Stochastic Signal Processing

Lesson 15: Basic of Markov Chain

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Outline

- Markov Process and Markov Chain: introduction
- Transition probabilities
- Transition matrix
- Higher transition probability and Chapman-Kolmogorov equation

Markov Process and Markov Chain

• Markov processes: the outcome at any instant depends only on the outcome that preceds it and none before that. In a Markov process $\mathbf{x}(t)$, the only the present influences the future:

For
$$t_{n-1} < t_n$$
: $P[\mathbf{x}(t_n) \le x_n \mid \mathbf{x}(t), t \le t_{n-1}] = P[\mathbf{x}(t_n) \le x_n \mid \mathbf{x}(t_{n-1})]$
For $t_1 < t_2 < \dots < t_n$: $P[\mathbf{x}(t_n) \le x_n \mid \mathbf{x}(t_{n-1}), \dots, \mathbf{x}(t_1)] = P[\mathbf{x}(t_n) \le x_n \mid \mathbf{x}(t_{n-1})]$

- A special kind of Markov process is a Markov chain where the system can occupy a finite or countably infinite number of states $e_1, e_2, ..., e_j$, ... such that the future evolution of the process, once it is in a given state, depends only on the present state and not on how it arrived at that state.
 - We only discuss discrete-time cases in this course.
- We first use some examples to illustrate the abundance of Markov processes in real world problems.

Markov Chain Examples

Random walk: The 1-D random walk model considered in last lecture is a special case of a Markov chain.

$$\mathbf{s}_n = \mathbf{x}_1 + \mathbf{x}_2 + \dots + \mathbf{x}_n; \quad \mathbf{s}_0 = 0$$

• The sequence of Bernoulli trials $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_n, ...$, at each stage are independent, and the accumulated partial sum \mathbf{s}_n that represents the relative position of the particle satisfies the recursion $\mathbf{s}_{n+1} = \mathbf{s}_n + \mathbf{x}_{n+1}$. Given $\mathbf{s}_n = j$, for $j = 0, \pm 1, \pm 2, ..., \pm n$, ..., the random variable \mathbf{s}_{n+1} can assume only two values: $\mathbf{s}_{n+1} = j + 1$ with probability p, and $\mathbf{s}_{n+1} = j - 1$ with probability q:

$$P(\mathbf{s}_{n+1} = j + 1 \mid \mathbf{s}_n = j) = p$$

 $P(\mathbf{s}_{n+1} = j - 1 \mid \mathbf{s}_n = j) = q$

• These conditional probabilities for \mathbf{s}_{n+1} depend only on the values of \mathbf{s}_n and are not affected by the values of $\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_{n-1}$.

Markov Chain Examples

Social mobility (社会流动)

- Let X_n represents the social class (社会阶层) of a family at the n-th generation, and assume that there are three classes: 1-lower, 2-middle, 3-upper. Then the change of the social class is a Markov chain:
 - If $X_n = 1$, the $P(X_{n+1} = 1 | X_n = 1) = p_{11}$, $P(X_{n+1} = 2 | X_n = 1) = p_{12}$, $P(X_{n+1} = 3 | X_n = 1) = p_{13}$, note that $p_{11} + p_{12} + p_{13} = 1$.
 - If $X_n = 2$, the $P(X_{n+1} = 1 | X_n = 2) = p_{21}$, $P(X_{n+1} = 2 | X_n = 2) = p_{22}$, $P(X_{n+1} = 3 | X_n = 2) = p_{23}$
 - If $X_n = 3$, the $P(X_{n+1} = 1 | X_n = 3) = p_{31}$, $P(X_{n+1} = 2 | X_n = 3) = p_{32}$, $P(X_{n+1} = 3 | X_n = 3) = p_{33}$
- For a completely fair society, $p_{ik} = p_{jk}$ for any i, j, k.

Transition probabilities

• In a discrete-time Markov chain $\{\mathbf{x}_n\}$ with a finite or infinite set of states $e_1, e_2, \ldots, e_i, \ldots$, let $\mathbf{x}_n = \mathbf{x}(t_n)$ represent the state of the system at $t = t_n$. If $t_n = nT$, then for $n \ge m \ge 0$, the sequence $\mathbf{x}_m \to \mathbf{x}_{m+1} \to \cdots \to \mathbf{x}_n, \ldots$ represents the evolution of the system. Let

$$p_i(m) = P\{\mathbf{x}_m = e_i\}$$

represents the probability that at time $t = t_m$ the system occupies the state e_i , and

