V1: Last Edited: 2024-01-25

Changes: v0 -> v1 Q2: Remove the data point that cause log(0) Q1: three -> four

- Deadline: Feb 5, at 23:59PM.
- Submission: You need to submit your solutions through Crowdmark, including all your derivations, plots, and your code. You can produce the files however you like (e.g. LATEX, Microsoft Word, etc), as long as it is readable. Points will be deducted if we have a hard time reading your solutions or understanding the structure of your code.
- Collaboration policy: After attempting the problems on an individual basis, you may discuss and work together on the assignment with up to two classmates. However, you must write your own code and write up your own solutions individually and explicitly name any collaborators at the top of the homework.

Q1 - Decision Theory

One successful use of probabilistic models is for building spam filters, which take in an email and take different actions depending on the likelihood that it's spam.

Imagine you are running an email service. You have a well-calibrated spam classifier that tells you the probability that a particular email is spam: p(spam|email). You have four options for what to do with each email: You can list it as important email, show it to the user, put it in the spam folder, or delete it entirely.

Depending on whether or not the email really is spam, the user will suffer a different amount of wasted time for the different actions we can take, L(action, spam):

Action	Spam	Not spam
Important	15	0
Show	5	1
Folder	1	40
Delete	0	150

Q1.1

[3pts] Plot the expected wasted user time for each of the three possible actions, as a function of the probability of spam: p(spam.

|email)

```
In [19]:
```

```
import numpy as np
import matplotlib.pyplot as plt
```

```
In [20]:
```

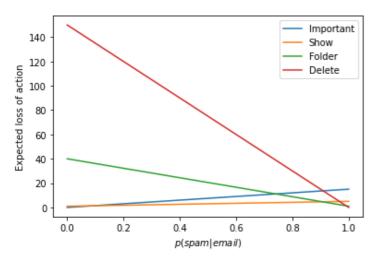
```
#@title
losses = [[15, 0],[5, 1], [1, 40],[0, 150]]
actions_names = ['Important','Show', 'Folder', 'Delete']
num_actions = len(losses)
def expected_loss_of_action(prob_spam, action):
    #TODO: Return expected loss over a Bernoulli random variable
    # with mean prob_spam.
    # Losses are given by the table above.
    return losses[action][1]*(1-prob_spam)+losses[action][0]*prob_spam

prob_range = np.linspace(0., 1., num=600)
```

```
# Make plot
for action in range(num_actions):
   plt.plot(prob_range, expected_loss_of_action(prob_range, action), label=actions_names
[action])
plt.xlabel('$p(spam|email)$')
plt.ylabel('Expected loss of action')
plt.legend()
```

Out[20]:

<matplotlib.legend.Legend at 0x7fd32b133040>



Q1.2

[2pts] Write a function that computes the optimal action given the probability of spam.

```
In [21]:
```

```
def optimal_action(prob_spam):
    #TODO: return best action given the probability of spam.
#Hint: np.argmin might be helpful.
loss=[]
for action in actions_names:
    index = actions_names.index(action)
    loss.append(expected_loss_of_action(prob_spam, index))
    return actions_names[np.argmin(loss)]
```

Q1.3

[4pts] Plot the expected loss of the optimal action as a function of the probability of spam.

Color the line according to the optimal action for that probability of spam.

In [22]:

```
prob_range = np.linspace(0., 1., num=600)
Prob, Loss = [[], [], [], []], [[], [], []] #partition
optimal_losses = []
optimal_actions = []

# TODO: Compute the optimal action and its expected loss for
# probability of spam given by p.

#use a dictionary to combine the action with index
actions_name_dict = {'Important': 0,'Show': 1, 'Folder': 2, 'Delete': 3}
optimal_actions = [optimal_action(p) for p in prob_range]
for index in range(len(optimal_actions)):
```

```
action_index = actions_name_dict[optimal_actions[index]]
optimal_losses.append(expected_loss_of_action(prob_range[index], action_index))
Prob[action_index].append(prob_range[index])
Loss[action_index].append(optimal_losses[index])

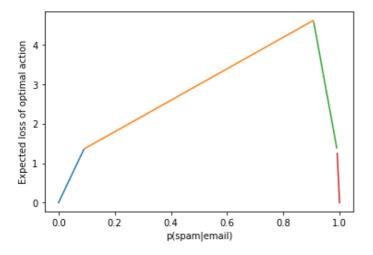
colors = ['red', 'green', 'blue', 'black']
for inputPindex in range(len(Prob)):
   plt.plot(Prob[inputPindex], Loss[inputPindex])

plt.xlabel('p(spam|email)')
plt.ylabel('Expected loss of optimal action')

#plt.plot(prob_range, optimal_losses, color = )
```

