

Bayes Classifier and Naive Bayes

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Introduction:

Basic idea:

In machine learning, the naive Bayes classifier is a series of simple probability classifiers based on the Bayesian theorem under strong independent assumptions.

- Training Data: $D = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\}$, (\mathbf{x}_i, y_i) is sampled i.i.d from unknown distribution $P(X, Y)$. So we obtain:

$$P(D) = P((\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)) = \prod_{\alpha=1}^n P(\mathbf{x}_\alpha, y_\alpha).$$

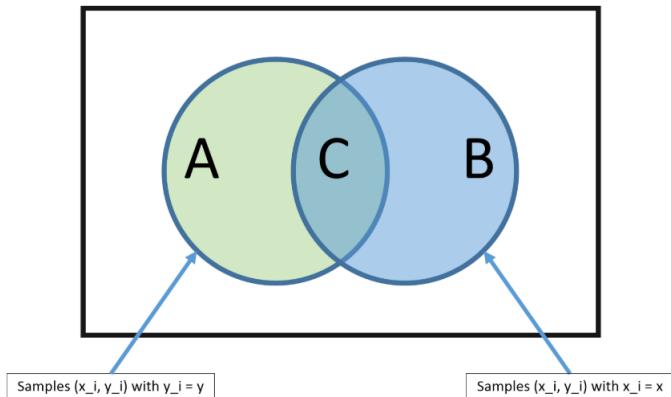
- Estimate $P(X, Y)$:

$$\hat{P}(\mathbf{x}, y) = \frac{\sum_{i=1}^n I(\mathbf{x}_i = \mathbf{x} \wedge y_i = y)}{n}.$$
$$I(\mathbf{x}_i = \mathbf{x} \wedge y_i = y) = 1 \quad \text{if} \quad \mathbf{x}_i = \mathbf{x} \quad \text{and} \quad y_i = y.$$

- Estimate $P(y|\mathbf{x})$: predict the label y from the features \mathbf{x}

$$\hat{P}(y|\mathbf{x}) = \frac{\hat{P}(y, \mathbf{x})}{P(\mathbf{x})} = \frac{\sum_{i=1}^n I(\mathbf{x}_i = \mathbf{x} \wedge y_i = y)}{\sum_{i=1}^n I(\mathbf{x}_i = \mathbf{x})}.$$

Visualization:



Venn diagram

- The Venn diagram illustrates that the MLE method estimates:

$$\hat{P}(y|\mathbf{x}) = \frac{|C|}{|B|}.$$

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Bayes rule

If we can estimate $P(y)$ and $P(\mathbf{x} | y)$, since, by Bayes rule,

$$P(y|\mathbf{x}) = \frac{P(\mathbf{x}|y)P(y)}{P(\mathbf{x})}.$$

Estimating $P(y)$

- Estimating $P(y)$ is easy: For example, if Y takes on discrete binary values estimating $P(Y)$ reduces to coin tossing. We simply need to count how many times we observe each outcome (in this case each class):

$$P(y = c) = \frac{\sum_{i=1}^n I(y_i = c)}{n} = \hat{\pi}_c$$

Estimating $P(\mathbf{x} | y)$

Naive Bayes Assumption:

$$P(\mathbf{x}|y) = \prod_{\alpha=1}^d P(x_{\alpha}|y), \text{ where } x_{\alpha} = [\mathbf{x}]_{\alpha} \text{ is the value for feature } \alpha.$$

i.e., feature values are independent given the label!