$$p_{ik}(m,r) \triangleq P\{x_r = e_k \mid x_m = e_i\}$$

represents the probability that the system goes into state e_k at $t = t_r$ given that it was in state e_i at $t = t_m$ (regardless of its behavior prior to t_m). Futhermore, assume at time t_n , n > r, the state is e_j , and let the $p_{kj}(r,n)$ represent the transition probabilities of the Markov chain from state e_k at t_r to state e_j at t_n . Then:

$$P\{\mathbf{x}_n=e_j,\mathbf{x}_r=e_k,\mathbf{x}_m=e_i\}$$
 the whole system if what we care is the states at these three times

$$= P\{\mathbf{x}_n = e_i \mid \mathbf{x}_r = e_k\} P\{\mathbf{x}_r = e_k \mid \mathbf{x}_m = e_i\} P\{\mathbf{x}_m = e_i\} = p_{ki}(r, n) p_{ik}(m, r) p_i(m)$$

Homogeneous chain

• A Markov chain is said to be homogeneous (齐次) if $p_{ij}(m,n)$ depends only on the difference n-m. In that case, the transition probabilities are said to be stationary and

$$P\{\mathbf{x}_{m+n} = e_j \mid \mathbf{x}_m = e_i\} \stackrel{\Delta}{=} p_{ij}(n) = p_{ij}^{(n)}$$

represents the conditional probability that a homogeneous Markov chain will move from state e_i to state e_j in n steps. The one-step transition probabilities are usually denoted simply as p_{ij} . Thus

$$p_{ij} = P\{\mathbf{x}_{n+1} = e_j \mid \mathbf{x}_n = e_i\}$$

• The time duration y that a homogeneous Markov process spends in a given state (interarrival time) must be memoryless, since the present state is sufficient to determine the future. Thus in the discrete case if the time instants t_n are uniformly placed at $t_n = nT$, then y satisfies the relation

$$P(\mathbf{y} > m + n \mid \mathbf{y} > m) = P(\mathbf{y} > n)$$

• In this course, we will mainly discuss the Homogeneous Chain.

Transition matrix (转移矩阵)

• It is convenient to arrange the transition probabilities $p_{ij}(m,n)$ in a matrix form P(m,n) as

$$P(m,n) = \begin{pmatrix} p_{11}(m,n) & p_{12}(m,n) & \cdots & p_{1j}(m,n) & \cdots \\ p_{21}(m,n) & p_{22}(m,n) & \cdots & \cdots & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ p_{i1}(m,n) & \cdots & \cdots & p_{ij}(m,n) & \cdots \\ & \cdots & \cdots & \cdots & \cdots & \cdots \end{pmatrix}$$

P(m,n) is a matrix whose entries are all nonnegative, and $\sum_j p_{ij}(m,n) = \sum_j P\{\mathbf{x}_n = e_j \mid \mathbf{x}_m = e_i\} = 1$

- This is the transition probability matrix (转移概率矩阵) that completely define the Markov chain.
- In the special case of a homogeneous Markov chain, we have the one step transition matrix *P*

$$p_k(0) \triangleq P\{\mathbf{x}_0 = e_k\}$$

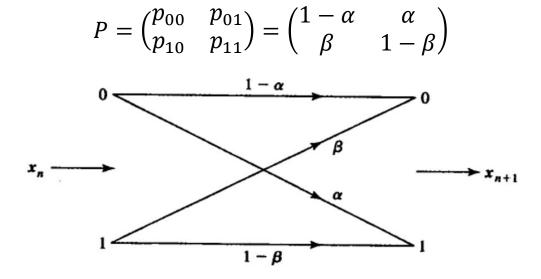
That can completely defines the process.

Binary communication channel:

• The figure below represents a time-invariant binary communication channel: \mathbf{x}_n denotes the input and \mathbf{x}_{n+1} the output. The input and the output each possess two states e_0 and e_1 that represent the two binary symbols "0" and "1" respectively. The channel delivers the input symbol to the output with a certain error probability that may depend on the symbol being transmitted. In a time invariant channel, these error probabilities remain constant over various transmitted symbols so that

$$P\{\mathbf{x}_{n+1} = 1 \mid \mathbf{x}_n = 0\} = p_{01} = \alpha$$
 $P\{\mathbf{x}_{n+1} = 0 \mid \mathbf{x}_n = 1\} = p_{10} = \beta$

and the corresponding Markov chain is homogeneous. The 2×2 homogeneous one step transition matrix P is



Social mobility (社会流动)

- Let X_n represents the social class (社会阶层) of a family at the n-th generation, and assume that there are three classes: 1-lower, 2-middle, 3-upper. Then the change of the social class is a Markov chain:
 - If $X_n = 1$, the $P(X_{n+1} = 1 | X_n = 1) = p_{11}$, $P(X_{n+1} = 2 | X_n = 1) = p_{12}$, $P(X_{n+1} = 3 | X_n = 1) = p_{13}$, note that $p_{11} + p_{12} + p_{13} = 1$.
 - If $X_n = 2$, the $P(X_{n+1} = 1 | X_n = 2) = p_{21}$, $P(X_{n+1} = 2 | X_n = 2) = p_{22}$, $P(X_{n+1} = 3 | X_n = 2) = p_{23}$
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 - A possible one step transition matrix might be:

$$\begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$$

Now we have a question: in the long run, the percentage of the three classes will approach a certain number?

