Supplementary material: Topological classification for intersection singularities of exceptional surfaces in pseudo-Hermitian systems

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1. Pseudo-Hermiticity and metric operator

The pseudo-Hermiticity can be regarded as a symmetry in non-Hermitian physics [1], and a formal definition of pseudo-Hermiticity is always accompanied with a metric operator η

$$\eta H \eta^{-1} = H^{\dagger} \tag{S1}$$

Hence, a pseudo-Hermitian system is also called a η -pseudo-Hermitian system, and the metric operator η is a Hermitian matrix. Recently, the parity-time inversion symmetry (PT) is included in pseudo-Hermiticity symmetry [2,3]. The considered system thus includes two inequivalent pseudo-Hermitian symmetries. In quantum mechanics, the Hamiltonians of two systems can be considered to be equivalent if they can transform to each other via unitary transformations ($U^{-1} = U^{\dagger}$)

$$H\varphi = E\varphi \to UHU^{\dagger}U\varphi = EU\varphi \to H'\varphi' = E\varphi' \tag{S2}$$

We apply the transformation to Eq. S1

$$U\eta H\eta^{-1}U^{\dagger} = UH^{\dagger}U^{\dagger}$$

$$\to U\eta U^{\dagger}UHU^{\dagger}U\eta^{-1}U^{\dagger} = UH^{\dagger}U^{\dagger}$$

$$\to \eta' H'\eta'^{-1} = H'^{\dagger}$$
(S3)

where $\eta' = U\eta U^{\dagger}$ is the transformed metric operator. One finds that the metric operator is not unique, and can transform with the Hamiltonian simultaneously. For the considered system in Eq. 2, one can apply an SU(2) transformation to the Hamiltonian, e.g.

$$H' = e^{i\frac{\theta}{2}\sigma_1} H e^{-i\frac{\theta}{2}\sigma_1}$$

$$= (f_2(\mathbf{k})i\sigma_2 + f_3(\mathbf{k})\sigma_3)\cos\theta + (-f_2(\mathbf{k})i\sigma_3 + f_3(\mathbf{k})\sigma_2)\sin\theta$$
(S4)

It is found that the Hamiltonian can be transformed to a *PT*-symmetric system with equal gain and loss for $\theta = \pi / 2$,

$$H' = -f_2(\mathbf{k})i\sigma_3 + f_3(\mathbf{k})\sigma_2 \tag{S5}$$

and the metric operator is simultaneously transformed to

$$\eta' = \begin{bmatrix} 0 & i \\ -i & 0 \end{bmatrix} \tag{S6}$$

Hence, the classification in this work can be extended to other *PT*-symmetric systems (e.g. realized by equal gain and loss, Eq. S5) [4].

2. Quotient space and stratified space

In topology, the quotient space of a topological space under given equivalence relations is a new topological space constructed by endowing the quotient set of the original topological space with the quotient topology [2]. Let (X, τ_X) be a topological space, and let \sim be equivalent relation on X. The quotient set $Y=X/\sim$ is the set of equivalence classes of elements of X. The equivalence class of $x \in X$ is denoted by [x]. The quotient map associated with \sim refer to the surjective map

$$q: X \to X/\sim x \to \lceil x \rceil$$
 (S7)

Intuitively speaking, any points of each equivalence class are identified or glued together. A well-known example of quotient space is the Brillouin zone. In the momentum space of periodic systems, a point k is identified with points $\mathbf{k}+m_a\mathbf{G}_a$ because they have the same eigenvalues and eigenstates. Here \mathbf{G}_a are reciprocal lattice vectors and m_a are integers. Besides, on the Brillouin zone boundaries, points under translations by G_a are also identified. Hence, there are two equivalent relations in the momentum space. As simple examples, the first Brillouin zone is a quotient map of the momentum space under equivalence relation of translations by G_a , and point in the first Brillouin zone is an element in the equivalence class. For 1D periodic systems, identifying points on the Brillouin zone boundary constructs a quotient space, which is a 1D circle S^1 (see Fig. S1a1-a2). Similarly, opposite edges (p_1 and p_2 , and p_3 and p_4) of the Brillouin zone of 2D periodic systems can be identified (see Fig. S1b1). By gluing l_1 and l_2 , the Brillouin zone becomes a cylinder (see Fig. S1b2). We further glue p_3 with p_4 , and the cylinder becomes a torus T (see Fig. S1b3). p_1 (or p_2) and p_3 (or p_4) are called the skeleton of the torus, and is a bouquet of two circles with a common basepoint $S^1 \vee S^1$. The surface of the torus is called the two-cell. Assembling the skeleton and the two-cell, the torus can be described by the product $T = S^1 \times S^1$. The topology of the torus is thus described by its fundamental group $\pi_1(T) = \mathbf{Z} \times \mathbf{Z}$. This is an Abelian group composed of products of two generators, and the two generators commute. It is shown that the torus is different from the "figure eight", because the two-cell in the torus makes the two generators commute.

