#### VARIATION ON A VARIATIONAL PRINCIPLE

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ABSTRACT. We prove that alternating links in the thickened torus remain hyperbolic after certain augmen-

# 1. Introduction

Alice TODO

## Definitions, Notations, and Conventions

Always assume surface  $\Sigma$  (our case  $\Sigma = \mathbb{T}^2$ ) is oriented.

define cellular decomp of surface

V, E, F are set of vertices, edges, faces.

 $\vec{E}$  is the set of oriented edges. We may identify an oriented edge  $\vec{e}$  with the pair  $(f_{\vec{e}}, e)$ , where  $f_{\vec{e}}$  is the face to the left of  $\vec{e}$ .

Recall circle pattern.

A circle pattern is determined by the radius of the circle  $C_f$  associated to each face,  $r_f$ , and the angle that each edge subtends in adjacent faces,  $\varphi_{\vec{e}}$ . (see figure TODO) Thus determines, and is determined by a point in  $\mathfrak{R} \times \mathfrak{Q}$ , where

- $\bullet \ \underline{\mathfrak{R}} := \mathbb{R}_{+}^{F} = \{ (r_f)_{f \in F} | r_f \in \mathbb{R}_{+} \}$   $\bullet \ \underline{\mathfrak{Q}} := \mathbb{R}^{\vec{E}} = \{ (\varphi_{\vec{e}})_{\vec{e} \in \vec{E}} | \varphi_{\vec{e}} \in \mathbb{R} \}$

but clearly not every point  $c \in \mathfrak{R} \times \mathfrak{Q}$  determines a circle pattern.

On  $\Re \times \mathfrak{Q}$ , there are several functions to consider:

- $\Phi_f = 2 \sum_{\vec{e} \in \partial f} \varphi_{\vec{e}}$ , measuring the cone angle at the center of  $C_f$
- $\bullet \ \theta_e = \pi \varphi_{\vec{e}} \varphi_{\leftarrow}$
- $l_{\vec{e}} = r_{f_{\vec{e}}} \sin \varphi_{\vec{e}}$

These fit together to give maps to the following spaces:

- $\bullet \ \underline{\boldsymbol{\Phi}} := \mathbb{R}^F = \{ (\boldsymbol{\Phi}_f)_{f \in F} | \boldsymbol{\Phi}_f \in \mathbb{R} \}$   $\bullet \ \underline{\boldsymbol{\Theta}} := \mathbb{R}^E = \{ (\boldsymbol{\theta}_e)_{e \in E} | \boldsymbol{\theta}_e \in \mathbb{R} \}$
- $\mathfrak{L} := \mathbb{R}^{\vec{E}} = \{(l_{\vec{e}})_{\vec{e} \in E} | l_{\vec{e}} \in \mathbb{R}\}$

Our main argument is to deform "degenerate" circle patterns, where adjacent circles may be identical or tangent, into ones that don't look so degenerate, hence it is conveneint to extend the notion of circle pattern:

**Definition 1.1.** An extended circle pattern is  $c = ((r_f), (\varphi_{\vec{e}})) \in \underline{\mathfrak{R}} \times \underline{\mathfrak{Q}}$  such that  $l_{\vec{e}} = l_{\leftarrow}$  for all edges  $e \in E$ . We denote by  $\underline{\mathfrak{C}}$  the set of extended circle patterns.

$$\underline{\mathfrak{C}} = \{l_{\vec{e}} = l_{\stackrel{\leftarrow}{e}}\} \quad \subseteq \quad \underline{\mathfrak{R}} \times \underline{\mathfrak{Q}} \xrightarrow{\Theta} \underline{\Theta}$$

$$\downarrow_{\Phi}$$

[Check this] The usual notion of circle pattern would be restricted to those  $c \in \underline{\mathfrak{C}}$  with  $\varphi_{\vec{e}} \in (0,\pi)$  and  $\theta_e \in (0,\pi)$ . One may consider deforming a circle pattern so as to have some  $\theta_e$  approach 0 or  $\pi$ . The limit  $\theta_e \to \pi$  is easy to picture, one simply gets that the two circles  $C_f, C_{f'}$  of the adjacent faces become tangent. The limit  $\theta_e \to 0$  is a bit more complex, as the final shape of  $Q_e$  (the quadrangle associated to e) depends also on  $\varphi_{\vec{e}}$  (which equals  $\pi - \varphi_{\vec{e}}$  in the limit. If we parametrize circle patterns by  $(r_f)$  and  $(\theta_e)$  as in TODO [?BS], the limiting shape would depend on how  $r_f$  approaches  $r_{f'}$ , some sort of blow up stuff TODO.