Bayes Classifier

Because of the Naive Bayes assumption

$$h(\mathbf{x}) = \operatorname{argmax}_y P(y|\mathbf{x}) \quad (1)$$

$$= \operatorname{argmax}_y \frac{P(\mathbf{x}|y)P(y)}{P(\mathbf{x})} \quad (2)$$

$$= \operatorname{argmax}_y P(\mathbf{x}|y)P(y) \quad (P(\mathbf{x}) \text{ does not depend on } y) \quad (3)$$

$$= \operatorname{argmax}_y \prod_{\alpha=1}^d P(x_{\alpha}|y)P(y) \quad (\text{by the naive Bayes assumption}) \quad (4)$$

$$= \operatorname{argmax}_y \sum_{\alpha=1}^d \log(P(x_{\alpha}|y)) + \log(P(y)) \quad (\text{as log is a monotonic function}) \quad (5)$$

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Categorical features

Features:

$$[\mathbf{x}]_{\alpha} \in \{f_1, f_2, \dots, f_{K_{\alpha}}\}.$$

Model $P(x_{\alpha} | y)$:

$$P(x_{\alpha} = j | y = c) = [\theta_{jc}]_{\alpha} \text{ and } \sum_{j=1}^{K_{\alpha}} [\theta_{jc}]_{\alpha} = 1.$$

$[\theta_{jc}]_{\alpha}$ is the probability of feature α having the value j , given that the label is c . And the constraint indicates that x_{α} must have one of the categories $\{1, \dots, K_{\alpha}\}$.

Parameter estimation:

$$[\hat{\theta}_{jc}]_{\alpha} = \frac{\sum_{i=1}^n I(y_i = c) I(x_{i\alpha} = j) + l}{\sum_{i=1}^n I(y_i = c) + l K_{\alpha}}, \quad (6)$$

$$x_{i\alpha} = [\mathbf{x}_i]_{\alpha},$$

l is a smoothing parameter. By setting $l=0$ we get an MLE estimator, $l > 0$ leads to MAP. If we set $l=+1$ we get Laplace smoothing. in words, this means:

$$\frac{\text{of samples with label } c \text{ that have feature } \alpha \text{ with value } j}{\text{of samples with label } c}.$$

$$h(\mathbf{x}) = \operatorname{argmax}_y \prod_{\alpha=1}^d P(x_{\alpha}|y)P(y)$$

$$\operatorname{argmax}_y P(y = c \mid \mathbf{x}) \propto \operatorname{argmax}_y \hat{\pi}_c \prod_{\alpha=1}^d [\hat{\theta}_{jc}]_{\alpha}$$

$$\hat{\pi}_c = P(y = c) = \frac{\sum_{i=1}^n I(y_i = c)}{n}$$

Play-tennis example: estimating $P(x_i | C)$

Outlook	Temperature	Humidity	Windy	Class
sunny	hot	high	false	N
sunny	hot	high	true	N
overcast	hot	high	false	P
rain	mild	high	false	P
rain	cool	normal	false	P
rain	cool	normal	true	N
overcast	cool	normal	true	P
sunny	mild	high	false	N
sunny	cool	normal	false	P
rain	mild	normal	false	P
sunny	mild	normal	true	P
overcast	mild	high	true	P
overcast	hot	normal	false	P
rain	mild	high	true	N

$$P(p) = 9/14$$

$$P(n) = 5/14$$

outlook	
$P(\text{sunny} p) = 2/9$	$P(\text{sunny} n) = 3/5$
$P(\text{overcast} p) = 4/9$	$P(\text{overcast} n) = 0$
$P(\text{rain} p) = 3/9$	$P(\text{rain} n) = 2/5$
temperature	
$P(\text{hot} p) = 2/9$	$P(\text{hot} n) = 2/5$
$P(\text{mild} p) = 4/9$	$P(\text{mild} n) = 2/5$
$P(\text{cool} p) = 3/9$	$P(\text{cool} n) = 1/5$
humidity	
$P(\text{high} p) = 3/9$	$P(\text{high} n) = 4/5$
$P(\text{normal} p) = 6/9$	$P(\text{normal} n) = 2/5$
windy	
$P(\text{true} p) = 3/9$	$P(\text{true} n) = 3/5$
$P(\text{false} p) = 6/9$	$P(\text{false} n) = 2/5$

