

Yide Gu

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EDUCATION

University of Michigan-Ann Arbor (UM)	Michigan, US	Sep. 2018-Dec. 2020
Master of Science in Computer Science and Engineering		GPA: 3.85/4.00
Master of Science in Mechanical Engineering (dual master's degree)		GPA: 3.90/4.00
Shanghai Jiao Tong University (SJTU)	Shanghai, China	Sep. 2014-Aug. 2018
Bachelor of Science in Electrical and Computer Engineering		GPA: 3.60/4.00

WORKING EXPERIENCE

Sodexo USA, Maryland	<i>Technical Solution Engineer</i>	May 2020-Aug. 2020
<ul style="list-style-type: none">Analyzed financial data and provided suggestion from engineering perspectiveDesigned database to store COVID-19 related transactions and generated reportsProductionized MapReduce pipeline to generate and preprocess training data for the model		
Panasonic Coop, Shanghai	<i>Research Engineer</i>	May 2018-Aug. 2018
<ul style="list-style-type: none">Developed a system to fulfill gesture recognition task under complex backgroundSegmented hand gestures from complicated background by using computer vision algorithmsDesigned the structure for CNN (VGG16 model) to classify gestures and verified its accuracyDelivered an interactive game application to demonstrate improved classification performance		
Shanghai General Motor, Shanghai	<i>System Engineer</i>	Jun. 2017-Aug. 2017
<ul style="list-style-type: none">Consolidated management system of powertrain control departmentImproved backend services implementation and optimized tree data structure stored in databaseImplemented line detection for road recognition using feature extraction techniquesDesigned and deployed the entire employment management pipeline		

RESEARCH EXPERIENCE

4 Progress Robotics Lab Research Assistant, UM	Prof. Chad Jenkins	May 2019-Aug. 2019
<ul style="list-style-type: none">Developed novel Scene-Graph based Partially Observable Monte Carlo Process (SG-POMCP) method to solve POMDP problem with scene graph as prior knowledgeConsolidated remote communication system between ROS robot agent and end-usersFormulated and implemented belief-state updates by using particle filter methodsVisualized robot trajectory and environment by using publisher/subscriber pattern and RVIZ		
Deep Learning Lab Assistant, UM	Prof. Honglak Lee	Feb. 2019-May 2019
<ul style="list-style-type: none">Integrated and trained an outperforming Monocular Depth Estimation model for 3D object detection and depth estimationEvaluated different machine learning algorithms (regression, clustering, SVM, etc.) and implemented CNN, RNN, LSTM, style transfer, GAN, CVAE neural network modelsEnhanced Mask-RCNN algorithm to detect 3D bounding box using data sampled from a single camera and generated the corresponding left/right image with GAN model		
Robotics Institute of SJTU, SJTU	Prof. Fu Zhuang	Jul. 2016-Aug. 2016
<ul style="list-style-type: none">Researched on multiple heuristic search algorithms to improve AI perception-action strategies which improved performance of a professional service robotDesigned circuits and feedback loops of the control system and optimized parameters of Mecanum wheels to achieve high accuracy in speed control of the omnidirectional mobile robot		

PROGRAMMING PROJECTS

Web Application Development	Jan. 2020-Apr. 2020
<ul style="list-style-type: none">Designed an application using flask framework and deployed on AWSImplemented MapReduce tasks using Python processes, threads libraries and developed communication between master and worker servers using sockets libraryBuilt a search engine with index server and Hadoop framework to generate inverted index	

TECHNICAL SKILLS

- Environments: Linux, Windows, Android
- Languages/tools: C/C++, Python, C#, Java, Assembly (Arm Thumb2, LC2K), Verilog, SQL, html, CSS, JavaScript, Vue, Bootstrap, jquery, MATLAB, MySQL, SQLite3, gdb, git, MapReduce, AWS