

# 21 Introduction to Distributed Databases



# **ADMINISTRIVIA**

Project #4 is due Sun Dec 11th @ 11:59pm

→ Zoom Q&A Session **TONIGHT** @ **8:00pm** 

Homework #5 is due Sun Dec 4th @ 11:59pm



# PARALLEL VS. DISTRIBUTED

# **Parallel DBMSs:**

- → Nodes are physically close to each other.
- → Nodes connected with high-speed LAN.
- → Communication cost is assumed to be small.

# **Distributed DBMSs:**

- $\rightarrow$  Nodes can be far from each other.
- → Nodes connected using public network.
- → Communication cost and problems cannot be ignored.



# **DISTRIBUTED DBMSs**

Use the building blocks that we covered in singlenode DBMSs to now support transaction processing and query execution in distributed environments.

- → Optimization & Planning
- → Concurrency Control
- → Logging & Recovery



# **TODAY'S AGENDA**

System Architectures

Design Issues

Partitioning Schemes

Distributed Concurrency Control



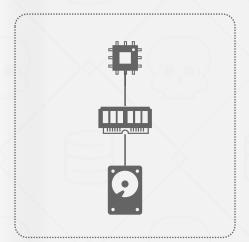
# SYSTEM ARCHITECTURE

A distributed DBMS's system architecture specifies what shared resources are directly accessible to CPUs.

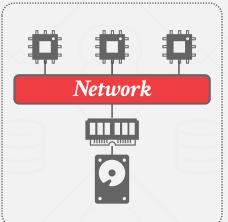
This affects how CPUs coordinate with each other and where they retrieve/store objects in the database.



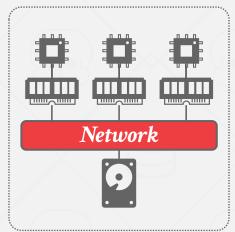
# SYSTEM ARCHITECTURE



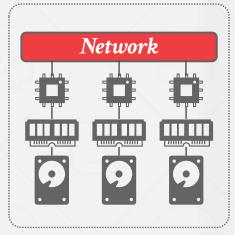
Shared Everything



Shared Memory



Shared Disk



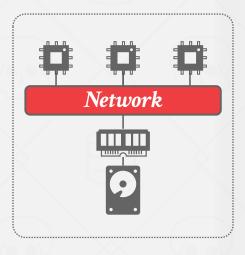
Shared Nothing



# SHARED MEMORY

CPUs have access to common memory address space via a fast interconnect.

- → Each processor has a global view of all the in-memory data structures.
- → Each DBMS instance on a processor must "know" about the other instances.





# SHARED DISK

All CPUs can access a single logical disk directly via an interconnect, but each have their own private memories.

- → Can scale execution layer independently from the storage layer.
- → Must send messages between CPUs to learn about their current state. -> druid