Let's solve it!

• Example 1: Let X_n represents the social class (社会阶层) of a family at the n-th generation, and assume that there are three classes: 1-lower, 2-middle, 3-upper. The one step transition matrix is:

$$\begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$$

Calculate the stationary distributions of the three classes, which is defined as

$$\begin{bmatrix} a & b & c \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} = \begin{bmatrix} a & b & c \end{bmatrix}$$

Which means, at step n, the distribution is $\begin{bmatrix} a & b & c \end{bmatrix}$ (note that the summation is 1), and at step n+1, the distribution is still $\begin{bmatrix} a & b & c \end{bmatrix}$, this is defined as stationary distributions.

Try to calculate it yourself!

• Example 1: Let X_n represents the social class (社会阶层) of a family at the n-th generation, and assume that there are three classes: 1-lower, 2-middle, 3-upper. The one step transition matrix is:

 $\begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$

Calculate the stationary distributions of the three classes.

Solution:

$$\begin{bmatrix} a & b & c \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} = \begin{bmatrix} a & b & c \end{bmatrix} \Rightarrow 0.7a + 0.3b + 0.2c = a \\ 0.2a + 0.5b + 0.4c = b \\ 0.1a + 0.2b + 0.4c = c \end{bmatrix}$$

And according to the definition:

$$a+b+c=1$$

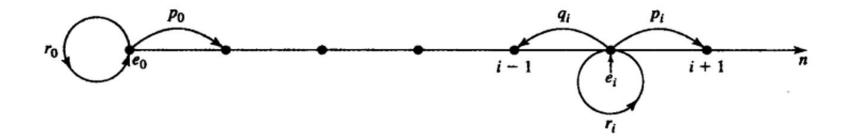
$$\rightarrow$$

$$a = 22/47, b = 16/47, c = 9/47$$

Random walk:

• Consider a general one-dimensional random walk on the possible states e_0, e_1, e_2, \dots Let \mathbf{s}_n represent the location of the particle at time n on a straight line such that at each interior state e_j , the particle either moves to the right to e_{j+1} with probability p_j , or to the left to e_{j-1} with probability q_j or remains where it is at e_j with probability r_j . Obviously when at state e_0 , it can either stay there with probability r_0 or move to the right to e_1 with probability p_1 . This gives the corresponding transition matrix P to be

$$P = \begin{pmatrix} r_0 & p_0 & 0 & 0 & 0 & \cdots \\ q_1 & r_1 & p_1 & 0 & 0 & \cdots \\ 0 & q_2 & r_2 & p_2 & 0 & \cdots \\ 0 & 0 & q_3 & r_3 & p_3 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{pmatrix}$$
(15-1)



Random walk with absorbing barriers (吸收壁): let the number of states in a random walk be finite $(e_0, e_1, e_2, ..., e_N)$ and consider the special case of (14-1) as

$$P = \begin{pmatrix} 1 & 0 & 0 & 0 & \cdot & \cdot & \cdot & 0 \\ q & 0 & p & 0 & 0 & \cdot & \cdot & 0 \\ 0 & q & 0 & p & 0 & \cdot & \cdot & 0 \\ \vdots & \vdots \\ 0 & 0 & \cdot & \cdot & \cdot & q & 0 & p \\ 0 & 0 & \cdot & \cdot & \cdot & 0 & 0 & 1 \end{pmatrix}$$

- Thus from the interior states $e_1, e_2, ..., e_{N-1}$, transitions to the left and right neighbors are possible with probabilities q and p, respectively, while no transition is possible from e_0 and e_N to any other state. The system may move from one interior state to the other, but once it reaches a boundary it stays there forever (the particle gets absorbed).
 - It is easy to see that the gambler's ruin problem discussed in last lecture, where both players have finite wealth, corresponds to this case with N = a + b. In that case the game starts from the fixed point a (state e_a) of the interval (0, a + b).

Now we have a question: can we calculate the gambler's ruin probability from this Markov chain model?

