Weak Solution: Convex Integration

Yiran Hu

May 31, 2020

1 Introduction

First let's give an example to help define what is the weak solution.

Example 1.1.

$$\Delta u = f$$

If u don't have to be continuous take a test function: $\forall \phi \in C_c^{\infty}(\mathbb{R}^d), \int_{\mathbb{C}} \phi \Delta u = \int_{\mathbb{C}} \phi f$. If u is holomorphic $u: \mathbb{C} \to \mathbb{C}$

$$\frac{d}{dt}u(z+t_{\alpha}) = \frac{\partial u}{\partial z}\alpha + \frac{\partial u}{\partial \overline{z}}\overline{\alpha} = \frac{\partial u}{\partial x}Re\alpha + \frac{\partial u}{\partial y}Im\alpha$$

i.e. $du = \frac{\partial u}{\partial z}dz + \frac{\partial u}{\partial \overline{z}}d\overline{z}$.

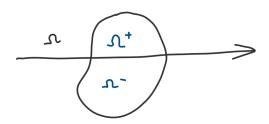
Theorem 1.1. If $\frac{\partial u}{\partial z} = 0$ or $\Delta u = 0$ in the weak sense(against all test function). Then $u \in C^{\infty}(\mathbb{R})$ and satisfies the equation in the classical sense.

Useful: $f_k(z)$ holomorphic $u(z) = \sum_{k=0}^{\infty} f_k(z)$, the series is absolutely convergent.

Fubini
$$\begin{aligned} & -\int_{\mathbb{C}} \frac{\partial \phi}{\partial \overline{z}} u(z) \\ & -\sum_{k=0}^{\infty} \int_{\mathbb{C}} \frac{\partial \phi}{\partial \overline{z}} f_k(z) \\ & = & \sum_{k=0}^{\infty} \int_{\mathbb{C}} \phi \frac{\partial f_k}{\partial \overline{z}} = 0 \end{aligned}$$

(???)

Theorem 1.2. (Swartz reflection principle.) If f is holomorphic on $\Omega \cap \{y > 0\}$ and $\Omega \cap \{y < 0\}$. If f is continu-



ous on Ω on Ω including $\Omega \cap \{y = 0\}$. Then f is holomorphic on Ω .

In D' $f = \lim_{\delta \to 0} f(H(y - \varepsilon) + H(\varepsilon - y))$, here H is heaviside function.

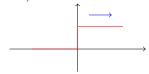
$$\frac{\partial f}{\partial \bar{z}} = \lim_{\varepsilon \to 0} \frac{\partial f}{\partial \bar{z}} + f(\frac{\partial y}{\partial \bar{z}} \delta(y - \varepsilon) - \frac{\partial y}{\partial z} \delta(\varepsilon - y))$$

Since f is continuous $\lim_{\varepsilon \to 0} f(\delta(y - \varepsilon) - \delta(\varepsilon - y)) = 0$

$$\Box u = 0 \quad \text{where } \Box := -\partial_t^2 + \partial_1^2 + \dots + \partial_n^2$$

$$\forall \phi \in C_c^{\infty}(\mathbb{R}^{d-1}) \qquad \int_{\mathbb{R}}^{d+1} \Box \phi u = 0$$
(Wave)

(Wave) has a solution on \mathbb{R}^{1+1} given by u(t,x)=u(t-x), a traveling wave:



Example 1.2.

$$u(t,x) = H(t-x) - H(t+x)$$

is the unique solution to (Wave) on \mathbb{R}^{1+d}

The green lines are smooth approximation. After some time, it is still good enough to approximate the real world solution.

