## ECE26400 Programming Assignment #4

This assignment is related to PE07. Some functions in PE07 will be re-used here. You will also write a few new functions. There is also a chance to earn some bonus points.

The main learning goals are:

- 1. How to read and write a structure into a file.
- 2. How to manipulate arrays.
- 3. How to perform bit-wise operations.
- 4. How to implement the Floyd-Steinberg dithering algorithm (if you want to earn some bonus points).

### 1 Getting started

You should unzip on eceprog.ecn.purdue.edu the zip file pa04\_files.zip using the following command:

```
unzip pa04_files.zip
```

The zip file pa04\_files.zip contains a folder, named PA04, and two files within the folder and two subfolders containing some sample files:

- 1. answer04.h: This is a "header" file and it declares the functions you will be writing for this assignment.
- 2. images: This is a subfolder with valid BMP files.
- 3. dithered: This is a subfolder with valid BMP files generated using the Floyd-Steinberg dithering algorithm (for bonus points).
- 4. idiff\_tol: An executable that helps you to identify the differences in the output files generated using your implementation of the Floyd-Steinberg algorithm and image files in the dithered subfolder.

In this assignment, you have to define in answer04.c six out of the seven functions that have been declared in answer04.h and create a file called pa04.c for the main function for full credit. If you also implement the seventh function described in Section 9, you may earn bonus points.

Please note that starting from PE07, there are changes to the gcc command used for the compilation of your program. **Please read Section 4**.

This assignment requires you to know intimately the BMP image file format. Please refer to Section 2 of PE07 for details.

## 2 Bit operations

This assignment requires you to convert a 24-bit BMP file into a 16-bit BMP file, and vice versa.

For the 24-to-16-bit converion, you may have to deal with bit-wise operations. Here are a few that could be useful: shift, bit-wise AND, and bit-wise OR. Assume that you have three variables a, b, and k, all of type int.

If you are not dealing with an unsigned int, the left shift operation may turn a positive number into a negative number.

If you are dealing with an unsigned int, the right shift will shift 0's into the most significant bit.

My understanding of the ALU (Arithmetic-Logic Unit) design is that since a is an int, which has 32 bits, only the least signicant 5 bits of k will be used to decide the number of positions to shift. If a is a long int, only the least significant 6 bits of k will be used to decide the number of positions to shift.

Also, if variable a is a short or char, and b is an int (32 bits), as the operation is carried out on a 32-bit register, b would be assigned the value as if variable a is an int. However, if b is a long int, the value of b can become unpredictble because the shifting is performed based on 32 bits.

### To avoid unpredictable results, try to have variables a and b that are of the same type.

In this assignment, the 8 bits or 5 bits representing a color should be treated as an unsigned value. In other words, the 8 bits allow values 0 through 255 and the 5 bits allow values 0 through 31.

(Note that the following description is an example, not how we actually represent a pixel in a BMP file.) Suppose you have an int, but only the 3 lower significant bytes are storing the color information of a pixel (for 24-bit representation). The format RGB means that the red color (R) occupies a more significant position and the blue color (B) occupies a less significant position. (Note that if I treat the int as an array of 4 unsigned chars, say unsigned char \*array, array[0] is B, array[1] is G, and array[2] is R.)

To extract the value of RGB from the int (pixel is the variable name), we can use bit-wise AND operator:

```
int red_value = (pixel & 0xFF0000) >> 16;
int green_value = (pixel & 0xFF00) >> 8;
int blue_value = (pixel & 0xFF);
```

The operator & (which is different from logical AND operator &&) performs bit-wise AND operator at every corresponding bit position. The bit pattern 0xFF0000 has eight 1's at the second most significant byte (of an int). When you bit-wise AND 0xFF0000 with variable pixel, the result will match the contents in pixel at only the second most significant byte; the most significant byte, the second least significant byte, and the least significant byte of the result will be 0. Shifting the result by 16 bits will now store the correct value for the red color in the variable red\_value. The pattern 0xFF0000 is called a bit mask.

The following shows where the values of the red, green, and blue colors of a pixel are stored if a pixel is represented by, for example, short, unsigned short, int16\_t, uint16\_t?

```
/* bit positions of RGB in a 16-bit representation */
/* R: 0111110000000000 */
/* G: 0000001111100000 */
/* B: 000000000011111 */
```

What should be corresponding masks for the red, green, and blue colors of a pixel?