We will mostly be working with extended circle patterns that mostly "look normal", with all  $\varphi_{\vec{e}}$  in some range  $(-\varepsilon, \pi + \varepsilon)$ .

**Definition 1.2.** An extended circle pattern is said to be *face non-singular* if  $\Phi_f = 2\pi$  for all faces f; it is said to be *vertex non-singular* if  $\sum_{e\ni v} \theta_e = 2\pi$  for all vertices v. Finally it is said to be *non-singular* if it is both.

non-degenerate circle pattern?

**Definition 1.3.** Given some extended circle pattern  $c \in \underline{\mathfrak{C}}$ , we say a face f is *convex* if for all edges  $\vec{e} \in \partial f$ , we have  $\varphi_{\vec{e}} \in [0, \pi/2)$ . We say f is *thin* if exactly two edges  $\vec{e}, \vec{e'} \in \partial f$  have nonzero  $\varphi_{\bullet}$ , and furtheremore,  $0 < \varphi_{\vec{e}} = \pi - \varphi_{\vec{e'}} < \pi/2$ .

TODO figures for convex, thin faces

**Definition 1.4.** Given an extended circle pattern  $c \in \underline{\mathfrak{C}}$ , an edge e is *short* if it has length 0,  $l_{\vec{e}} = l_{\overleftarrow{e}} = 0$ ; it is *long* otherwise.

**Definition 1.5.** Given an extended circle pattern  $c \in \underline{\mathfrak{C}}$ , a thick path is a sequence of faces  $f_0, f_1, \ldots, f_n$  such that  $f_i, f_{i+1}$  share a long edge. A thick cycle is a thick path with  $f_0 = f_n$ .

**Definition 1.6.** A slit-convex circle pattern is an extended circle pattern  $c \in \underline{\mathfrak{C}}$  such that all its faces are either convex or thin.

**Lemma 1.7.**  $\underline{\mathfrak{C}}$  is a manifold near slit-convex circle patterns.

Proof.  $d(l_{\vec{e}} - l_{\overleftarrow{e}}) = \sin \varphi_{\vec{e}} dr_{f_{\vec{e}}} + r_{f_{\vec{e}}} \cos \varphi_{\vec{e}} d\varphi_{\vec{e}} - \sin \varphi_{\overleftarrow{e}} dr_{f_{\overleftarrow{e}}} - r_{f_{\overleftarrow{e}}} \cos \varphi_{\overleftarrow{e}} d\varphi_{\overleftarrow{e}}$ , and since having only convex of thin faces implies  $\cos \varphi_{\vec{e}} \neq 0$ , we see the differentials are linearly independent at a slit-convex circle pattern c.

# 2. Main ?? results

TODO: make a list of images of vectors, e.g.  $\Theta_*(\frac{\partial}{\partial \varphi_{\vec{e}}}) = -\frac{\partial}{\partial \theta_e}$ .

Our general strategry for obtaining a (non-singular) circle pattern is to start with an assignment  $\underline{\theta} = (\theta_{\bullet})$  for which we know an extended circle pattern exists (say from results of [?BS]), and a path  $\gamma$  in  $\underline{\Theta}$  starting at  $\underline{\theta}$ . We then attempt to lift  $\gamma$  to a path  $\tilde{\gamma}$  in  $\underline{\mathfrak{C}}$ , so that  $\tilde{\gamma}$  remains (face) non-singular (vertex non-singularity is already determined by  $\gamma$ ).

Note that since  $\sum_{e \in E} \theta_e = 2\pi |E| - \sum_{\vec{e} \in \vec{E}} \varphi_{\vec{e}} = 2\pi |E| - \sum_{f \in F} \Phi_f$ , we see that maintaining face non-singularity of  $\tilde{\gamma}$  forces  $\sum \theta_e$  to be constant. We will show that this is the only obstruction on  $\gamma$  to the lifting to such  $\tilde{\gamma}$ .

To that end, let L be the (|E|-1)-plane distribution on  $\underline{\Theta}$  tangent to the level sets of  $\sum \theta_v$ . The following proposition proves it (avoid using 'it'?) up to first order at a point:

**Proposition 2.1.** Let  $c \in \underline{\mathfrak{C}}$  be an extended circle pattern such that

- $\Phi_f = 2\pi \text{ for all } f \in F;$
- all faces are eithe convex or thin, with at least one convex face;
- every pair of faces is connected by a thick path.