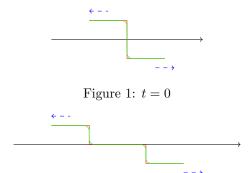


Figure 2: t = 1

2 Fluid Mechanics

2.1 Incompressible Euler Equation

Define 2 velocity field: $v: \mathbb{R} \times \mathbb{R}^d \to \mathbb{R}$ $p: \mathbb{R} \times \mathbb{R}^d \to \mathbb{R}$

$$\partial_t v^{\ell} + \nabla_j (v^j v^{\ell}) + \nabla^{\ell} p = 0$$

$$\nabla_i v^j = 0$$
 divergence free

This system obvious make sense for $v \in L^2_{loc}$. Let's recall the derivation of Euler equation. $\forall \Omega$ with C^1 $\partial \Omega$

$$\int_{\partial\Omega} v \cdot \overrightarrow{n} d\sigma = 0 \quad \forall t$$

meaning water coming in is exactly the same as water going out.

$$\frac{d}{dt} \begin{bmatrix} \text{total momentum} \\ m \cdot v \end{bmatrix} = \begin{bmatrix} \text{Force on } \Omega \end{bmatrix} + \begin{bmatrix} \text{Flux of} \\ \text{momentum} \end{bmatrix} \quad \Rightarrow \frac{d}{dt} \int_{\Omega} v^{\ell} dx = \int_{\partial \Omega} p \overrightarrow{n}^{\ell} dx \quad \forall t$$

These integral gives also the weak form of equation, let's say if p is good enough. If $v, pinC^1$, use $\int_{\partial\Omega} f \overrightarrow{n}_j d\sigma = -\int_{\Omega} \nabla_j f dx$

$$\frac{d}{dt} \int_{\Omega} v^{\ell} = -(\int_{\Omega} \nabla^{\ell} p + \nabla_{j} (v^{j} v^{\ell}) dx$$

$$\int_{\Omega} (\partial_{t} v^{\ell} + \nabla_{j} (v^{j} v^{\ell}) + \nabla^{\ell} p) dx = 0 \qquad \forall \Omega, \quad \forall t$$

Here comes a natural question: Are weak solution to the Euler equation physical meaningful? Some physical properties are required. Take $\Omega = \mathbb{R}^d$ and $v \in L^2_{t,x}(I \times \mathbb{R}^d)$

$$\frac{d}{dt} \int_{\mathbb{R}^d} K_{\ell} v^{\ell}(t, x) dx = 0$$

If $(1+|x|)v \in L^1_{t,x}(I \times \mathbb{R}^d)$, then linear angular momentum conserved? Here $\forall K^\ell$ s.t. $\nabla_i K_\ell + \nabla_\ell K_i = 0$ on \mathbb{R}^d

Example 2.1. $K = e_{(i)}$ the basis vector, $\int_{\mathbb{R}^d} K_\ell v^\ell dx = \int_{\mathbb{R}^d} v^{(i)} dx$

Example 2.2. Rotation $K(a, b) = x^{a}e_{b} - x^{b}e_{a}, 1 \le a < b \le d$.

$$\int_{\mathbb{R}^d} K_{\ell}(\partial_t v^{\ell} + \nabla : (v^j v^{\ell}) + \nabla^{\ell} p) dx = 0$$

$$\frac{d}{dt} \int_{\mathbb{R}^d} K_{\ell} v^{\ell} - \int \nabla : K_{\ell}(v^j v^{\ell}) - \int_{\mathbb{R}^d} \nabla^{\ell} K_{\ell} p dx = 0$$

where div $K = \nabla^{\ell} K_{\ell} = \delta^{j\ell} \nabla_{j} K_{\ell} = \frac{1}{2} \delta^{j\ell} (\nabla_{j} K_{\ell} + \nabla_{\ell} K_{j}) = 0$ by assumption.

$$\partial v^{\ell} + \nabla : (v^{j}v^{\ell}) + \nabla^{\ell}p)dx = 0$$

Test against a space cut-off function $K^{\ell}(B) := q(t)\varphi(\frac{|x|}{B})(x^be_m - x^ae_b)$. Here K is rotationally symmetric, so it is divergence-free.

$$-\int_{\mathbb{R}^+} \eta'(t) [\int_{\mathbb{R}^d} K_\ell^{(\beta)} v^\ell dx] dt - \int_{\mathbb{R}} \eta \int_{\mathbb{R}^d} \nabla_j K_\ell^{(\beta)} v^j v^\ell - \int_{\mathbb{R}^+} \eta(t) \int_{\mathbb{R}^d} \nabla^\ell K_\ell^{(\beta)} p dx dt = 0$$

