

Final presentation for Road Closure Marking Robot Project

# SEP Group 2 presentation

"Coding Pharaohs":
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#### Outline

- Introduction of the Project Progress
- Introduction of the Product
- What we learnt from the Project

#### Look at the Schedule first



### Detailed progress

- Week 3 and Week 4 to collect requirements
- Week 5 started to do milestones until Week 10
  - Week 5-Week 8 milestones were good performed
  - Week 9-Week 10 milestones were partial achieved
- Week 5 till Mid-break was the design phase
- For the rest of time we programming and programming and programming, and also testing ~~~

#### Visible Outcomes

- SRS\_First\_Draft: Jianqiu Li and Yu Hong
- SPMP\_First\_Draft: Abdulaziz Alhulayfi and Yifei Pei
- SDD\_First\_Draft: Matthew Nestor and Bowen Tao
- Final documentation and User Manual: Abdulaziz
   Alhulayfi
- Testing Reports: everyone
- \* and the whole system

#### Resources allocation

#### People

- People did what their responsibility lies
- Yu and Matt coded magnificently

#### Time

- A big chunk of time which was approximately 30% of the whole project spent on learning new things
- In the perspective of the project timeline, about half of the time was spent on design the system due to inexperience

# Risk Management

- Six types of risks
  - Technology
  - \* Tool
  - Team
  - Requirement
  - Organisation
  - Estimation

### Risk Management Plan

- Probability: Low/Moderate/High
- Effect: Tolerable/Moderate/Serious/Catastrophic
- Strategy: Steps to be followed to avoid risk occurrence
- Risk Indicator: Circumstances that lead to risk occurrence

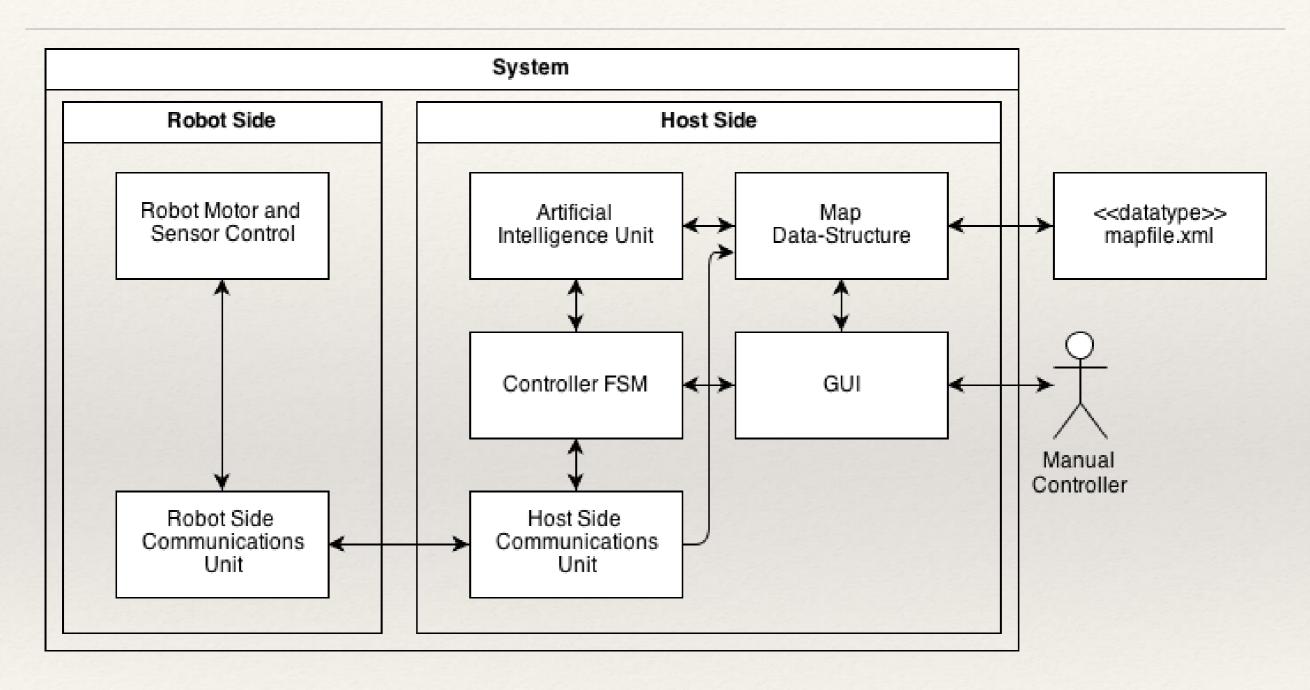
# Quality Assurance and Testing

- Provisional activity: we made a detailed risk management plan and V&V process to ensure things are done within frames
- Standards: Documentation followed the rubrics provided by lecturers and the standard for Program is to pass tests
- Testing: Make sure the program can achieve the designed functionality and the collected requirements