Random walk with reflecting barriers (反射壁):

• Suppose the two boundaries in previous example reflect the particle back to the adjacent state instead of absorbing it. With $e_1, e_2, ..., e_N$ representing the N states, the end reflection probabilities to the right and left are given by

$$p_{1,2} = p$$
 and $p_{N,N-1} = q$

and this gives the $N \times N$ transition matrix to be

$$P = \begin{pmatrix} q & p & 0 & 0 & \cdot & \cdot & \cdot & 0 \\ q & 0 & p & 0 & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & q & 0 & p & 0 & \cdot & \cdot & \cdot & \cdot \\ \vdots & & & & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdot & \cdot & q & 0 & p \\ 0 & 0 & 0 & \cdot & \cdot & 0 & q & p \end{pmatrix}$$

• In gambling, this corresponds to a fun game where every time a player loses the game, his counterparty returns just the stake amount so that the game is kept alive and it continues forever.

Higher transition probability and Chapman-Kolmogorov equation

Recall

$$P\{\mathbf{x}_n = e_j, \mathbf{x}_r = e_k, \mathbf{x}_m = e_i\}$$

probability of three states at three times, which is, the whole system if what we care is the states at these three times

$$= P\{\mathbf{x}_n = e_j | \mathbf{x}_r = e_k\} P\{\mathbf{x}_r = e_k | \mathbf{x}_m = e_i\} P\{\mathbf{x}_m = e_i\} = p_{kj}(r, n) p_{ik}(m, r) p_i(m)$$

• The transition probability function of any Markov chain $\{\mathbf{x}_n\}$ satisfies the Chapman-Kolmogorov equation, and for n > r > m, we have

$$P\{\mathbf{x}_n = e_j, \mathbf{x}_m = e_i\} = \sum_k P\{\mathbf{x}_n = e_j, \mathbf{x}_r = e_k, \mathbf{x}_m = e_i\}$$

$$= \sum_k P\{\mathbf{x}_n = e_j | \mathbf{x}_r = e_k, \mathbf{x}_m = e_i\} P\{\mathbf{x}_r = e_k, \mathbf{x}_m = e_i\}$$

$$= \sum_k P\{\mathbf{x}_n = e_j | \mathbf{x}_r = e_k\} P\{\mathbf{x}_r = e_k, \mathbf{x}_m = e_i\}$$

Higher transition probability and Chapman-Kolmogorov equation

$$p_{ij}(m,n) = P\{x_n = e_j | x_m = e_i\} = \sum_k P\{x_n = e_j | x_r = e_k\} P\{x_r = e_k | x_m = e_i\}$$

that is

$$p_{ij}(m,n) = \sum_{k} p_{ik}(m,r) p_{kj}(r,n)$$

- In matrix form, it is P(m,n) = P(m,r)P(r,n) where m < r < n
- by letting r = m + 1, m + 2, ... we get P(m, n) = P(m, m + 1)P(m + 1, m + 2) ... P(n 1, n)
- It means: to obtain P(m,n) for all $n \ge m$, it is sufficient to know the one-step transition probability matrices $P(0,1), P(1,2), P(2,3), \dots, P(n,n+1), \dots$

Higher transition probability and Chapman-Kolmogorov equation

$$P(m,n) = P(m,m+1)P(m+1,m+2) \dots P(n-1,n)$$
 (15-2)

• For a homogeneous Markov chain, all transition probability matrices in (15-2) are equal to *P*:

$$P(m,n) = P^{n-m}$$

Or

$$P(n) = P^n$$

This is called n step transition matrix

• Example 1-1: Let X_n represents the social class (社会阶层) of a family at the n-th generation, and assume that there are three classes: 1-lower, 2-middle, 3-upper. The one step transition matrix is:

 $\begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$

If the initial distribution is [1 0 0], what is the distribution after 1 generation? 2 generations?

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If the initial distribution is [1 0 0], what is the distribution after 1 generation? 2 generations?

Solution:

the distribution after 1 generation is

$$\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} = \begin{bmatrix} 0.7 & 0.2 & 0.1 \end{bmatrix}$$

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Solution:

the distribution after 1 generation is

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the distribution after 2 generation is

$$\begin{bmatrix} 0.7 & 0.2 & 0.1 \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}^2$$

$$= \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}^2 = \begin{bmatrix} 0.57 & 0.28 & 0.15 \end{bmatrix}$$

n step transition matrix and distributions

Note that

$$\begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} \begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$$

$$= \begin{bmatrix} 0.57 & 0.28 & 0.15 \\ 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix} = \begin{bmatrix} 0.57 & 0.28 & 0.15 \\ 0.57 & 0.28 & 0.15 \end{bmatrix}$$

We get the following for a homogeneous Markov chain:

