Weak Solution: Convex Integration

Yiran Hu

February 9, 2020

1 Introduction

First let's give an example to help define what is the weak solution.

Example 1.1.

$$\Delta u = f$$

If u don't have to be continuous take a test function: $\forall \phi \in C_c^{\infty}(\mathbb{R}^d), \int_{\mathbb{C}} \phi \Delta u = \int_{\mathbb{C}} \phi f$. If u is holomorphic $u: \mathbb{C} \to \mathbb{C}$

$$\frac{d}{dt}u(z+t_{\alpha}) = \frac{\partial u}{\partial z}\alpha + \frac{\partial u}{\partial \overline{z}}\overline{\alpha} = \frac{\partial u}{\partial x}Re\alpha + \frac{\partial u}{\partial y}Im\alpha$$

i.e. $du = \frac{\partial u}{\partial z}dz + \frac{\partial u}{\partial \overline{z}}d\overline{z}$.

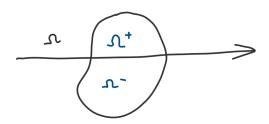
Theorem 1.1. If $\frac{\partial u}{\partial z} = 0$ or $\Delta u = 0$ in the weak sense(against all test function). Then $u \in C^{\infty}(\mathbb{R})$ and satisfies the equation in the classical sense.

Useful: $f_k(z)$ holomorphic $u(z) = \sum_{k=0}^{\infty} f_k(z)$, the series is absolutely convergent.

Fubini
$$\begin{aligned} & -\int_{\mathbb{C}} \frac{\partial \phi}{\partial \overline{z}} u(z) \\ & -\sum_{k=0}^{\infty} \int_{\mathbb{C}} \frac{\partial \phi}{\partial \overline{z}} f_k(z) \\ & = & \sum_{k=0}^{\infty} \int_{\mathbb{C}} \phi \frac{\partial f_k}{\partial \overline{z}} = 0 \end{aligned}$$

(???)

Theorem 1.2. (Swartz reflection principle.) If f is holomorphic on $\Omega \cap \{y > 0\}$ and $\Omega \cap \{y < 0\}$. If f is continu-



ous on Ω on Ω including $\Omega \cap \{y = 0\}$. Then f is holomorphic on Ω .

In D' $f = \lim_{\delta \to 0} f(H(y - \varepsilon) + H(\varepsilon - y))$, here H is heaviside function.

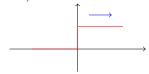
$$\frac{\partial f}{\partial \bar{z}} = \lim_{\varepsilon \to 0} \frac{\partial f}{\partial \bar{z}} + f(\frac{\partial y}{\partial \bar{z}} \delta(y - \varepsilon) - \frac{\partial y}{\partial z} \delta(\varepsilon - y))$$

Since f is continuous $\lim_{\varepsilon \to 0} f(\delta(y - \varepsilon) - \delta(\varepsilon - y)) = 0$

$$\Box u = 0 \quad \text{where } \Box := -\partial_t^2 + \partial_1^2 + \dots + \partial_n^2$$

$$\forall \phi \in C_c^{\infty}(\mathbb{R}^{d-1}) \qquad \int_{\mathbb{R}}^{d+1} \Box \phi u = 0$$
(Wave)

(Wave) has a solution on \mathbb{R}^{1+1} given by u(t,x)=u(t-x), a traveling wave:



Example 1.2.

$$u(t,x) = H(t-x) - H(t+x)$$

is the unique solution to (Wave) on \mathbb{R}^{1+d}

The green lines are smooth approximation. After some time, it is still good enough to approximate the real world solution.

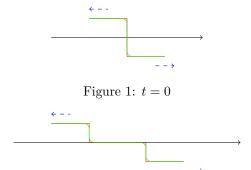


Figure 2: t = 1

2 Fluid Mechanics

2.1 Incompressible Euler Equation

Define 2 velocity field: $v: \mathbb{R} \times \mathbb{R}^d \to \mathbb{R}$ $p: \mathbb{R} \times \mathbb{R}^d \to \mathbb{R}$

$$\partial_t v^l + \nabla_j (v^j v^l) + \nabla^l p = 0$$

$$\nabla_i v^j = 0$$
 divergence free

This system obvious make sense for $v \in L^2_{loc}$. Let's recall the derivation of Euler equation. $\forall \Omega$ with C^1 $\partial \Omega$

$$\int_{\partial\Omega} v \cdot \overrightarrow{n} d\sigma = 0 \quad \forall t$$

meaning water coming in is exactly the same as water going out.