Out[22]:

Text(0, 0.5, 'Expected loss of optimal action')



Q1.4

[4pts] For exactly which range of the probabilities of an email being spam should we delete an email?

Find the exact answer by hand using algebra.

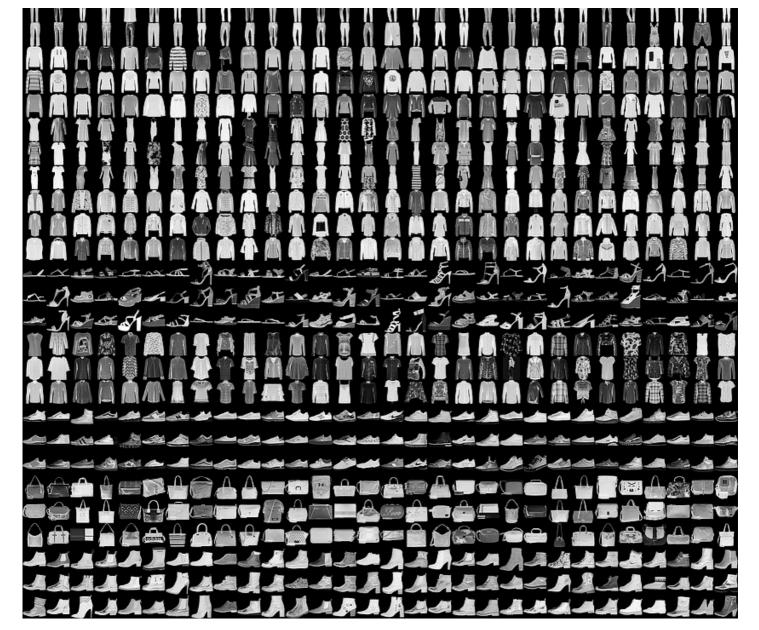
[Type up your derivation here]

Your answer:

By definition of optimal action, we need to find the action which minimize the loss. Then, if we need to delete an email, we must make sure that deleting action is the optimal action, which means $E(Loss|Delete) \le E(Loss|Important)$, E(Loss|Show) and E(Loss|Folder).\ E(Loss|Important) = 15 P(spam|email) + 0 (1-P(spam|email)) = E(Loss|Show) = 5 P(spam|email) + 1 (1-P(spam|email)) = E(Loss|Show) = 1 E(Loss|Show) =

Q2 - Naïve Bayes, A Generative Model





In this question, we'll fit a Naïve Bayes model to the fashion MNIST dataset, and use this model for making predictions and generating new images from the same distribution. MNIST is a dataset of 28x28 black-and-white images of items of clothing. We represent each image by a vector $x^{(i)} \in \{0,1$, where 0 and 1 represent white

and black pixels respectively. Each class label $c^{(i)}$ is a different item of clothing, which in the code is represented by a 10-dimensional one-hot vector.

The Naïve Bayes model parameterized by θ and π defines the following joint probability of x and c,

$$egin{aligned} p(x,c| heta,\pi) \ &= p(c|\pi)p(x) \ &|c, heta) \ &= p(c|\pi) \ \prod_{j=1}^{784} p(x_j|c, \ heta). \end{aligned}$$

where $x_j|c, heta$ or in other words $p(x_j|c, heta)$, and $c|\pi$ follows a simple categorical distribution, i.e.

$$\sim$$
 Bernoulli $= heta_{jc}^{x_j}(1 \ (heta_{jc}) \ - heta_{jc})^{1-x_j}$

 $p(c|\pi) = \pi_c$.