Let  $K_c = \ker(\Phi_*|_c : T_c\underline{\mathfrak{C}} \to T_{\Phi(c)}\underline{\Phi})$ . Then  $\Theta_*(K_c) = L_{\Theta(c)}$ .

In other words, for any vector  $a = a^e \partial_{\theta_e}$  with sum of coefficients 0, one can vary c so that its first order change in  $\theta_{\bullet}$  is a, and also remains face non-singular up to first order.

Before we prove this, it is convenient to first prove the following:

**Lemma 2.2.** Let  $c \in \mathfrak{C}$  be as in Proposition 2.1. Then  $\Phi$  is a submersion in a neighbourhood of c.

*Proof.* We construct vectors  $\beta_f \in T_c \underline{\mathfrak{C}}$  so that  $\Phi_*(\beta_f) = \frac{\partial}{\partial \Phi_f}$ . The vector

(2.1) 
$$\alpha_f := \frac{\partial}{\partial r_f} - \sum_{\vec{e} \in \partial f} \frac{\tan \varphi_{\vec{e}}}{r_f} \frac{\partial}{\partial \varphi_{\vec{e}}} \in T(\underline{\mathfrak{R}} \times \underline{\mathfrak{Q}})$$

doesn't change  $l_{\vec{e}}$ , so is in  $T_c \underline{\mathfrak{C}}$ . Intuitively,  $\alpha_f$  is like pulling the center of  $C_f$  up off the plane, increasing  $r_f$ and decreasing all  $\varphi$ 's. Its pushforward under  $\Phi$  is simply  $\Phi_*(\beta_f) = \frac{1}{r_f} \sum_{\vec{e} \in \partial f} \tan \varphi_{\vec{e}} \frac{\partial}{\partial \Phi_f}$ .

If f is a convex face, then the  $\tan \varphi_{\vec{e}}$  are all non-negative, being 0 if and only if e is short. so  $\Phi_*(\alpha_f)$  is a negative multiple of  $\frac{\partial}{\partial \Phi_f}$ ; we choose  $\beta$  so that

(2.2) 
$$\beta_f := \beta \cdot \alpha_f; \quad \Phi_*(\beta_f) = \frac{\partial}{\partial \Phi_f}$$

If f is thin, we actually have that  $\alpha_f \in K_c$ , since the coefficients sum to 0 so that  $\Phi_*(\alpha_f) = 0$ , so we need a different approach. First suppose f shares an edge e with a convex face f'. We can increase  $l_e$  by increasing  $\varphi_{\vec{e}}, \varphi_{\leftarrow}$  while holding  $r_f, r_{f'}$  constant. This will affect both  $\Phi_f, \Phi_{f'}$ , so we use  $\beta_{f'}$  to make  $\Phi_{f'}$ constant. More explicitly, consider

(2.3) 
$$\alpha_e = \frac{1}{2r_f \cos \varphi_{\vec{e}}} \frac{\partial}{\partial \varphi_{\vec{e}}} + \frac{1}{2r_{f'} \cos \varphi_{\leftarrow}} \frac{\partial}{\partial \varphi_{\leftarrow}}$$

Then we can take

(2.4) 
$$\beta_f = r_f \cos \varphi_{\vec{e}} (\alpha_e - \frac{1}{r_{f'} \cos \varphi_{\vec{e}}} \beta_{f'})$$

which increases  $l_{\vec{e}}, l_{\overleftarrow{e}}$  at unit speed,  $dl_{\vec{e}}(\alpha_e) = dl_{\overleftarrow{e}}(\alpha_e) = 1$ . We can repeat this procedure with f' set to this thin face, and f set to another thin face adjacent to it, etc.

Proof of Proposition 2.1. We construct a vector  $u_e \in K_c \subseteq T_c \underline{\mathfrak{C}}$  for each edge e and show that  $\{\Theta_*(u_e)\}_{e \in E}$ spans an |E|-1 dimensional space, thus must be equal  $L_{\Theta_c}$ .

