Appendices to our MedAI 2024 Paper*

1	Hov	How we extract the radiomics features from the phantoms?				
	1.1	Dataset				
	1.2	Region of Interests (ROIs)				
	1.3	Extraction of Radiomics Features				
	1.4	Existence of Scanner Effects				
	1.5	A Simple Example to Remove Scanner Effects				
2	Nev	New Method for Harmonizing Scanner Effects Across Classes				
	2.1	Notations				
	2.2	Model without scanner effects				
	2.3	Model with scanner effects				
	2.4	Solve the model by EM algorithm				
		2.4.1 E step				
		2.4.2 M step				
		2.4.3 Summary of the algorithm				
	2.5	Remove scanner effects with the estimated parameters				
	2.6	Experiment results and discussion				

1 How we extract the radiomics features from the phantoms?

1.1 Dataset

Our dataset contains MRI data of two kinds of phantoms (i.e. homogeneous phantom and heterogeneous phantom) designed by Ammari et al. [1], the details are described as below.

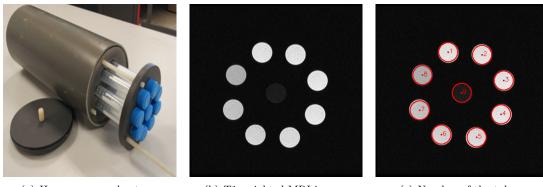
• Homogeneous Phantom

Homogeneous phantom is designed to mimic cerebrospinal fluid and opacified blood vessels. It is defined with different gadolinium concentrations: eight 30-ml tubes were filled with demineralized water mixed with increasing gadolinium chelate concentration (Gadoteric Acid; Dotarem \mathbb{R} , Guerbet): 0.25, 0.5, 0.75, 1, 1.25, 1.5, 1.75 and 2 mmol/l and a central demineralized water tube. The nine tubes were numbered as 1 to 9, as shown in Figure 1.

• Heterogeneous Phantom

Heterogeneous phantom, designed to mimic the brain white matter, are composed of agarose gel coating polystyrene beads. The proton density of agarose has similar characteristics and relaxation times to the biological tissue [2]. Six heterogeneous tubes and two homogeneous tubes are defined in the two central columns, numbered by tube 1 to 8, as shown in Figure 2. Six 30-ml tubes are filled with polystyrene beads of different diameters (1, 2 and 3 mm) in an agarose gel solution (2%), either pure or mixed with 0.25 mmol/l gadolinium chelate, and

^{*} ComBat-MLE: A Novel Perspective to Developing and Solving ComBat Harmonization Method



(a) Homogeneous phantom

(b) T1 weighted MRI image

(c) Number of the tubes

Figure 1: Homogeneous phantom , its T1 weighted MRI image and Number of tubes. Number 1-8 correspond to demineralized water mixed with 2, 1.75, 1.5, 1.25, 1, 0.75, 0.5 and 0.25 mmol/l gadolinium chelate concentration, and number 9 corresponds to pure demineralized water tube.

two 30-ml tubes are filled with agarose gel solution (2%) and two different concentration of gadolinium chelate [3], more details are as listed as follows:

- Tube 1: Agarose gel + 0.25 mmol/l gadolinuim chelate + large polystyrene beads (diameters range from 2 to 3.5 mm)
- Tube 2: Agarose gel + 0.25 mmol/l gadolinuim chelate + medium polystyrene beads (diameters range from 1.5 to 2.5 mm)
- Tube 3: Agarose gel + 0.25 mmol/l gadolinuim chelate + small polystyrene beads (diameters range from 0.9 to 1.5 mm)
- Tube 4: Agarose gel + 0.25 mmol/l gadolinuim chelate
- Tube 5: Agarose gel + large polystyrene beads (diameters range from 2.5 to 3.5 mm)
- Tube 6: Agarose gel + medium polystyrene beads (diameters range from 1.5 to 2.5 mm)
- Tube 7: Agarose gel + small polystyrene beads (diameters range from 0.9 to 1.5 mm)
- Tube 8: Pure agarose gel

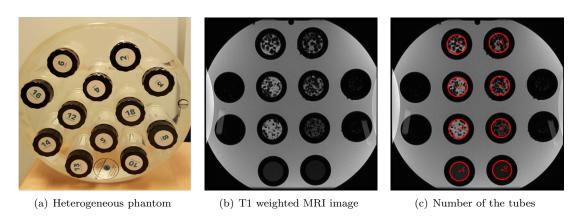


Figure 2: Heterogeneous phantom, its T1 weighted MRI image and Number of tubes.

The phantoms are scanned by different devices with different acquisition settings to introduce the scanner effects. We can simply summarize it as 10 scanner settings (different in magnetic field strength, field of view and matrix) as listed in Table 1.

Scanner setting	canner setting Magnetic field strength, FOV and Matr	
1	1.5T - FOV24 - 256×256	
2	1.5T - FOV24 - 256×128	
3	1.5T - FOV24 - 128×128	
4	1.5T - FOV18 - 256×256	
5	1.5T - FOV12 - 256×256	
6	3T - FOV24 - 256×256	
7	3T - FOV24 - 256×128	
8	3T - FOV24 - 128×128	
9	3T - FOV18 - 256×256	
10	3T - FOV12 - 256×256	

Table 1: 10 experiment settings used to scan the phantoms.

1.2 Region of Interests (ROIs)

The homogenous phantom and heterogeneous phantom are scanned based on each acquisition setting in Table 1, so we have 10 3D MRI images for each phantom. Region of Interests (ROIs) will be extracted from certain slices of these 3D MRI images, that is, 51-th to 120-th slices for homogenous phantom and 21-th to 50-th slices for heterogeneous phantom will be used to extract ROIs.

The ROIs are extracted from each slice by three steps. Firstly, detect all the circles in each image slice automatically using the HoughCircles function in OpenCV. Secondly, clip the circles with a fixed radius for scanner settings with the same phantom type and FOV, as listed in Table 2. Thirdly, select the interested circles as ROIs for radiomics analysis, i.e., 9 ROIs (numbered by 1 to 9) for homogeneous phantom, and 6 ROIs (numbered by 1,2,3,5,6,7) for heterogeneous phantom, as shown in Figure 3.

Phantom Type	FOV	Radius of ROIs
	FOV24	14
Homogeneous Phantom	FOV18	18
	FOV12	28
Heterogeneous Phantom	FOV24	22
	FOV18	28
	FOV12	42

Table 2: Radius of VOIs corresponding to different phantom type and FOV.

1.3 Extraction of Radiomics Features

Pyradiomics [4], an open-source python package for the extraction of radiomics features from medical imaging, will be used in our research to extract texture features from the region of interests (ROIs). The texture features extracted using PyRadiomics can be subdivided into the following classes:

• First Order Statistics: 19 features

 \bullet Shape-based (3D): 16 features

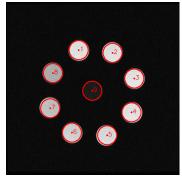
• Shape-based (2D): 10 features

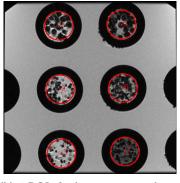
• Gray Level Cooccurence Matrix (GLCM): 24 features

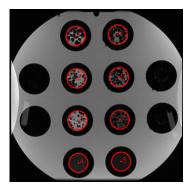
• Gray Level Run Length Matrix (GLRLM): 16 features

• Gray Level Size Zone Matrix (GLSZM): 16 features

• Neighbouring Gray Tone Difference Matrix (NGTDM): 5 features





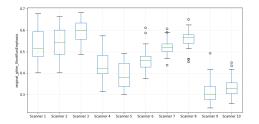


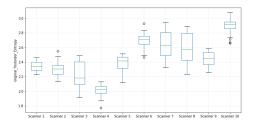
(a) 9 ROIs for homogeneous phantom

(b) 6 ROIs for heterogeneous phantom with FOV=12.