$$\frac{d}{dt} \begin{bmatrix} \text{total momentum} \\ m \cdot v \end{bmatrix} = \begin{bmatrix} \text{Force on } \Omega \end{bmatrix} + \begin{bmatrix} \text{Flux of} \\ \text{momentum} \end{bmatrix} \quad \Rightarrow \frac{d}{dt} \int_{\Omega} v^l dx = \int_{\partial \Omega} p \overrightarrow{n}^l dx \quad \forall t$$

These integral gives also the weak form of equation, let's say if p is good enough. If $v, pinC^1$, use $\int_{\partial\Omega} f \overrightarrow{n}_j d\sigma = -\int_{\Omega} \nabla_j f dx$

$$\frac{d}{dt} \int_{\Omega} v^l = -\left(\int_{\Omega} \nabla^l p + \nabla_j (v^j v^l) dx\right)$$
$$\int_{\Omega} (\partial_t v^l + \nabla_j (v^j v^l) + \nabla^l p) dx = 0 \qquad \forall \Omega, \quad \forall t$$

Here comes a natural question: Are weak solution to the Euler equation physical meaningful? Some physical properties are required. Take $\Omega = \mathbb{R}^d$ and $v \in L^2_{t,x}(I \times \mathbb{R}^d)$

$$\frac{d}{dt} \int_{\mathbb{R}^d} K_l v^l(t, x) dx = 0$$

If $(1+|x|)v \in L^1_{t,x}(I \times \mathbb{R}^d)$, then linear angular momentum conserved? Here $\forall K^l$ s.t. $\nabla_i K_l + \nabla_l K_i = 0$ on \mathbb{R}^d

Example 2.1. $K = e_{(i)}$ the basis vector, $\int_{\mathbb{R}^d} K_l v^l dx = \int_{\mathbb{R}^d} v^{(i)} dx$

Example 2.2. Rotation $K(a, b) = x^{a}e_{b} - x^{b}e_{a}, 1 \le a < b \le d$.

$$\int_{\mathbb{R}^d} K_l(\partial_t v^l + \nabla : (v^j v^l) + \nabla^l p) dx = 0$$

$$\frac{d}{dt} \int_{\mathbb{R}^d} K_l v^l - \int \nabla : K_l(v^j v^l) - \int_{\mathbb{R}^d} \nabla^l K_l p dx = 0$$

where div $K = \nabla^l K_l = \delta^{jl} \nabla_j K_l = \frac{1}{2} \delta^{jl} (\nabla_j K_l + \nabla_l K_j) = 0$ by assumption.

$$\partial v^l + \nabla : (v^j v^l) + \nabla^l p) dx = 0$$

Test against a space cut-off function $K^l(B) := q(t)\varphi(\frac{|x|}{B})(x^be_m - x^ae_b)$. Here K is rotationally symmetric, so it is divergence-free.

$$-\int_{\mathbb{R}^+} \eta'(t) [\int_{\mathbb{R}^d} K_l^{(\beta)} v^l dx] dt - \int_{\mathbb{R}} \eta \int_{\mathbb{R}^d} \nabla_j K_l^{(\beta)} v^j v^l - \int_{\mathbb{R}^+} \eta(t) \int_{\mathbb{R}^d} \nabla^l K_l^{(\beta)} p dx dt = 0$$

Here, due to divergence-free, like what we did previously, $\int_{\mathbb{R}^+} \eta(t) \int_{\mathbb{R}^d} \nabla^l K_l^{(\beta)} p dx dt = 0$. i.e.

$$-\int_{\mathbb{R}^+} \eta'(t) [\int_{\mathbb{R}^d} K_l^\beta v^l dx] dt - \frac{1}{2} \int_{\mathbb{R}^+} \int_{\mathbb{R}^d} \left(\nabla_j K_l^{(\beta)} + \nabla_l K_j^{(\beta)} \right) v^j v^l dx dt - \frac{1}{2} \int_{\mathbb{R}} \eta(t) \int_{\mathbb{R}^d} \nabla_j \varphi(\frac{|x|}{B})) K_l v^j v^l dx dt = 0$$

The 1st term is dominated by $|x| \cdot v \in L^1_{t,x}$ by assumption. $\frac{1}{|x|} \cdot v$ dominated the derivative and integrant.