Network





YDB























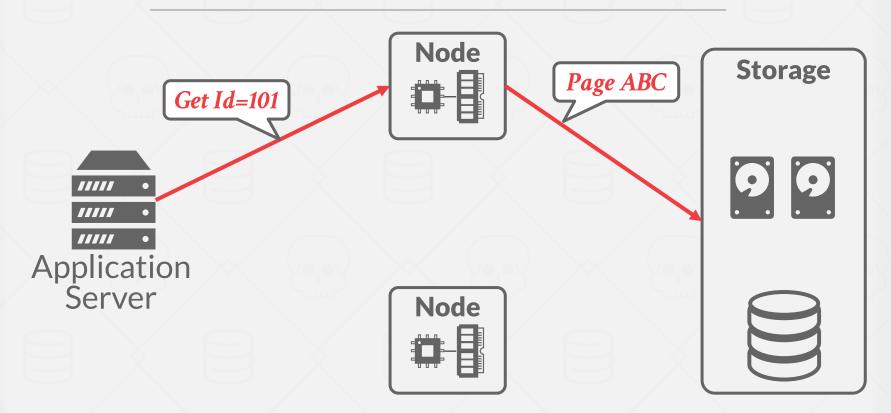




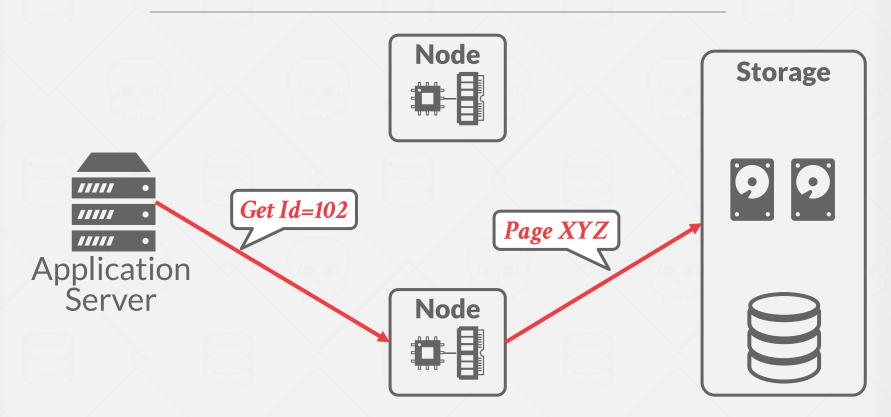




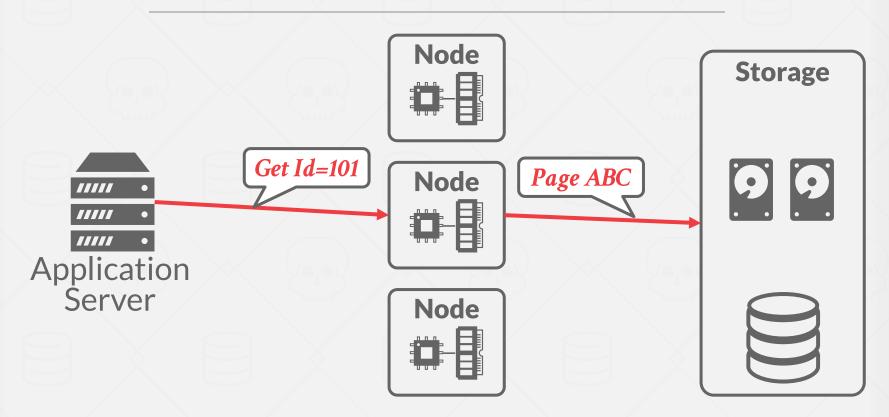




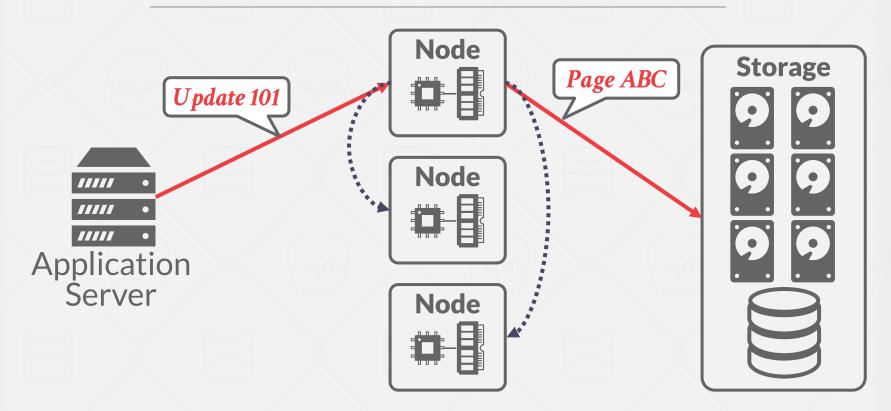














# SHARED NOTHING

Each DBMS instance has its own CPU, memory, and local disk.

Nodes only communicate with each other via network.

- $\rightarrow$  Harder to scale capacity.
- → Harder to ensure consistency.
- → Better performance & efficiency.













Greenplum

Yellowbrick





















Assassin





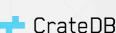






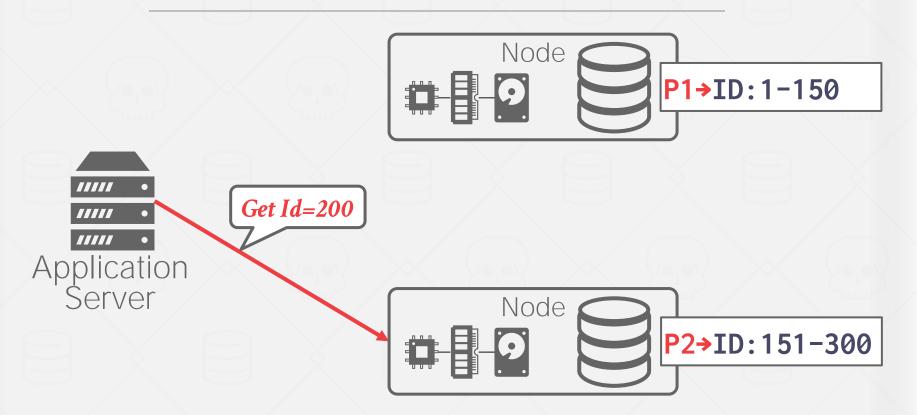


etcd



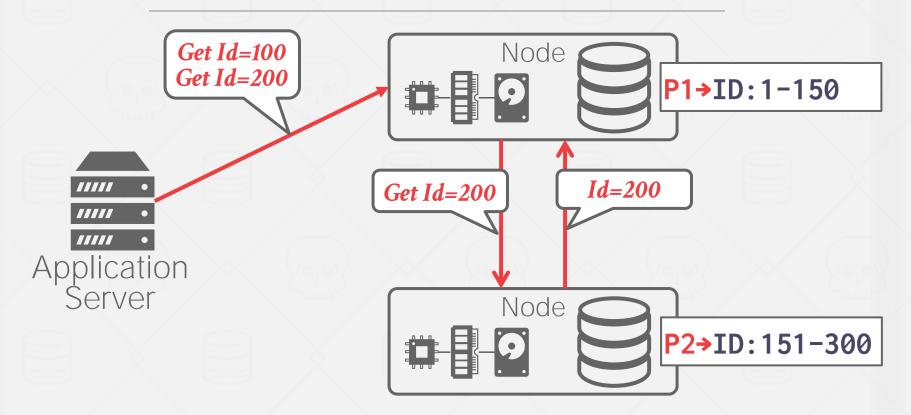
Network

# SHARED NOTHING EXAMPLE





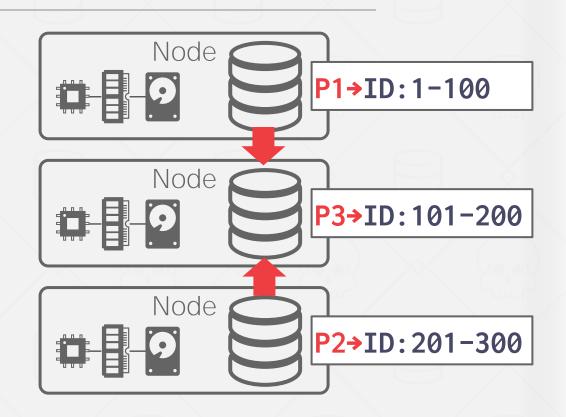
# SHARED NOTHING EXAMPLE





# SHARED NOTHING EXAMPLE







# EARLY DISTRIBUTED DATABASE SYSTEMS

MUFFIN – UC Berkeley (1979)

**SDD-1** – CCA (1979)

System R\* – IBM Research (1984)

Gamma – Univ. of Wisconsin (1986)

NonStop SQL – Tandem (1987)



Stonebraker



Mohan



Bernstein



**DeWitt** 



Gray



# **DESIGN ISSUES**

How does the application find data?

Where does the application send queries?

How to execute queries on distributed data?

- $\rightarrow$  Push query to data.
- $\rightarrow$  Pull data to query.

How does the DBMS ensure correctness? **Next Class** 

How do we divide the database across resources?