# Testing

- Unit testing
- System testing
- Plan and implementation

## The product



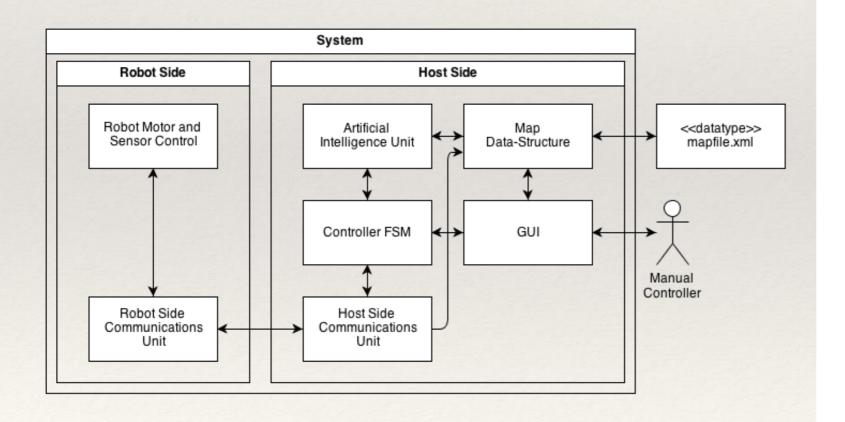
# Brief summary of requirements

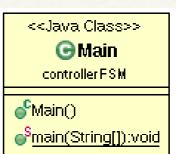
- The terminal goal: to mark road closures by robot on map
- Host side and Robot side requirements
- Host: GUI, manual control, emergency stop, display, save, load map, communication message.
- Robot: Automatic movement, detecting road and intersections, identify obstacles and disaster zone
- Safety and others

#### Brief summary of architecture

#### 1. Overview

- 2. Highest level architecture uses MVC pattern
  - 3. Pipe-and-filter for remote control
- 4. Selective Repeat for the communication pipeline
- 5. Finite State Machine for the control of robot events
  - 6. Graph to manipulate the Al





<<Java Class>>

G ControllerFSM

controller FSM

🛮 gui: GuiOfSEP

🏮 map: Map

receiver: PCReceiver

o communicator: PCComms

Al: ArtificialIntelligenceFSM

state: int

S<sub>o</sub>FMANUAL: int

SaF AUTOMATIC: int

- setGUI(GuiOfSEP):void
- setMap(Map):void
- getGraph():Graph
- setReceiver(PCReceiver):void
- createPCComms():PCComms
- executeCommand(int):void
- setAl(ArtificialIntelligenceFSM):void
- getPCComms():PCComms
- AlFoundNext():void
- stopPressed():void
- ConnectionFailure():void
- startAutomaticMapping():void
- exceptionThrown(Exception):void

# Major features of product

- Remote control
- Al and Al view
- Map update
- Selective Repeat for the COMMS

#### What can be improved

- The project phases and time frame was not good defined
  - We spent too much time on system design phase which should have been done before mid-break
  - Architecture ought to be subject to change, but the top level framework should be early defined
  - Major mistake: data structure definition delayed

#### What can be improved

- Quality control of the project did not consider time constraints
  - The user interface did not primarily achieve the expected quality. However it took too much time for us to redefine it.
  - Most goals did not have clear deadline of reasonable quality delivery, which delayed the whole project

#### What we can improve

- Risk management plan was detailed and sufficient, but the execution of risk management lacks of practice
  - We can't keep a sheet of risk management plan in hands. Due to the poor experience in real project management, we cannot identify the risks immediately when it occurs.

#### What can be improved

- People need time to adjust the status of working in a team and get familiar with teamwork conventions
  - All our group members are deadline-oriented workers, who are likely to rush in final hours

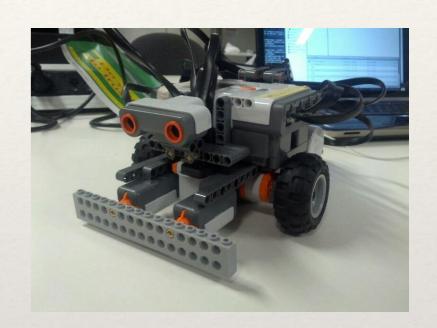
#### Future?

 Start to learn early, design early, and communicate much more frequently

# Thanks you all. Any Questions?



"Knowledge is power"



-Francis Bacon