We begin by learning the parameters $\,\theta$ and $\,\pi$. The following code will download and prepare the training and test sets.

```
In [23]:
import numpy as np
import os
import gzip
import struct
import array
import matplotlib.pyplot as plt
import matplotlib.image
from urllib.request import urlretrieve
def download(url, filename):
   if not os.path.exists('data'):
       os.makedirs('data')
    out file = os.path.join('data', filename)
    if not os.path.isfile(out file):
       urlretrieve (url, out file)
def fashion mnist():
   base url = 'http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/'
    def parse labels(filename):
        with gzip.open(filename, 'rb') as fh:
            magic, num data = struct.unpack(">II", fh.read(8))
            return np.array(array.array("B", fh.read()), dtype=np.uint8)
    def parse images(filename):
        with gzip.open(filename, 'rb') as fh:
            magic, num_data, rows, cols = struct.unpack(">IIII", fh.read(16))
            return np.array(array.array("B", fh.read()), dtype=np.uint8).reshape(num_dat
a, rows, cols)
    for filename in ['train-images-idx3-ubyte.gz',
                     'train-labels-idx1-ubyte.gz',
                     't10k-images-idx3-ubyte.gz',
                     't10k-labels-idx1-ubyte.gz']:
        download(base_url + filename, filename)
    train images = parse images('data/train-images-idx3-ubyte.gz')
    train labels = parse labels('data/train-labels-idx1-ubyte.gz')
    test images = parse images('data/t10k-images-idx3-ubyte.gz')
    test labels = parse labels('data/t10k-labels-idx1-ubyte.gz')
    # Remove the data point that cause log(0)
    remove = (14926, 20348, 36487, 45128, 50945, 51163, 55023)
    train_images = np.delete(train_images,remove, axis=0)
    train_labels = np.delete(train_labels, remove, axis=0)
    return train images, train labels, test images[:1000], test labels[:1000]
def load fashion mnist():
   partial flatten = lambda x: np.reshape(x, (x.shape[0], np.prod(x.shape[1:])))
   one hot = lambda x, k: np.array(x[:, None] == np.arange(k)[None, :], dtype=int)
    train images, train labels, test images, test labels = fashion mnist()
    train images = (partial flatten(train images) / 255.0 > .5).astype(float)
    test images = (partial flatten(test images) / 255.0 > .5).astype(float)
    train labels = one hot(train labels, 10)
    test labels = one hot(test labels, 10)
   N_data = train_images.shape[0]
```

[2pts] Derive the expression for the Maximum Likelihood Estimator (MLE) of $\,\theta$ and $\,\pi$.

return N data, train images, train labels, test images, test labels

[Type up your derivation here]

Your answer:

Suppose we have N objects $x^{(i)}$ with labels $C^{(i)}$, The likelihood function can be represented as $L(\theta,\pi) = \frac{n}{||} P(\chi^{(i)}, C^{(i)} | \theta, \pi)$ Then the log-likelihood function is $\mathcal{L}(\theta, \mathbb{T}) = \log(L) = \sum_{i=1}^{N} \log P(x^{(i)}, c^{(i)} | \theta, \mathbb{T})$ $= \sum_{i=1}^{N} \left[\log \left(P(C^{(i)} | \pi) \prod_{i=1}^{184} P(\mathcal{X}_{i}^{(i)} | C, \Theta) \right) \right]$ Since each class label $C^{(i)}$ is a different item of clothing, and we have to different types, $P\left(C^{(t)}=c\mid \pi\right)=\prod_{c=0}^{q}\mathbb{E}_{c}^{1\left\{ C^{(t)}=c\right\} }$ Then, deriving the log-likelihood function, $\mathcal{L}(\Theta, \pi) = \sum_{i=1}^{N} \left[\log P(C^{(i)}|\pi) + \log \left(\prod_{i=1}^{|\mathcal{B}|} P(X_{i}^{(i)}|C^{(i)}, \Theta) \right) \right]$ $=\sum_{i=1}^{N}\left[\mathbb{1}(\hat{C}^{i})^{i}\hat{C}\sum_{c=1}^{q}\log_{j}\mathbb{T}_{c}+\sum_{c=1}^{18^{d}}\left[\hat{\chi}_{i}^{(i)}\log_{j}\theta_{jc}+\left(1-\chi_{j}^{(i)}\right)\log_{j}\left(1-\theta_{jc}\right)\right]\right]$ We know the MLE of π and θ are separable, so we can compute MLE of IL and Dic independently MLE of θ_{ir} before taking the derivative respect to θ_{jc} , we need to understand that the value of Θ is determined by $j \in [1,784]$ (pixels, integer) and $C \in [0.9]$ (class, integer only). to make the expression of Θ_{jc} more rigorious. I'll use a new variable K to represent the pixel. $\frac{\partial}{\partial \theta_{i}} \mathcal{L} = \sum_{j=1}^{N} \sum_{k=1}^{N+4} \frac{\partial}{\partial \theta_{i}} \left[\chi_{k}^{(i)} \log \theta_{k} c^{(i)} + (|-\chi_{k}^{(i)}|) \log (|-\theta_{k} c^{(i)}|) \right]$ when $k \neq j \Rightarrow$ this pixel doesn't contribute to parameter θ . when k=j, the MLE is valid with 1{C'0-c} $= \underbrace{\sum_{i=1}^{N} \left[\left(\chi_{i}^{(i)} - \theta_{jc}^{(i)} \right) \ \mathbf{1} \left\{ c^{a_{i}^{2}} c \right\} \right]}_{\sum_{i=1}^{N} \left[\theta_{jc}^{a_{i}} \left(\left[+ \theta_{jc}^{a_{i}} \right) \ \mathbf{1} \left\{ c^{a_{i}^{2}} c \right\} \right] \right]}_{\left[\theta_{jc}^{a_{i}^{2}} \right]} = O$ There fore, we solve above get $\underbrace{\left\{ \sum_{i=1}^{N} \left[\chi_{i}^{(i)} \mathbf{1} \left\{ c^{a_{i}^{2}} c \right\} \right] \right\}}_{\left[\theta_{jc}^{a_{i}^{2}} \right]} = O$ MLE of TE : We still a new variable k. K has range 0 29, represents class. $=\sum_{i=1}^{N}\sum_{k=0}^{q}\frac{\partial}{\partial \mathbb{T}_{c}}\left[1\left\{\left(^{(i)}\cdot k\right\}\log \mathbb{T}_{k}+1-\sum_{k=0}^{q}\mathbb{T}_{k}\right]\right] \quad \text{since} \quad \sum_{\text{off closes}}\mathbb{T}_{c}_{k}=1$ when $k \neq C$, the derivative will be 0 because we take derivative respect to 0 k = C, $\frac{\partial}{\partial \mathbb{T}_c} \mathbb{T}_k = 1$ So $\frac{\partial}{\partial \mathbb{T}_c} \int_{\mathbb{T}_c} = \sum_{i=1}^{N} \left[\frac{1\{C^{c_i^2} \in \vec{C}\}}{\mathbb{T}_c} - 1 \right] = 0 \implies \hat{\mathbb{T}_c} = \frac{\sum_{i=1}^{N} 1\{C^{c_i^2} \in \vec{C}\}}{N}$

Q2.2

[4pts] Using the MLE for this data, many entries of $\,\theta$ will be estimated to be 0, which seems extreme. So we look for another estimation method.

Assume the prior distribution of θ is such that the entries are i.i.d. and drawn from Beta(2,2). Derive the Maximum A Posteriori (MAP) estimator for θ (it has a simple final form). You can return the MLE for π in your implementation. From now on, we will work with this estimator.