# HOMOGENOUS VS. HETEROGENOUS

# Approach #1: Homogenous Nodes

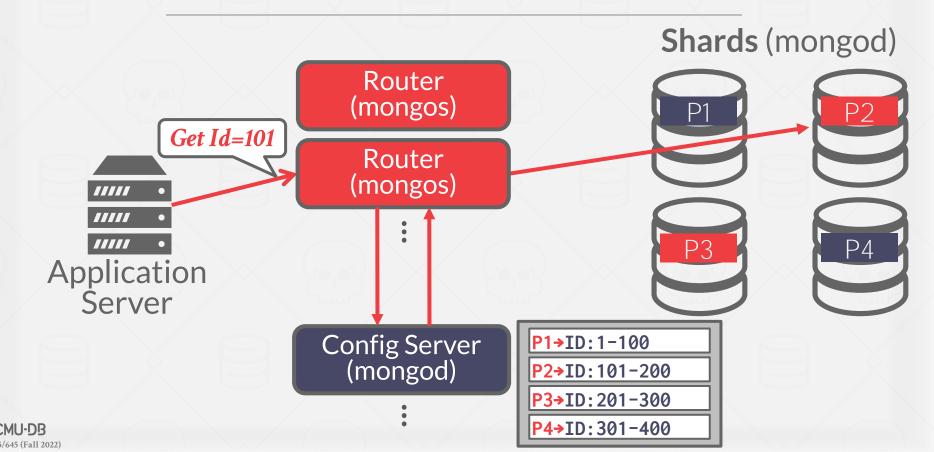
- → Every node in the cluster can perform the same set of tasks (albeit on potentially different partitions of data).
- → Makes provisioning and failover "easier".

# Approach #2: Heterogenous Nodes

- → Nodes are assigned specific tasks.
- → Can allow a single physical node to host multiple "virtual" node types for dedicated tasks.



# MONGODB HETEROGENOUS ARCHITECTURE



# DATA TRANSPARENCY

Applications should not be required to know where data is physically located in a distributed DBMS.

→ Any query that run on a single-node DBMS should produce the same result on a distributed DBMS.

In practice, developers need to be aware of the communication costs of queries to avoid excessively "expensive" data movement.



# **DATABASE PARTITIONING**

Split database across multiple resources:

- $\rightarrow$  Disks, nodes, processors.
- → Often called "sharding" in NoSQL systems.

The DBMS executes query fragments on each partition and then combines the results to produce a single answer.

The DBMS can partition a database **physically** (shared nothing) or **logically** (shared disk).



# NAÏVE TABLE PARTITIONING

Assign an entire table to a single node.

Assumes that each node has enough storage space for an entire table.

Ideal if queries never join data across tables stored on different nodes and access patterns are uniform.

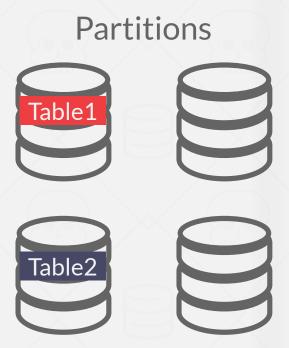


# NAÏVE TABLE PARTITIONING



Ideal Query:

**SELECT** \* **FROM** table





# **VERTICAL PARTITIONING**

Split a table's attributes into separate partitions.

Must store tuple information to reconstruct the original record.

```
CREATE TABLE foo (
  attr1 INT,
  attr2 INT,
  attr3 INT,
  attr4 TEXT
);
```

```
Tuple#1
           attr1
                      attr2
                                attr3
                                                   attr4
Tuple#2
           attr1
                      attr2
                                attr3
                                                   attr4
Tuple#3
           attr1
                      attr2
                                attr3
                                                   attr4
Tuple#4
           attr1
                      attr2
                                 attr3
                                                   attr4
```



# **VERTICAL PARTITIONING**

Split a table's attributes into separate partitions.

Must store tuple information to reconstruct the original record.

# Partition #1

Tuple#1	attr1	attr2	attr3
Tuple#2	attr1	attr2	attr3
Tuple#3	attr1	attr2	attr3
Tuple#4	attr1	attr2	attr3

CREATE TABLE foo (
attr1 INT,
attr2 INT,
attr3 INT,
attr4 TEXT
);

## Partition #2

Tuple#1	attr4
Tuple#2	attr4
Tuple#3	attr4
Tuple#4	attr4



# HORIZONTAL PARTITIONING

Split a table's tuples into disjoint subsets based on some partitioning key and scheme.

→ Choose column(s) that divides the database equally in terms of size, load, or usage.

# Partitioning Schemes:

- → Hashing
- $\rightarrow$  Ranges
- → Predicates



# HORIZONTAL PARTITIONING

## Partitioning Key Table 1 2022-11-29 hash(a)%4 = P2hash(b)%4 = P4hash(c)%4 = P32022-11-27 hash(d)%4 = P2104 105 e XYY 2022-11-29 hash(e)%4 = P1Ideal Query: FROM table