Here, due to divergence-free, like what we did previously, $\int_{\mathbb{R}^+} \eta(t) \int_{\mathbb{R}^d} \nabla^{\ell} K_{\ell}^{(\beta)} p dx dt = 0$. i.e.

$$-\int_{\mathbb{R}^+} \eta'(t) [\int_{\mathbb{R}^d} K_\ell^\beta v^\ell dx] dt - \frac{1}{2} \int_{\mathbb{R}^+} \int_{\mathbb{R}^d} \left(\nabla_j K_\ell^{(\beta)} + \nabla_\ell K_j^{(\beta)} \right) v^j v^\ell dx dt - \frac{1}{2} \int_{\mathbb{R}} \eta(t) \int_{\mathbb{R}^d} \nabla_j \varphi(\frac{|x|}{B})) K_\ell v^j v^\ell dx dt = 0$$

The 1st term is dominated by $|x| \cdot v \in L^1_{t,x}$ by assumption. $\frac{1}{|x|} \cdot v$ dominated the derivative and integrant.

2.2 Conservation of Energy

If $(1+|x|)v \in L^1_{t,x}(I \times \mathbb{R}^d)$, $v \in L^2_{t,x}(I \times \mathbb{R}^d)$, then $\forall K^\ell$, $\nabla_j K_l + \nabla_l K_j = 0$, then we have the conservation of angular momentum:

$$\frac{d}{dt} \int_{\mathbb{R}^d} K_{\ell} v^{\ell}(t, x) dx = 0,$$

where $K \in \text{span}\{x^a e_b = x^b e_a : e_i, 1 \le i \le d, 1 \le a < b \le d\}$. Here decay assumption is needed but not the regularity assumption. If $f \in \mathcal{D}'(\mathbb{R}), \frac{df}{dt} = 0 \Rightarrow f = c$ limit of constant.

$$\delta_j^{\ell} = \nabla_j w^{j\ell} \quad w^{j\ell} = -w^{lj}$$
 antisymmetric

Approximate by $\nabla(\phi(\frac{|x|}{B}w^{j\ell})$

$$w^{j\ell} = x^2 (\delta_2^j \delta_1^\ell - \delta_1^j \delta_2^\ell)$$

$$\nabla_j (x^2 (\delta_2^j \delta_1^\ell - \delta_1^j \delta_2^\ell))$$

$$= \delta_j^2 (\delta_2^j \delta_1^\ell - \delta_1^j \delta_2^\ell) = \delta_1^\ell$$

If $w^{il} = -w^{lj}$

$$\nabla_j \nabla_j w^{j\ell} = -\nabla_\ell \nabla_j w^{lj} = -\nabla_j \nabla_\ell w^{lj} = -\nabla_\ell \nabla_j w^{j\ell}$$

Conservation of energy means that $\frac{d}{dt} \int_{\mathbb{R}^d} \frac{|v|}{2}(t,x) dx = 0$. Note that energy is nonlinear.

$$\partial_t \left(\frac{|v|^2}{2}\right) + \nabla_j \left(\left(\frac{|v|}{2} + p\right)v^j\right) = 0$$

If $v \in C^1 \cap L^2_{t,x} \cap L^3_{t,x}(I \times \mathbb{R}^d)$ both local and global conservation of energy hold. Note that here B could be ∞ . Multiply the local energy by $\eta(t)\varphi(\frac{|x|}{B})$

$$\int \eta \frac{d}{dt} \int \varphi(\frac{|x|}{B}) \frac{|v|^2}{2}(t, x) dx dt - \int \eta(t) \int \nabla_j [\varphi(\frac{|x|}{B})] (\frac{|v|^2}{2} + p) v^j dx dt$$
(1)
$$(1) = -\int \underline{\eta'(t)} \int \varphi(\frac{|x|}{B}) \frac{|v|}{2}(t, x) dx dt \quad \text{Intergral by parts}$$
dominated by $\frac{|x|^2}{2} |\eta'| \in L^1_{t,x}$ (Local)

term (2) converge to 0 pointwisely when $B \to \infty$ and dominated by $|\eta t|(\frac{|v|^3}{2} + |p||v|)$. Let's recall Euler equation.