2.2 Conservation of Energy

If $(1+|x|)v \in L^1_{t,x}(I \times \mathbb{R}^d)$, $v \in L^2_{t,x}(I \times \mathbb{R}^d)$, then $\forall K^l$, $\nabla_j K_l + \nabla_l K_j = 0$, then we have the conservation of angular momentum:

$$\frac{d}{dt} \int_{\mathbb{R}^d} K_l v^l(t, x) dx = 0,$$

where $K \in \text{span}\{x^a e_b = x^b e_a : e_i, 1 \le i \le d, 1 \le a < b \le d\}$. Here decay assumption is needed but not the regularity assumption. If $f \in \mathcal{D}'(\mathbb{R}), \frac{df}{dt} = 0 \Rightarrow f = c$ limit of constant.

$$\delta_j^l = \nabla_j w^{jl} \quad w^{jl} = -w^{lj}$$
 antisymmetric

Approximate by $\nabla(\phi(\frac{|x|}{B}w^{jl})$

$$w^{jl} = x^2 (\delta_2^j \delta_1^l - \delta_1^j \delta_2^l)$$

$$\nabla_j (x^2 (\delta_2^j \delta_1^l - \delta_1^j \delta_2^l))$$

$$= \delta_j^2 (\delta_2^j \delta_1^l - \delta_1^j \delta_2^l) = \delta_1^l$$

If $w^{il} = -w^{lj}$

$$\nabla_i \nabla_i w^{jl} = -\nabla_l \nabla_i w^{lj} = -\nabla_i \nabla_l w^{lj} = -\nabla_l \nabla_i w^{jl}$$

Conservation of energy means that $\frac{d}{dt} \int_{\mathbb{R}^d} \frac{|v|}{2}(t,x) dx = 0$. Note that energy is nonlinear.

$$\partial_t \left(\frac{|v|^2}{2}\right) + \nabla_j \left(\left(\frac{|v|}{2} + p\right)v^j\right) = 0$$

If $v \in C^1 \cap L^2_{t,x} \cap L^3_{t,x}(I \times \mathbb{R}^d)$ both local and global conservation of energy hold. Note that here B could be ∞ . Multiply the local energy by $\eta(t)\varphi(\frac{|x|}{B})$

$$\int \eta \frac{d}{dt} \int \varphi(\frac{|x|}{B}) \frac{|v|^2}{2}(t, x) dx dt - \int \eta(t) \int \nabla_j [\varphi(\frac{|x|}{B})] (\frac{|v|^2}{2} + p) v^j dx dt$$
(1)
$$(1) = -\int \underline{\eta'(t)} \int \varphi(\frac{|x|}{B}) \frac{|v|}{2}(t, x) dx dt \quad \text{Intergral by parts}$$
dominated by $\frac{|x|^2}{2} |\eta'| \in L^1_{t,x}$ (Local)

term (2) converge to 0 pointwisely when $B \to \infty$ and dominated by $|\eta t|(\frac{|v|^3}{2} + |p||v|)$. Let's recall Euler equation.

$$\begin{cases} \partial_t v^l + \nabla_j (v^j v^l) + \nabla^l p &= 0, \\ \nabla_j v^j &= 0 \end{cases}$$
 (Euler)

Take divergence over (Euler), \Rightarrow

$$\nabla_i \nabla_l (v^j v^l) + \nabla_l \nabla^l p = 0$$

i.e.

$$p = \underbrace{(-\Delta)^{-1} \nabla_l \nabla_j (v^j v^l)}_{\text{zero order operator}} \underbrace{(v^j v^l)}_{\in L^{3/2}_{t,x}}$$

Thus naturally $p \in L_x^{3/2}$ a.e. $t \in \mathbb{R}^+$

$$||p||_{L_x^{3/2}(L_t^{3/2})} = ||p||_{L_{t,x}^{3/2}} < \infty$$
$$v_l(\partial_t v^l + \nabla(v^j v^l) + \nabla^l p) = 0$$
$$\nabla_j v^j = 0$$