(c) 6 ROIs (1,2,3,5,6,7) for heterogeneous phantom (FOV=18 or 24).

Figure 3: Examples of Region of Interests (ROIs). Note that for heterogeneous phantom with FOV=18 or 24, 8 circles are detected, but to keep consistent with FOV=12, only 6 circles (numbered by 1,2,3,5,6,7) will be used as ROIs.





(a) "Short runs emphasis" feature for pattern 1 of homo- (b) "Entropy" feature for pattern 1 of heterogeneous geneous phantom phantom

Figure 4: Box plots to show the existence of scanner effects.

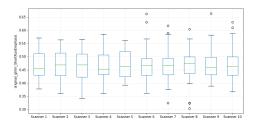
• Gray Level Dependence Matrix (GLDM): 14 features

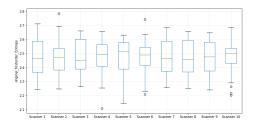
From all the available features, we will discard these features: 1) our data is 2-dimensional, so we discard the 16 Shape-based (3D) features. 2) GLCM is symmetrical, therefore Sum Average = 2×10^{-2} Joint Average, so we only calculate Joint Average in our experiments.

Finally, 91 texture features are extracted for each ROI. The detail meaning and calculation of these features can be found in IBSI [5], which defines the standardisation of extracting image biomarkers from acquired imaging for the purpose of high-throughput quantitative image analysis (radiomics).

1.4 Existence of Scanner Effects

We have successfully extracted 91 texture features for each ROI collected from different scanner settings. Now we will investigate whether there exists scanner effects among these texture features by drawing box plots. Figure 4 shows an example of the box plots for homogeneous phantom and heterogeneous phantom, respectively. Obviously, the same phantom scanned by different scanner settings has different mean and variances for the extracted features, which indicates the existence of scanner effects.





(a) "Short runs emphasis" feature for pattern 1 of homo- (b) "Entropy" feature for pattern 1 of heterogeneous geneous phantom

Figure 5: Box plots of the harmonized features by our proposed MLE ComBat method.

1.5 A Simple Example to Remove Scanner Effects

After applying our proposed ComBat-MLE harmonization method to the features for each pattern class separately, most of the scanner effects can be removed from these texture features. Figure 5 shows the box plots of the harmonized features (harmonized by our proposed MLE ComBat method) corresponding to features in Figure 4. We can easily see that after harmonization by our proposed MLE ComBat method, the mean and variance of the features are similar for all scanner settings, which verifies the effectiveness of our proposed method to remove scanner effects.

2 New Method for Harmonizing Scanner Effects Across Classes

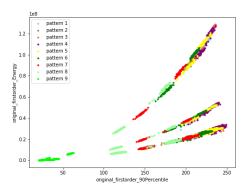
Orlhac et al. [6] mentioned one kind of failure cases of ComBat method we also met in our experiments. We explain it in detail in Figure 6. Obviously, before ComBat harmonization, the two example radiomic features suffer from severe scanner effects (Figure 6(a)). If we apply the harmonization methods for different pattern classes separately, then most of the scanner effects can be removed successfully (Figure 6(b)). But if the pattern class is unknown, and we apply harmonization methods one time for the data consisting of all pattern classes, then some scanner effects can't be removed (Figure 6(c)). The reason lies in the unmet assumptions of the data and the ComBat method. ComBat model is built based on the assumption that scanner effects are the same for feature data extracted from the same scanner setting. However, in this example, when applying ComBat harmonization for the data from all different pattern classes together, the feature data from the same scanner setting but from different pattern classes actually has different scanner effects.

In this section, we aim to develop a new harmonization method, with the assumption that, the data are composed of different pattern classes, but the feature data from the same scanner setting has different scanner effects for different pattern classes.

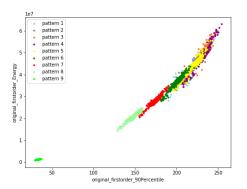
2.1 Notations

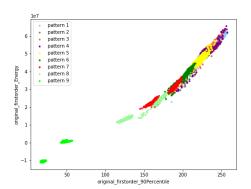
Let $X_s \in \mathbb{R}^p$ be a random variable representing the observed feature data from scanner setting $s \in \{1, 2, ..., S\}$. Suppose for each scanner setting $s \in \{1, 2, ..., S\}$, we have N_s observations $\{\boldsymbol{x}_1^{(s)}, ..., \boldsymbol{x}_{N_s}^{(s)}\}$ of variable X_s , and denote the $N_s \times p$ matrix X_s as the set of all observations from scanner setting s, where the n-th row represents $(\boldsymbol{x}_n^{(s)})^{\top}$.

To represent the pattern class label of \boldsymbol{X}_s , we introduce a binary random variable $\boldsymbol{Z}_s \in \mathbb{R}^C$. For each realization $\boldsymbol{z}^{(s)} = (z_1^{(s)}, z_2^{(s)}, ..., z_C^{(s)})^{\top}$ of variable \boldsymbol{Z}_s , it has a 1-of-C representation in which a particular element $z_c^{(s)}$ is equal to 1 and all other elements are equal to 0. Therefore, the values of $z_c^{(s)}$ satisfy $z_c^{(s)} \in \{0,1\}$ and $\sum_{c=1}^C z_c^{(s)} = 1$. Let the realizations $\{\boldsymbol{z}_1^{(s)},...,\boldsymbol{z}_{N_s}^{(s)}\}$ of \boldsymbol{Z}_s be the pattern classes corresponding to $\{\boldsymbol{x}_1^{(s)},...,\boldsymbol{x}_{N_s}^{(s)}\}$, then we can use a $N_s \times C$ matrix Z_s with rows $(\boldsymbol{z}_n^{(s)})^{\top}$ to represent the pattern class corresponding to X_s .



(a) Before harmonization





(b) Apply parametric ComBat method for each pattern class separately.

(c) Apply parametric ComBat method for data consisting of all pattern classes.

Figure 6: Compare harmonization results of applying ComBat methods (use parametric ComBat as an example) in different ways. (a) The radiomic features before harmonization suffer from severe scanner effects, appearing as several clusters for each pattern class (i.e. color). (b)If harmonizing features for each pattern class separately, data from same pattern class (i.e. same color) are harmonized to one cluster, indicating that scanner effects are successfully removed. (c)If harmonizing features for all pattern class data one time, then each pattern class (i.e. color) are still composed of two different clusters, meaning that some scanner effects still exist.

