

# Remotely Operated Vehicle (ROV) with Touch Sensing Control

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## I. INTRODUCTION

## II. TOUCHING PAD

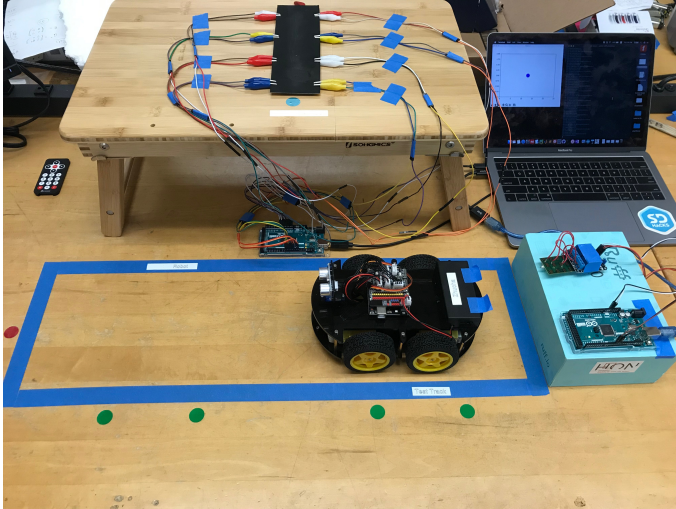


FIG. 1. Setup of ROV and touching pad

### A. Electric sensing principle

### B. Touching pad setup

### C. Measuring procedures

### D. Implementation

## III. VISUALIZATION AND FINGER LOCALIZATION

### A. Voltage color-map

### B. Machine learning for finger localization

## IV. REMOTELY OPERATED ROBOT (ROV)

### A. Modules

### B. Control method

### C. Communication with the touching pad

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