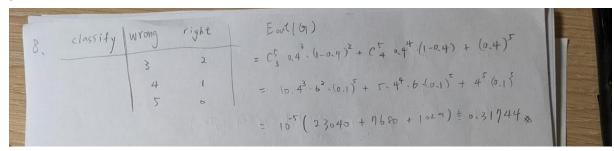
6. b

6.
$$\frac{\partial}{\partial a_{m}} \operatorname{err} = 2 \left(r_{nm} - w_{m}^{T} v_{n} - a_{m} - b_{n} \right) \cdot (-1)$$
, $d_{m} \leftarrow d_{m} - \left(\frac{h}{2} \right) \frac{\partial}{\partial a_{m}} \operatorname{err}$

$$a_{m} \leftarrow a_{m} + \eta \left(r_{nm} - w_{n}^{T} v_{n} - a_{m} - b_{n} \right)$$

$$= \left(1 - \eta \right) a_{n} + \eta \left(r_{nm} - w_{n}^{T} v_{n} - b_{n} \right) \times$$

8. c



9. b

9.
$$(1-\frac{1}{N})^{0.5N} = ((1-\frac{1}{N})^{N})^{0.5} = (\frac{1}{e})^{0.5} = 06065$$

10. e, because there is no the same answer as what I derived.

The |xi' - xi| / 2 in the last row should be |xi' - xi|, since I forgot to add two cases together, so there will be no answer according to all answers except (e).

10:
$$\phi_{ds}(x) T \phi_{ds}(x') = \sum \sum \sum sisign(x'_2 - \theta) sign(x'_2 - \theta) = \sum \sum sisn(x'_2 - \theta)(x'_2 - \theta)$$

$$|x'_2 - x_1| = numbers \cdot f \theta \text{ will cause value } t - 1, \frac{2R - 1 - \epsilon 2L + 1}{2} + 1 = R - L$$

$$(R - L) - |x'_2 - x'_2| = numbers \cdot f \theta \text{ will cause value } t \cdot 1$$

$$S = \pm 1 \text{ is the same, and there are } d \text{ dim.}$$

$$\sum_{l=1}^{d} ((R - L) - |x'_2 - x'_2|) = 2d(R - L) - ||x'_2 - x'_1||_{L^2}$$

11. a

$$\sum_{N=1}^{N} M_{n}^{t} \left[y_{n} t g_{t}(x_{n}) \right] / \sum_{N=1}^{N} M_{n}^{t} \left[y_{n} t g_{t}(x_{n}) \right] = U_{t} \left[1 - 2t \right]$$

$$\frac{U_{t+1}}{U_{t}} = \frac{1}{N} \sum_{n=1}^{N} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t} g_{t}(x_{n}) \right) - \frac{1}{N} \sum_{n=1}^{\xi_{t}} t x_{n} \left(-y_{n} \frac{1}{\xi_{t}} \sqrt{t$$

13. d

13.
$$|MAX \circ f| - |MA - M - | = 1$$
, when $|MA = M - = 0.5$
if $|MA > M - | - |MA - M - | = 1 - M + M - = 2M - |MA = 1 - M - |MA = 1 - M - |MA - M - | = 2M + |MA = 2M + |MA = 1 - M - |MA = 1 - |MA - M - | = 2M + |MA = 2M + |MA = 1 - |MA$

14. c

```
yiwenlai@YiWens-MacBook-Pro ~/Desktop/hw6 INSERT
14: 0.166
15: 0.229115
16: 0.014
17: 0.155
18: 0.072
```

```
train_x, train_y, test_x, test_y = dataloader()
root = DecisionTree(train_x,train_y,'','root')
err_count = 0
for i in range(test_x.shape[0]):
   node = root
   result = 0
   while(True):
       i_feature, s, theta = node.data
        result = np.sign(test_x[i][i_feature] - theta) * s
        if result > 0:
           if node.right == None:
               break
           node = node.right
       else:
           if node.left == None:
               break
           node = node.left
   if result != test_y[i]:
       err_count += 1
print('Q14: ', err_count/1000)
```

```
# Q14 predict
print('Q14')
print('=======train========')
root = DecisionTree(train_x,train_y,'','root')
print(root.data)
print("=======predict=======")
err_count = 0
for i in range(test_x.shape[0]):
   node = root
    result = 0
   while(True):
       i_feature, s, theta = node.data
       result = np.sign(test_x[i][i_feature] - theta) * s
       if result > 0:
           if node.right == None:
               # print('here')
               break
           node = node.right
       else:
           if node.left == None:
               # print('here')
               break
           node = node.left
    # print(i, result)
    if result != test_y[i]:
       err_count += 1
print('Eout ', err_count/1000)
```