[Type up your derivation here]

Your answer:

Since the prior given is Beta(a,a), so the PDF of prior will be $f(\theta) = \frac{\theta(1-\theta)}{6}$

In MAP, we're supposed to optimize $p(x,c|\theta,\pi)f(\theta)$, and we have the likelihood function from previous question.

$$\begin{split} \log \left(P(x \mid \theta) \cdot \int_{(\Theta)} \right) &= \left(\sum_{i=1}^{N} \sum_{c=0}^{q} \mathbf{1}_{\{C^{G_{i}} c \}} \log \pi_{c} + \sum_{i=1}^{N} \sum_{j=1}^{2p} \left[x_{j}^{G_{i}} \log \theta_{jc} \cdot ([-X_{j}^{G_{i}}) \log (1-\theta_{jc})] \right) + \log \left(\frac{\theta(c|-\theta)}{6} \right) \right. \\ &= \left(\sum_{i=1}^{N} \sum_{c=0}^{q} \mathbf{1}_{\{C^{G_{i}} c \}} \log \pi_{c} + \sum_{i=1}^{N} \sum_{j=1}^{2p} \left[x_{j}^{G_{i}} \log \theta_{jc} \cdot ([-X_{j}^{G_{i}}) \log (1-\theta_{jc})] \right) + \log (\theta) + \log (1-\theta) - \log (6) \right] \end{split}$$

Thun take the derivative respect to θ , and use part of result from previous question.

$$\begin{split} \sum_{i=1}^{N} \left(\frac{\chi_{,j}^{(i)}}{\Theta_{jc}} - \frac{1 - \chi_{,j}^{(i)}}{1 - \Theta_{jc}} \right) \mathbb{I}\left\{ c^{\omega_{,i}} \mathcal{C} \right\} &+ \frac{1}{\Theta} - \frac{1}{1 - \Theta} &= 0 \\ & \sum_{i=1}^{N} \frac{\chi_{,j}^{(i)} - \Theta_{,ic}}{\Theta_{,c} \left(1 - \Theta_{jc} \right)} \mathbb{I}\left\{ C^{\omega_{,c}} \mathcal{C} \right\} + \frac{1}{\Theta_{,c}} - \frac{1}{1 - \Theta_{,ic}} &= 0 \end{split}$$
 Solving for Θ , we have
$$\hat{\Theta}_{\text{map}} = \frac{\sum_{i=1}^{N} \left[\chi_{,i}^{(i)} \mathbb{I}\left\{ C^{\omega_{,c}} \mathcal{C} \right\} \right] + 1}{\sum_{i=1}^{N} \left[\mathbb{I}\left\{ C^{\omega_{,c}} \mathcal{C} \right\} \right] + 2} \end{split}$$

In [24]:

```
def train_map_estimator(train_images, train_labels):
    """ Inputs: train_images (N_samples x N_features), train_labels (N_samples x N_classe
s)
    Returns the MAP estimator theta_est (N_features x N_classes) and the MLE
```

```
estimator pi_est (N_classes)"""
#use the MLE of pi: number of correct lable / number of samples
pi_est = np.mean(train_labels, 0)
#use the result above
theta_est = (1 + np.matmul(train_images.T, train_labels)) / (2 + np.sum(train_labels, 0))
return theta_est, pi_est
```

[5pts] Derive an expression for the class log-likelihood $\log p(c|x,\theta,$ for a single image. Then, complete the $\pi)$

implementation of the following functions. Recall that our prediction rule is to choose the class that maximizes the above log-likelihood, and accuracy is defined as the fraction of samples that are correctly predicted.

Report the average log-likelihood $\frac{1}{N}\sum_{i=1}^N\log$ (where N is the number of samples) on the training test, as well $p(c^{(i)}|x^{(i)},\hat{\theta},\hat{\pi})$

the training and test errors.

[Type up your derivation here]

Your answer:

By Bayes' rule,
$$P(c|x,\theta,\pi) = \frac{P(c,x|\theta,\pi)}{P(x|\theta,\pi)}$$
 Now take log to $P(c|x,\theta,\pi)$, we have
$$\log P(c|x,\theta,\pi) = \log \frac{P(c,x|\theta,\pi)}{P(x|\theta,\pi)} = \log P(x|\theta,\pi)$$

$$= \log P(c,x|\theta,\pi) - \log P(x|\theta,\pi)$$

$$= \log P(c|\pi) P(x|c,\theta) - \log P(x|\theta,\pi)$$
 where
$$P(C|\pi) = \pi c,$$

$$\log P(c|\pi) + \log P(x|C,\theta) - \log P(x|\theta,\pi)$$
 where
$$P(C|\pi) = \pi c,$$

