

# Yichong SUN

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The Chinese University of Hong Kong  
Faculty of Medicine  
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Education    **The Chinese University of Hong Kong**  
                  Ph.D. in Medical Robotics, 2022.08 - Current  
                  Faculty of Medicine  
                  Supervisor: Prof. Li Zheng and Prof. Yip Honchi

**Harbin Institute of Technology**  
M.Sc. in Mechanical Engineering, 2020.09 - 2022.07  
School of Mechatronics Engineering

**Chongqing University**  
B.Eng. in Mechanical Design and Automation, 2016.09 - 2020.07  
College of Mechanical and Vehicle Engineering

Interests    **Medical Robotics**  
**System Design and Control**  
**Learning Method for Robotic-Assisted Surgery**

Teaching    **Teaching Assistant for MSc course (BMEG 5750)**  
                  Medical Robotics, The Chinese University of Hong Kong, 2023-2025

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## Selected Publications

1. **Y. Sun**, Y. Xian et al. A MagsL-HUD Endoscopic System for Magnetic Compression Anastomosis Surgery in Unstructured Endoluminal Environment. *IEEE Transactions on Robotics*, 2025
2. **Y. Sun**, R. Xu et al. A Novel Wireless Magnetic Leader Device for Six-DoF Robotic Tele-operation Control with Expandable Workspace. *IEEE Transactions on Automation Science and Engineering*, 2025
3. **Y. Sun**, L. Li et al. Design and In-Vivo Validation of Clinically Wireless Localization System for Magnetic Robots: A Reconfigurable Sensor Array Approach. *IEEE/ASME Transactions on Mechatronics*, 2025
4. R. Xu, **Y. Sun** et al. Whole-Body Model Predictive Control for Magnetically Actuated Robotic Endoscope. *IEEE/ASME Transactions on Mechatronics*, 2025
5. Y. Xian, **Y. Sun** et al. Task Automated Stereotactic Brain Biopsy Robotic System with CLF-CBF-Based Safety-Critical Neuronavigation. *IEEE/ASME Transactions on Mechatronics*, 2025

6. L. Nie, H. Wang, **Y. Sun**. Switched LPV Resilient Tracking Control for Rigid-Body with Defective Actuators and Sensors. *Journal of the Franklin Institute*, 2025
7. **Y. Sun**, W. Chan et al. An Octopus-Inspired-Configuration Sensor Array Concept toward Torso-Oriented Magnetic Localization Task and Simulation Verification. *IEEE/RSJ IROS*, 2024
8. W. Chan, **Y. Sun** et al. Robotic Flexible Magnetic Retractor for Dynamic Tissue Manipulation in Endoscopic Submucosal Dissection. *IEEE ICRA*, 2025
9. X. Ren, T. Pan, **Y. Sun** et al. Simultaneous Locomotion with Stiffness Perception of an Earthworm-Like Robot in a Soft Tubular Environment. *Soft Robotics*, 2025
10. Y. Li, WY. Ng, **Y. Sun** et al. Colon Lumen Center Detection Enables Autonomous Navigation of an Electromagnetically Actuated Soft-Tethered Colonoscope. *IEEE Trans. on Instrumentation and Measurement*, 2024
11. **Y. Sun**, M. Xie et al. Design and Control of Deformable Quadrotor with Varying Length Arms. *Science China Technological Sciences*, 2023
12. **Y. Sun**, Y. Li et al. Model-Based Bending Control of Magnetically-Actuated Robotic Endoscopes for Automatic Retroflexion in Confined Spaces. *IEEE/RSJ IROS*, 2023
13. **Y. Sun**, B Cai, et al. Bumpless Transfer Control for a Class of Hybrid Stochastic Systems and Application to Electromagnetic Oscillation Circuit. *IECON 2021*, 2021

## US Patents

1. A wirelessly magnetic location-aware system using reconfigurable sensor array technique. *Status: Pending*
2. System and method for endoluminal magnetic compression anastomosis. *Status: Pending*
3. System and method for endoluminal tissue manipulation. *Status: Pending*
4. System and method for automatic stomach screening. *Status: Pending*

## Selected Honors

- Gold Medal, 49th International Exhibition of Inventions of Geneva (First Author)
- Third Prize, 10th Hong Kong University Student Innovation and Entrepreneurship Competition (Team Leader)
- Silver Medal, 49th International Exhibition of Inventions of Geneva (Second Author)
- National First Prize, 14th National Undergraduate NXP Smart Car Competition
- Outstanding Graduate, Chongqing University, Class of 2020
- Excellent Graduate Student Leader, Chongqing University, Class of 2020