Play-tennis example: classifying X

- An unseen sample $X = \langle \text{rain, hot, high, false} \rangle$
- $P(X|p) \cdot P(p) =$
 $P(\text{rain}|p) \cdot P(\text{hot}|p) \cdot P(\text{high}|p) \cdot P(\text{false}|p) \cdot P(p) =$
 $3/9 \cdot 2/9 \cdot 3/9 \cdot 6/9 \cdot 9/14 = 0.010582$
- $P(X|n) \cdot P(n) =$
 $P(\text{rain}|n) \cdot P(\text{hot}|n) \cdot P(\text{high}|n) \cdot P(\text{false}|n) \cdot P(n) =$
 $2/5 \cdot 2/5 \cdot 4/5 \cdot 2/5 \cdot 5/14 = 0.018286$
- Sample X is classified in class n (don't play)

Multinomial features

Multinomial features

If feature values don't represent categories (e.g. male/female) but counts we need to use a different model. E.g. in the text document categorization, feature value $x_\alpha = j$ means that in this particular document \mathbf{x} the α^{th} word in my dictionary appears j times. Let us consider the example of spam filtering. Imagine the α^{th} word is indicative towards *spam*. Then if $x_\alpha = 10$ means that this email is likely spam (as word α appears 10 times in it). And another email with $x'_\alpha = 20$ should be even more likely to be spam (as the spammy word appears twice as often). With categorical features this is not guaranteed.

Features:

$$x_\alpha \in \{0, 1, 2, \dots, m\} \text{ and } m = \sum_{\alpha=1}^d x_\alpha \quad (7)$$

Each feature α represents a count and m is the length of the sequence. An example of this could be the count of a specific word α in a document of length m and d is the size of the vocabulary.

Model $P(\mathbf{x}|y)$

Use the multinomial distribution:

$$P(\mathbf{x} \mid m, y = c) = \frac{m!}{x_1! \cdot x_2! \cdot \dots \cdot x_d!} \prod_{\alpha=1}^d (\theta_{\alpha c})^{x_{\alpha}}$$

where $\theta_{\alpha c}$ is the probability of selecting x_{α} and $\sum_{\alpha=1}^d \theta_{\alpha c} = 1$. So, we can use this to generate a spam email, i.e., a document \mathbf{x} of class $y = \text{spam}$ by picking m words independently at random from the vocabulary of d words using $P(\mathbf{x} \mid y = \text{spam})$. Parameter estimation:

$$\hat{\theta}_{\alpha c} = \frac{\sum_{i=1}^n I(y_i = c) x_{i\alpha} + l}{\sum_{i=1}^n I(y_i = c) m_i + l \cdot d} \quad (8)$$

where $m_i = \sum_{\beta=1}^d x_{i\beta}$ denotes the number of words in document i . The numerator sums up all counts for feature x_{α} and the denominator sums up all counts of all features across all data points. In words:

$$\frac{\text{of times word } \alpha \text{ appears in all spam emails}}{\text{of words in all spam emails combined}}.$$

Prediction:

$$\operatorname{argmax}_c P(y = c \mid \mathbf{x}) \propto \operatorname{argmax}_c \hat{\pi}_c \prod_{\alpha=1}^d \hat{\theta}_{\alpha c}^{x_{\alpha}}$$

Continuous features

Features:

$$x_\alpha \in \mathbb{R} \quad (\text{each feature takes on a real value}) \quad (9)$$

Model $P(x_\alpha | y)$ Use Gaussian distribution:

$$P(x_\alpha | y = c) = \mathcal{N}(\mu_{\alpha c}, \sigma_{\alpha c}^2) = \frac{1}{\sqrt{2\pi}\sigma_{\alpha c}} e^{-\frac{1}{2}\left(\frac{x_\alpha - \mu_{\alpha c}}{\sigma_{\alpha c}}\right)^2} \quad (10)$$