$$\log P(x|c,\theta) = \frac{\pi d}{j+1} P(x_j|c,\theta) = \sum_{j=1}^{\infty} \left[\chi_j \log \theta_{jc} + (j-\chi_j) \log(j-\theta_{jc}) \right]$$

$$P(x|\theta,\pi) = \sum_{c=0}^{\infty} P(c|\pi) P(x|c,\theta)$$
 For the following function log-likelihood:
$$\pi c \text{ is given by MLE } \hat{\pi}_c,$$

$$\theta_{jc} \text{ is given by images}$$

```
In [25]:
```

```
from numpy.core.fromnumeric import argmax
from numpy.ma.core import log
def log likelihood(images, theta, pi):
    """ Inputs: images (N_samples x N_features), theta, pi
        Returns the matrix 'log like' of loglikehoods over the input images where
        \log like[i,c] = \log p (c /x^{(i)}, theta, pi) using the estimators that and pi.
        log like is a matrix of (N samples x N classes)
    Note that log likelihood is not only for c^(i), it is for all possible c's."""
    # YOU NEED TO WRITE THIS PART
    p c given pi = pi
    log p c given pi = np.log(pi)
   log p x given c theta = np.matmul(images,np.log(theta))+(np.matmul(1-images,np.log(1
-theta)))
   log_p_c_x_given_theta_pi = log_p_c_given_pi + log_p_x_given_c_theta
   p x given c theta = np.exp(log p x given c theta)
    p_x_given_theta_pi = np.matmul(p_x_given_c_theta, p_c_given_pi)
    \log p \times \text{given theta pi} = \text{np.log}(p \times \text{given theta pi}).\text{reshape}(-1, 1)
    log_like = log_p_c_x_given_theta_pi - log_p_x_given_theta_pi
    return log like
def accuracy(log like, labels):
    """ Inputs: matrix of log likelihoods and 1-of-K labels (N samples x N classes)
    Returns the accuracy based on predictions from log likelihood values"""
    # YOU NEED TO WRITE THIS PART
    prediction = np.argmax(log like, axis =1)
    actual = np.argmax(labels, axis = 1)
    accuracy = np.mean(prediction == actual)
    return accuracy
N data, train images, train labels, test images, test labels = load fashion mnist()
theta est, pi est = train map estimator(train images, train labels)
loglike train = log likelihood(train images, theta est, pi est)
avg_loglike = np.sum(loglike_train * train_labels) / N_data
train accuracy = accuracy(loglike train, train labels)
```

```
loglike_test = log_likelihood(test_images, theta_est, pi_est)
test_accuracy = accuracy(loglike_test, test_labels)

print(f"Average log-likelihood for MAP is {avg_loglike:.3f}")
print(f"Training accuracy for MAP is {train_accuracy:.3f}")
print(f"Test accuracy for MAP is {test_accuracy:.3f}")
```

Average log-likelihood for MAP is -34.231 Training accuracy for MAP is 0.651 Test accuracy for MAP is 0.638

Q2.4

[2pts] Given this model's assumptions, is it always true that any two pixels x_i and x_j with $i \neq j$ are indenepdent given c? How about after marginalizing over c? Explain your answer.

[Type up your answer here]

Your answer:

Naive Bayes model is built on the assumption of conditional independence. If we have a pixels Xi and Xj, i = j It and L_1 are independent given C=c. So I agree with $p(x_i, x_j | c) = p(x_i | c) p(x_j | c)$ But x_i and x_j are marginal independent if $P(x_i, x_j) = P(x_i) P(x_j)$ Now we marginalize over C, C is the class from 0 to 9 $p(X_i, Y_j) = \sum_{c=0}^{r} p(X_i, X_j, c)$ $= \sum_{i}^{\prime} P(\chi_{i}, \chi_{j} | c) P(c)$ = $\sum_{c=1}^{4} P(X_i|c) P(X_j|c) P(c)$ by conditional independence we notice that $P(\chi_i) P(\chi_j) = \sum_{c=0}^{q} P(\chi_{i,c}) \sum_{c=0}^{l} P(\chi_{j,c})$ = $\sum_{c=1}^{q} P(\chi_{i}|c) P(c) \sum_{c=1}^{q} P(\chi_{j}|c) P(c)$ by Bayos' Rule $\stackrel{\neq}{\times} \sum_{i=0}^{q} P(\chi_{i}|c) P(\chi_{j}|c) P(c) = P(\chi_{i}, \chi_{j})$

