

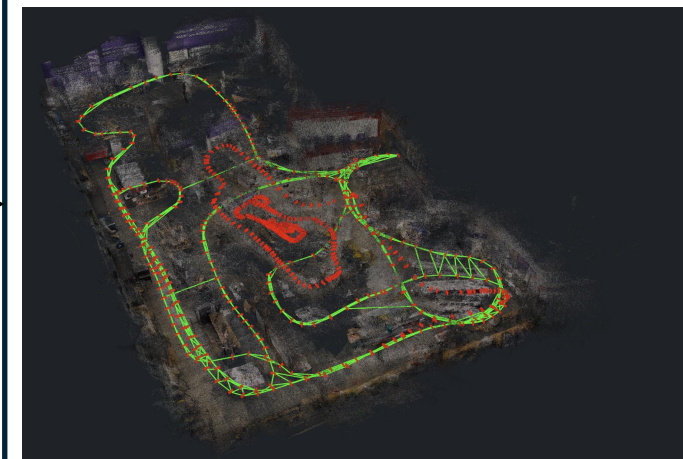
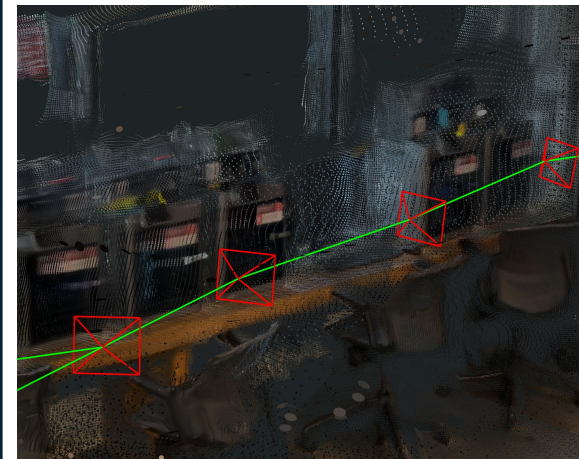
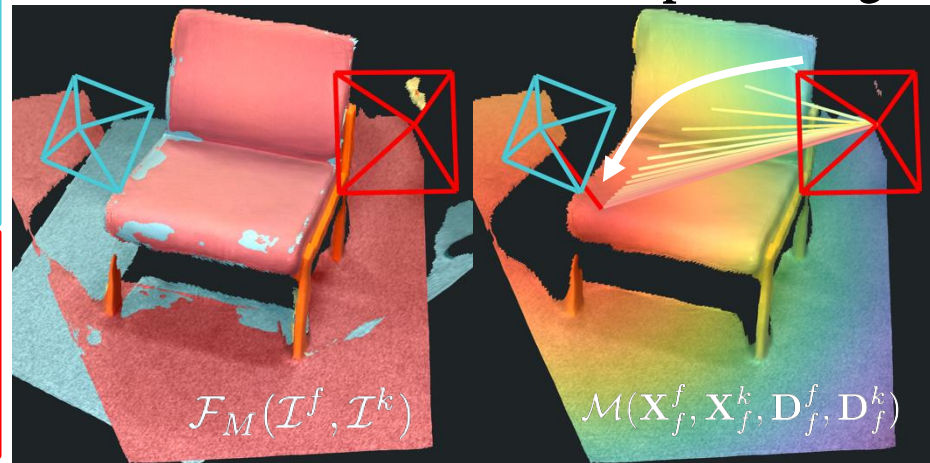
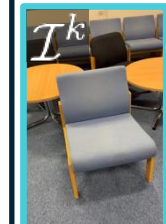
New Image ↓ Current Keyframe

MASt3R

Pointmap Matching

Tracking and Pointmap Fusion

Loop Closure and Global Opt.



Loop Closure Candidates