Note that the model specified above is based on our assumption about the data - that each feature α comes from a class-conditional Gaussian distribution. The full distribution:

$$P(\mathbf{x}|y) \sim \mathcal{N}(\mu_y, \Sigma_y)$$

where Σ_y is a diagonal covariance matrix with

$$[\Sigma_y]_{\alpha, \alpha} = \sigma_{\alpha, y}^2$$

Parameter estimation:

Parameter estimation:

As always, we estimate the parameters of the distributions for each dimension and class independently. Gaussian distributions only have two parameters, the mean and variance. The mean $\mu_{\alpha,y}$ is estimated by the average feature value of dimension α from all samples with label y . The (squared) standard deviation is simply the variance of this estimate.

$$\mu_{\alpha c} \leftarrow \frac{1}{n_c} \sum_{i=1}^n I(y_i = c) x_{i\alpha} \quad \text{where } n_c = \sum_{i=1}^n I(y_i = c) \quad (11)$$

$$\sigma_{\alpha c}^2 \leftarrow \frac{1}{n_c} \sum_{i=1}^n I(y_i = c) (x_{i\alpha} - \mu_{\alpha c})^2 \quad (12)$$

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Multinomial Features

Suppose that $y_i \in \{-1, +1\}$ and features are multinomial. So:

$$h(\mathbf{x}) = \underset{y}{\operatorname{argmax}} P(y) \prod_{\alpha=1}^d P(x_{\alpha} | y) = \operatorname{sign}(\mathbf{w}^{\top} \mathbf{x} + b)$$

$$\mathbf{w}^{\top} \mathbf{x} + b > 0 \iff h(\mathbf{x}) = +1.$$

As before, we define:

$$P(x_{\alpha} | y = +1) \propto \theta_{\alpha+}^{x_{\alpha}}; P(Y = +1) = \pi_{+}.$$

$$[\mathbf{w}]_{\alpha} = \log(\theta_{\alpha+}) - \log(\theta_{\alpha-}) \quad (13)$$

$$b = \log(\pi_{+}) - \log(\pi_{-}) \quad (14)$$

$$\mathbf{w}^\top \mathbf{x} + b > 0 \iff \sum_{\alpha=1}^d [\mathbf{x}]_\alpha \overbrace{(\log(\theta_{\alpha+}) - \log(\theta_{\alpha-}))}^{[\mathbf{w}]_\alpha} + \overbrace{\log(\pi_+) - \log(\pi_-)}^b > 0 \quad (15)$$

$$\iff \exp \left(\sum_{\alpha=1}^d [\mathbf{x}]_\alpha (\log(\theta_{\alpha+}) - \log(\theta_{\alpha-})) + \log(\pi_+) - \log(\pi_-) \right) > 1 \quad (16)$$

$$\iff \prod_{\alpha=1}^d \frac{\exp(\log \theta_{\alpha+}^{[\mathbf{x}]_\alpha} + \log(\pi_+))}{\exp(\log \theta_{\alpha-}^{[\mathbf{x}]_\alpha} + \log(\pi_-))} > 1 \quad (17)$$

$$\iff \prod_{\alpha=1}^d \frac{\theta_{\alpha+}^{[\mathbf{x}]_\alpha} \pi_+}{\theta_{\alpha-}^{[\mathbf{x}]_\alpha} \pi_-} > 1 \quad (18)$$

$$\iff \frac{\prod_{\alpha=1}^d P([\mathbf{x}]_\alpha | Y = +1) \pi_+}{\prod_{\alpha=1}^d P([\mathbf{x}]_\alpha | Y = -1) \pi_-} > 1 \quad (19)$$

$$\iff \frac{P(\mathbf{x} | Y = +1) \pi_+}{P(\mathbf{x} | Y = -1) \pi_-} > 1 \quad (20)$$

$$\iff \frac{P(Y = +1 | \mathbf{x})}{P(Y = -1 | \mathbf{x})} > 1 \quad (21)$$

$$\iff P(Y = +1 | \mathbf{x}) > P(Y = -1 | \mathbf{x}) \quad (22)$$

$$\iff \operatorname{argmax}_y P(Y = y | \mathbf{x}) = +1 \quad (23)$$

Gaussian Naive Bayes

In the case of continuous features (Gaussian Naive Bayes), we can show that:

$$P(y \mid \mathbf{x}) = \frac{1}{1 + e^{-y(\mathbf{w}^\top \mathbf{x} + b)}}$$

This model is also known as logistic regression.