WHERE partitionKey =

# **Partitions**



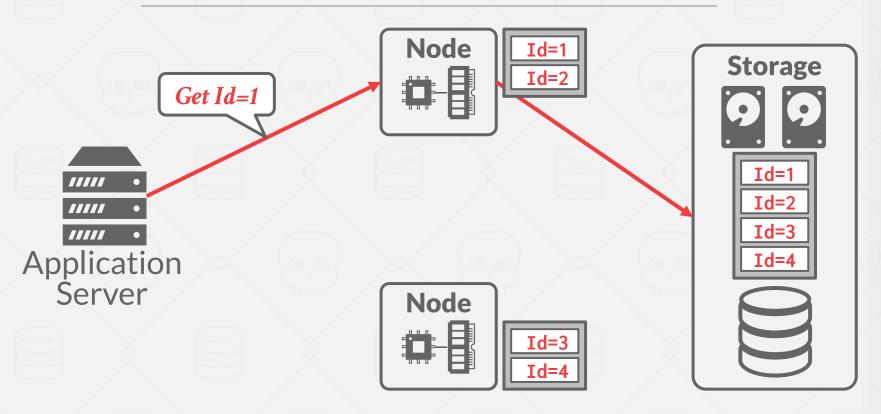






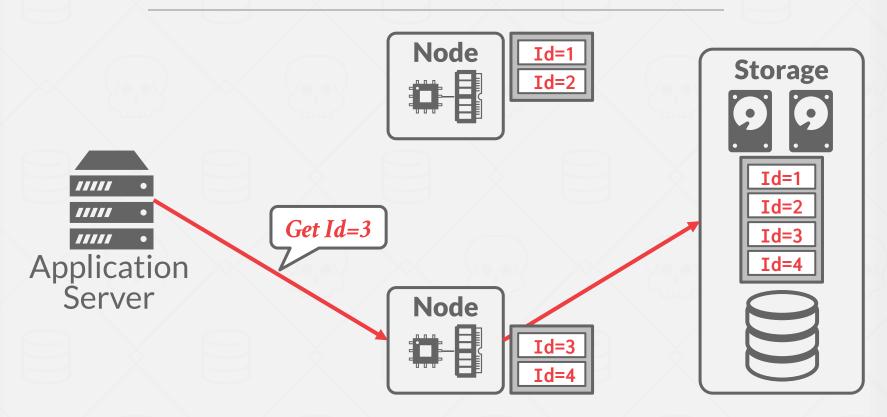


# LOGICAL PARTITIONING



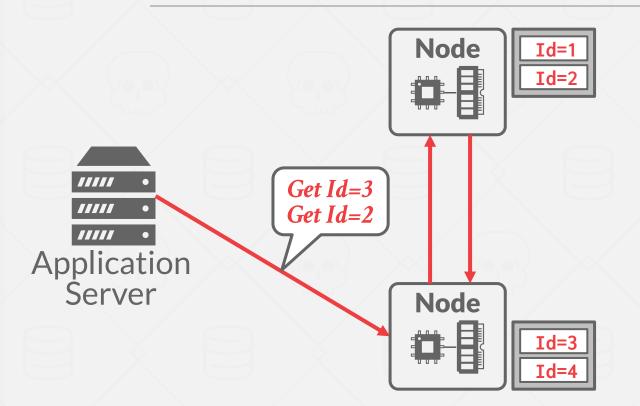


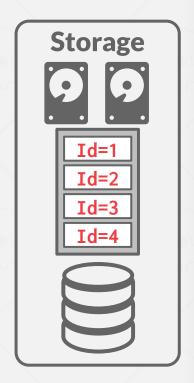
# LOGICAL PARTITIONING





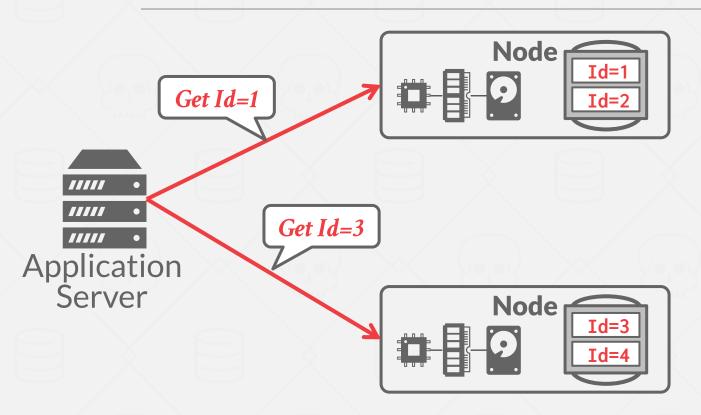
# LOGICAL PARTITIONING







# PHYSICAL PARTITIONING





# HORIZONTAL PARTITIONING

# Partitioning Key Table 1

101 a	XXX	2022-11-29	hash(a)%4 = P2
-------	-----	------------	----------------

102 b XXY	2022-11-28	hash(b)%4 = P4
-----------	------------	----------------

103 c XYZ 2022-11-29 
$$hash(c)\%4 = P3$$

04 d XYX 2022-11-27 
$$hash(d)\%4 = P2$$

			1
105 e	XYY	2022-11-29	hash(e)%4 = P

# Ideal Query:

SELECT \* FROM table
WHERE partitionKey = ?

# **Partitions**













# HORIZONTAL PARTITIONING

hash(e)%5 = P3

# Partitioning Key Table 1 101 a XXXX 2022-11-29 hash(a)%5 = P4 102 b XXY 2022-11-28 hash(b)%5 = P3 103 c XYZ 2022-11-29 hash(c)%5 = P5 104 d XYX 2022-11-27 hash(d)%5 = P1

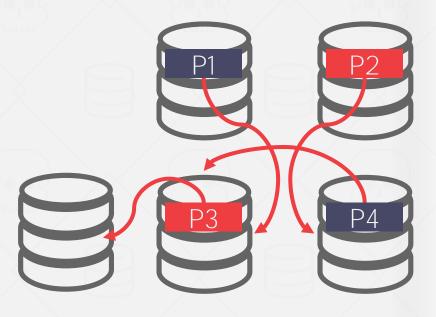
2022-11-29

#### Ideal Query:

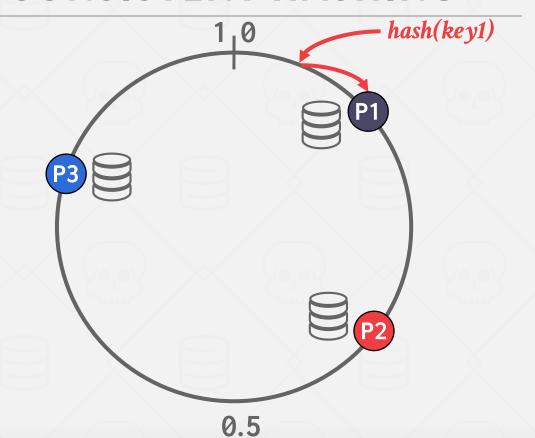
105

SELECT \* FROM table
WHERE partitionKey = ?