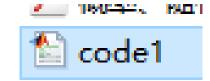
- Given the n step transition matrix P^n
- If the initial distribution is p(0), then the distribution after n steps is

$$p(n) = p(0)P^n$$

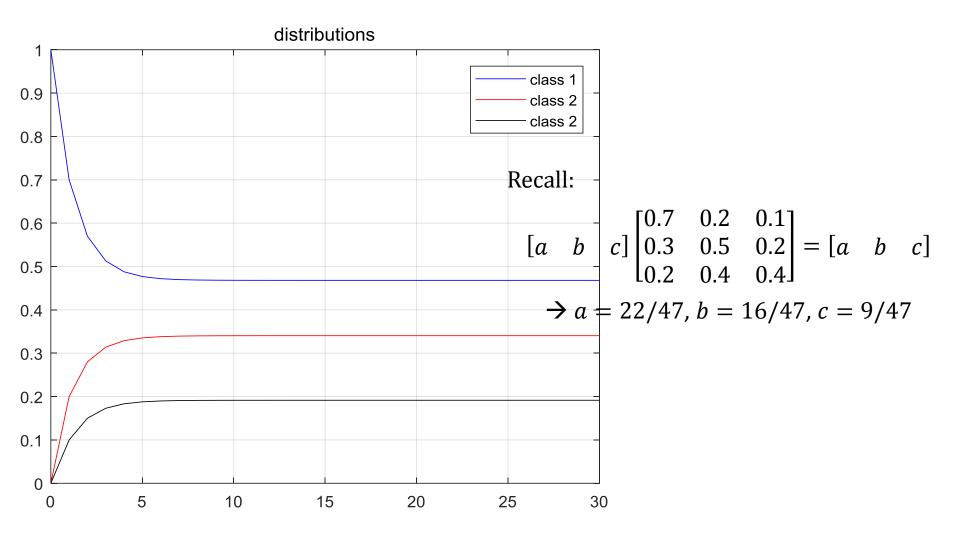
• Example 1-2: Let X_n represents the social class (社会阶层) of a family at the n-th generation, and assume that there are three classes: 1-lower, 2-middle, 3-upper. The one step transition matrix is:

 $\begin{bmatrix} 0.7 & 0.2 & 0.1 \\ 0.3 & 0.5 & 0.2 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$

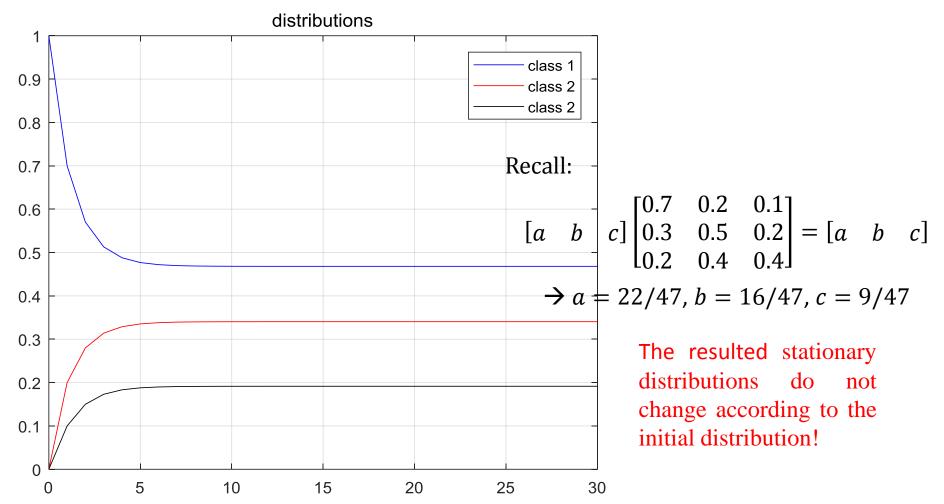
If the initial distribution is [1 0 0], what is the distribution for 30 generations?