2.2 Model without scanner effects

Suppose random variable $X_s \in \mathbb{R}^p$ representing the observed feature data from scanner setting $s \in \{1, 2, ..., S\}$ doest not suffer from scanner effects, and it consists of data from C pattern classes. The pattern class variable $Z_s \in \mathbb{R}^C$ corresponding to X_s can be specified in terms of mixing coefficients π_{sc} , such that

$$p(z_c^{(s)} = 1) = \pi_{sc},\tag{1}$$

where for each scanner setting $s \in \{1, 2, ..., S\}$, the parameters $\{\pi_{sc}\}$ must satisfy

$$0 \le \pi_{sc} \le 1, \quad \sum_{c=1}^{C} \pi_{sc} = 1, \tag{2}$$

so the distribution of variable Z_s can be written as

$$p(\mathbf{Z}_s) = \prod_{c=1}^{C} (\pi_{sc})^{z_c^{(s)}}.$$
 (3)

Then the conditional distribution of X_s given a particular value of Z_s is

$$p(X_s|z_{sc}=1) = \mathcal{N}(X_s|\mu_c, \Sigma_c), \tag{4}$$

or, equivalently,

$$p(\boldsymbol{X}_s|\boldsymbol{Z}_s) = \prod_{c=1}^{C} \mathcal{N}(\boldsymbol{X}_s|\boldsymbol{\mu}_c, \boldsymbol{\Sigma}_c)^{z_c^{(s)}},$$
 (5)

where $\mu_c \in \mathbb{R}^p$ and $\Sigma_c \in \mathbb{R}^{p \times p}$ are the mean and variance matrix of the c-th pattern class. So the joint distribution $p(X_s, Z_s)$ is

$$p(\boldsymbol{X}_s, \boldsymbol{Z}_s) = p(\boldsymbol{Z}_s)p(\boldsymbol{X}_s|\boldsymbol{Z}_s) = \prod_{c=1}^{C} [\pi_{sc} \mathcal{N}(\boldsymbol{X}_s|\boldsymbol{\mu}_c, \boldsymbol{\Sigma}_c)]^{z_c^{(s)}},$$
(6)

the marginal distribution of X_s can be obtained by summing joint distribution over all possible states of Z_s as

$$p(\boldsymbol{X}_s) = \sum_{\boldsymbol{Z}_s} p(\boldsymbol{X}_s, \boldsymbol{Z}_s) = \sum_{c=1}^{C} \pi_{sc} \, \mathcal{N}(\boldsymbol{X}_s | \boldsymbol{\mu}_c, \boldsymbol{\Sigma}_c).$$
 (7)

So if there is no scanner effects, for each scanner setting $s \in \{1, 2, ..., S\}$, the observed feature data $X_s \in \mathbb{R}^p$ follows a Gaussian mixture distribution:

$$p(\mathbf{X}_s) = \sum_{c=1}^{C} \pi_{sc} \, \mathcal{N}(\mathbf{X}_s | \boldsymbol{\mu}_c, \boldsymbol{\Sigma}_c), \tag{8}$$

where

$$0 \le \pi_{sc} \le 1, \quad \sum_{c=1}^{C} \pi_{sc} = 1$$
 (9)

holds for s=1,2,...,S.

2.3 Model with scanner effects

Now let us model the case when the observed feature data $X_s \in \mathbb{R}^p$ suffers from scanner effects. Suppose that the scanner effects are different for each pattern class, and they affect the mean and variance of each pattern class, then the observed data X_s suffering scanner effects from scanner setting s can be assumed to follow the following Gaussian mixture distribution:

$$p(\boldsymbol{X}_s) = \sum_{c=1}^{C} \pi_{sc} \, \mathcal{N}(\boldsymbol{X}_s | \boldsymbol{\mu}_c + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_c), \tag{10}$$

where $\gamma_{sc} \in \mathbb{R}^p$ and $\Delta_{sc} \in \mathbb{R}^{p \times p}$ represent the additive and multiplicative scanner effects, respectively, and

$$0 \le \pi_{sc} \le 1, \quad \sum_{c=1}^{C} \pi_{sc} = 1 \tag{11}$$

holds for s=1,2,...,S.

Note that in model (10), parameters μ_c and γ_{sc} (similarly, Δ_{sc} and Σ_c) are not identifiable, so proper constraints should be proposed. As an reasonable option, we propose the following additive and multiplicative constraints:

• additive constraints:

$$\sum_{s=1}^{S} w_s \gamma_{sc} = \mathbf{0}, \ c = 1, 2, ..., C.$$
 (12)

• multiplicative constraints:

$$\prod_{s=1}^{S} (\Delta_{sc})^{w_s} = I, \ c = 1, 2, ..., C.$$
(13)

With these additive and multiplicative constraints, after removing scanner effects, the mean (variance) of pattern class c will be the weighted center (variance) of predicted pattern classes of c in all scanner settings, where $w_s = \frac{N_s}{\sum_{s=1}^S N_s}, \ s=1,2,...,S$ are the weight coefficients.

2.4 Solve the model by EM algorithm

The proposed model (10) with constraints (11)(12)(13), which models the case when scanner effects are different for each pattern class, can be solved by Expectation Maximization (EM) algorithm. Moreover, the E (expectation) and M (maximization) step can be summarized as follows:

2.4.1 E step

In the E step, for each scanner setting $s \in \{1, 2, ..., S\}$, we will compute the posterior distribution $p_s(Z_s|X_s, \boldsymbol{\theta}^{\text{old}})$ given the current parameters $\boldsymbol{\theta}^{\text{old}}$, and then use this posterior distribution to find the expected complete-data log likelihood evaluated for some general parameter value $\boldsymbol{\theta}$, where $\boldsymbol{\theta}$ represents the set of all the model parameters and is defined as

$$\boldsymbol{\theta} = \{ \pi_{sc} \in \mathbb{R}, \ \boldsymbol{\mu}_c \in \mathbb{R}^p, \ \boldsymbol{\Sigma}_c \in \mathbb{R}^{p \times p}, \ \boldsymbol{\gamma}_{sc} \in \mathbb{R}^p, \ \boldsymbol{\Delta}_{sc} \in \mathbb{R}^{p \times p} \mid s = 1, 2, ..., S; \ c = 1, 2, ..., C \}.$$
(14)

Specifically, consider the complete data set (X_s, Z_s) from scanner setting $s \in \{1, 2, ..., S\}$, the complete-data likelihood function takes the form

$$p_s(X_s, Z_s | \boldsymbol{\theta}) = \prod_{n=1}^{N_s} \prod_{c=1}^C [\pi_{sc} \, \mathcal{N}(\boldsymbol{x}_n^{(s)} | \boldsymbol{\mu}_c + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_c)]^{z_{nc}^{(s)}}, \tag{15}$$

and thus the logarithm of complete-data likelihood function takes the form

$$\ln p_s(X_s, Z_s | \boldsymbol{\theta}) = \sum_{n=1}^{N_s} \sum_{c=1}^{C} z_{nc}^{(s)} [\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_n^{(s)} | \boldsymbol{\mu}_c + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_c)],$$
(16)

where $z_{nc}^{(s)}$ represents the c^{th} components of $\boldsymbol{z}_{n}^{(s)}$. The expectation of complete-data log likelihood function, denoted by $\mathcal{Q}_{s}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$, can be calculated by

$$Q_{s}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) = \mathbb{E}_{Z_{s}|X_{s},\boldsymbol{\theta}^{\text{old}}} \left[\ln p_{s}(X_{s}, Z_{s}|\boldsymbol{\theta}) \right]$$

$$= \sum_{n=1}^{N_{s}} \sum_{c=1}^{C} \mathbb{E}_{Z_{s}|X_{s},\boldsymbol{\theta}^{\text{old}}} [z_{nc}^{(s)}] \cdot \left[\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)}|\boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc}\boldsymbol{\Sigma}_{c}) \right]$$

$$= \sum_{n=1}^{N_{s}} \sum_{c=1}^{C} \alpha(z_{nc}^{(s)}) \left[\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)}|\boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc}\boldsymbol{\Sigma}_{c}) \right],$$

$$(17)$$

where

$$\mathbb{E}_{Z_{s}|X_{s},\boldsymbol{\theta}}[z_{nc}^{(s)}] = p_{s}(z_{nc}^{(s)} = 1|\boldsymbol{x}_{n}^{(s)},\boldsymbol{\theta}) \times 1 + p_{s}(z_{nc}^{(s)} = 0|\boldsymbol{x}_{n}^{(s)},\boldsymbol{\theta}) \times 0$$