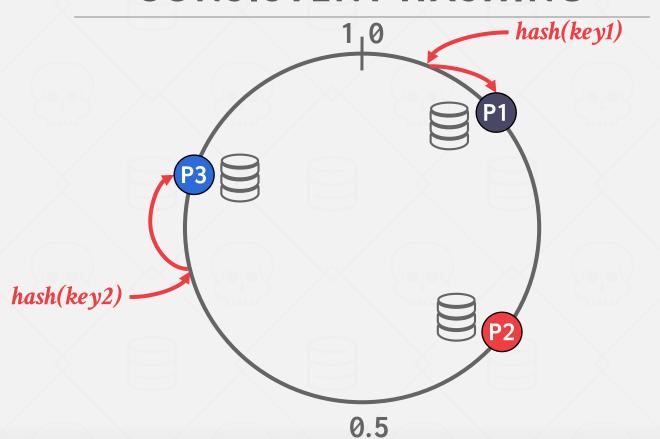
# **Partitions**



# **CONSISTENT HASHING**

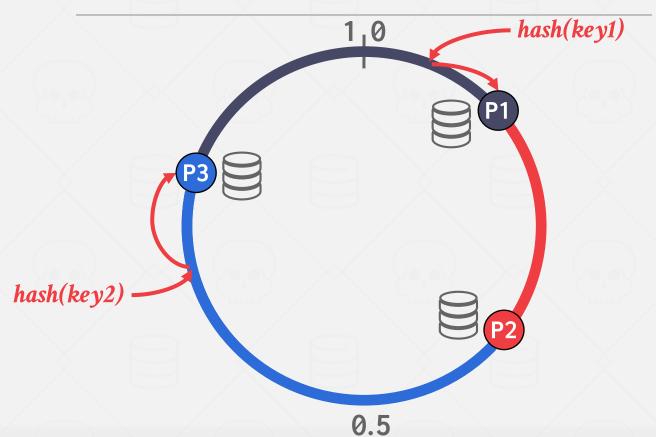




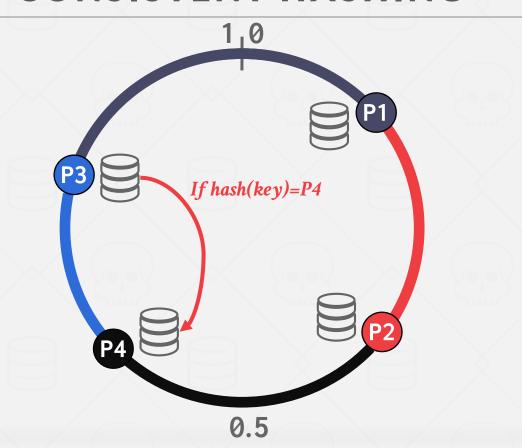




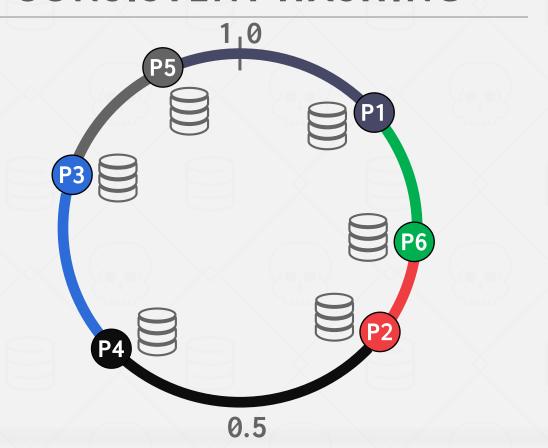




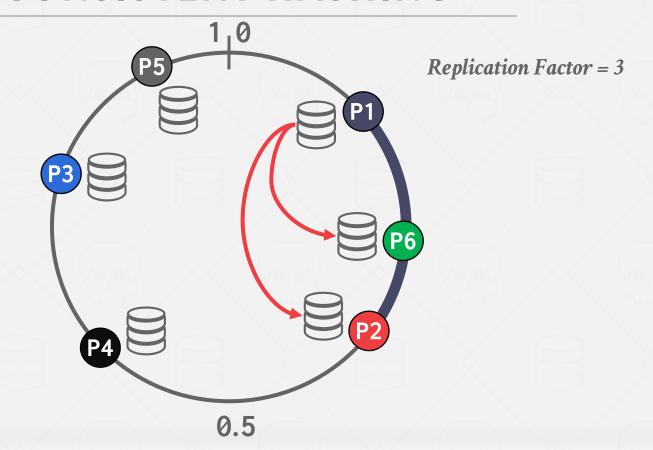


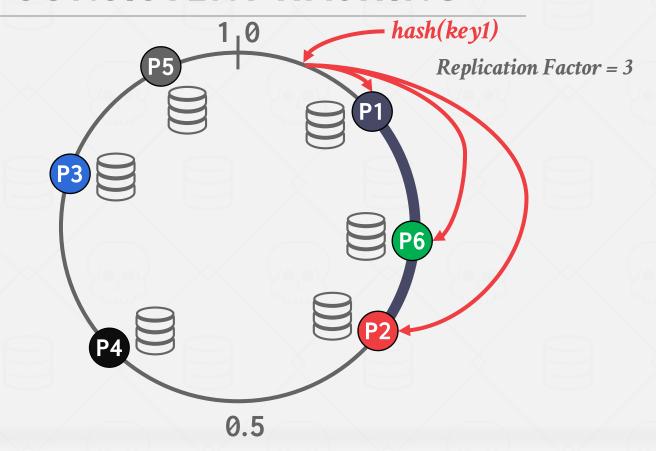










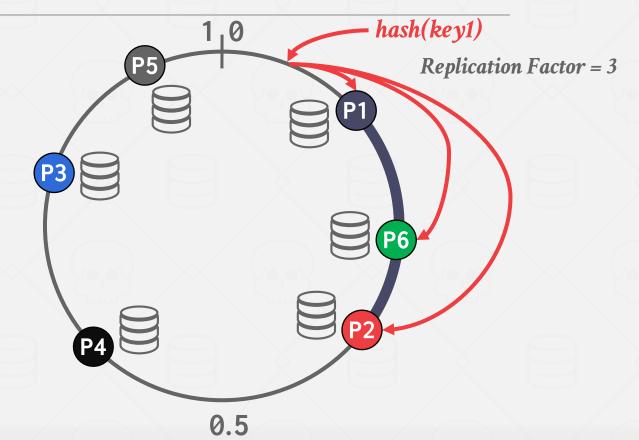














#### SINGLE-NODE VS. DISTRIBUTED

A <u>single-node</u> txn only accesses data that is contained on one partition.

→ The DBMS may not need check the behavior concurrent txns running on other nodes.

A <u>distributed</u> txn accesses data at one or more partitions.

 $\rightarrow$  Requires expensive coordination.



## TRANSACTION COORDINATION

If our DBMS supports multi-operation and distributed txns, we need a way to coordinate their execution in the system.

Two different approaches:

- → **Centralized**: Global "traffic cop".
- → **Decentralized**: Nodes organize themselves.



