

# Lec 6.

## Warm up

$$A = [\vec{a}_1 \ \vec{a}_2], \quad \vec{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{a}_2 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

- ① Columns of  $A$  lin. indep.? **YES.**
- ② " " " span  $\mathbb{R}^2$ ? **NO.**
- ③ " " " span  $\mathbb{R}^3$ ? **No.**

Linear indep.

span

$\{\vec{v}_1, \dots, \vec{v}_k\}$  lin. indep. in  $\mathbb{R}^n$

$\Leftrightarrow [\vec{v}_1, \dots, \vec{v}_k; \vec{0}]$  has  
unique, trivial sol  $\vec{0}$

$\Rightarrow k \leq n$

$\{\vec{v}_1, \dots, \vec{v}_k\}$  spans  $\mathbb{R}^n$

$\Leftrightarrow$  for any  $\vec{b} \in \mathbb{R}^n$   
 $\vec{b} = x_1 \vec{v}_1 + \dots + x_k \vec{v}_k$

$\Leftrightarrow [\vec{v}_1, \dots, \vec{v}_k; \vec{b}]$  always has sol

$\Rightarrow k \geq n$

deleting vectors helps

adding vectors helps.

# Linear transformation

$$A x = b.$$

Focus on properties of  $A$ .

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Map / Mapping / Transformation.

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\vec{x} \in \mathbb{R}^n \mapsto T(\vec{x}) \in \mathbb{R}^m$$

Matrix transformation.

$A$  of size  $m \times n$ .

$$T(\vec{x}) := A \vec{x} := x_1 \vec{a}_1 + \dots + x_n \vec{a}_n$$

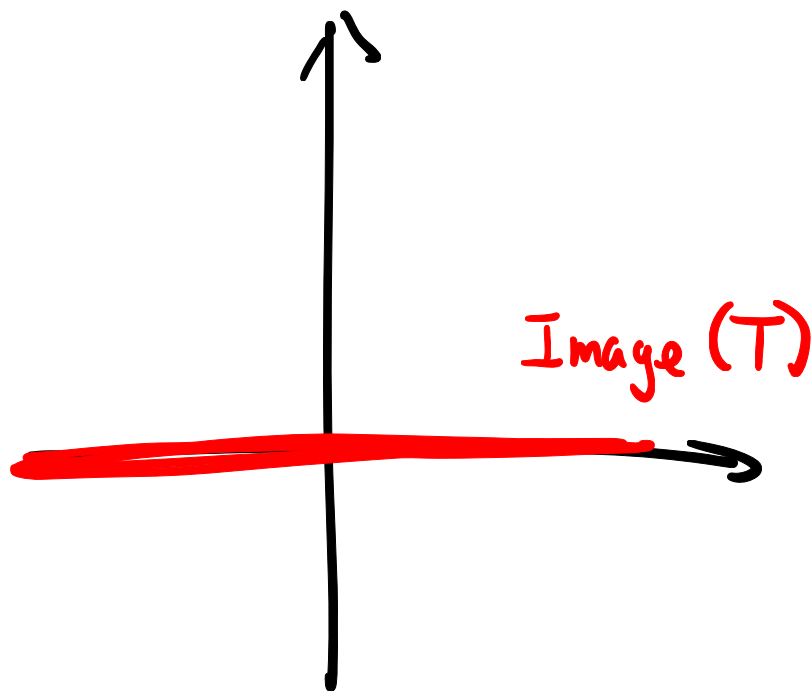
$$\text{Image}(T) = \{ \vec{b} \in \mathbb{R}^m \mid \text{there exists } \vec{x} \in \mathbb{R}^n \\ \text{s.t. } \vec{b} = T(\vec{x}) \}.$$

$$\text{Ex. } A = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$T: \mathbb{R} \rightarrow \mathbb{R}^2$$

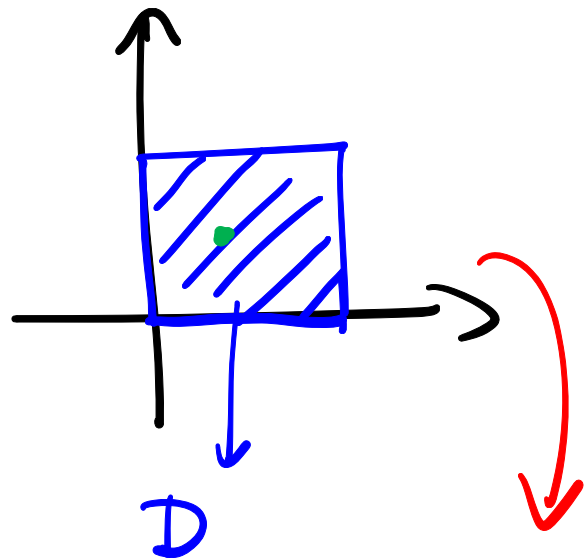
$$x \mapsto Ax = \begin{bmatrix} x \\ 0 \end{bmatrix}$$

Image (T) ?

