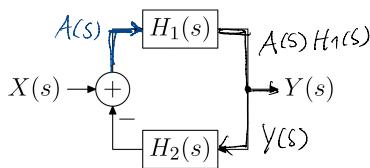


7. Tutorium : Lineare Systeme im Frequenzbereich, Blockschaltbilder

2. 1. c)



ges. : $H_{\text{ges}}(s)$, PN-Verteilungen

$$\star H(s) = \frac{\text{Ausgang}}{\text{Eingang}} = \frac{Y(s)}{X(s)}$$

$$\begin{aligned} Y(s) &= A(s) \cdot H_1(s) = X(s)H_1(s) - H_1(s)H_2(s)Y(s) \\ A(s) &= X(s) - H_2(s) \cdot Y(s) \end{aligned}$$

$$Y(s) = X(s)H_1(s) - H_1(s)H_2(s)Y(s)$$

$$Y(s) + H_1(s)H_2(s)Y(s) = X(s)H_1(s)$$

$$Y(s)(1 + H_1H_2) = X(s)H_1(s)$$

$$\therefore Y(s) = \frac{X(s)H_1(s)}{1 + H_1H_2}$$

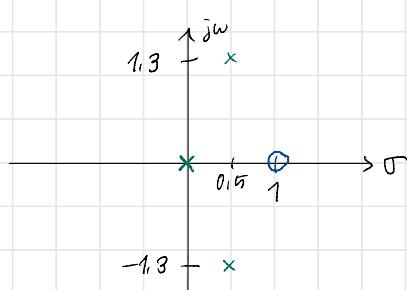
$$\therefore H_{\text{ges}}(s) = \frac{Y(s)}{X(s)} = \frac{X(s)H_1(s)}{1 + H_1H_2} \cdot \frac{1}{X(s)} = \frac{H_1(s)}{1 + H_1H_2} = \frac{\frac{s-1}{s+1}}{1 + \frac{s-1}{s+1} \cdot \frac{s^2+1}{s^2+1}} = \frac{\frac{s-1}{s+1}}{1 + \frac{s^3+s^2-s-1}{s^3+s^2+1}}$$

$$\frac{\frac{s-1}{s+1}}{1 + \frac{s^3+s^2-s-1}{s^3+s^2+1}} = \frac{\frac{s-1}{s+1}}{\cancel{(s+1)s^2+s^3+s^2+1}} = \frac{\cancel{(s-1)}}{\cancel{(s+1)s^2+s^3+s^2+1}} =$$

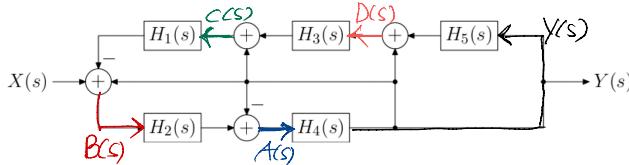
$$\frac{(s-1)}{(s^3+s^2+2s)} = 0 \quad s_N = 1 \quad \text{Nullstelle}$$

$$\left\{ \begin{array}{l} s_{P1} = 0 \\ s_{P2,3} = \frac{1 \pm \sqrt{1-4}}{2} \end{array} \right.$$

$$= \frac{1}{2} \pm \sqrt{\frac{-3}{4}} = \frac{1}{2} \pm \frac{\sqrt{7}}{2} j \approx 1,3$$



2.1. e)



$$\text{ges. : } H_{\text{ges}}(s) = \frac{Y(s)}{X(s)}$$

$$Y(s) = A(s) \cdot H_4(s) = X(s) H_2 H_4 - Y(s) (\underbrace{H_4 - H_2 H_4 + H_1 H_2 H_4 + H_1 H_2 H_3 H_4 + H_1 H_2 H_3 H_5}_{K})$$

$$A(s) = -Y(s) + B(s) \cdot H_2(s) = X(s) H_2(s) - Y(s) (1 - H_2 + H_1 H_2 + H_1 H_2 H_3 + H_1 H_2 H_5)$$

$$B(s) = X(s) + Y(s) - C(s) H_1(s) = X(s) + Y(s) (1 - H_1 - H_1 H_3 - H_1 H_2 H_5)$$

$$C(s) = Y(s) + D(s) H_3(s) = Y(s) (1 + H_3(s) + H_3 H_5)$$

$$D(s) = Y(s) + H_5(s) Y(s) = Y(s) (1 + H_5)$$

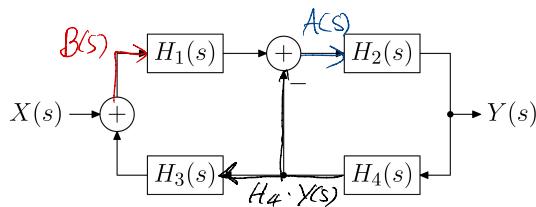
$$Y(s) = X(s) H_2 H_4 - Y(s) \cdot K$$

$$Y(s) (1 + K) = X(s) H_2 H_4$$

$$\Leftrightarrow Y(s) = \frac{X(s) H_2 H_4}{1 + K}$$

$$\therefore H_{\text{ges}}(s) = \frac{Y(s)}{X(s)} = \frac{\cancel{X(s)} H_2 H_4}{1 + K} \times \frac{1}{\cancel{X(s)}} = \frac{H_2 H_4}{1 + K}$$