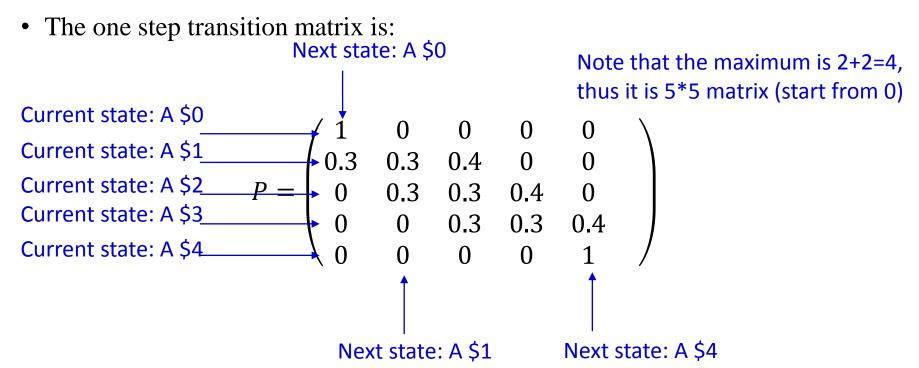
```
clear
 clc
 P = [0.7, 0.2, 0.1; 0.3, 0.5, 0.2; 0.2, 0.4, 0.4];
                                  gens = [0, gens]:
 Total Gen No = 30;
                                 figure(1)
 Vec ini = [1, 0, 0];
                                 plot(gens, Vec_all(:, 1), 'b'), grid on, hold on
 % Vec ini = [0, 0, 1];
                                 plot(gens, Vec all(:, 2), 'r'), grid on, hold on
                                 plot(gens, Vec all(:, 3), 'k'), grid on, hold on
 gens = 1:Total Gen No:
                                 xlim([0, Total_Gen_No])
 Vec current = Vec ini:
                                 vlim([0,1])
 Vec all = Vec ini;
                                 legend('class 1', 'class 2', 'class 2')
\Box for i = gens
                                 title('distributions')
      Vec_current = Vec_current*P;
      Vec all = [Vec all; Vec current];
 end
```



If the initial distribution is $[0 \ 0 \ 1]$, what is the distribution for 30 generations?

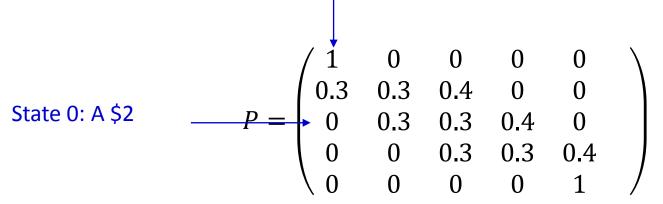


• Example 2: Two players A and B play a game consecutively till one of them loses all his capital. Suppose A starts with a capital of \$2 and B with a capital of \$2 and the loser pays \$1 to the winner in each game. Assume that there are three outcomes of one game: A wins with probability 0.4, draw (平局) with probability 0.3, and A loses with probability 0.3. What is the probability of A ruined in 1,2,3,...,30 games?



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- The one step transition matrix is:

Next state: A \$0 (A ruined)



In 1 game, the prob. Of A ruined is 0

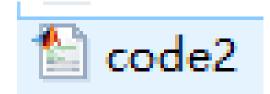
State 0: A \$2

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- The one step transition matrix is:

$$P2 = P*P$$
:

Next state: A \$0 (A ruined)

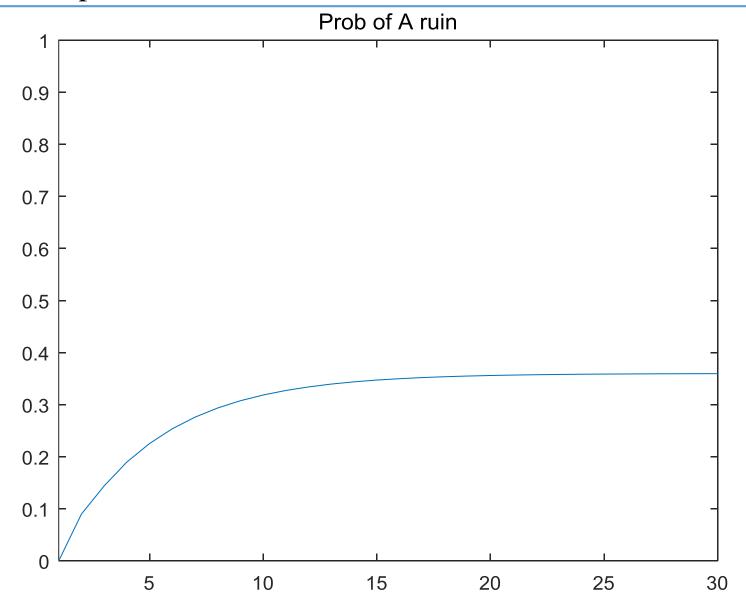
P2 × 5x5 double					
	1	2	3	4	5
1	1	0	0	0	0
2	0.3900	0.2100	0.2400	0.1600	0
3	0.0900	0.1800	0.3300	0.2400	0.1600
4	0	0.0900	0.1800	0.2100	0.5200
5	0	0	0	0	1