#### **TP MONITORS**

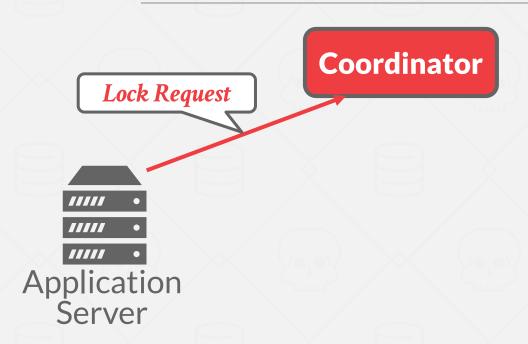
A **TP Monitor** is an example of a centralized coordinator for distributed DBMSs.

Originally developed in the 1970-80s to provide txns between terminals and mainframe databases.

→ Examples: ATMs, Airline Reservations.

Standardized protocol from 1990s: X/Open XA





#### **Partitions**

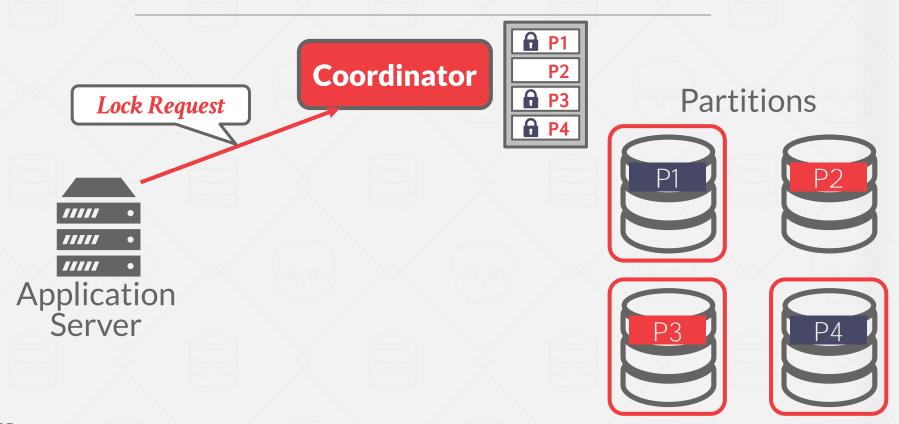




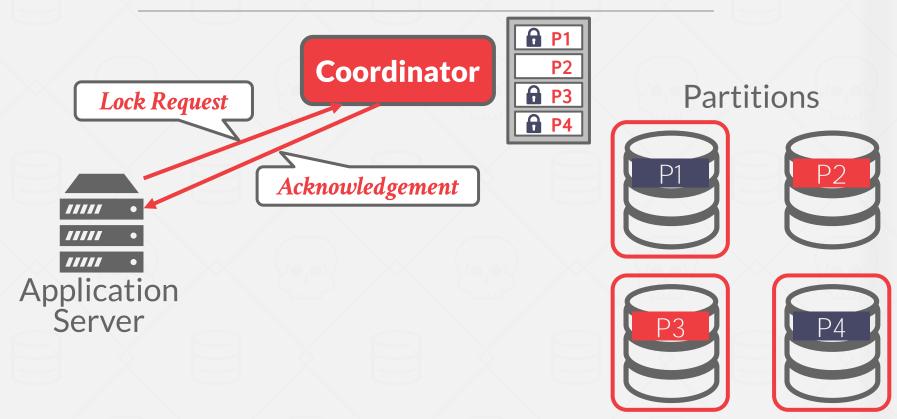