Bit-wise AND operation can be used to extract selected group of bits from an int (or any other types). Bit-wise OR operation |, which is different from logical OR operator | |, can be used to put group of bits at selected locations into an int (or any other types).

Continuing with the 24-bit example, to assemble three bytes of RBG information into an int pixel, we can use

```
pixel = (red_value << 16) | (green_value << 8) | blue_value;</pre>
```

Of course, we do not have to use any of these operations for 24-bit representation, because each color is a byte, and therefore unsigned char can easily represent each color. You may have to use the shift, bit-wise AND, and bit-wise OR to handle 16-bit representation, where bits 0 through 14 are for the three colors. The most significant bit should be 0 (and not used in a meaningful way for this assignment).

### 3 Functions you have to define

#### 3.1 Function in answer04.c

You should copy answer07.c from PE07 into a new file named answer04.c, and keep only the relevant functions in the new file. In particular, you should keep the following functions:

```
• BMP_image *read_BMP_image(char *filename);
```

- bool is\_BMP\_header\_valid(BMP\_header \*bmp\_hdr, FILE \*fptr);
- int write\_BMP\_image(char \*filename, BMP\_image \*image);
- void free\_BMP\_image(BMP\_image \*image);

To earn full credit for PA04, you have to write two new functions in answer04.c and the main function in pa04.c. To earn bonus points, please see Section 9.

Here are the two new functions to be written in answer04.c.

```
// Given a BMP_image, create a new 16-bit image that is converted from a given
// 24-bit image
//
BMP_image *convert_24_to_16_BMP_image(BMP_image *image);
```

For the given image, you may assume that it is a valid 24-bit image; otherwise, this function should not be called at all.

You have to take the 24-bit representation and convert it into a 16-bit representation. Note that you should not modify the original image. Instead, the function should allocate new memory spaces to store the new header information and the new image data.

The header information of the new image should not be identical to that of the original image. In particular, you would have to compute the number of bytes in each row and the total image size, and therefore the file size.

You have to downscale 8 bits to 5 bits for each color. You have to scale 0 through 255 to 0 through 31. A division of a color value by 8 or a right shift of 3 position should achieve similar outcome because you are

dealing with non-negative numbers. You also have to combine the three colors into two bytes (using perhaps bit-wise OR operation). Lastly, you have to store the two bytes into the data array of the new BMP\_image.

It is important that the padding bytes, if required, are all assigned 0.

```
// Given a BMP_image, create a new 24-bit image that is converted from a given
// 16-bit image
//
BMP_image *convert_16_to_24_BMP_image(BMP_image *image);
```

This function performs the reverse of the preceding function. For the given image, you may assume that it is a valid 16-bit image; otherwise, this function should not be called at all.

You have to take the 16-bit representation and convert it into a 24-bit representation. Note that you should not modify the original image. Instead, the function should allocate new memory space to store the new image.

You cannot simply perform a left shift of 3 bit positions or a multiplication of 8 map 0 through 31 to 0 through 255. The reason is that in that case, you will not have the highest possible value for 24-bit representation, which is 255. Rather, you will have 248 as the highest value. To make sure that the highest intensity of 31 in a 16-bit representation is mapped to the highest intensity of 255 in a 24-bit representation, you should use the following formula:

```
((5-bit value)*255)/31
```

(This conversion formula is important if you plan to work on the function for bonus points.) It is important that the padding bytes, if required, are all assigned 0.

#### 3.2 main function in pa04.c

Your main function should expect argy [1] as the input file and argy [2] as the output file.

If argv[1] does not provide you a valid BMP file, you should not produce a new BMP file, and you should return EXIT\_FAILURE. Based on the format of a valid BMP file, you should perform a 24-to-16 bit conversion or a 16-to-24 bit conversion (see Section 3.1), and save the new image in argv[2].

If for whatever reasons (insufficient arguments, memory allocation problem, file opening issue, format issue), the conversion should not be performed, the output file should not be produced and you should return EXIT\_FAILURE.

Return EXIT\_SUCCESS only if it is a successful conversion.

You are responsible for opening and closing files, allocating and deallocating memory.

### 3.3 Printing, helper functions and macros

All debugging, error, or log statements in answer04.c and pa04.c should be printed to stderr.