$$= \frac{p_{s}(\boldsymbol{x}_{n}^{(s)}|z_{nc}^{(s)} = 1,\boldsymbol{\theta})p_{s}(z_{nc}^{(s)} = 1|\boldsymbol{\theta})}{p_{s}(\boldsymbol{x}_{n}^{(s)}|\boldsymbol{\theta})}$$

$$= \frac{p_{s}(\boldsymbol{x}_{n}^{(s)}|z_{nc}^{(s)} = 1,\boldsymbol{\theta})p_{s}(z_{nc}^{(s)} = 1|\boldsymbol{\theta})}{\sum_{j=1}^{C} p_{s}(\boldsymbol{x}_{n}^{(s)}|z_{nj}^{(s)} = 1,\boldsymbol{\theta})p_{s}(z_{nj}^{(s)} = 1|\boldsymbol{\theta})}$$

$$= \frac{\pi_{sc} \mathcal{N}(\boldsymbol{x}_{n}^{(s)}|\boldsymbol{\mu}_{c} + \gamma_{sc}, \boldsymbol{\Delta}_{sc}\boldsymbol{\Sigma}_{c})}{\sum_{j=1}^{C} \pi_{sj} \mathcal{N}(\boldsymbol{x}_{n}^{(s)}|\boldsymbol{\mu}_{j} + \gamma_{sj}, \boldsymbol{\Delta}_{sj}\boldsymbol{\Sigma}_{j})} \triangleq \alpha(z_{nc}^{(s)}).$$
(18)

Note that $\alpha(z_{nc}^{(s)})$ is calculated by the old parameter $\boldsymbol{\theta}^{\text{old}}$, and will be regarded as a constant in M step.

So in the E step, for each scanner setting $s \in \{1, 2, ..., S\}$, we have finished calculating the expectation of complete-data log likelihood function $Q_s(\theta, \theta^{\text{old}})$ as described in Equation (17).

2.4.2 M step

In the M step, we will maximize the expected complete-data log likelihood function $Q_s(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$, s = 1, 2, ..., S with respect to the parameters $\boldsymbol{\theta}$. Since we have S expectation function $Q_s(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ to be optimized, and they share the same parameters $\{\boldsymbol{\mu}_c, \boldsymbol{\Sigma}_c, c = 1, 2, ..., C\}$, so we cannot maximize only one $Q_s(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ with respect to $\{\boldsymbol{\mu}_c, \boldsymbol{\Sigma}_c, c = 1, 2, ..., C\}$, but to optimize these S expectation functions together. In this case, it is natural to define $Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ as a weighted sum of the $Q_s(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$, s = 1, 2, ..., S to be final objective function to be optimized as follows:

$$\mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) = \sum_{s=1}^{S} w_s \mathcal{Q}_s(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})
= \sum_{s=1}^{S} w_s \sum_{n=1}^{N_s} \sum_{c=1}^{C} \alpha(z_{nc}^{(s)}) [\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_n^{(s)} | \boldsymbol{\mu}_c + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_c)],$$
(19)

where w_s is the weight of scanner setting s and can be set to

$$w_s = \frac{N_s}{\sum_{s=1}^S N_s},$$
 (20)

and

$$\mathcal{N}(\boldsymbol{x}_{n}^{(s)}|\boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc}\boldsymbol{\Sigma}_{c}) = \frac{1}{(2\pi)^{\frac{p}{2}}|\boldsymbol{\Delta}_{sc}\boldsymbol{\Sigma}_{c}|^{\frac{1}{2}}} \exp\Big\{-\frac{1}{2}(\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc})^{\top}(\boldsymbol{\Delta}_{sc}\boldsymbol{\Sigma}_{c})^{-1}(\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc})\Big\}.$$
(21)

Then we can update parameters $\boldsymbol{\theta}$ as $\boldsymbol{\theta}^{\text{new}}$ by

$$\boldsymbol{\theta}^{\text{new}} = \underset{\boldsymbol{\theta}}{\operatorname{arg max}} \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}),$$
 (22)

where θ is the set of the model parameters as defined by Equation (14).

Following the coordinate descent optimization strategy, each parameter of $\boldsymbol{\theta}$ can be updated iteratively to gradually maximize the objective function $\mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ by taking the derivative of $\mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ with respect to the parameter, and the method of Lagrange multipliers will be included to deal with the parameter constraints (12) and (13), the details can be found as below.

Update μ_c :

In order to update μ_c , we can calculate the derivatives of $\mathcal{Q}(\theta, \theta^{\text{old}})$ with respect to μ_c , and set it to zero as follows

$$\frac{\partial \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})}{\partial \boldsymbol{\mu}_{c}} = \frac{\partial \left\{ \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \sum_{c=1}^{C} \alpha(z_{nc}^{(s)}) [\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})] \right\}}{\partial \boldsymbol{\mu}_{c}}$$

$$= \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) \frac{\partial \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})}{\partial \boldsymbol{\mu}_{c}}$$

$$= \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) = 0.$$
(23)

Multiply Σ_c on both sides and rearrange the equation, we can get the

$$\mu_c = \left[\sum_{s=1}^{S} w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \Delta_{sc}^{-1}\right]^{-1} \cdot \left[\sum_{s=1}^{S} w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \Delta_{sc}^{-1} (\boldsymbol{x}_n^{(s)} - \boldsymbol{\gamma}_{sc})\right].$$
(24)

Update γ_{sc} :

Now let's update γ_{sc} . To ensure the identifiability of the parameter μ_c and γ_{sc} , we assume

$$\sum_{s=1}^{S} w_s \gamma_{sc} = \mathbf{0}, \ c = 1, 2, ..., C.$$
 (25)

Notice here we use w_s , which means that each scanner setting s have similar amount of data for each pattern class, otherwise, it should use w_{sc} . We will consider this case later.

Let $\lambda_c = (\lambda_{1c}, \lambda_{2c}, ..., \lambda_{pc})^T \in \mathbb{R}^p$, and define the Lagrange function as follows:

$$\mathcal{L}_{1} = \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) + \sum_{i=1}^{p} \lambda_{ic} \left(\sum_{s=1}^{S} w_{s} \gamma_{isc} \right) \\
= \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \sum_{c=1}^{C} \alpha(z_{nc}^{(s)}) [\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})] + \sum_{i=1}^{p} \lambda_{ic} \left(\sum_{s=1}^{S} w_{s} \gamma_{isc} \right).$$
(26)

The derivatives of \mathcal{L}_1 with respect to γ_{sc} is

$$\frac{\partial \mathcal{L}_{1}}{\partial \boldsymbol{\gamma}_{sc}} = w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) \frac{\partial \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})}{\partial \boldsymbol{\gamma}_{sc}} + w_{s} \boldsymbol{\lambda}_{c}$$

$$= w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) + w_{s} \boldsymbol{\lambda}_{c} = 0.$$
(27)

Re-arranging the above equation, we can get

$$\boldsymbol{\gamma}_{sc} = \left[\sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_c)^{-1}\right]^{-1} \cdot \left[\sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_c)^{-1} (\boldsymbol{x}_n^{(s)} - \boldsymbol{\mu}_c) + \boldsymbol{\lambda}_c\right]. \tag{28}$$

Since $\sum_{s=1}^{S} w_s \gamma_{sc} = \mathbf{0}$, c = 1, 2, ..., C, so we can get λ_c as follows:

$$\lambda_{c} = -\left[\sum_{s=1}^{S} w_{s} \left[\sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1}\right]^{-1}\right]^{-1} \\
\cdot \left\{\sum_{s=1}^{S} w_{s} \left[\left[\sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1}\right]^{-1} \cdot \left[\sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c})\right]\right]\right\}.$$
(29)

So γ_{sc} can be updated by Equation (28), where λ_c is calculated by Equation (29).