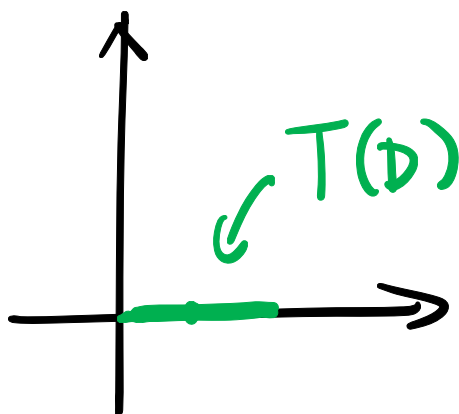


$$\text{Ex. } A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix},$$

$$T(\vec{x}) = A \vec{x} = x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} x_1 \\ 0 \end{bmatrix}$$



what  $T(D) := \{ \vec{b} \mid \text{there exists } \vec{x} \in D \text{ s.t. } T(\vec{x}) = \vec{b} \}$

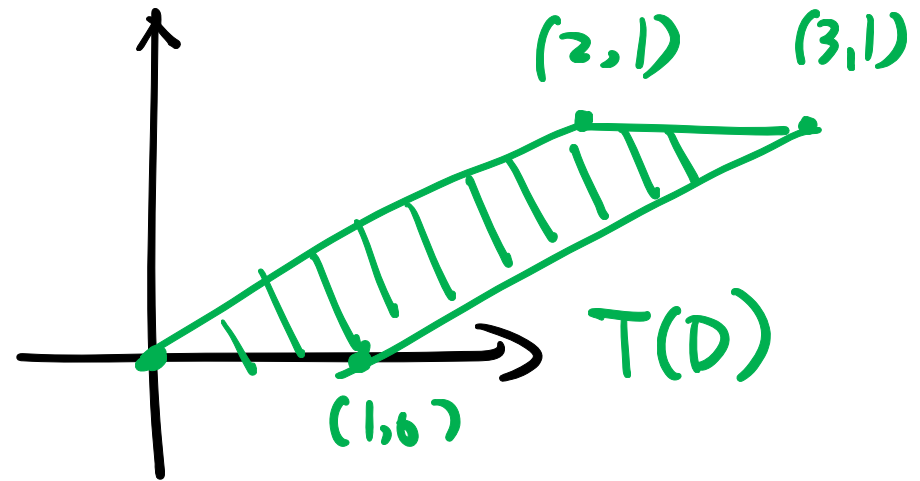
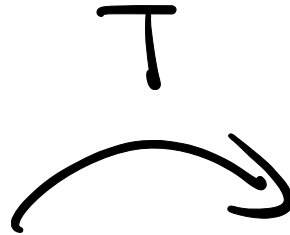
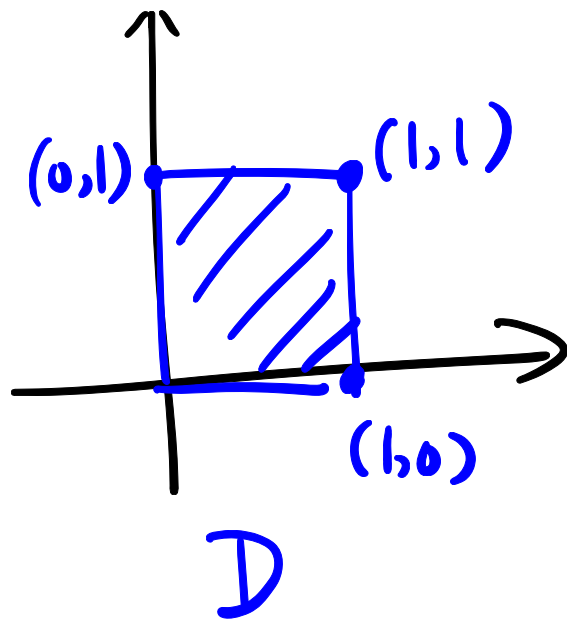


projection.

Ex. shearing.

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

$$A \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 + 2x_2 \\ x_2 \end{bmatrix}$$



## Properties of matrix trans.

$$\vec{u}, \vec{v} \in \mathbb{R}^n, \quad A \quad m \times n, \quad c \in \mathbb{R}$$

$$(1) \quad A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v}$$

$$(2) \quad A(c\vec{u}) = c(A\vec{u}).$$

Linearity.  $\forall c_1, c_2 \in \mathbb{R}, \vec{u}, \vec{v} \in \mathbb{R}^n$

$$A(c_1\vec{u} + c_2\vec{v}) = c_1(A\vec{u}) + c_2(A\vec{v})$$