 $P(x_i, x_j) \Rightarrow P(x_i) P(x_j)$

So lir ly are not marginally independent

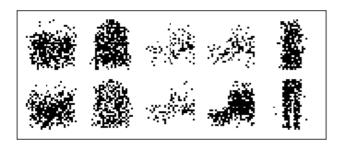
Therefore we conclude that

[4pts] Since we have a generative model for our data, we can do more than just prediction. Randomly sample and plot 10 images from the learned distribution using the MAP estimates. (Hint: You first need to sample the class c, and then sample pixels conditioned on c.)

```
In [26]:
```

```
def image_sampler(theta, pi, num_images):
    """ Inputs: parameters theta and pi, and number of images to sample
    Returns the sampled images (N images x N features)"""
    # YOU NEED TO WRITE THIS PART
    # Get number of features for each image
   N features = theta.shape[0]
    # Sample the class for each image using the class probabilities 'pi'
    sampled classes = np.random.choice(pi.shape[0], size=num images, p=pi)
    # Get the probabilities of each pixel being 1 for the sampled classes
    probs = theta[:, sampled classes]
    # Generate the binary values for each pixel of each image using the pixel probabiliti
es
    sampled images = np.random.binomial(1, probs)
    # Transpose the sampled images to have 'num images' rows and 'N features' columns
    return sampled images. T
def plot images (images, ims per row=5, padding=5, image dimensions=(28, 28),
                cmap=matplotlib.cm.binary, vmin=0., vmax=1.):
    """Images should be a (N_images x pixels) matrix."""
    fig = plt.figure(1)
    fig.clf()
    ax = fig.add subplot(111)
   N images = images.shape[0]
    N rows = np.int32(np.ceil(float(N images) / ims per row))
    pad value = vmin
    concat images = np.full(((image dimensions[0] + padding) * N rows + padding,
                             (image dimensions[1] + padding) * ims per row + padding),
pad value)
    for i in range(N images):
       cur image = np.reshape(images[i, :], image dimensions)
       row ix = i // ims per row
       col ix = i % ims per row
       row_start = padding + (padding + image_dimensions[0]) * row_ix
       col_start = padding + (padding + image_dimensions[1]) * col_ix
       concat images[row start: row start + image dimensions[0],
                      col start: col start + image dimensions[1]] = cur image
       cax = ax.matshow(concat images, cmap=cmap, vmin=vmin, vmax=vmax)
       plt.xticks(np.array([]))
       plt.yticks(np.array([]))
```

plt.plot()
sampled_images = image_sampler(theta_est, pi_est, 10)
plot images(sampled images)



Q2.6

[4pts] One of the advantages of generative models is that they can handle missing data, or be used to answer different sorts of questions about the model. Assume we have only observed some pixels of the image. Let $x_E = \{x_p : p \text{ is observed}\}$. Derive an expression for $p(x_j|x_E,\theta)$, the conditional probability of an unobserved pixel $p \text{ is observed}\}$

j given the observed pixels and distribution parameters. (Hint: You have to marginalize over c.)

$$\begin{array}{lll} \lambda.6 & \text{we have } \chi_{E} \text{ (observed)} \text{ , } \chi_{J} \text{ (unobserved)} \\ & P(\chi_{J} | \chi_{E}, \theta, \pi) = \frac{P(\chi_{J}, \chi_{E} | \theta, \pi)}{P(\chi_{E} | \theta, \pi)} \\ & = \frac{\sum\limits_{C=0}^{9} P(\chi_{J}, \chi_{E}, c | \theta, \pi)}{\sum\limits_{C=0}^{9} P(\chi_{J}, \chi_{E} | c, \theta) P(c | \pi)} & \text{marginalize over } c \\ & = \frac{\sum\limits_{C=0}^{9} P(\chi_{J}, \chi_{E} | c, \theta) P(c | \pi)}{\sum\limits_{C=0}^{9} P(\chi_{J} | c, \theta) P(\chi_{E} | c, \theta) P(c | \pi)} & \text{since } P(\chi, c | \theta, \pi) = P(c | \pi) P(\chi_{E} | c, \theta) P(\chi_{E} | c, \theta) P(c | \pi) \\ & = \frac{\sum\limits_{C=0}^{9} P(\chi_{J} | c, \theta) P(\chi_{E} | c, \theta) P(c | \pi)}{\sum\limits_{C=0}^{9} P(\chi_{E} | c, \theta) P(c | \pi)} & \text{by conditional independence} \end{array}$$