For long edges e,  $u_e$  will have the following property: if  $\Theta_*(u_e) = \sum_{e' \in E} a^{e'} \frac{\partial}{\partial \theta_{-}}$ , then

- $\begin{aligned} \bullet & a^e = 1; \\ \bullet & a^{e'} \leq 0 \text{ for all } e' \neq e; \\ \bullet & a^{e'} = 0 \text{ for short edges } e'. \end{aligned}$

Furthermore, these  $u_e$ 's collectively satisfy the following connectivity property: consider the graph  $G_{long}$ whose vertex set is the set of long edges, and we connect two long edges e, e' by an edge if there is some e'such that  $a^e, a^{e'}$  are both nonzero in  $\Theta_*(u_{e''})$ ; then  $G_{\text{long}}$  is connected.

In addition, for short edges e,  $u_e$  have the following property: again writing  $\Theta_*(u_e) = \sum_{e' \in E} a^{e'} \frac{\partial}{\partial \theta_i}$ , one has

- $a^e = 1$ ;  $a^{e'} = 0$  for other short edges e'.

Let us first suppose we have constructed such  $u_e$ , and show that these properties ensure that  $\{\Theta_*(u_e)\}_{e\in E}$ spans an |E|-1 dimensional space. This is a simple exercise in linear algebra, but we show it for completeness.

Put the  $\Theta_*(u_e)$ 's into a  $E \times E$  matrix, denoted M, so that the e-th row corresponds to  $u_e$ . By virtue of  $u_e \in K_c$ , we have that  $(1 \ 1 \ \cdots \ 1)^T$  is in the null space of M; our goal is to show that it spans the null space.

Suppose  $b = (b_e)^T$  is in the null space of M. Reorder E, if necessary, so that long edges come before short edges. Then by the last property of  $u_e$ 's for long edges, the top right block of long-by-short entries are 0. Thus the vector  $b_{\text{long}} := (b_e)_{e \in \text{long}}^T$  is in the null space of the submatrix  $M_{\text{long}}$  of long-by-long entries.

Let  $|b_e|$  be the largest among components of  $b_{long}$ ; rescale b so that  $b_e = 1$ . The e-th component of  $M_{\text{long}}b_{\text{long}}$  is  $1-\sum a^{e'}b_{e'}$ . Since  $\sum a^{e'}=1$ , this can 0 if and only if for all e' with  $a^{e'}<0$ , we have exactly  $b_{e'} = 1$ . By connectedness of  $G_{long}$ , this implies  $b_{long} = (1 \cdots 1)^T$ .

Returning to the full M, it is now easy to see that for a short edge e, by looking at the e-th row of M, we have  $b_e = \sum a^{e'} = 1$ , so we are done.

Now we construct the  $u_e$ 's. First suppose that e is a long edge between two convex faces f, f' (so  $\vec{e} \in \partial f, \ \vec{e} \in \partial f'$ ). Observe that  $\alpha_e$  from (2.3) increases  $\Phi_f$  and  $\Phi_{f'}$ , and we can compensate using  $\beta_f$  from (2.2), so we consider

$$w_e = \alpha_e - \frac{1}{\cos \varphi_{\vec{e}}} \beta_f - \frac{1}{\cos \varphi_{\overleftarrow{e}}} \beta_{f'} \in K_c$$

For  $\vec{e'} \in \partial f \cup \partial f' \setminus \{\vec{e}, \overleftarrow{e}\}$ , the  $\frac{\partial}{\partial \varphi_{\vec{e'}}}$  component only appears in  $\beta_f$  or  $\beta_{f'}$ , which is positive by construction (this requires f, f' to be convex faces); thus,  $d\theta_{e'}(w_e) \geq 0$  for such e', and is equal 0 if and only if e' is short. Finally, since  $w_e \in K_c$ , it leaves the sum  $\sum_{e \in E} \theta_e$  constant, so  $d\theta_e(w_e) < 0$ , so we can take

$$(2.5) u_e := (d\theta_e(w_e))^{-1} \cdot w_e$$

In general, we consider a thick path of faces  $f_0, \ldots, f_n$ , such that all faces except  $f_0$  and  $f_n$  are thin, and  $f_i$  are distinct except possibly  $f_0 = f_n$ . Let  $e_i$  be the long edge between  $f_i$  and  $f_{i+1}$ , and orient so that  $\vec{e_i} \in \partial f_i$ ,  $\overleftarrow{e_i} \in \partial f_{i+1}$ .

We will construct  $u_{e_i}$  for  $i = 1, \ldots, n$ .