Thus

$$\Rightarrow \partial_t \left(\frac{|v|^2}{2}\right) + v_l v^j \nabla_j v^l + v_l \nabla^l p = 0$$

$$\Rightarrow \partial_t \left(\frac{|v|^2}{2}\right) + v^j \nabla_j \left(\frac{|v|^2}{2} + v_j v^j p = 0\right)$$

$$\nabla_j v^j = 0$$

$$\partial_t \left(\frac{|v|^2}{2} + \nabla_j \left(\left(\frac{|v|^2}{2} + p\right) v^j\right)\right) = 0$$

Using $\nabla_j v^j = 0$ and product rule, conservation of energy is proved for sufficient regular solutions. But how sufficient do we need?

In turbulence situation (Navier-Stokes equations with $\nu \ll 1$

$$v_l(\partial_t v^l + \nabla_j (v^j v^l) + \nabla^l p) = \nu v_l \Delta v^l$$

$$\frac{d}{dt} \int \frac{|v|^2}{2} (t, x) dx = -\nu \int |\nabla v|^2 dx = \nu \int v_l \nabla_i \nabla^i v^l$$

Taking a formal limit, ∃ incompressible Euler flows with

$$\frac{d}{dt} \int \frac{|v|}{2} (t, x) dx < -\varepsilon < 0$$

Theorem 2.1. Onsager's Conjecture

- $(+) \text{ If } \alpha > 1/3 \text{ and } (v(t, x + \Delta x) v(t, x)) \leq c|\Delta x| \text{ where } x \in \mathbb{T}^3 (v \in L^\infty_t C^\alpha_x), \text{ then the energy conserved.}$
- $(-) \ (K41) If \ \alpha \leq 1/3 \ \exists \ incompressible \ Euler \ flows \ with \ v \in L^{\infty}_t L^{\alpha}_x \ s.t. \ \int_{\mathbb{T}^d}^{\frac{|v|^2}{2}} (t,x) dx \ is \ not \ constant.$

Now we follow [2] and discuss the (+) part first.

$$\partial_t v^l + \nabla_j (v^j v^l) + \nabla^l p = 0$$

In order to get thto Onsager's explanation of how this might be possible, we expand the velocity v in Fourier series,

$$v(x,t) = \sum_{k \in \mathbb{Z}^3} a_k(t)e^{ik \cdot x}.$$

Obviously $a_{-k} = \overline{a_k}$, because v is real-valued. Moreover the divergence-free con-straint translates into the identity $k \cdot a_k = 0$. We then rewrite the remaining equations of (2.2) as an infinite-dimensional system of ODEs for the a_k :

$$\frac{da_k}{dt} = i \sum_{\ell} a_{k-\ell} \cdot \ell \left[-a_{\ell} + \frac{(a_{\ell} \cdot k) k}{|k|^2} \right] - \nu |k|^2 a_k \tag{1}$$

The total kinetic energy is (up to a constant factors) $\sum_{k} |a_k|^2$. (Don't understand) Energy starts at low wave numbers and moves to higher wave numbers in finite number.

(Don't understand) Energy starts at low wave numbers and moves to higher wave numbers
$$\sum_{\frac{\lambda}{2} \le |k| \le 2\lambda} |a_k|^2 \sim \lambda^{-2/3}$$
 matches (K41), corresponding to exactly 1/3 regularity for solutions.

Low frequency energy will goes to all frequency and when it goes to infinity, it will disappear.

(K 41) $E \lim_{v \to 0} \left\langle v \int |\nabla v|^2 dx \right\rangle$ and v determine all statistic properties of turbulent flows.

$$\langle |v(x+\Delta x) - v(x)|^p \rangle^{1/p} \sim \varepsilon^p |\Delta x|^{1/3}$$

Try to find $|\Delta x| < L \sim \varepsilon^a v^b$.

Now (+) is solved by [3] and [1] with the goal $L_t^3 B_{3,C(N)}^{1/3}$, $L_t^3 B_{3,\infty}^{1/3+\varepsilon}$.