You may define your own helper functions in pa04.c and answer04.c. All these functions should be declared and defined as static functions. In other words, the scope of these functions are only within the files that they are found. Declaring and defining these functions as static eliminate the conflicts in function names.

You should not use macros that start with  $T_-$  (Upper case T and underscore) in their names. We will use such macros in the evaluation of your submissions. If you use such macros, we may not be able to evaluate your submission properly.

## 4 Compiling your program

As you have advanced to this stage, we believe that you have the necessary experience to decide what warnings are allowed and what warnings should be eliminated. We will now remove the -Werror flag from the gcc command.

```
gcc -std=c99 -Wall -Wshadow -Wvla -g -pedantic -fstack-protector-strong \
    --param ssp-buffer-size=1 pa04.c answer04.c -o pa04
```

When we evaluate your program, we also use the optimization flag -03 (uppercase letter 0 and number three) instead of the -g flag as follows:

```
gcc -std=c99 -Wall -Wshadow -Wvla -03 -pedantic -fstack-protector-strong \
--param ssp-buffer-size=1 pa04.c answer04.c -o pa04
```

You are recommended to copy the Makefile from PE01 and modify it appropriately for PA04.

In fact, we will remove the -Werror flag for all exercises and assignments that come after PE07. However, for the re-submissions of PA01, PA02, and PA03, we will continue to use the gcc command as mentioned in the respective PDF files for those assignments.

### 5 Writing, running and testing your program

We provide a few test cases for you. The images subfolder contains some images that are of the correct format. Some of the images are converted from the original format. For example, car16.bmp is converted from car.bmp, and car24.bmp is converted from car16.bmp. There are also images that are without the converted versions.

You can use the diff command to compare your own output files and the corresponding files in the images subfolder.

See also the images and corrupted subfolders from PE07 for more valid image files and corrupted image files.

You should also run ./pa04 with appropriate arguments under valgrind.

Please see PE01 description about valgrind.

### 6 Submission

You must submit a zip file called PAO4.zip, which contains two files:

- 1. answer04.c
- 2. pa04.c

Assuming that you are in the folder that contains answer04.c and pa04.c, use the following command to zip your files:

```
zip PA04.zip answer04.c pa04.c
```

Make sure that you name the zip file as PAO4. zip. Moreover, the zip file should not contain any folders. Submit PAO4. zip through Brightspace. You may submit as many versions as you like. Brightspace will keep only the most recent submission, and we will grade only the final submission.

## 7 Grading

All debugging messages should be printed to stderr. It is important that if the instructor has a working version of pa04.c, it should be compilable with your answer04.c to produce an executable. For evaluation purpose, we will use different combinations of your submitted .c files and our .c files to generate different executables. If a particular combination does not allow an executable to be generated, you do not get any credit for the function(s) that the executable is supposed to evaluate. We use both -g and -03 flags (separately) to compile your submission. Your submission is evaluated only when compilation using each of the flags is successful.

It is important to note that the .c files from the instructor do not assume the presence of global variables that are declared by the students. Of course, the .c files from the instructor may use global variables that are in C libraries, such as errno, stdout, stderr, and so on. If your submission contains global variables that are declared by you, it is unlikely that your executable will work correctly.

Be aware that we set a time-limit for each test case based on the size of the test case. If your program does not complete its execution before the time limit for a test case, it is deemed to have failed the test case. We will not announce the time-limits that we will use. They will be very reasonable.

The read\_BMP\_image function accounts for 15%. The write\_BMP\_image function accounts for 10%. The convert\_24\_to\_16\_BMP\_image function accounts for 40%. The convert\_16\_to\_24\_BMP\_image function accounts for 30%. The main function accounts for 5%.

The occurrence of any memory issues (memory errors or memory leaks flagged in a valgrind report) will result in 50-point penalty.

### 8 A few points to remember

All debugging messages should be printed to stderr. If the program creates an output file when it should not, or the output file is correct, you get 0 for that test case.

You can declare and define additional static functions that you have to use in pa04.c and answer04.c. You should not use macros that start with T\_.

Grading of programming exercises and assignments is performed on machines with similar setup as eceprog.ecn.purdue.edu. You should perform testing of your work on eceprog.ecn.purdue.edu before submission. Correct output on your computer does not translate into correct output on eceprog.ecn.purdue.edu.