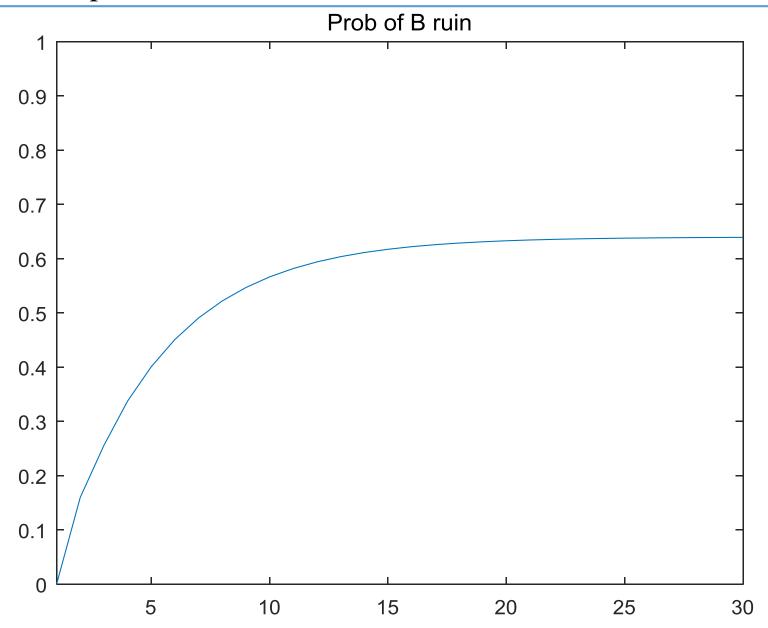


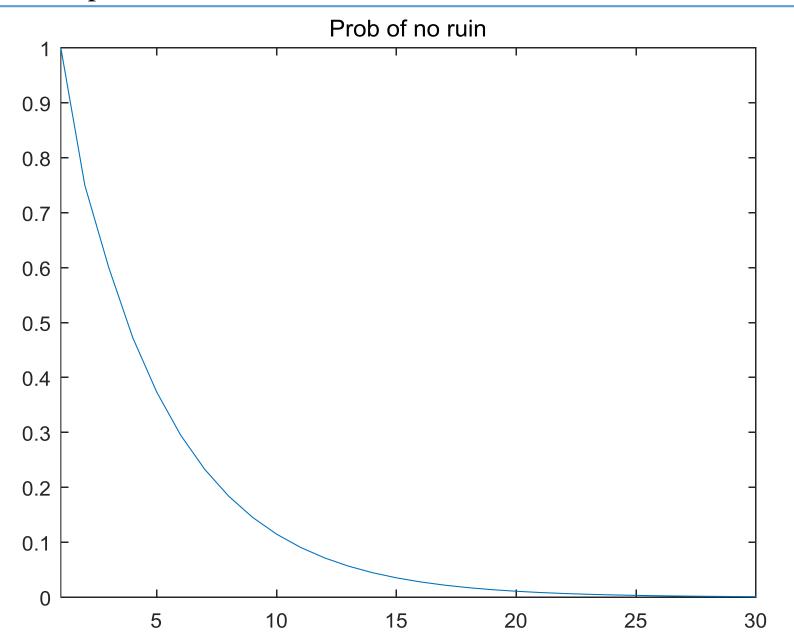
In 2 games, the prob. Of A ruined is 0.09

```
clear
 clc
 P = [1, 0, 0, 0, 0; 0, 3, 0, 4, 0, 0; 0, 0, 3, 0, 4, 0; 0, 0, 0, 3, 0, 3, 0, 4; 0, 0, 0, 0, 1];
 % P2 = P*P:
 Prob_of_A_ruin = [];
 Prob of B ruin = [];
 Prob of no ruin = [];
 Total Game No = 30;
 A start = 2:
 B start = 2:
 P_current = eye(A_start+B_start+1);
  games = 1:Total Game No;
\exists for i = games
      P_current = P_current*P;
      Prob of A ruin = [Prob of A ruin, P current(A start+1, 1)];
      Prob_of_B_ruin = [Prob_of_B_ruin, P_current(A_start+1, end)];
      Prob of no ruin = [Prob of no ruin, 1-P current(A start+1, 1)-P current(A start+1, end)];
  end
                                                                                                   30
```

```
figure(1)
plot(games, Prob_of_A_ruin)
xlim([1, Total_Game_No])
y1im([0, 1])
title('Prob of A ruin')
figure(2)
plot(games, Prob_of_B_ruin)
xlim([1, Total_Game_No])
ylim([0, 1])
title('Prob of B ruin')
figure(3)
plot(games, Prob_of_no_ruin)
xlim([1, Total_Game_No])
y1im([0, 1])
title('Prob of no ruin')
```







• Example 2: Two players A and B play a game consecutively till one of them loses all his capital. Suppose A starts with a capital of \$2 and B with a capital of \$2 and the loser pays \$1 to the winner in each game. Assume that there are three outcomes of one game: A wins with probability 0.4, draw (平局) with probability 0.3, and A loses with probability 0.3. What is the probability of A ruined in the 5-th game?