The momentum space of the considered system is a stratified space [6]. In topology, a stratified space is a triple (V,S,ζ) , where V is a topological space (often we require it to be locally compact, Hausdorff, and second countable), S is a decomposition of V into strata $V = \bigcup_{X \in S} X$, and ζ is the set of control data $\{(T_X),(\pi_X),(\rho_X)|X \in S\}$, where T_X is an open neighborhood of the stratum X, π_X : $T_X \rightarrow X$ is a continuous retraction, and ρ_X : $T_X \rightarrow [0,+\infty)$ is a continuous function. These data need to satisfy the following conditions:

- 1. Each stratum T is a locally closed subset, and the decomposition S is locally finite.
- 2. The decomposition S satisfies the axiom of the frontier: if X, $Y \in S$ and $T \in \overline{X}$. The condition implies that there is a partial order among strata: Y < X if and only if $T \in \overline{X}$ and $Y \ne X$.
- 3. Each stratum is a smooth manifold.
- 4. $X=\{v\in T_X| \rho_X(v)=0\}$. So ρ_X can be viewed as the distance function from the stratum X.
- 5. For each pair of strata $Y \le X$, the restriction (π_X, ρ_X) : $T_X \cap X \to Y \times (0, +\infty)$ is a submersion.
- 6. For each pair of strata Y<X, there holds $\pi_Y \circ \pi_X = \pi_Y$ and $\rho_Y \circ \pi_X = \rho_Y$.

The exceptional surfaces and intersections in the considered system is a typical example. Here the decomposition S of V gives a set of strata X. The exceptional surfaces are hypersurfaces in momentum

space and are singular varieties of X, denoted by Sing(X). The intersections of singular surfaces Sing(Sing(X)) eventually gives a natural stratification.

Our classification is based on eigenstates. The Hamiltonian in the real and imaginary line gaps can be expressed with the sum

$$H = \sum_{i=1,2} E_i \left| \varphi_i^L \right\rangle \left\langle \varphi_i^R \right| \tag{S8}$$

where $\varphi_i^{L(R)}$ denote the left and right eigenstates of the Hamiltonian. The pseudo-Hermiticity symmetry of the system enforces the left and right eigenstates to be connected by the following relation

$$\varphi_i^L = \eta \varphi_i^R \tag{S9}$$

The quotient space is constructed by identifying points with the same eigenstates. Hence, the construction from Fig. 1a-1b in the maintext can be easily understood, because antipodal points on ESs have the same eigenstates (up to an arbitrary phase).

$$\varphi_{1} = \varphi_{2} = \begin{bmatrix} -1\\1 \end{bmatrix} \quad \text{for } f_{2} = f_{3}$$

$$\varphi_{1} = \varphi_{2} = \begin{bmatrix} 1\\1 \end{bmatrix} \quad \text{for } f_{2} = -f_{3}$$
(S10)

In spaces without gap closing, by adding a minus sign to the Hamiltonian in Eq. S8, both eigenenergies take negative signs, but the eigenstates remain the same. This process can be realized by taking the negatives of f_2 and f_3 , which are just the antipodal points lying in opposite regions with respect to the intersection. In our classification, the two points are identified. The constructed space Eq. (3) in the main text is a stratified quotient space, and the corresponding topology Eq. (4) is thus a quotient space topology.

3. Riemannian geometry in adiabatic transformations

The metric operator in pseudo-Hermiticity plays a similar role as the space-time metric in general relativity [7,8], and the eigenstates are like local coordinate frames (or tetrad). The local metric g can be defined with the indefinite inner product $g_{mn} = \langle \varphi_m | \eta \varphi_n \rangle$. The pseudo-Hermitian symmetry provides an orthogonality relation to eigenstates

$$\varphi_{m}^{T} \eta \varphi_{n} \begin{cases} = 0 & m \neq n \\ \neq 0 & m = n \end{cases}$$
(S11)

Since the Hamiltonian is gauged to be real, the eigenstates are real by removing arbitrary phases in exact phases ($|f_3| > |f_2|$), and thus the eigenstates have another orthogonal relation

$$\left\langle \varphi_{m} \mid \eta \varphi_{n} \right\rangle \begin{cases} = 0 & m \neq n \\ \neq 0 & m = n \end{cases}$$
 (S12)

However, the self-inner products of the two eigenstates have opposite signs, i.e., one vector is space-like, and the other is time-like, which imposes the Riemannian geometry of adiabatic transformations. In the following we will construct the relation between the adiabatic transformation and SO(1,1) transformation.