# 9 Bonus points

To earn bonus points, you will write a function to perform Floyd-Steinberg dithering (see below) so that when you downscale the 24-bit bitmap representation to the 16-bit bitmap representation, the image continues to look reasonable.

If you do not plan to earn bonus points, do not define the convert\_24\_to\_16\_BMP\_image\_with\_dithering function in answer04.c. Please also note that your pa04.c should not call this function, so that your submissions can be compiled successfully even without the definition of this function.

#### 9.1 Floyd-Steinberg dithering algorithm

In the function convert\_24\_to\_16\_BMP\_image, the conversion of a 24-bit BMP into a 16-bit BMP file results in some loss in accuracy. When you use 32 levels (5-bit representation) to represent 256 levels (8-bit

representation), the conversion suffers quantization error, which is defined as follows:

```
16_bit_value = 24_bit_value / 8;
equiv_24_bit_value_for_16_bit_value = (16_bit_value * 255) / 31;
quantization_error = 24_bit_value - equiv_24_bit_value_for_16_bit_value;
```

Note that although both 16-bit value and 24-bit value are non-negative, the quantization error may be positive, zero, or negative. You should recognize that in the preceding three equations, you have seen the first two, which you have used for 24-bit-to-16-bit conversion and 16-bit-to-24-bit conversion, respectively.

In the 24-bit-to-16-bit conversion we described in Section 3.1, we simply ignore the quantization errors at all pixels. As a consequence, the nice blue sky in the image airplane.bmp (in the images subfolder) became a sky with 50 shades of blue in airplane16.bmp and airplane24.bmp.

To render the quantization errors less noticeable, a dithering algorithm diffuses the quantization error of a pixel to 4 neighboring pixels, as shown below:

The quantization error of pixel X at location (x,y) is diffused to its right pixel (x+1,y) with a weight of 7/16, to three pixels below X at locations (x-1,y-1), (x,y-1) and (x+1,y-1) by a weight of 3/16, 5/16, and 1/16, respectively. Note that the denominator of 16 is for normalization as it is the sum of the weights 7, 3, 5, 1.

By diffusion, it means that the weighted quantization error of X is added to the pixel values of its 4 neighbors.

While a pixel contributes its quantization error to four neighbors, it also receives quantization errors from four neighbors.

Here, we assume a Cartesian coordinate system, with (0,0) being the lower-left corner pixel of the image. In the BMP format, the first byte after the header information belongs to the pixel at (0,0) format. The pixels are stored in the file from the bottom to the top of an image, and from the left to the right.

The following pseudo code shows that Floyd-Steinberg dithering algorithm.

```
/* FloydSteinberg dithering
 * for each y from TOP to BOTTOM
 * for each x from LEFT to RIGHT
 * oldpixel := pixel[x][y]
 * newpixel := oldpixel scaled to fewer number of bits
 * pixel[x][y] := newpixel
 * quant_error := oldpixel - (newpixel scaled back to
 * original number of bits)
 * pixel[x+1][y] := pixel[x+1][y] + quant_error * 7/16
 * pixel[x-1][y-1] := pixel[x-1][y-1] + quant_error * 3/16
 * pixel[x][y-1] := pixel[x][y-1] + quant_error * 5/16
 * pixel[x+1][y-1] := pixel[x+1][y-1] + quant_error * 1/16
 */
```

Here, pixel[x][y] refers to a particular color (R, G, or B) of the pixel, and the weighted quantization error is added to the corresponding color of the neighboring pixels. You have to do it for each color of RGB. Also, you diffuse the quantization error to only valid pixel locations (the pseudo-code did not check for the validity of the locations).

Lastly, you have to combine the 5 bits of each color into 16-bit. It is important to note that addition of the quantization error may result in invalid value (> 255 or < 0). You have to make sure that you are dealing with valid pixel value. If the addition results in a value > 255, assign 255 to the pixel. If the addition results in a value < 0, assign 0 to the pixel.

The results of an implementation of the algorithm are shown in the dithered subfolder. You may compare the image airplane16\_dithered.bmp in the dithered subfolder and airplane16.bmp in the images subfolder. You should observe that the 50 shades of blue have magically disappeared.