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Filter spam with naive bayes

Core algorithm: Naive Bayesian classifier training function

```
def trainNB0(trainMatrix, trainCategory): 计算训练的文档数目
    numTrainDocs = len(trainMatrix) 计算文档的词条数
    numWords = len(trainMatrix[0]) 文档属于侮辱类的概率
    pAbusive = sum(trainCategory)/float(numTrainDocs) 初始化
    p0Num = ones(numWords); p1Num = ones(numWords)
    p0Denom = 2.0; p1Denom = 2.0
    for i in range(numTrainDocs):
        if trainCategory[i] == 1: 统计计算词语属于侮辱类的条件概率所需的数据
            p1Num += trainMatrix[i]
            p1Denom += sum(trainMatrix[i])
        else: 统计计算属于非侮辱类的条件概率所需的数据
            p0Num += trainMatrix[i]
            p0Denom += sum(trainMatrix[i])
    相除计算概率向量
    p1Vect = log(p1Num / p1Denom)
    p0Vect = log(p0Num / p0Denom)
    返回词语属于侮辱类的条件概率向量，词语属于非侮辱类的条件概率向量，文档属于侮辱类概率。
```

Classify

```
def classifyNB(vec2Classify, p0Vec, p1Vec, pClass1):
```

输入为需要分类的词向量，以及词语属于侮辱类的条件概率向量，词语属于非侮辱类的条件概率向量，文档属于侮辱类的概率

```
    p1=sum(vec2Classify*p1Vec)+log(pClass1)
```

```
    p0=sum(vec2Classify*p0Vec)+log(1.0-pClass1)
```

```
    if p1 > p0:
```

```
        return 1
```

```
    else:
```

```
        return 0
```

Because:

$$p(c_i|\mathbf{w}) = \frac{p(\mathbf{w}|c_i)p(c_i)}{p(\mathbf{w})}, w : \text{word vector}; c_i : \text{label}$$

$$p(\mathbf{w}|c_i) = p(w_0, w_1, \dots, w_N|c_i) = p(w_0|c_i)p(w_1|c_i)\dots p(w_N|c_i)$$

$$\log(p(\mathbf{w}|c_i)p(c_i))$$

$$= \log(p(w_0|c_i)p(w_1|c_i)\dots p(w_N|c_i)p(c_i))$$

$$= \log(p(w_0|c_i)) + \log(p(w_1|c_i)) + \dots + \log(p(w_N|c_i)) + \log(p(c_i))$$

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Summary of Naive Bayes

Bayesian formula:

$$p(X|Y) = \frac{p(Y|X)p(X)}{p(Y)}$$

Assumption:

$$p(x_1, x_2, \dots, x_n|y) = p(x_1|y)p(x_2|y)\dots p(x_n|y)$$

Likelihood function:

$$\prod_{i=1}^n p(x_i|y, \theta)$$

Log-likelihood:

$$\sum_{i=1}^n \log(p(x_i|y, \theta))$$

Maximum likelihood estimation:

$$\operatorname{argmax}_{\theta} \sum_{i=1}^n \log(p(x_i|y, \theta))$$

Classify:

$$\operatorname{argmax}_y p(y) \prod_{i=1}^n p(x_i|y, \theta) = \operatorname{argmax}_y \log(p(y)) + \sum_{i=1}^n \log(p(x_i|y, \theta))$$

The End