We want to increase the lengths of  $e_i$ 's all together. Let  $E' = \{\vec{e_i}, \stackrel{\leftarrow}{e_i} | i = 1, \dots, n\}$ . Consider

$$x := \sum_{i=0,\dots,n-1} \alpha_{e_i} = \sum_{\vec{e} \in E'} \frac{1}{2r_{f_{\vec{e}}} \cos \varphi_{\vec{e}}} \frac{\partial}{\partial \varphi_{\vec{e}}}$$

with  $\alpha_e$  from (2.3). It is clear that x increases all oriented  $e_i$  lengths  $l_{\vec{e}}$  equally fast, i.e.  $dl_{\vec{e}_i}(x) = dl_{\vec{e}_i}(x) = 1$  for all i, so  $x \in T_c \mathfrak{C}$ . It is also clear that for the thin faces  $f_i$ , x makes one of the angles  $\varphi_{e_{i-1}}$ ,  $\varphi_{\vec{e}_i}$  increase and makes the other decrease, both at the same rate, thus  $d\Phi_{f_i}(x) = 0$ .

The vector x increase  $\Phi_{f_0}$  and  $\Phi_{f_n}$ , so it is compensated using  $\beta_f$ 's, so that

$$y := x - \frac{1}{r_{f_0} \cos \varphi_{\vec{e_0}}} \beta_{f_0} - \frac{1}{r_{f_n} \cos \varphi_{\vec{e_{n-1}}}} \beta_{f_n} \in K_c$$

Before we modify y to give the desired  $u_{e_i}$ , we note that for  $\vec{e} \in (\cup \partial f_i) \backslash E'$ , the coefficient of  $\frac{\partial}{\partial \varphi_{\vec{e}}}$  in y is non-positive, and is 0 if and only if e is short; so  $\Theta_*(y)$  satisfies two of the three properties desired in  $u_e$ .

Recall that for thin face f,  $\alpha_f$  from (2.1) is in  $K_c$ , and we have

$$\Theta_*(\frac{r_{f_i}}{\tan \varphi_{\vec{e_i}}}\alpha_{f_i}) = \frac{\partial}{\partial \theta_{e_i}} - \frac{\partial}{\partial \theta_{e_{i-1}}}$$

Write  $\bar{\alpha}_{f_i} = \frac{r_{f_i}}{\tan \varphi_{e_i^*}} \alpha_{f_i}$ . Then it is easy to see that using  $\bar{\alpha}_{f_i}$ 's, we can push the coefficients of  $\frac{\partial}{\partial \theta_{e_i}}$ 's in  $\Theta_*(y)$  around so only one is nonzero. More precisely, if  $\Theta_*(y) = \sum_e y^e \frac{\partial}{\partial \theta_e}$ , the image under  $\Theta_*$  of the vector

$$\bar{u}_{e_0} := y - y^{e_{n-1}} \bar{\alpha}_{f_{n-1}} - (y^{e_{n-2}} + y^{e_{n-1}}) \bar{\alpha}_{f_{n-2}} - \dots$$

would have  $\frac{\partial}{\partial \theta_{e_i}}$  coefficients 0 for all i except 0. Finally, we can take

$$u_{e_0} := (d\theta_{e_0}(\bar{u}_{e_0}))^{-1} \cdot \bar{u}_{e_0}; \quad u_{e_i} = u_{e_{i-1}} + \bar{\alpha}_{f_i}$$

We still need to show the collective connectivity property of the  $u_e$ 's. It is easy to see that the long edges of a convex face are connected in  $G_{\text{long}}$  (for example,  $u_{e_0}$  defined above clearly does it for  $f_0$ ). Furthermore, all the  $\Theta_*(u_{e_i})$  share most of the same coefficients, so  $e_i$  are in the same connected component of  $G_{\text{long}}$ . Thus connectivity of  $G_{\text{long}}$  follows from the thick-path-connectivity of faces.

Finally, for short edges e, we simply define  $u_e$  as in (2.5) (here we do not worry about whether faces are thin or convex, as there is no non-positivity condition of  $a^{e'}$  is absent).

**Proposition 2.3.** Let  $c \in \underline{\mathfrak{C}}$  be as in Proposition 2.1. Given a path  $\gamma : [0, \varepsilon] \to \underline{\Theta}$  starting at  $\gamma(0) = \Theta(c)$  and has constant value  $(\sum \theta_e) \circ \gamma$ , there exists a lift  $\tilde{\gamma} : [0, \varepsilon] \to \underline{\mathfrak{C}}$  that starts at  $\tilde{\gamma}(0) = c$  and has constant value  $\Phi \circ \tilde{\gamma}$ .

$$Proof.$$
 TODO.

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<sup>&</sup>lt;sup>1</sup>Picture a slinky linking two rocks.