16. a

```
root_list = []
for t in range(10):
    bag = []
    while(len(bag)<500):
        r = np.random.randint(0, 1000, 1)
        if r not in bag:
            bag.append(r[0])
    # print(len(bag))
    part_x, part_y = [], []
    # print(train_x.shape[0])
    for i in range(train_x.shape[0]):
        if i in bag:
            part_x.append(train_x[i])
            part_y.append(train_y[i])
    part_x, part_y = np.array(part_x), np.array(part_y)
    # print(part_x.shape, part_y.shape)
    root = DecisionTree(part_x, part_y, '', 'root')
    root_list.append(root)
```

```
err_count = 0
for i in range(train_x.shape[0]):
    tmp_in = 0
    for root in root_list:
        node = root
        result = 0
        while (True):
            i_feature, s, theta = node.data
            result = np.sign(test_x[i][i_feature] - theta) * s
            if result > 0:
                if node.right == None:
                    break
                node = node.right
                if node.left == None:
                    break
                node = node.left
        tmp_in += result
    if np.sign(tmp_in) != train_y[i]:
        err_count += 1
print('Q16: '_err_count / 1000)
```

```
err_count = 0
for i in range(test_x.shape[0]):
   tmp_out = 0
   for root in root_list:
       node = root
        result = 0
       while (True):
            i_feature, s, theta = node.data
            result = np.sign(test_x[i][i_feature] - theta) * s
            if result > 0:
                if node.right == None:
                    # print('here')
                    break
                node = node.right
           else:
                if node.left == None:
                    # print('here')
                    break
                node = node.left
        # print(i, result)
        tmp_out += result
   if np.sign(tmp_out) != test_y[i]:
        err_count += 1
print('Q17: '_err_count / 1000)
```

18. b

```
root_list = []
bag_list = []
for t in range(200):
    bag = []
    while(len(bag) < 500):</pre>
        r = np.random.randint(0, 1000, 1)
        if r not in bag:
            bag.append(r[0])
    # print(len(bag))
    part_x, part_y = [], []
    # print(train_x.shape[0])
    for i in range(train_x.shape[0]):
        if i in bag:
            part_x.append(train_x[i])
            part_y.append(train_y[i])
    part_x, part_y = np.array(part_x), np.array(part_y)
    # print(part_x.shape, part_y.shape)
    root = DecisionTree(part_x, part_y, '', 'root')
    root_list.append(root)
    bag_list.append(bag)
err_count = 0
```

```
for i in range(train_x.shape[0]):
    tmp_roots = []
    for j in range(len(bag_list)):
        if i not in bag_list[j]:
            tmp_roots.append(root_list[j])
    if len(tmp_roots) == 0:
        if -1 != train_y[i]:
            err_count += 1
    else:
        tmp_in = 0
        for root in tmp_roots:
            node = root
            result = 0
            while (True):
                i_feature, s, theta = node.data
                result = np.sign(test_x[i][i_feature] - theta) * s
                if result > 0:
                    if node.right == None:
                        break
                    node = node.right
                else:
                    if node.left == None:
                        # print('here')
                        break
                    node = node.left
            # print(i, result)
            tmp_in += result
        if np.sign(tmp_in) != train_y[i]:
            err_count += 1
print('Q18: '_err_count / 1000)
```

19. d

感覺是較為成熟且許多人在使用的概念,並且有搭配上圖做說明,讓學生學習時容易 理解。

20. b

可能是課程規劃緣故,沒有做太多深入地講解,但這節的概念對初步了解推薦系統似乎有幫助,對期末比賽也是。