Update Σ_c :

Now let's analyze the way to update Σ_c and Δ_{sc} . We assume them to be diagonal matrices, namely, suppose $\Sigma_c = \text{diag}(\sigma_{1c}, ..., \sigma_{pc})$, $\Delta_{sc} = \text{diag}(\delta_{1sc}, ..., \delta_{psc})$. If we take the derivatives of $\mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ with respect to Σ_c and Δ_{sc} directly, we can't assure that the updated matrices are still diagonal. In order to solve this problem, we introduce Γ_c and Λ_{sc} as follows

$$\mathbf{\Gamma}_c = (\sigma_{1c}, ..., \sigma_{pc})^T, \quad \mathbf{\Lambda}_{sc} = (\delta_{1sc}, ..., \delta_{psc})^T, \tag{30}$$

which obviously satisfy

$$\Sigma_c = \operatorname{diag}(\Gamma_c), \ \Sigma_c \cdot e = \Gamma_c,$$

$$\Delta_{sc} = \operatorname{diag}(\Lambda_{sc}), \ \Delta_{sc} \cdot e = \Lambda_{sc},$$
(31)

where $e = (1, 1, ..., 1)^T \in \mathbb{R}^p$. So we will update Γ_c and Λ_{sc} by calculating the derivatives of $\mathcal{Q}(\theta, \theta^{\text{old}})$ with respect to Γ_c and Λ_{sc} , respectively, and then update Σ_c and Δ_{sc} by

$$\Sigma_c = \operatorname{diag}(\Gamma_c), \quad \Delta_{sc} = \operatorname{diag}(\Lambda_{sc}).$$
 (32)

The derivatives of $\mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ with respect to Γ_c takes the form

$$\frac{\partial \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})}{\partial \boldsymbol{\Gamma}_{c}} = \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) \frac{\partial \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})}{\partial \boldsymbol{\Gamma}_{c}}$$

$$= \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) \left\{ -\frac{1}{2} \frac{\partial \ln |\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c}|}{\partial \boldsymbol{\Gamma}_{c}} - \frac{1}{2} \frac{\partial \left\{ (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc})^{T} (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) \right\}}{\partial \boldsymbol{\Gamma}_{c}} \right\}. \tag{33}$$

On the one hand,

$$-\frac{1}{2}\frac{\partial \ln |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|}{\partial \mathbf{\Gamma}_{c}} = -\frac{1}{2}|\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|^{-1} \cdot \frac{\partial |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|}{\partial \mathbf{\Gamma}_{c}},$$
(34)

since we have supposed $\Sigma_c = \operatorname{diag}(\sigma_{1c},...,\sigma_{pc})$ and $\Delta_{sc} = \operatorname{diag}(\delta_{1sc},...,\delta_{psc})$, so

$$|\Delta_{sc}\Sigma_c| = \prod_{i=1}^p \delta_{isc}\sigma_{ic}.$$
 (35)

Then

$$\frac{\partial |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|}{\partial \mathbf{\Gamma}_{c}} = \frac{\partial (\prod_{i=1}^{p} \delta_{isc}\sigma_{ic})}{\partial \mathbf{\Gamma}_{c}} \\
= \begin{pmatrix} \frac{\partial (\prod_{i=1}^{p} \delta_{isc}\sigma_{ic})}{\partial \sigma_{c}} \\ \frac{\partial (\prod_{i=1}^{p} \delta_{isc}\sigma_{ic})}{\partial \sigma_{2c}} \\ \vdots \\ \frac{\partial (\prod_{i=1}^{p} \delta_{isc}\sigma_{ic})}{\partial \sigma_{pc}} \end{pmatrix} = (\prod_{i=1}^{p} \delta_{isc}\sigma_{ic}) \begin{pmatrix} \frac{1}{\sigma_{1c}} \\ \frac{1}{\sigma_{2c}} \\ \vdots \\ \frac{1}{\sigma_{pc}} \end{pmatrix} = |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}| \cdot \mathbf{\Sigma}_{c}^{-1} \cdot \mathbf{e}, \tag{36}$$

so we can get

$$-\frac{1}{2}\frac{\partial \ln |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|}{\partial \mathbf{\Gamma}_{c}} = -\frac{1}{2}|\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|^{-1} \cdot \frac{\partial |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|}{\partial \mathbf{\Gamma}_{c}} = -\frac{1}{2}\mathbf{\Sigma}_{c}^{-1} \cdot \boldsymbol{e} . \tag{37}$$

On the other hand.

$$\frac{\partial \left\{ (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc})^{T} (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) \right\}}{\partial \Gamma_{c}}$$

$$= \begin{pmatrix}
\frac{\partial (x_{1n}^{(s)} - \mu_{1c} - \gamma_{1sc})^{2} (\delta_{1sc} \sigma_{1c})^{-1}}{\partial \sigma_{1c}} \\
\frac{\partial (x_{2n}^{(s)} - \mu_{2c} - \gamma_{2sc})^{2} (\delta_{1sc} \sigma_{2c})^{-1}}{\partial \sigma_{2c}} \\
\vdots \\
\frac{\partial (x_{pn}^{(s)} - \mu_{pc} - \gamma_{psc})^{2} (\delta_{psc} \sigma_{pc})^{-1}}{\partial \sigma_{pc}}
\end{pmatrix} = -\begin{pmatrix}
(x_{1n}^{(s)} - \mu_{1c} - \gamma_{1sc})^{2} \cdot \delta_{1sc}^{-1} \cdot \sigma_{1c}^{-2} \\
(x_{2n}^{(s)} - \mu_{2c} - \gamma_{2sc})^{2} \cdot \delta_{2sc}^{-1} \cdot \sigma_{2c}^{-2} \\
\vdots \\
(x_{pn}^{(s)} - \mu_{pc} - \gamma_{psc})^{2} \cdot \delta_{psc}^{-1} \cdot \sigma_{pc}^{-2}
\end{pmatrix}$$

$$= -\boldsymbol{\Sigma}_{c}^{-2} \boldsymbol{\Delta}_{sc}^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \gamma_{sc}) \circ (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \gamma_{sc}).$$
(38)

where \circ represents the Hadamard product (also known as element-wise product). Taking Equation (37) and Equation (38) into Equation (33), we have

$$\frac{\partial \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})}{\partial \boldsymbol{\Gamma}_{c}} = \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) \left[-\frac{1}{2} \boldsymbol{\Sigma}_{c}^{-1} \cdot \boldsymbol{e} + \frac{1}{2} \boldsymbol{\Sigma}_{c}^{-2} \boldsymbol{\Delta}_{sc}^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) \circ (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) \right]. \tag{39}$$

Set this derivative to zero, and multiply $2\Sigma_c^2$ on both sides, we have

$$\sum_{s=1}^{S} w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \left[-\sum_c \cdot e + \Delta_{sc}^{-1} (x_n^{(s)} - \mu_c - \gamma_{sc}) \circ (x_n^{(s)} - \mu_c - \gamma_{sc}) \right] = 0.$$
 (40)

Notice $\Sigma_c \cdot e = \Gamma_c$, so rearranging the above equation, we have

$$\Gamma_c = \left[\sum_{s=1}^{S} w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)})\right]^{-1} \cdot \left[\sum_{s=1}^{S} w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \Delta_{sc}^{-1}(\boldsymbol{x}_n^{(s)} - \boldsymbol{\mu}_c - \boldsymbol{\gamma}_{sc}) \circ (\boldsymbol{x}_n^{(s)} - \boldsymbol{\mu}_c - \boldsymbol{\gamma}_{sc})\right]. \tag{41}$$

So we get the equation 41 to update Γ_c , then Σ_c can be easily updated by $\Sigma_c = \operatorname{diag}(\Gamma_c)$.