Here we use the normalization $\varphi_m / \langle \varphi_m | \eta \varphi_m \rangle$ in exact phases, e.g., region I in Fig. 1a of the maintext, and the local metric can be obtained as

$$g = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \tag{S13}$$

The parameter-dependent eigenvalue problem is governed by

$$H(\lambda(\xi))|\varphi_m(\lambda(\xi))\rangle = i\partial_{\xi}|\varphi_m(\lambda(\xi))\rangle \tag{S14}$$

where λ is the parameter space of the Hamiltonian and has components λ^k (k=1,2,3,...), which are functions of ξ . The completeness of eigenstates shows that a field can be expanded as

$$\phi_n(\lambda(\xi)) = \sum_m [U(\lambda(\xi))]^{-1} {}_n^m \phi_m(\lambda(\xi))$$
 (S15)

Applying the partial derivative with respect to ξ , one obtains

$$i\frac{\partial}{\partial \xi}\phi_{n}(\lambda(\xi)) = H[U(\lambda(\xi))]_{n}^{-1} \varphi_{m}(\lambda(\xi))$$

$$= i\frac{\partial [U(\lambda(\xi))]_{n}^{-1} \varphi_{m}(\lambda(\xi)) + i[U(\lambda(\xi))]_{n}^{-1} \frac{\partial}{\partial \xi} \varphi_{m}(\lambda(\xi))}{\partial \xi}$$
(S16)

The adiabatic approximation allows the eigenvalue problem

$$H(\lambda(\xi))\varphi_m(\lambda(\xi)) = E_m \varphi_m(\lambda(\xi))$$
 (S17)

and applying a scalar product $\langle \varphi_i |$ from the left of Eq. S15 yields

$$-iE_{l}[U(\lambda(\xi))]^{-1}_{n} = \frac{\partial [U(\lambda(\xi))]^{-1}_{n}}{\partial \xi} + \left\langle \varphi_{l} \left| \eta \frac{\partial \left| \varphi_{m}(\lambda(\xi)) \right\rangle}{\partial \xi} [U(\lambda(\xi))]^{-1}_{n} \right\rangle$$
(S18)

The partial derivative with respect to ξ can be expanded as

$$\frac{\partial \left| \varphi_{m}(\lambda(\xi)) \right\rangle}{\partial \xi} = \sum_{k} \frac{\partial \left| \varphi_{m}(\lambda(\xi)) \right\rangle}{\partial \lambda^{k}} \frac{\partial \lambda^{k}}{\partial \xi}$$
(S19)

We define the affine connection

$$A_{k_{m}}^{n} = -\left\langle \varphi_{n} \left| \eta \frac{\partial \left| \varphi_{m}(\lambda(t)) \right\rangle}{\partial \lambda^{k}} \right. = -\left\langle \varphi_{n} \left| \eta \frac{\partial}{\partial \lambda^{k}} \right| \varphi_{m} \right\rangle \tag{S20}$$

and the solution for U^{-1} is thus obtained as

$$U^{-1} = \exp\left[\int_0^{\xi} ds \frac{\partial \lambda^k}{\partial s} A_k - i \int_0^{\xi} ds \omega(\lambda(s))\right] = \exp\left(\int_{\lambda(0)}^{\lambda(\xi)} d\lambda^k A_k\right) \times \exp\left[i \int_0^{\xi} ds E(\lambda(s))\right]$$
(S21)

Ignoring the dynamical phase (the second term in Eq. S21), the geometric phase is simply

$$U^{-1} = \exp(\int_{\lambda(0)}^{\lambda(\xi)} d\lambda^k A_k)$$
 (S22)

We would like to construct a relation between the affine connection and the local metric g. The local metric is a constant, and thus the partial derivative with respect to time is zero

$$0 = \partial_{\varepsilon} g_{mn} = \partial_{\varepsilon} \langle \varphi_m | \eta \varphi_n \rangle \tag{S23}$$