$$\begin{cases} \partial_t v^{\ell} + \nabla_j (v^j v^{\ell}) + \nabla^{\ell} p &= 0, \\ \nabla_j v^j &= 0 \end{cases}$$
 (Euler)

Take divergence over (Euler), \Rightarrow

$$\nabla_j \nabla_\ell (v^j v^\ell) + \nabla_\ell \nabla^\ell p = 0$$

i.e.

$$\begin{aligned} \Delta p &= -\nabla_{\ell} \nabla_{j} (v^{j} v^{\ell}) \\ p &= \underbrace{(-\Delta)^{-1} \nabla_{\ell} \nabla_{j} (v^{j} v^{\ell})}_{\text{zero order operator}} &\underbrace{(v^{j} v^{\ell})}_{\ell t, x} \end{aligned}$$

Thus naturally $p \in L_x^{3/2}$ a.e. $t \in \mathbb{R}^+$

$$\begin{split} \|p\|_{L^{3/2}_x(L^{3/2}_t)} &= \|p\|_{L^{3/2}_{t,x}} < \infty \\ v_\ell(\partial_t v^\ell + \nabla(v^j v^\ell) + \nabla^\ell p) &= 0 \\ \nabla_j v^j &= 0 \end{split}$$

Thus

$$\Rightarrow \partial_t \left(\frac{|v|^2}{2}\right) + v_\ell v^j \nabla_j v^\ell + v_\ell \nabla^\ell p = 0$$

$$\Rightarrow \partial_t \left(\frac{|v|^2}{2}\right) + v^j \nabla_j \left(\frac{|v|^2}{2} + v_j v^j p = 0\right)$$

$$\nabla_j v^j = 0$$

$$\partial_t \left(\frac{|v|^2}{2} + \nabla_j \left(\left(\frac{|v|^2}{2} + p\right)v^j\right) = 0$$

Using $\nabla_j v^j = 0$ and product rule, conservation of energy is proved for sufficient regular solutions. But how sufficient do we need?

In turbulence situation (Navier-Stokes equations) with $\nu \ll 1$

$$v_{\ell}(\partial_t v^{\ell} + \nabla_j (v^j v^{\ell}) + \nabla^{\ell} p) = \nu v_{\ell} \Delta v^{\ell}$$

$$\frac{d}{dt} \int \frac{|v|^2}{2} (t, x) dx = -\nu \int |\nabla v|^2 dx = \nu \int v_\ell \nabla_i \nabla^i v^\ell$$

Taking a formal limit, ∃ incompressible Euler flows with

$$\frac{d}{dt} \int \frac{|v|}{2} (t, x) dx < -\varepsilon < 0$$

Theorem 2.1. Onsager's Conjecture

- $(+) \text{ If } \alpha > 1/3 \text{ and } (v(t, x + \Delta x) v(t, x)) \leq c|\Delta x| \text{ where } x \in \mathbb{T}^3 (v \in L^\infty_t C^\alpha_x), \text{ then the energy conserved.}$
- $(-) \ (K41) If \ \alpha \leq 1/3 \ \exists \ incompressible \ Euler \ flows \ with \ v \in L^{\infty}_t L^{\alpha}_x \ s.t. \ \int_{\mathbb{T}^d}^{\frac{|v|^2}{2}} (t,x) dx \ is \ not \ constant.$

Now we follow [2] and discuss the (+) part first.

$$\partial_t v^\ell + \nabla_j (v^j v^\ell) + \nabla^\ell p = 0$$

In order to get thto Onsager's explanation of how this might be possible, we expand the velocity v in Fourier series,

$$v(x,t) = \sum_{k \in \mathbb{Z}^3} a_k(t) e^{ik \cdot x}.$$

Obviously $a_{-k} = \overline{a_k}$, because v is real-valued. Moreover the divergence-free con-straint translates into the identity $k \cdot a_k = 0$. We then rewrite the remaining equations of (2.2) as an infinite-dimensional system of ODEs for the a_k :

$$\frac{da_k}{dt} = i \sum_{\ell} a_{k-\ell} \cdot \ell \left[-a_{\ell} + \frac{(a_{\ell} \cdot k) k}{|k|^2} \right] - \nu |k|^2 a_k \tag{1}$$

The total kinetic energy is (up to a constant factors) $\sum_{k} |a_{k}|^{2}$. (Don't understand)Energy starts at low wave numbers and moves to higher wave numbers in finite number.