Update Δ_{sc} :

We will use the similar way to update $\Delta_{sc} = \text{diag}(\Lambda_{sc})$. To ensure the identifiability of the parameter Σ_c and Δ_{sc} , we assume

$$\prod_{s=1}^{S} \Delta_{sc} = \mathbb{I}, \ c = 1, 2, ..., C.$$
(42)

or

$$\prod_{s=1}^{S} \mathbf{\Lambda}_{sc} = \mathbf{e}, \ c = 1, 2, ..., C.$$
(43)

where $\mathbb{I} \in \mathbb{R}^{p \times p}$ is the identity matrix and $e = (1, 1, ..., 1)^T \in \mathbb{R}^p$.

Let $\hat{\boldsymbol{\lambda}}_c = (\hat{\lambda}_{1c}, \hat{\lambda}_{2c}, ..., \hat{\lambda}_{pc})^T \in \mathbb{R}^p$, and define the Lagrange function as

$$\mathcal{L}_{2} = \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) + \sum_{i=1}^{p} \hat{\lambda}_{ic} (\prod_{s=1}^{S} \delta_{isc} - 1)$$

$$= \sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \sum_{c=1}^{C} \alpha(z_{nc}^{(s)}) [\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})] + \sum_{i=1}^{p} \hat{\lambda}_{ic} (\prod_{s=1}^{S} \delta_{isc} - 1).$$

$$(44)$$

Calculate the derivatives of \mathcal{L}_2 with respect to Λ_{sc} , we have

$$\frac{\partial \mathcal{L}_{2}}{\partial \mathbf{\Lambda}_{sc}} = w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) \frac{\partial \ln \mathcal{N}(\mathbf{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})}{\partial \mathbf{\Lambda}_{sc}} + \boldsymbol{\Delta}_{sc}^{-1} \hat{\boldsymbol{\lambda}}_{c}$$

$$= w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)}) \left\{ -\frac{1}{2} \frac{\partial \ln |\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c}|}{\partial \mathbf{\Lambda}_{sc}} - \frac{1}{2} \frac{\partial \left\{ (\mathbf{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc})^{T} (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1} (\mathbf{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) \right\}}{\partial \mathbf{\Lambda}_{sc}} \right\} + \boldsymbol{\Delta}_{sc}^{-1} \hat{\boldsymbol{\lambda}}_{c}, \tag{45}$$

where

$$-\frac{1}{2}\frac{\partial \ln |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|}{\partial \mathbf{\Lambda}_{sc}} = -\frac{1}{2}|\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|^{-1} \cdot \frac{\partial |\mathbf{\Delta}_{sc}\mathbf{\Sigma}_{c}|}{\partial \mathbf{\Lambda}_{sc}} = -\frac{1}{2}\mathbf{\Delta}_{sc}^{-1} \cdot e$$
(46)

and

$$\frac{\partial \left\{ (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc})^{T} (\boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) \right\}}{\partial \boldsymbol{\Lambda}_{sc}}$$

$$= -\boldsymbol{\Delta}_{sc}^{-2} \boldsymbol{\Sigma}_{c}^{-1} \cdot (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}) \circ (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c} - \boldsymbol{\gamma}_{sc}).$$
(47)

Taking Equation (46) and (47) into Equation (45), we can get the derivatives of \mathcal{L}_2 with respect to Λ_{sc} as follows

$$\frac{\partial \mathcal{L}_2}{\partial \mathbf{\Lambda}_{sc}} = w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \left[-\frac{1}{2} \mathbf{\Delta}_{sc}^{-1} \cdot \mathbf{e} + \frac{1}{2} \mathbf{\Delta}_{sc}^{-2} \mathbf{\Sigma}_c^{-1} \cdot (\mathbf{x}_n^{(s)} - \boldsymbol{\mu}_c - \boldsymbol{\gamma}_{sc}) \circ (\mathbf{x}_n^{(s)} - \boldsymbol{\mu}_c - \boldsymbol{\gamma}_{sc}) \right] + \mathbf{\Delta}_{sc}^{-1} \hat{\boldsymbol{\lambda}}_c$$
(48)

Set this derivative to zero, multiply Δ_{sc}^2 on both sides and then rearranging the equation, we can get

$$\Lambda_{sc} = \frac{1}{\left[w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \cdot \boldsymbol{e} - 2\hat{\boldsymbol{\lambda}}_c\right]} \\
\circ \left[w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \cdot \boldsymbol{\Sigma}_c^{-1} \cdot (\boldsymbol{x}_n^{(s)} - \boldsymbol{\mu}_c - \boldsymbol{\gamma}_{sc}) \circ (\boldsymbol{x}_n^{(s)} - \boldsymbol{\mu}_c - \boldsymbol{\gamma}_{sc})\right]. \tag{49}$$

Now we aim to use the constraints $\prod_{s=1}^{S} \mathbf{\Lambda}_{sc} = \mathbf{e}, \ c = 1, 2, ..., C$ to solve $\hat{\boldsymbol{\lambda}}_{c}$. Define

$$A_{isc} = w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}), \quad B_{isc} = w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \cdot \sigma_{ic}^{-1} (x_{in}^{(s)} - \mu_{ic} - \gamma_{isc})^2, \tag{50}$$

for i = 1, ..., p, then δ_{isc} can be represented as

$$\delta_{isc} = \frac{B_{isc}}{A_{isc} - 2\hat{\lambda}_{ic}}. (51)$$

Since the constraints $\prod_{s=1}^{S} \mathbf{\Lambda}_{sc} = \mathbf{e}, \ c = 1, 2, ..., C$ hold, we can easily conclude

$$\prod_{s=1}^{S} \delta_{isc} = \prod_{s=1}^{S} \frac{B_{isc}}{A_{isc} - 2\hat{\lambda}_{ic}} = 1$$
 (52)

hold for i = 1, ..., p, c = 1, 2, ..., C. Define

$$h(\hat{\lambda}_{ic}) = \prod_{s=1}^{S} B_{isc} - \prod_{s=1}^{S} (A_{isc} - 2\hat{\lambda}_{ic}),$$
 (53)

then

$$h'(\hat{\lambda}_{ic}) = 2 \left[\prod_{s=1}^{S} (A_{isc} - 2\hat{\lambda}_{ic}) \right] \cdot \left[\sum_{s=1}^{S} \frac{1}{A_{isc} - 2\hat{\lambda}_{ic}} \right].$$
 (54)

Then $\hat{\lambda}_{ic}$ can be calculated numerically by Newton method as follows:

Algorithm 1 Newton method to solve λ s.t. $h(\lambda) = 0$

```
Input: a positive number \epsilon which is small enough; one initialization value \lambda^{(1)}. Output: numerical solution \lambda^* s.t. h(\lambda^*) \approx 0, namely, \|h(\lambda^*)\| < \epsilon

1:
2: for t=1,2,... do
3: \lambda^{(t+1)} = \lambda^{(t)} - \frac{h(\lambda^{(t)})}{h'(\lambda^{(t)})}
4: if \|h(\lambda^{(t+1)})\| \le \epsilon then
5: \lambda^* = \lambda^{(t+1)}
6: break
7: end if
```

8: end for 9: return λ^*

In summary, we can update $\Delta_{sc} = \text{diag}(\Lambda_{sc})$ by equation 49, where λ_c can be solved numerically by the Newton method (Algorithm 1).

