

# Task 1

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1. Real symmetric matrices, upper and lower triangular matrices and diagonal matrices have only real eigenvalues
2. The eigenvalues of triangular matrix are the elements on the diagonal of the matrix.
3. For a diagonal matrix, its eigenvalues are also the elements on the diagonal

The eigenvectors of diagonal matrix  $\text{diag}(a_1, \dots, a_n)$  are  $a_1, \dots, a_n$  and the corresponding eigenvectors are their standard basis vectors  $e_1, \dots, e_n$ .

## Task 2.

$$1. a) \bar{x}_1 = \frac{1}{2}(-1+1)=0, \bar{x}_2 = \frac{1}{2}(0+0)=0, \bar{x}_3 = \frac{1}{2}(0+0)=0, \bar{X} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\hat{\Sigma} = \frac{1}{n} (X - \bar{X})(X - \bar{X})^T$$

$$= \frac{1}{2} \begin{bmatrix} -1 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Standard PCA

$$b) \det(\hat{\Sigma} - \lambda I) = \begin{vmatrix} 1-\lambda & 0 & 0 \\ 0 & 0-\lambda & 0 \\ 0 & 0 & 0-\lambda \end{vmatrix} = -\lambda^3 + \lambda^2 = -\lambda^2(\lambda-1) = 0$$

$$\lambda_1 = 1, \lambda_2 = \lambda_3 = 0$$

$$(A - \lambda_1 I) \cdot W = 0 \Rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} w_2 = 0 \\ w_3 = 0 \end{cases} \Rightarrow W = \left\{ X_1 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{So the first principal direction is } W = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$c) H = W^T X$$

$$= [1 \ 0 \ 0] \begin{bmatrix} -1 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} = [-1, 1]$$

$$2. a) K = X^T X = \begin{bmatrix} -1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

Linear Kernel PCA

$$b) \det(K - \lambda I) = \begin{vmatrix} 1-\lambda & -1 \\ -1 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 - (-1)^2 = \lambda^2 - 2\lambda + 1 - 1 = \lambda(\lambda-2)$$

$$\lambda_1 = 0, \lambda_2 = 2$$

$$(A - \lambda_2 I) \alpha = 0 \Rightarrow \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \alpha_1 + \alpha_2 = 0$$

$$\Rightarrow \alpha = \left\{ X_2 \cdot \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$K\alpha = \lambda\alpha$$

$$K \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$$

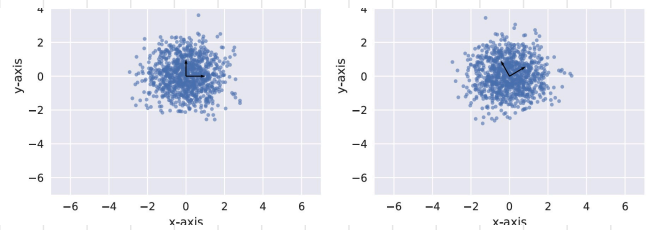
$$= \begin{bmatrix} \alpha_1 - \alpha_2 \\ -\alpha_1 + \alpha_2 \end{bmatrix} = \begin{bmatrix} 2\alpha_1 \\ 2\alpha_2 \end{bmatrix}$$

