



GLOBALRISK
INSTITUTE

CPP question

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Two CPP questions.

Assume vector x is the vector of mitigation levels we are looking for. Let $f(x)$ be the function we are minimizing. For now assume x is given and we are just evaluating $f(x)$. $f(x)$ is evaluated on the computation tree going *backward* in time starting from time $t = T_F$

Each node in the graph corresponds to a subfunction – say f_i corresponds to node i and x_i corresponds to the mitigation level on node i . Think of f_i written as

$$y_i = f_i(x, y_{k>i}(x), S_i)$$

Where $y_{k>i}$ is a subset of subfunction values computed to the right of node i (That is with time stamps after i). Note that $y_{k>i}$ is a function of x .

S_i corresponds to state information and is not a function of x (and is precomputed).

Question 1: What is the form of f_i ? Does this function explicitly depend only on component x_i (and depend on some other components of x ONLY through $y_{k>i}$?)

Question 2: Is f_i a convex fcn of x_i ? Is $f(x)$ a convex function of x ? Could you do some experiments to check the convexity before doing any theoretical proof?