Update π_{sc} :

Finally, for each scanner setting $s \in \{1, 2, ..., S\}$, we will analyze the way to update the mixing coefficients π_{sc} . we will maximize $\mathcal{Q}_s(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$ with respect to π_{sc} under the constraints $\sum_{c=1}^{C} \pi_{sc} = 1$ by taking a Lagrange multiplier and maximizing the following quantity

$$\mathcal{L}_{s} = \mathcal{Q}_{s}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) + \lambda \left(\sum_{c=1}^{C} \pi_{sc} - 1\right)
= \sum_{n=1}^{N_{s}} \sum_{c=1}^{C} \alpha(z_{nc}^{(s)}) \left[\ln \pi_{sc} + \ln \mathcal{N}(\boldsymbol{x}_{n}^{(s)} | \boldsymbol{\mu}_{c} + \boldsymbol{\gamma}_{sc}, \boldsymbol{\Delta}_{sc} \boldsymbol{\Sigma}_{c})\right] + \lambda \left(\sum_{c=1}^{C} \pi_{sc} - 1\right),$$
(55)

the derivative of \mathcal{L}_s with respect to π_{sc} takes the form

$$\frac{\partial \mathcal{L}_s}{\partial \pi_{sc}} = \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}) \frac{1}{\pi_{sc}} + \lambda. \tag{56}$$

Set $\frac{\partial \mathcal{L}_s}{\partial \pi_{sc}} = 0$, then we can get π_{sc} as

$$\pi_{sc} = -\frac{1}{\lambda} \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}). \tag{57}$$

Notice that

$$\sum_{c=1}^{C} \pi_{sc} = 1, \tag{58}$$

taking Equation (57) to Equation (58), we can get the value of λ as

$$\lambda = -\sum_{n=1}^{N_s} \sum_{c=1}^{C} \alpha(z_{nc}^{(s)}) = -N_s, \tag{59}$$

taking Equation (59) into Equation (57), we get π_{sc} as follows

$$\pi_{sc} = \frac{1}{N_s} \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)}). \tag{60}$$

2.4.3 Summary of the algorithm

We summarize the algorithm for estimating the set of the model parameters θ in Equation (14) for our proposed model (10) with constraints (11)(12)(13) as follows.

Algorithm 2 Estimate the set of the parameters θ of the proposed model (10) with constraints (11)(12)(13).

Input: For each setting class $s \in \{1, 2, ..., S\}$, we have N_s observed data $\{\boldsymbol{x}_1^{(s)}, ..., \boldsymbol{x}_{N_s}^{(s)}\}$. Let ϵ be a positive number that is small enough.

Output: Estimated value θ^* of the set of model parameters θ as defined in Equation (14).

1: Choose the results of Gaussian mixture model as an initialization of $\boldsymbol{\theta}$, denoted as $\boldsymbol{\theta}^{(0)}$ as below. And initialize the logarithm likelihood function $\mathcal{L}(\boldsymbol{\theta}^{(0)}) = -\infty$.

$$\boldsymbol{\theta}^{(0)} = \{ \pi_{sc}^{(0)} \in \mathbb{R}, \ \boldsymbol{\mu}_{c}^{(0)} \in \mathbb{R}^{p}, \ \boldsymbol{\Sigma}_{c}^{(0)} \in \mathbb{R}^{p \times p}, \\ \boldsymbol{\gamma}_{sc}^{(0)} \in \mathbb{R}^{p}, \ \boldsymbol{\Delta}_{sc}^{(0)} \in \mathbb{R}^{p \times p} \mid s = 1, 2, ..., S; \ c = 1, 2, ..., C \}.$$
(61)

- 2: **for** k=1,2,... **do**
- 3: **E Step**: Evaluate the responsibilities using the parameters $\theta^{(k-1)}$

$$\alpha(z_{nc}^{(s)})^{(k)} = \frac{\pi_{sc} \, \mathcal{N}(\boldsymbol{x}_n^{(s)} | \boldsymbol{\mu}_c^{(k-1)} + \boldsymbol{\gamma}_{sc}^{(k-1)}, \boldsymbol{\Delta}_{sc}^{(k-1)} \boldsymbol{\Sigma}_c^{(k-1)})}{\sum_{j=1}^{C} \pi_{sj} \, \mathcal{N}(\boldsymbol{x}_n^{(s)} | \boldsymbol{\mu}_j^{(k-1)} + \boldsymbol{\gamma}_{sj}^{(k-1)}, \boldsymbol{\Delta}_{sj}^{(k-1)} \boldsymbol{\Sigma}_j^{(k-1)})}$$
(62)

- 4: **M Step**: Re-estimate the parameters $\boldsymbol{\theta}$ as $\boldsymbol{\theta}^{(k)}$ using the responsibilities $\alpha_s(z_{nc})^{(k)}$ and the parameters $\boldsymbol{\theta}^{(k-1)}$.
 - Update $\gamma_{sc}^{(k)}$:

$$\boldsymbol{\gamma}_{sc}^{(\mathbf{k})} = \left[\sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)})^{(\mathbf{k})} (\boldsymbol{\Delta}_{sc}^{(\mathbf{k}-1)} \boldsymbol{\Sigma}_c^{(\mathbf{k}-1)})^{-1}\right]^{-1} \cdot \left[\sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)})^{(\mathbf{k})} (\boldsymbol{\Delta}_{sc}^{(\mathbf{k}-1)} \boldsymbol{\Sigma}_c^{(\mathbf{k}-1)})^{-1} (\boldsymbol{x}_n^{(s)} - \boldsymbol{\mu}_c^{(\mathbf{k}-1)}) + \boldsymbol{\lambda}_c^{(\mathbf{k})}\right]$$
(63)

where

$$\lambda_{c}^{(k)} = -\left[\sum_{s=1}^{S} w_{s} \left[\sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)})^{(k)} (\boldsymbol{\Delta}_{sc}^{(k-1)} \boldsymbol{\Sigma}_{c}^{(k-1)})^{-1}\right]^{-1}\right]^{-1} \\
\cdot \left\{\sum_{s=1}^{S} w_{s} \left[\left[\sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)})^{(k)} (\boldsymbol{\Delta}_{sc}^{(k-1)} \boldsymbol{\Sigma}_{c}^{(k-1)})^{-1}\right]^{-1} \cdot \left[\sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)})^{(k)} (\boldsymbol{\Delta}_{sc}^{(k-1)} \boldsymbol{\Sigma}_{c}^{(k-1)})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\mu}_{c}^{(k-1)})\right]\right]\right\}$$
(64)

• Update $\Delta_{sc}^{(k)} = diag(\Lambda_{sc})^{(k)}$:

$$\Lambda_{sc}^{(k)} = \frac{1}{\left[w_s \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)})^{(k)} \cdot e - 2\hat{\lambda}_c^{(k)}\right]} \\
\circ \left[w_s \sum_{r=1}^{N_s} \alpha(z_{nc}^{(s)})^{(k)} \cdot (\Sigma_c^{(k-1)})^{-1} \cdot (x_n^{(s)} - \mu_c^{(k-1)} - \gamma_{sc}^{(k)}) \circ (x_n^{(s)} - \mu_c^{(k-1)} - \gamma_{sc}^{(k)})\right]$$
(65)

and $\hat{\boldsymbol{\lambda}}_c^{(k)}$ can be solved numerically by Newton method.