Q. 1, d)



$$Y(s) = A(s) \cdot H_2(s) = X(s)H_1H_2 + H_1H_2H_4Y(s) - H_2H_4Y(s)$$

$$A(s) = B(s) \cdot H_1(s) - H_4(s) \cdot Y(s) = X(s)H_1 + H_1H_4Y(s) - H_4Y(s)$$

$$B(s) = X(s) + H_4(s) \cdot Y(s)$$

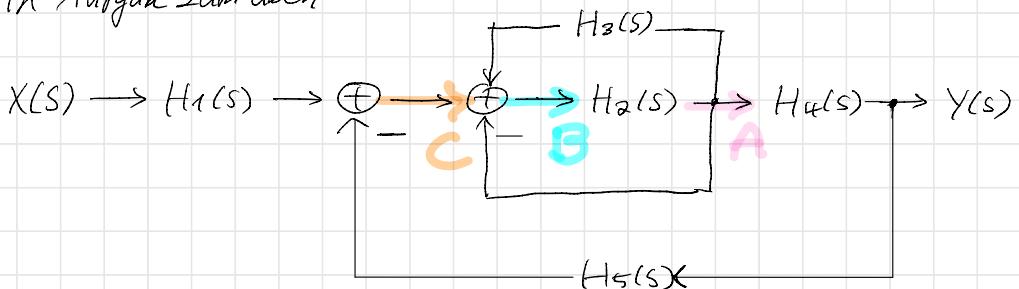
$$Y(s) - H_1H_2H_4Y(s) + H_2H_4Y(s) = X(s)H_1H_2$$

$$\Leftrightarrow Y(s)(1 - H_1H_2H_4 + H_2H_4) = X(s)H_1H_2$$

$$\Leftrightarrow Y(s) = \frac{X(s)H_1H_2}{1 - H_1H_2H_4 + H_2H_4}$$

$$\therefore H_{sys}(s) = \frac{Y(s)}{X(s)} = \frac{\cancel{X(s)}H_1H_2}{1 - H_1H_2H_4 + H_2H_4} \cdot \frac{1}{\cancel{X(s)}}$$
$$= \frac{H_1H_2}{1 - H_1H_2H_4 + H_2H_4}$$

AK Aufgabe zum Üben



Bestimme A, B und C
Y(s) und H(s)

$$Y(s) = A(s)H_4(s) = B(s)H_2H_4$$

$$A(s) = B(s)H_2(s)$$

$$B(s) = C(s) + A(s)H_3(s) - A(s) = X(s)H_1 - H_5Y(s) + A(s)H_3(s) - A(s)$$

$$C(s) = X(s)H_1(s) - H_5(s)Y(s)$$

$$\begin{aligned} B(s) &= X(s)H_1 - H_5Y(s) + A(s)H_3(s) - A(s) \\ &= X(s)H_1 - H_5Y(s) + B(s)H_2H_3 - B(s)H_2(s) \end{aligned}$$

$$B(s)(1 - H_2H_3 + H_2) = X(s)H_1 - H_5Y(s)$$

$$\Leftrightarrow B(s) = \frac{X(s)H_1 - H_5Y(s)}{1 - H_2H_3 + H_2}$$

$$Y(s) = B(s)H_2H_4 = \frac{X(s)H_1H_2H_4 - H_2H_4H_5Y(s)}{1 - H_2H_3 + H_2}$$

$$= \frac{X(s)H_1H_2H_4}{1 - H_2H_3 + H_2} - \frac{H_2H_4H_5Y(s)}{1 - H_2H_3 + H_2}$$

$$\Leftrightarrow Y(s) \left(1 + \frac{H_2H_4H_5}{1 - H_2H_3 + H_2} \right) = \frac{X(s)H_1H_2H_4}{1 - H_2H_3 + H_2}$$

$$\Leftrightarrow Y(s) = \frac{X(s)H_1H_2H_4}{1 - H_2H_3 + H_2} \cdot \frac{1 - H_2H_3 + H_2}{1 - H_2H_3 + H_2 + H_2H_4H_5} = \frac{X(s)H_1H_2H_4}{1 - H_2H_3 + H_2 + H_2H_4H_5}$$

$$\therefore H(s) = \frac{X(s)H_1H_2H_4}{1 - H_2H_3 + H_2 + H_2H_4H_5} \cdot \frac{1}{X(s)} = \frac{H_1H_2H_4}{1 - H_2H_3 + H_2 + H_2H_4H_5}$$