

# Yicong Hong

Ph.D. in Computer Science at CECC, ANU

**Vision-and-Language, Text/Image-to-3D Generation, Embodied AI**

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## EDUCATION

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### Ph.D. in Computer Science

*Australian National University*

Chair: Prof. Stephen Gould, Supervisors: Prof. Qi Wu, Prof. Lexing Xie

Thesis: Learning Language-Guided Visual Navigation.

### Embodied Vision-and-Language

*Feb 2019 - July 2023*

### Bachelor of Engineering (First-Class Honours)

*Australian National University*

GPA: 6.594 / 7

Thesis: Marker-Less Human Pose and Shape Visualisation from Multi-View Images.

### Major in Mechatronics Systems

*Feb 2015 - Nov 2018*

## EXPERIENCE

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### Professional.....

#### Research Internship

*Adobe Research - San Jose, United States*

- Text/Occupancy map guided 3D shape generation via latent diffusion.
- Learning generic representations for single image-to-3D reconstruction.

#### Language/Image-to-3D Reconstruction

*Mar 2023 - Jun 2023*

#### Research Internship

*Adobe Research - San Jose, United States*

- Representation learning and contrastive learning for visual navigation.

#### Visual Representation Learning

*Mar 2022 - Nov 2022*

#### Student Researcher

*Australian Center for Robotic Vision (ACRV)*

- Recurrent BERT, graph neural networks, vision-language pre-training.

#### Vision-and-Language Navigation

*Feb 2019 - Dec 2020*

#### Research Internship/Student

*Data61, Commonwealth Scientific and Industrial Research Organisation*

- 3D human pose and shape visualization from multi-view images.

#### Human Pose and Shape

*Nov 2017 - Nov 2018*

### Teaching.....

#### Teaching Assistance

*College of Engineering and Computer Science, ANU*

- Running labs and tutorials, designing and marking students' assignments, organizing group projects.

#### Deep Learning (ENGN8536)

*2019 & 2020*

#### Postgraduate and PhD Student Advisor

*Australian National University & University of Adelaide*

- Zun Wang: ICCV2023 and CVPR2022 publication in VLN, winner of the RxR Habitat Challenge.
- Gengze Zhou: Applying LLMs in visual navigation.
- Bahram Mohammadi: Applying external knowledge graph for navigation.

#### Vision-and-Language Navigation

*2021 - 2023*

#### Guest Lectures

*College of Engineering and Computer Science, ANU*

- COMP6490 Document Analysis, 2021. & ENGN8536 Deep Learning, 2020.

#### Vision-and-Language Research

*2020 - 2021*

## SELECTED WORKS

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### **LRM: Large Reconstruction Model for Single Image to 3D** (*Preprint 2023*)

- Yicong Hong, Kai Zhang, Jiuxiang Gu, Sai Bi, Yang Zhou, Difan Liu, Feng Liu, Kalyan Sunkavalli, Trung Bui, Hao Tan.
- Build transformer-based large vision model to predict 3D shape of an object in an image.

### **A Recurrent Vision-and-Language BERT for Navigation** (*CVPR 2021 Oral*)

- Yicong Hong, Qi Wu, Yuankai Qi, Cristian Rodriguez-Opazo, Stephen Gould.
- Build recurrence into Transformers for sequential decision-making in navigation.

### **Bridging the Gap Between Learning in Discrete and Continuous Envs for VLN** (*CVPR 2022*)

- Yicong Hong, Zun Wang, Qi Wu, Stephen Gould.
- Propose a waypoint predictor to enable high-level actions in continuous environments.

### **Language and Visual Entity Relationship Graph for Agent Navigation** (*NeurIPS 2020*)

- Yicong Hong, Cristian Rodriguez-Opazo, Yuankai Qi, Qi Wu, Stephen Gould.
- A graph neural network to model language-object/scene-action correspondence in navigation.

### **NavGPT: Explicit Reasoning in Vision-and-Language Navigation with LLMs** (*AAAI 2023*)

- Gengze Zhou, Yicong Hong, Qi Wu.
- Use GPT-3.5 and GPT-4 to reason and zero-shot sequential navigation tasks.

### **Learning Navigational Visual Representations with Semantic Map Supervision** (*ICCV 2023*)

- Yicong Hong, Yang Zhou, Ruiyi Zhang, Franck Deroncourt, Trung Bui, Stephen Gould, Hao Tan.
- Encoders trained with contrastive learning between agent's egocentric views and top-down maps.

### **Scaling Data Generation in Vision-and-Language Navigation** (*ICCV 2023 Oral*)

- Zun Wang, Jialu Li, Yicong Hong\*, Yi Wang, Qi Wu, Mohit Bansal, Stephen Gould, Hao Tan, Yu Qiao.
- Generate 4.9 million instruction-trajectory pairs to boost agent's R2R success rate to 80%.
- \*Project Lead: Initialized the project and coordinated collaboration among five institutes.

## ADDITIONAL

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### Websites.....

**Open Source Projects** <https://github.com/YicongHong>

### Award.....

- **CVPR'2022** 1st Place Winner of the (RxR) Habitat Challenge in the Embodied AI workshop.
- **ICCV'2021, CVPR'2021** Outstanding reviewer.
- **NVIDIA Academic Hardware Grant 2022.**

### Services.....

#### **Reviewer & Program Committee**

- CVPR'(23,22,21), ICCV'(23,21), ICLR'(24,23,22), ICRA'22, AAAI'(24,23,22,21), WACV'24, EMNLP'21, SpLU-RoboNLP'21, TNNLS'21, ECCV'20, DICTA'20.

## REFEREES

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**Prof. Stephen Gould** - Australian National University - ✉ Email: [stephen.gould@anu.edu.au](mailto:stephen.gould@anu.edu.au)

**Prof. Qi Wu** - University of Adelaide - ✉ Email: [qi.wu01@adelaide.edu.au](mailto:qi.wu01@adelaide.edu.au)

**Dr. Hao Tan** - Adobe Research - ✉ Email: [hatan@adobe.com](mailto:hatan@adobe.com)

**Prof. Nick Barnes** - Australian National University - ✉ Email: [nick.barnes@anu.edu.au](mailto:nick.barnes@anu.edu.au)