$$\Rightarrow \alpha_1 + \alpha_2 = 0$$

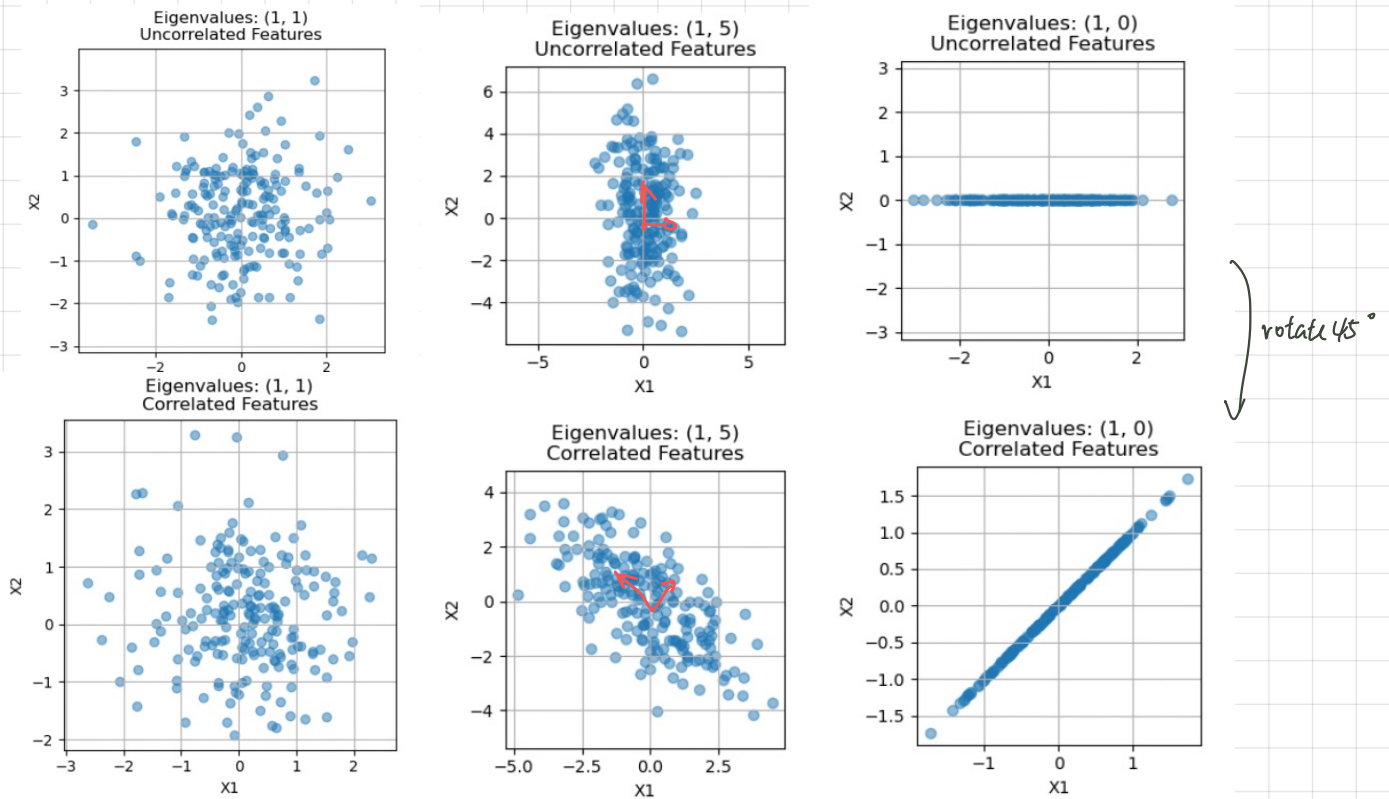
$$c) W = X_{\alpha} = \begin{bmatrix} -1 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$$

$$\lambda_1 = 1$$

$$\lambda_2 = 1$$



### Task 3.



### Task 4

1) Since  $S_{\alpha}$  is the scaled matrix, we have

$$S_{\alpha} v = \alpha S v \Rightarrow S_{\alpha} v = \alpha (S v)$$

Since  $S v = \lambda v$ , we get

$$S_{\alpha} v = \alpha (\lambda v) \Rightarrow S_{\alpha} v = \alpha \lambda v$$

This shows that  $v$  is also an eigenvector of  $S_{\alpha}$  with the eigenvalue  $\alpha \lambda$ .

$$\alpha S v = \alpha \lambda v$$

$$S_{\alpha} v = \alpha \lambda v$$

$$2) A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \Rightarrow A \text{ is an orthogonal matrix}$$

$$\det(A) = 0 \cdot 0 - 1 \cdot 1 = -1 \Rightarrow A \text{ is not a rotation matrix.}$$

Rotation Matrices

$$R_{\theta} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\det(R_{\theta}) = +1$$

### Task 5.

$$\tilde{X} = [\tilde{x}_1, \tilde{x}_2, \tilde{x}_3] = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 0 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$

$$H = [h_1, h_2, h_3] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$H = I$$

$$\tilde{X} = W \cdot I = W$$

$$\Rightarrow \tilde{X} = W$$

$$\tilde{X} = WH \Rightarrow W = \tilde{X} H^{-1} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 0 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 0 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$