(Don't understand)Energy starts at low wave numbers and moves to higher wave numbers
$$\sum_{\frac{\lambda}{2} \le |k| \le 2\lambda} |a_k|^2 \sim \lambda^{-2/3}$$
 matches (K41), corresponding to exactly 1/3 regularity for solutions.

Low frequency energy will goes to all frequency and when it goes to infinity, it will disappear.

(K 41) $E \lim_{v \to 0} \left\langle v \int |\nabla v|^2 dx \right\rangle$ and v determine all statistic properties of turbulent flows.

$$\langle |v(x+\Delta x) - v(x)|^p \rangle^{1/p} \sim \varepsilon^p |\Delta x|^{1/3}$$

Try to find $|\Delta x| < L \sim \varepsilon^a v^b$.

Now (+) is solved by [4] and [1] with the goal $L_t^3 B_{3,C(N)}^{1/3}$, $L_t^3 B_{3,\infty}^{1/3+\varepsilon}$.

(-) is solved $(d \ge 3)$ with $\alpha = \frac{1}{3}$, using convex integration by Phillip Isett [7].

Convex integration originated from the Nash-Kuiper Paradox(50's) for C^1 isometric embedding. Connection to Euler equation discovered by Camillo De Lellis and László Székelyhidi (08,12). First result towards Onsager conjecture is in [8]. And $\alpha < \frac{1}{5}$ by [10]. The non-uniqueness example was first given by [12] and then Shnirelman give a different proof in [13].

Another way of proving (+)

(+) (Eyink, Constantin, E, Titi 94') $L^3(B_{3\infty}^{\alpha})$

$$||v||_{C^{\alpha}} = \sup_{h \neq 0} \frac{||v(x+h) - v(x)||_{L^{\infty}}}{|h|^{\alpha}}$$

$$\left\|v\right\|_{B^{\alpha}_{3,\infty}}=\sup_{h\neq 0}\frac{\left\|v(x+h)-v(x)\right\|_{L^{3}}}{\left|h\right|^{\alpha}}$$

Lemma 2.2. Commutator Estimate

$$\begin{split} R_{\varepsilon}^{j\ell} &= \eta_{\varepsilon} * (v^{j}v^{\ell}) - (v_{\varepsilon}^{j}v_{\varepsilon}^{\ell}) \\ & \|R_{\varepsilon}\|_{L^{3/2}} \lesssim \varepsilon^{2\alpha} \|v\|_{B_{\alpha}^{\alpha}}^{2}. \end{split}$$

Let's think $R_{\varepsilon}^{j\ell}$ as an expectation with the idea:

$$R = \mathbb{E}[v^2] - (\mathbb{E}[v])^2 = \mathbb{E}[(v - \mathbb{E}(v))^2],$$

which is quadratic.

$$\begin{array}{ll} R_{\varepsilon}^{j\ell} = & \int v^{i}(x-h)v^{\ell}(x-h)\eta_{\varepsilon}(h)dh - \int v^{j}(x-h_{1})\eta_{\varepsilon}(h_{1})dh_{1} \int v^{\ell}(x-h_{2})\eta_{\varepsilon}(h_{2})dh_{2} \\ \text{Using} & \int \eta_{\varepsilon}(h)dh = 1 \\ & = & \int (v^{j}(x-h) - v_{\varepsilon}^{j}(x))(v^{\ell}(x-h) - v_{\varepsilon}^{\ell}(x))\eta_{\varepsilon}(h)dh \end{array}$$