$$P(C|T) = TC$$

Since $X_E = \{X_P : \text{ pixel p is observed}\}$

we can express $P(X_E|C,\theta) = TTP(X_E|C,\theta)$

$$= TT\left(\theta_{ec}^{X_E} + (I-\theta_{ec})^{I-X_E}\right)$$

So
$$\log P(X_E | C, \theta) = \sum \left(\chi_e \log \theta_{ec} + (1-\chi_e) \log (1-\theta_{ec}) \right)$$

But here for χ_j , we are computing with $\chi_j = 1$
 $P(\chi_j = 1 | C, \theta) = \Theta_{jc}$
instead of the expression like $P(\chi_E | C, \theta)$

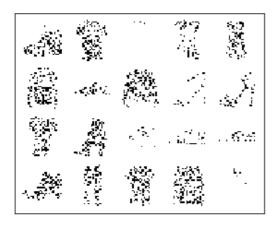
[4pts] We assume that only 30% of the pixels are observed. For the first 20 images in the training set, plot the images when the unobserved pixels are left as white, as well as the same images when the unobserved pixels are filled with the marginal probability of the pixel being 1 given the observed pixels, i.e. the value of the unobserved pixel j is $p(x_j=1|x_E)$.

 $\theta,\pi)$

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In [27]:
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```
def probabilistic imputer(theta, pi, original images, is observed):
    """Inputs: parameters theta and pi, original images (N images x N features),
        and is observed which has the same shape as original images, with a value
        1. in every observed entry and 0. in every unobserved entry.
    Returns the new images where unobserved pixels are replaced by their
    conditional probability"""
    # We compute his function from the expression in previous
    # Set up all values I need
    p c given pi = pi
   N images = original images.shape[0]
   N features = original images.shape[1]
    imputed_images = np.array(original_images)
    for image in range(N images):
     # Find x e, dim = N obs x 1
      x_e = original_images[image][is_observed[image] == 1]
      \# Find theta ec, dim = N obs x c, for the observed pixels
     theta ec = theta[is observed[image] == 1]
     log\_p\_xe\_c\_theta = np.matmul(np.log(theta\_ec.T), x\_e) + np.matmul(np.log(1 - theta))
_ec.T), 1 - x e)
     p_xe_given_c_theta = np.exp(log_p_xe_c_theta) # Nobs x c
      # Calculate the denominator
     p xe given theta pi = np.sum(p xe given c theta * p c given pi)
      # Find probability of xj given c and theta, which = theta jc as we claimed in previ
ous
      theta_jc = theta[is_observed[image] == 0] # Dim = N_unobs x c
      # Calculate the numerator, notice that p_xe_given_c_theta * theta_jc will
      \# yield (N_unobs,1), so we use sum() with respect to axis = 1
      p xj xe given theta pi = np.sum(p xe given c theta *
                                                            theta_jc * pi, axis = 1)
      # Calculate the probability of xj given xe, theta, pi
      p x j = p xj xe given theta pi / p xe given theta pi
      imputed images[image, is observed[image] == 0] = p x j
    # Return the imputed images
    return imputed images
num features = train images.shape[1]
```

```
is_observed = np.random.binomial(1, p=0.3, size=(20, num_features))
plot_images(train_images[:20] * is_observed)
```



In [28]:

```
imputed_images = probabilistic_imputer(theta_est, pi_est, train_images[:20], is_observed
)
plot_images(imputed_images)
```