We insert the identity operator $I = \sum_{l} \eta |\varphi_{l}\rangle \langle \varphi_{l}|$ (obtained by Eq. S9) into Eq. S23

$$\partial_{\lambda_{k}} \langle \varphi_{m} | \eta \varphi_{n} \rangle = \sum_{l} \langle \partial_{\lambda_{k}} \varphi_{m} | \eta | \varphi_{l} \rangle \langle \varphi_{l} | \eta \varphi_{n} \rangle + \sum_{l} \langle \varphi_{m} | \eta | \varphi_{l} \rangle \langle \varphi_{l} | \eta \partial_{\lambda_{k}} \varphi_{n} \rangle$$
(S24)

One notes that

$$\left\langle \partial_{\lambda_{k}} \varphi_{m} \mid \eta \mid \varphi_{l} \right\rangle = \left\langle \varphi_{l} \mid \eta \mid \partial_{\lambda_{k}} \varphi_{m} \right\rangle^{*} \tag{S25}$$

and thus Eq. S24 can be written as

$$0 = A_{k}^{*l} {}_{m} g_{ln} + g_{ml} A_{k}^{l}$$
 (S26)

Here the repeated index *l* means summed over according to the Einstein's summation rule [7]. The form of the metric Eq. S12 enforces the affine connection to have the following generators

$$T_{1} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, T_{2} = \begin{bmatrix} 0 & i \\ -i & 0 \end{bmatrix}$$
 (S27)

The latter in Eq. S27 can be eliminated because the eigenstates are gauged to be real, and the former generator survives. It is shown that the adiabatic transformation of eigenstates is defined on the SO(1,1) group, revealing the Riemannian geometry of the adiabatic transformations. In broken phases, the transformation is also SO(1,1), and can be demonstrated with similar derivation processes. If we assign U(1) phases to the eigenstates $\varphi e^{i\psi}$ (ψ is constant), the Lorentz transformation becomes complex and the generator becomes a linear combination of $T_{1,2}$ in Eq. S27

$$T' = \begin{bmatrix} 0 & e^{i\chi} \\ e^{-i\chi} & 0 \end{bmatrix}$$
 (S28)

which is still SO(1,1) transformation. Note that χ is a constant.

The Riemannian geometry of adiabatic transformation of eigenstates is very important in understanding the spin rotation of eigenstates and the presence of ESs. Taking T_1 in Eq. S27 as an example, the geometric phase induces a transformation

$$[\varphi_1', \varphi_2'] = [\varphi_1, \varphi_2]U^{-1}$$
 (S29)

where U^{-1} is the transformation operator given by the geometric phase $U^{-1} = \exp \beta T_1$. As β approaches infinity $+\infty$, $\cosh \beta \approx \sinh \beta$, and thus

$$U^{-1} \to \mu \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \tag{S30}$$

As β approaches negative infinity $-\infty$, $\cosh\beta \approx -\sinh\beta$, and thus

$$U^{-1} \to \mu' \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \tag{S31}$$

where μ and μ' are real, which only induces the amplitude change of eigenstates without inducing spin rotations, and thus can be ignored. It is shown that eigenstates are parallel to each other as $\beta \to \pm \infty$, and as β varies from $(-\infty, +\infty)$, the final states are perpendicular to the initial states. Physical pictures of the spin rotations via adiabatic transformations have been given in Fig. 2 of the maintext.

4. Hybrid topological invariants on a closed loop circulating the CIL.

In the maintext, we showed that the invariant α (or β) and its inverse is sensitive to the sequence of eigenstates whenever the path (or loop) traverses the ESs. This is because the two eigenstates experience opposite geometric phases, and the sequence of the two eigenstates cannot be uniquely determined as the two bands (both eigenstates and eigenenergies) become degenerate at ESs. Hence, a close loop circulating the CIL has hybrid topological invariant. Hybrid topological invariant of intersection singularities was firstly discussed for exceptional point of order three (EP3) in [9]. The EP3 is a cusp intersection singularity, and its topological invariant is discussed in high dimensions. Here we do not attempt to extend the dimensions with analytical continuation, because such process will break the symmetries (Eq. 1 in the maintext) of the system. Resultantly, the CIL is not expected to be present. The CIL has 2^4 =16 topological invariants as listed in Table 1, corresponding to different adiabatic variation processes of eigenenergies and eigenstates.