By Lemmas in [1], we decompose above equation into $\sum_{i=1}^{4} R_{\varepsilon i}^{j\ell}$, where

$$\begin{array}{ll} R_{\varepsilon 1} = & \int (v^j(x-h) - v^j_\varepsilon(x-h))(v^\ell(x-h) - v^\ell_\varepsilon(x-h))\eta_\varepsilon(h)dh \\ R_{\varepsilon 2} = & \int (v^j_\varepsilon(x-h) - v^j_\varepsilon(x))(v^\ell(x-h) - v^\ell_\varepsilon(x-h))\eta_\varepsilon(h)dh \\ R_{\varepsilon 3} = & \int (v^j(x-h) - v^j_\varepsilon(x-h))(v^\ell_\varepsilon(x-h) - v^\ell_\varepsilon(x))\eta_\varepsilon(h)dh \\ R_{\varepsilon 4} = & \int (v^j_\varepsilon(x-h) - v^j_\varepsilon(x-h))(v^\ell_\varepsilon(x-h) - v^\ell_\varepsilon(x))\eta_\varepsilon(h)dh \end{array}$$

For example,

$$R_{\varepsilon 2} = \int_{\mathbb{R}^d} \int_0^1 \frac{d}{d\sigma} v_{\varepsilon}^j(x - \sigma h) d\sigma(v^{\ell}(x - h) - v^{\ell}(x)) \eta_{\varepsilon}(h) dh$$

$$= \int_{\mathbb{R}^d} \int_0^1 d\sigma \nabla_i v_{\varepsilon}^i(x - \sigma h) h^i(v^{\ell}(x - h) - v^{\ell}(x) \eta_{\varepsilon}(h) dh$$

$$\left\| R_{\varepsilon 2}^j \right\| \leq_{\mathbb{R}^d} \int_0^1 \| \nabla v_{\varepsilon} \|_{L^3} |h| \| v(\cdot - h) - v(\cdot) \|_{L^3} |\eta_{\varepsilon}(h)| dh$$

Modify the equation with modifier η_{ε} :

$$\eta_{\varepsilon} * (\partial_t v^{\ell} + \nabla_j (v^j v^{\ell}) + \nabla^{\ell} p) = 0$$
$$\partial_t v_{\varepsilon}^{\ell} + \nabla_j (v_{\varepsilon}^j v_{\varepsilon}^{\ell}) + \nabla^{\ell} p_{\varepsilon} = -\nabla_j R_{\varepsilon}^{j\ell}$$

(Thus we need smoothness in time) $\times v_{\varepsilon}$ then integral by parts:

$$\partial (\frac{\left|v_{\varepsilon}\right|^{2}}{2}) + v_{\varepsilon l} \nabla_{j} (v_{\varepsilon}^{j} v_{\varepsilon}^{\ell}) + v_{\varepsilon l} \nabla^{\ell} p_{\varepsilon} = -v_{\varepsilon l} \nabla_{j} R_{\varepsilon}^{j\ell} = \int_{\mathbb{R}^{d}} \nabla_{j} \left| \frac{v_{\varepsilon}^{2}}{2} v_{\varepsilon}^{j} \right| \to 0$$

with assumption.

$$\frac{d}{dt} \int_{\mathbb{R}^d} \frac{\left|v_\varepsilon\right|^2}{2}(t,x) dx + \int_{\mathbb{R}^d} v_\varepsilon^j \nabla_j v_\varepsilon^\ell v_{\varepsilon l} + \underline{\nabla^\ell v_{\varepsilon l} p_\varepsilon} = \int_{\mathbb{R}^d} \nabla v_{\varepsilon l} R_\varepsilon^{j\ell}$$

 $\nabla^{\ell} v_{\varepsilon l} p_{\varepsilon} = 0$ for divergence-free.