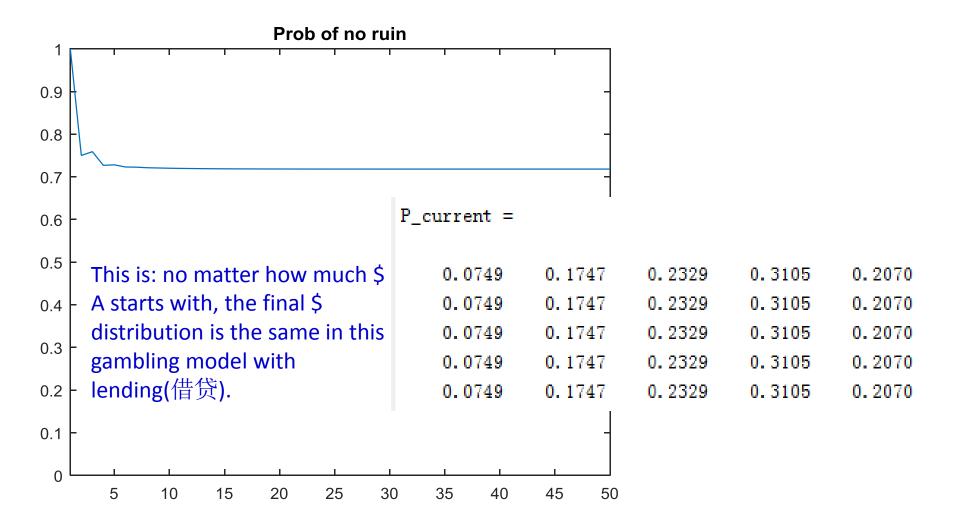
Let

Now we consider the reflecting barriers.

• Example 2: Two players A and B play a game consecutively till one of them loses all his capital. Suppose A starts with a capital of \$2 and B with a capital of \$2 and the loser pays \$1 to the winner in each game. Assume that there are three outcomes of one game: A wins with probability 0.4, draw (平局) with probability 0.3, and A loses with probability 0.3. Once A or B ruins (becomes \$0), the non-ruined person will lend the ruined person \$1 and thus the game goes on. What is the probability of the money of A and B are not 0 in the 100-th game?

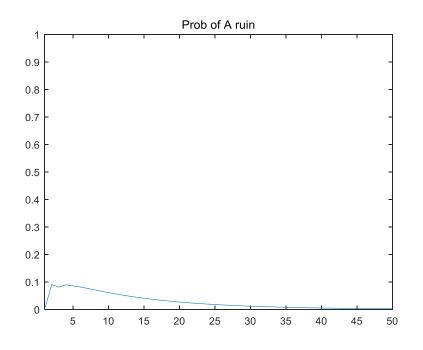
The one step transition matrix is:

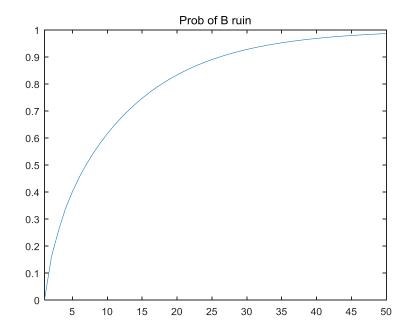
$$P = \begin{pmatrix} 0.3 & 0.7 & 0 & 0 & 0 \\ 0.3 & 0.3 & 0.4 & 0 & 0 \\ 0 & 0.3 & 0.3 & 0.4 & 0 \\ 0 & 0 & 0.3 & 0.3 & 0.4 \\ 0 & 0 & 0 & 0.6 & 0.4 \end{pmatrix}$$



Now we consider the reflecting barriers.

• How about
$$P = \begin{pmatrix} 0.3 & 0.7 & 0 & 0 & 0 \\ 0.3 & 0.3 & 0.4 & 0 & 0 \\ 0 & 0.3 & 0.3 & 0.4 & 0 \\ 0 & 0 & 0.3 & 0.3 & 0.4 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$
?





Arrangement

- Reading: 15.1,15.2
- The final week:
 - Review
 - Q&A
 - All courseworks
 - Exercise questions
 - Experiment 4

Others

• We start experiment 4 this week

• Submit your coursework 3 today

• Submit your experimental report 3 before 2024.06.19,23:59:59