5. Composite invariants α^2 and β^2

In the maintext, we discussed the invariant β^2 on the loop in Fig. 3c. In the segmented path l_4 , the sequence of the two eigenstates is swapped, and thus the topological invariant on l_4 is also α (instead of α^{-1}), the same as path l_2 . Here we discuss another way to realize α^2 . We first look at Fig. S2a, which is the quotient space constructed by an equivalence relation that antipodal points on ESs can be identified. Hence point A(B) can be identified with point A'(B'). As shown in Fig. S2(b1), the closed loop on the upper cone is a composite of the path l_7 (starts from A and terminates at B) and l_8 (starts from B' and terminates at A'). Under the convention given in the maintext, the invariants on both paths are also characterize by α , and hence the path $A \rightarrow B \rightarrow B' \rightarrow A'$ carries the invariant α^2 . The corresponding adiabatic variation of eigenstates is shown in Fig. S2(b3), and the eigenstates experience $\mp \pi$ rotations $(\varphi_{1,2}' = \exp(\mp i\pi\sigma_2)\varphi_{1,2})$ of polarization with respect to σ_2 . The invariant β^2 can be realized in the same way (see Fig. S2b), which is a composite path $C \rightarrow D \rightarrow D' \rightarrow C'$, corresponding to the closed loop in the lower cone in Fig. S2a. The corresponding adiabatic variation process is shown in Fig. S3(b3)-(b4) (corresponding to real and imaginary parts of eigenstates). The eigenstates experience $\mp \pi$ spin rotations but a long σ_3 axis ($\varphi'_{1,2} = \exp(\mp i\pi\sigma_3)\varphi_{1,2}$). The two invariants (α^2 and β^2) are integers, because the eigenstates evolve to the initial states. The existence of the CIL decomposes a loop carrying integer topological invariant into to two sub-loops, both of which carry fractional invariants.

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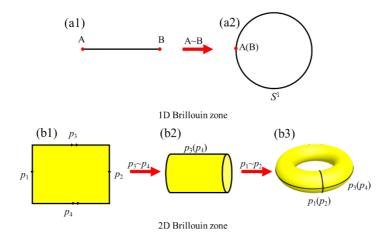


Fig. S1. Quotient space of momentum space in periodic systems. (a1)-(a2) The quotient space of 1D Brillouin zone is a circle (S^1) by identifying the two points on the Brillouin zone boundary. (b1)-(b3) Construction of quotient space of 2D Brillouin zone. Identifying the boundaries p_3 with p_4 gives a cylinder, which becomes a torus by identifying p_1 with p_2 .

	$lphaetalphaeta^{-1}$	$\alphaetalpha^{-1}eta$	$\alpha^{-1}\beta^{-1}\alpha\beta^{-1}$	$\alpha^{-1}\beta^{-1}\alpha^{-1}\beta$	
$\alphaetalpha^{-1}eta^{-1}$	$\alpha \beta^{-1} \alpha^{-1} \beta$	$\alpha^{-1}eta\alpha^{-1}eta$	$\alpha \beta^{-1} \alpha \beta^{-1}$	$\alpha^{-1}etalphaeta^{-1}$	$\alpha^{-1}\beta^{-1}\alpha\beta$
	$\alpha\beta^{-1}\alpha^{-1}\beta^{-1}$	$\alpha^{-1}eta\alpha^{-1}eta^{-1}$	$\alpha \beta^{-1} \alpha \beta$	$\alpha \beta^{-1} \alpha \beta$	
		αβαβ	$\alpha^{-1}\beta^{-1}\alpha^{-1}\beta^{-1}$		

Table. S1. Hybrid topological invariants of a loop circulating the CIL. The invariants on the right-hand side (with respect to the red line) are simply obtained by replacing the elements with their inverses.

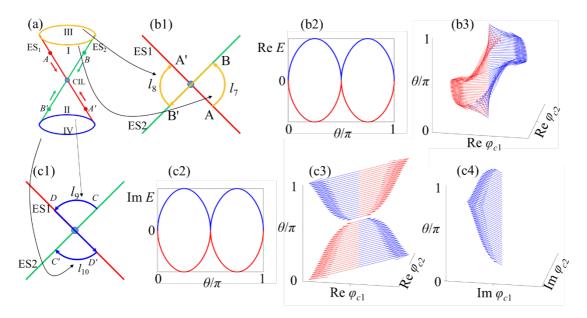


Fig. S2. Composite invariants α^2 and β^2 . (a) The invariants correspond to the loops in the double cone constructed by the first equivalent relation (identifying antipodal points on ESs). The closed loop in the upper and lower cone corresponds to the composite of paths l_7 and l_8 in (b1), and that of paths l_9 and l_{10} in (c1), respectively. The corresponding adiabatic evolutions of eigenvalues and of eigenstates for α^2 are shown in (b2)-(b3), and those for β^2 are shown in (c2)-(c4).