(-) is solved $(d \ge 3)$ with $\alpha = \frac{1}{3}$, using convex integration by Phillip Isett [4].

Local energy conservation 2.3

$$\partial_t v_{\varepsilon}^l + \nabla_l (v_{\varepsilon}^l v_{\varepsilon}^l) + \nabla^l p_{\varepsilon} = -\nabla_j R_{\varepsilon}^{jl}$$

where $R_{\varepsilon}^{jl} = \eta_{\varepsilon} * (v^j v^l) - v_{\varepsilon}^j v_{\varepsilon}^l$

$$||R_{\varepsilon}(t,.)||_{L_{t}^{3/2}} \leq \varepsilon^{2\alpha} ||v(t)||_{B_{3}^{\alpha}}^{2}$$

$$\frac{1}{2} \int \frac{|v_{\varepsilon}|}{2} (t, x) dx = \lim_{\varepsilon \to 0} \int \nabla_{j} v_{\varepsilon l} R_{\varepsilon}^{j l} dx$$

Here to clarify the space:

$$B_{3,c(N)}^{1/3} = (\overline{C^{\infty}})^{B_{3,\infty}^{1/3}} = B_{3,\infty}^{1/3} \cap \{\lim_{h \to 0} \frac{|v(x+h) - v(x)|}{|h|^{1/3}} = 0\}$$

The "Holder Continuity" is the reason for smooth approximation. Define

$$c^{1/3} = (\overline{C^{\infty}})^{C^{1/3}}$$

Note that, here $c^{1/3}$ is not dense in $C^{1/3}$. Let $\varphi(x)$ be a smooth cut off function, then, $|x|^{1/3} \in C^{1/3} \setminus c^{1/3}$, but $\varphi(x)|x|^{1/3} \notin C^{1/3} \setminus c^{1/3}$

Lemma 2.2. $\|\nabla v_{\varepsilon}\|_{L^3} = o(\varepsilon^{-1+\alpha})$ if $v \in B_{3,c(N)}^{\alpha}$

Proof. Claim: $\varepsilon^{1-\alpha}\nabla(\eta_{\varepsilon}*\cdot): B_{3,\infty}^{\alpha} \to L^3$ is uniformly bounded.

$$\|\nabla v_{\varepsilon}\|_{L_{x}^{3}} \lesssim \varepsilon^{-1+\alpha} \|v\|_{B_{3,\infty}^{\alpha}}$$

Let $\delta > 0$ be given, choose $\tilde{v} \in C^{\infty}$ s.t. $\|v - \tilde{v}\|_{B_{\alpha}^{\alpha}} < \frac{\delta}{2C_2}$.

$$\begin{array}{ll} \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * v \right\|_{L^{3}_{x}} & \leq \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * (v-\tilde{v}) \right\|_{L^{3}_{x}} + \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * \tilde{v} \right\|_{L^{3}_{x}} \\ & \frac{\delta}{2} + \varepsilon^{1-\alpha} \| \nabla \eta_{\varepsilon} * \tilde{v} \|_{L^{3}_{x}} \\ & \leq \frac{\delta}{2} + \varepsilon^{1-\alpha} \tilde{c} \quad \text{for} \varepsilon^{1-\alpha} < \frac{\delta}{2\tilde{c}} \text{ and } \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * v \right\|_{L^{3}_{x}} < \delta \end{array}$$

$$\int_{I} \frac{d}{dt} \int \frac{\left|v_{\varepsilon}\right|^{2}}{2}(t, x) dx dt \le$$

References

- [1] Peter Constantin, Edriss S Titi, and F Weinan. Onsager's conjecture on the energy conservation for solutions of euler's equation. *Communications in Mathematical Physics*, 165(1):207, 1994.
- [2] Camillo De Lellis and László Székelyhidi Jr. Continuous dissipative euler flows and a conjecture of onsager. In *European Congress of Mathematics*, pages 13–29. Eur. Math. Soc. Zürich, 2013.
- [3] Gregory L Eyink and Katepalli R Sreenivasan. Onsager and the theory of hydrodynamic turbulence. Reviews of modern physics, 78(1):87, 2006.
- [4] Philip Isett. On the endpoint regularity in onsager's conjecture. arXiv preprint arXiv:1706.01549, 2017.