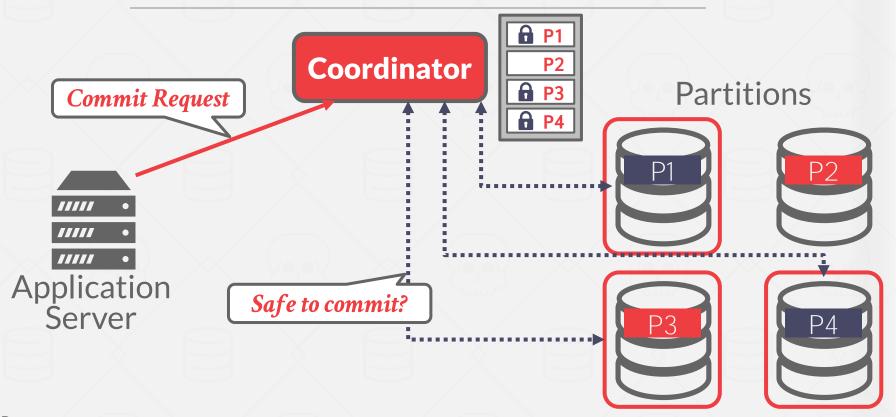




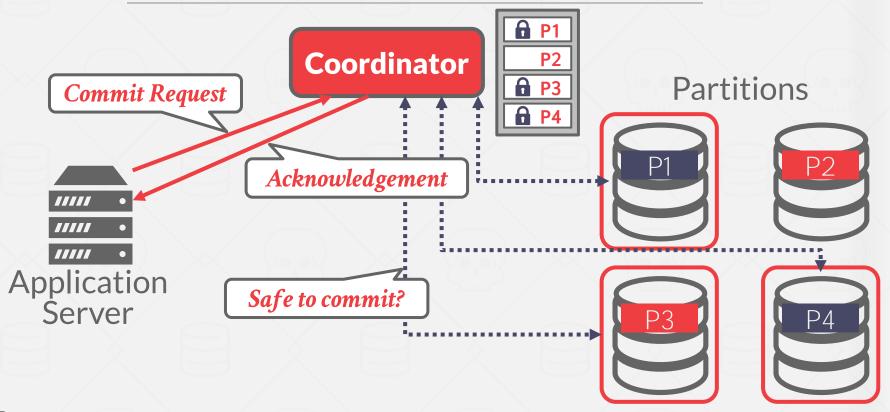




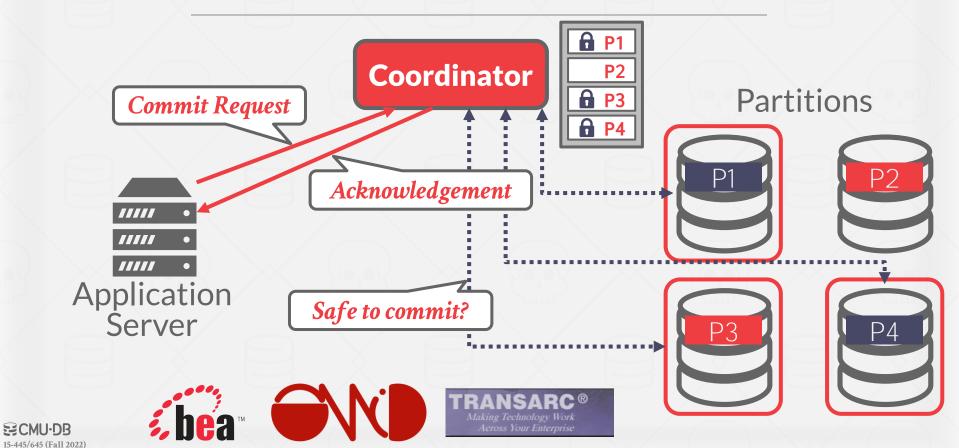




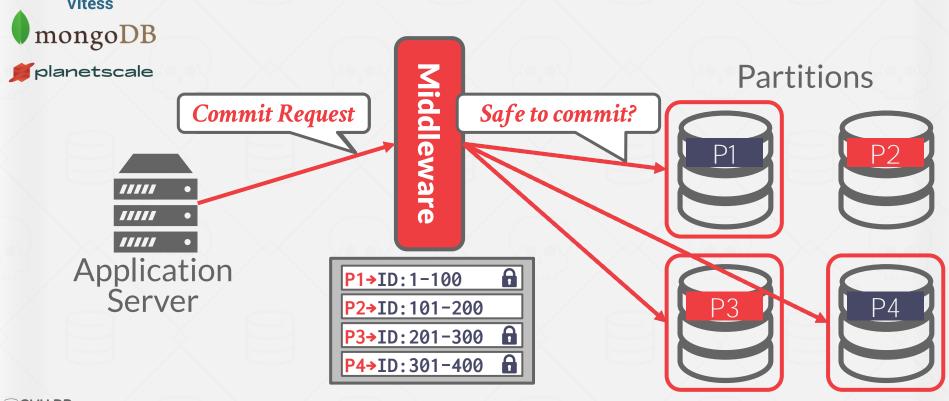




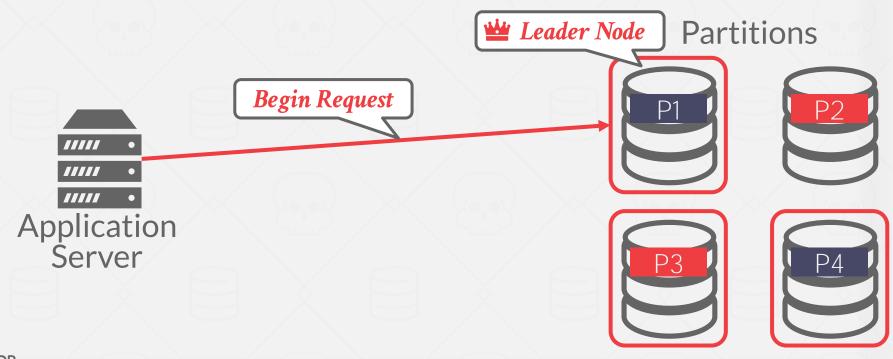




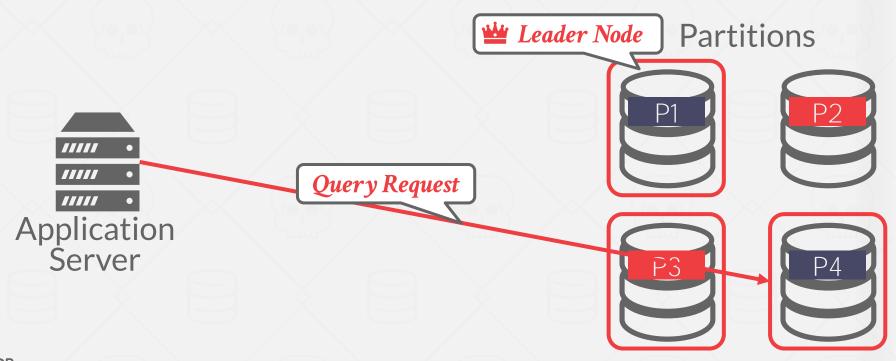




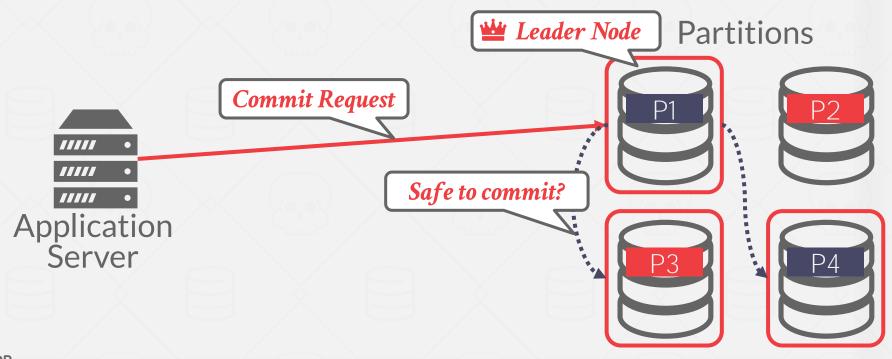














#### DISTRIBUTED CONCURRENCY CONTROL

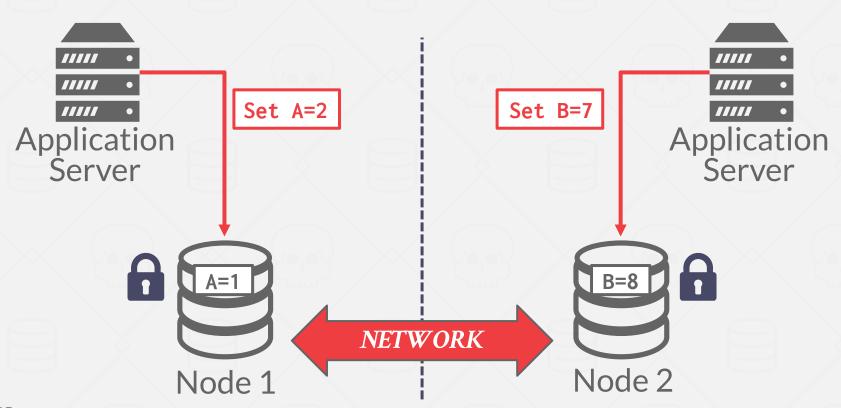
Need to allow multiple txns to execute simultaneously across multiple nodes.