• Update $\mu_c^{(k)}$:

$$\boldsymbol{\mu}_{c}^{(k)} = \left[\sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)})^{(k)} (\boldsymbol{\Delta}_{sc}^{(k)})^{-1}\right]^{-1} \cdot \left[\sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)})^{(k)} (\boldsymbol{\Delta}_{sc}^{(k)})^{-1} (\boldsymbol{x}_{n}^{(s)} - \boldsymbol{\gamma}_{sc}^{(k)})\right]$$
(66)

• Update $\Sigma_c^{(k)} = diag(\Gamma_c^{(k)})$:

$$\Gamma_{c}^{(k)} = \left[\sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)})^{(k)}\right]^{-1} \\
\cdot \left[\sum_{s=1}^{S} w_{s} \sum_{n=1}^{N_{s}} \alpha(z_{nc}^{(s)})^{(k)} (\mathbf{\Delta}_{sc}^{(k)})^{-1} (\mathbf{x}_{n}^{(s)} - \boldsymbol{\mu}_{c}^{(k)} - \boldsymbol{\gamma}_{sc}^{(k)}) \circ (\mathbf{x}_{n}^{(s)} - \boldsymbol{\mu}_{c}^{(k)} - \boldsymbol{\gamma}_{sc}^{(k)})\right]$$
(67)

```
• Update \pi_{sc}^{(k)}: \pi_{sc}^{(k)} = \frac{1}{N_s} \sum_{n=1}^{N_s} \alpha(z_{nc}^{(s)})^{(k)}
```

Calculate the logarithm likelihood function

$$\mathcal{L}(\boldsymbol{\theta}^{(k)}) = \sum_{s=1}^{S} w_s \sum_{n=1}^{N_s} \ln \left\{ \sum_{c=1}^{C} \pi_{sc}^{(k)} \mathcal{N}(\boldsymbol{x}_n^{(s)} | \boldsymbol{\mu}_c^{(k)} + \boldsymbol{\gamma}_{sc}^{(k)}, \boldsymbol{\Delta}_{sc}^{(k)} \boldsymbol{\Sigma}_c^{(k)}) \right\},$$
(68)

```
6: if \mathcal{L}(\boldsymbol{\theta}^{(k)}) - \mathcal{L}(\boldsymbol{\theta}^{(k-1)}) \leq \epsilon, then
7: \boldsymbol{\theta}^* = \boldsymbol{\theta}^{(k)}
8: break
9: end if
10: end for
11: return \boldsymbol{\theta}^*
```

2.5 Remove scanner effects with the estimated parameters

With the estimated parameters of model (10), then given an observed data $x_n^{(s)}$ from scanner setting $s \in \{1, 2, ..., S\}$, the pattern class label of $x_n^{(s)}$ can be estimated as

$$c = \arg\max_{c \in \{1, 2, \dots, C\}} \alpha(z_{nc}^{(s)}), \tag{69}$$

where $\alpha(z_{nc}^{(s)})$ represents the posterior probability of $\boldsymbol{x}_n^{(s)}$ belonging to pattern class c, or the responsibility that pattern class c takes for explaining the observation $\boldsymbol{x}_n^{(s)}$. Then the scanner effects adjusting data $\boldsymbol{y}_n^{(s)}$ corresponding to $\boldsymbol{x}_n^{(s)}$ can be expressed as

$$\mathbf{y}_{n}^{(s)} = \mu_{c} + \Omega_{sc}^{-1}(\mathbf{x}_{n}^{(s)} - \mu_{c} - \gamma_{sc}), \tag{70}$$

where $\Omega_{sc} = (\boldsymbol{\Delta_{sc}})^{\frac{1}{2}}$.

5:

2.6 Experiment results and discussion

To better understand the importance of the additive constraints (12) and multiplicative constraints (13), we apply our proposed model (10) for each pattern class separately with the number of pattern class C equal to 1. As shown in Figure (7), we can see that the additive and multiplicative constraints are essential because they help to make identifiable of the parameters and make the adjusted data to have reasonable mean and variance.

Now having realized the importance of the constraint conditions, we now show our experiment results in Figure 8. Note that the true pattern class labels are unknown and are predicted by our proposed model. As shown in Figure 8(b), the predicted pattern class labels are completely wrong, which leads to unacceptable harmonization results as shown in Figure 8(c). In other words, our proposed model fails to provide satisfying harmonization results.

By further analyzing the model in detail, we come to the conclusion that our model fails because it lacks enough constraints to help identify the parameters. More specifically, in model (10), we can see that for a given scanner setting s, the mean of the c-th Gaussian distribution is $\mu_c + \gamma_{sc}$, but μ_c and γ_{sc} can not be identified. In other words, each point from scanner setting s can be classified to an arbitrary pattern class just by defining a different additive scanner effects γ_{sc} . Similar problem exists for identify the variance Σ_c of pattern class c and the multiplicative scanner effects Δ_{sc} .

We have made it clear that our model fails to provide satisfying harmonization results because it lacks of enough constraints on parameters. Then it is natural to ask whether proper constraints could be imposed to help solve the problem? Unfortunately, the answer is No. No proper constraints could be proposed since we have no proper prior experience of the mean(or variance) and scanner effects for each pattern class. So more information should be provided if we want to have good harmonization results with the assumption that scanner effects are different for each pattern class.

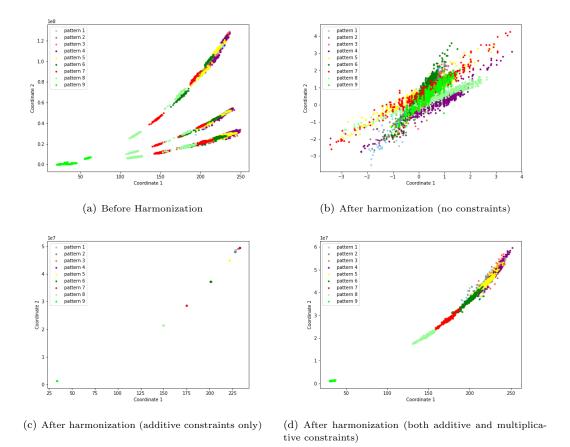
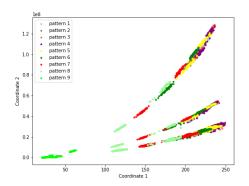


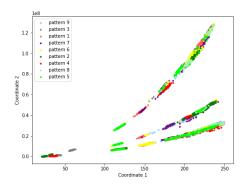
Figure 7: Effects of the additive and multiplicative constraints. Our proposed model is applied separately for each pattern class with the number of pattern class set to 1, and the model parameters are initialized randomly.

Now our problem can be regarded as solving an unsupervised classification problem and a harmonization problem simultaneously, it is indeed a tricky problem and impossible to solve without enough constraints to help identify the parameters. So we think to solve the problem by involving more information. For example, consider the problem as a learning problem (consisting of a training process and a prediction process), and suppose the pattern class labels are known during the training, then the problem becomes a supervised classification problem and at the same time a harmonization problem. We will consider this case as a future work.

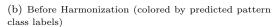
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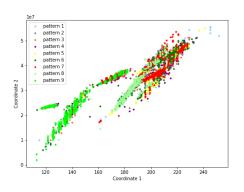
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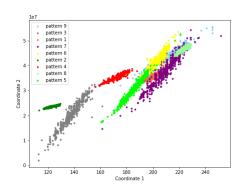




(a) Before Harmonization (colored by true pattern class labels)







(c) After harmonization (colored by true pattern class labels)

(d) After harmonization (colored by predicted pattern class labels)

Figure 8: Harmonization results by our proposed model. The number of pattern class is set to 9 (the real pattern number), and the model parameters are initialized by the results of Gaussian mixture model.

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