#### 9.2 Function you have to write

You will write the following function in answer04.c if you plan to earn bonus points; otherwise, you should not define this function in answer04.c. This function will not be called by any of your functions in answer04.c or pa04.c. I will write a different main function to invoke and test this function.

```
// Given a BMP_image, create with dithering a new 16-bit image that is
// converted from a given 24-bit image
//
BMP_image *convert_24_to_16_BMP_image_with_dithering(BMP_image *image);
```

For the given image, you may assume that it is a valid 24-bit image; otherwise, this function should not be called at all. You have to take the 24-bit representation and convert it into a 16-bit representation using the Floyd-Steinberg dithering algorithm.

As you have the experience of implementing the convert\_24\_to\_16\_BMP\_image function, we will highlight a few differences between the two 24-bit-to-16-bit functions, and provide you some pointers that may be helpful in the completion of this new function.

First, the dithering algorithm scans the pixels from the TOP to the BOTTOM, and from LEFT to RIGHT. In the BMP file, the pixels are stored from the bottom to the top, and from left to right. If you processed pixels from bottom to top in the convert\_24\_to\_16\_BMP\_image function, it may be helpful to copy the code from that function and modify it to perform the conversion of a 24-bit representation to a 16-bit representation from top to bottom. The correctness of conversion (without dithering) can be easily tested.

Second, you have to compute the quantization error. Pay attention that the quantization error for a color is not computed between the 8-bit value and the 5-bit value. Rather, it is between the 8-bit value and the 8-bit value converted from the 5-bit value. A static function for that may be useful.

Third, the algorithm shows that the weighted quantization error has to be added to the original 8-bit value of a color. However, as you are not allowed to make modifications to the given image (the header and the image data), you may want to store the sum of weighted quantization errors diffused to each pixel separately. Note that the algorithm involves only two rows of pixels when it scans from left to right for each row.

Fourth, the quantization error diffused to the neighbors of a pixel has to be divided by 16 (and multiplied by either 1, 3, 5, or 7). Consequently, the weighted quantization error from a single neighbor may become zero. It is therefore better to collect the quantization errors (multiplied by 1, 3, 5, or 7) from all four neighbors, and divide the sum by 16. In other words, although the quantization error from just a neighbor

may be small, the sum of quantization errors from all four neighbors can be large enough to affect the pixel. It is important that your implementation can capture quantization error properly.

Fifth, the addition of weighted quantization errors may not result in a valid 8-bit value for a color (nonnegative and < 256). You have to make sure that your implementation does not have an underflow/overflow issue.

#### 9.3 Test cases

The dithered subfolder contains some images that have been converted from a 24-bit representation (see the images subfolder) to a 16-bit representation with dithering.

We also included an executable called idiff\_tol that you may use to compare two images. You may run the executable as follows:

```
./idiff_tol max_count tol bmp_file1 bmp_file2
```

Both max\_count and tol should be replaced with integers. bmp\_file1 and bmp\_file2 should be replaced with the actual filenames of the BMP files you want to compare.

The comparison takes place only if the two files have identical header information. If not, the comparison stops.

A pixel from bmp\_file1 and the corresponding pixels from bmp\_file2 are checked for the RGB information. The (absolute) differences in R, G, and B values are added. If the sum is greater than the tol, the two pixels are considered to be different.

The output of the executable is made up of up to three parts. The optional first part reports the first max\_count pixels that are different in the two given files. The coordinates of these pixels are given, with a pixel per line.

The second to last output is a number that corresponds to the total number of pixels in the BMP file.

The last output is a number that corresponds to the total number of pixels that are different.

If you just want to count the number of different pixels, do

```
./idiff_tol 0 0 bmp_file1 bmp_file2
```

If you allow only one of the RGB values to differ by 1, and do not want to know the locations:

```
./idiff_tol 0 1 bmp_file1 bmp_file2
```

If you allow only the sum of the (absolute) differences of RGB values to be no more than 2, and want to know the first 5 locations that are different:

```
./idiff_tol 5 2 bmp_file1 bmp_file2
```

#### 9.4 Grading

We will write a main function that attempts to call the function convert\_24\_to\_16\_BMP\_image\_with\_dithering. If we are able to successfully compile this main function together with your submitted answer04.c file, we will evaluate your submission for bonus points. You may earn up to 50 bonus points for this function.

Since the PAs accounts for 45 points of the overall grade, the bonus points are equivalent to 4.5 points of the overall grade.