→ Many of the same protocols from single-node DBMSs can be adapted.

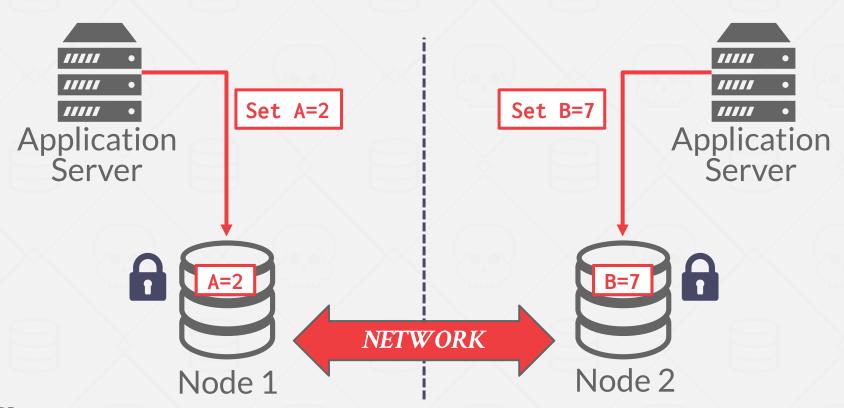
This is harder because of:

- $\rightarrow$  Replication.
- → Network Communication Overhead.
- → Node Failures.
- → Clock Skew.

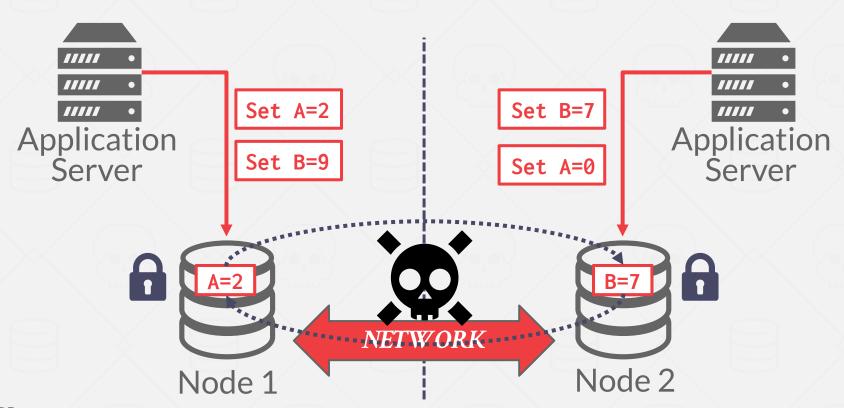




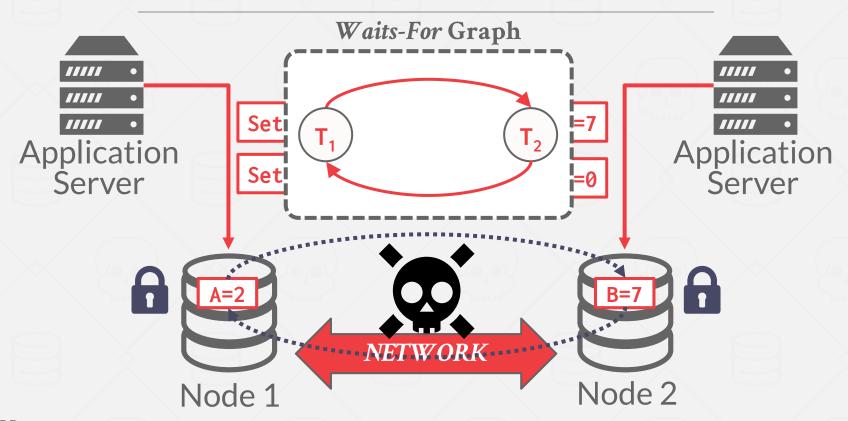














## CONCLUSION

I have barely scratched the surface on distributed database systems...

It is **hard** to get this right.



#### PROJECT #4 - CONCURRENCY CONTROL

You will add support for concurrent transactions using two-phase locking in BusTub!

- → Deadlock Detection
- → Hierarchical Locking (Table, Tuple)
- → Multiple Isolation Levels
- → Aborts/Rollbacks

You do <u>not</u> need to worry about logging txns to disk.



**Prompt**: A dramatic and vibrant painting of a giant eye in the clouds looking down on a field of grazing sheep with padlocks as their heads.



https://15445.courses.cs.cmu.edu/fall2022/project4/

#### PROJECT #3 - TASKS

#### Lock Manager

- → Maintain internal lock table and queues.
- → Track the growing/shrinking phases of txns.
- → Notify waiting txns when their locks are available.

#### **Deadlock Detector:**

→ Build the waits-for graph and <u>deterministically</u> identify what txn to kill off to break deadlocks

#### **Execution Engine**

→ Modify Project #3 executors to support txn requests.



## PROJECT #3 - LEADERBOARD

We have designed the Terrier benchmark to measure who has the fastest BusTub implementation!

#### Tasks:

- → UpdateExecutor
- → Predicate Pushdown



#### THINGS TO NOTE

Do <u>not</u> change any file other than the ones that you submit to Gradescope.

Make sure you pull in the latest changes from the BusTub main branch.

Post your questions on Piazza or come to TA office hours.

Compare against our solution in your browser!



#### PLAGIARISM WARNING

Your project implementation must be your own work.

- → You may **not** copy source code from other groups or the web.
- → Do **not** publish your implementation on Github.

Plagiarism will <u>not</u> be tolerated. See <u>CMU's Policy on Academic</u> <u>Integrity</u> for additional information.



## **NEXT CLASS**

Distributed OLTP Systems

Replication

**CAP** Theorem

Real-World Examples