LHS converges to $\frac{d}{dt} \int \frac{|v|^2}{2} (t,x) dx$ in $\mathcal{D}'(\mathbb{R})$ since $v_{\varepsilon} \to v$ in $L^2_{t,x}$.

$$\begin{split} & \left\| \frac{d}{dt} \int \frac{|v|^2}{2}(t,x) dx \right\|_{L^1_t} \leq \limsup_{\varepsilon \to 0} \int \int \left| \nabla_j v(t,x) R_\varepsilon^{j\ell} \right| dx dt \\ & \leq \limsup_{\varepsilon \to 0} \int \left\| \nabla v_\varepsilon(t,\cdot) \right\|_{L^3_x} \left\| R_\varepsilon \right\|_{L^{3/2}} dt \\ & \leq \limsup_{\varepsilon \to 0} \int \varepsilon^{-1+\alpha} \|v(t)\|_{B^{\alpha}_{3,\infty}} \|v(t,\cdot)\|_{B^{\alpha}_{3,\infty}}^2 \right) dt \\ & < \limsup_{\varepsilon \to 0} \varepsilon^{-1+3\alpha} \int \left\| v(t,\cdot) \right\|_{B^{\alpha}_{3,\infty}}^3 dt \quad \to 0 \quad \text{with } \alpha > \frac{1}{3} \end{split}$$

If $\alpha = \frac{1}{3}$ and v bounded in $L_t^1(I)$ for some finite time period.

$$\frac{d}{dt} \int \frac{|v|^2}{2}(t,x)dx = \lim_{\varepsilon \to 0} \frac{d}{dt} \int \frac{|v_{\varepsilon}|^2}{2}(t,x)dx$$

 $v\phi \in C_c^{\infty}(I)$

$$\frac{d}{dt} < \int \frac{|v|^2}{2}(t, x) dx, \phi \ge \|\phi\|_{L^{\infty}(I)}$$

LHS is of finite measure. $e(t) = \int \frac{|v|^2}{2}(t,x)$ is of bounded variation. IN fact $\frac{d}{dt}e(t)$ is finite. (???)If $v \in L^r B_{3,\infty}^{1/3}$, consider $\left\|\frac{d}{dt}e(t)\right\|_{L_t^{r/t}}$ using duality. $u \in L_t^{\infty} B_{3,\infty}^{1/3}$ uniformly $\left\|\frac{d}{dt}e(t)\right\|_{L^i nft y_t} \leq C$ and also $\frac{d}{dt}e(t) \leq -\varepsilon < 0$ is stable under perturbation. If not, the dissipation $\int_{\mathbb{R}^d} \nabla_j v_{\varepsilon l} R_{\varepsilon}^{j\ell} dx$ can be really big.

Remark. The singular support of a generalized function u is the complement of the largest open set on which u is smooth. Roughly speaking, it is the closed set where the distribution does not correspond to a smooth function.

2.4 Local energy conservation

$$\partial_t v_\varepsilon^\ell + \nabla_\ell (v_\varepsilon^\ell v_\varepsilon^\ell) + \nabla^\ell p_\varepsilon = -\nabla_j R_\varepsilon^{j\ell}$$

where $R_{\varepsilon}^{j\ell} = \eta_{\varepsilon} * (v^{j}v^{\ell}) - v_{\varepsilon}^{j}v_{\varepsilon}^{\ell}$

$$\|R_{\varepsilon}(t,.)\|_{L^{3/2}_{\varepsilon}} \leq \varepsilon^{2\alpha} \|v(t)\|_{B^{\alpha}_{3,\infty}}^2$$

$$\frac{1}{2} \int \frac{|v_{\varepsilon}|}{2} (t, x) dx = \lim_{\varepsilon \to 0} \int \nabla_{j} v_{\varepsilon l} R_{\varepsilon}^{j\ell} dx$$

Here to clarify the space:

$$B_{3,c(N)}^{1/3} = (\overline{C^{\infty}})^{B_{3,\infty}^{1/3}} = B_{3,\infty}^{1/3} \cap \{\lim_{h \to 0} \frac{|v(x+h) - v(x)|}{|h|^{1/3}} = 0\}$$

The "Holder Continuity" is the reason for smooth approximation. Define

$$c^{1/3} = (\overline{C^{\infty}})^{C^{1/3}}$$

Note that, here $c^{1/3}$ is not dense in $C^{1/3}$. Let $\varphi(x)$ be a smooth cut off function, then, $|x|^{1/3} \in C^{1/3} \setminus c^{1/3}$, but $\varphi(x)|x|^{1/3} \notin C^{1/3} \setminus c^{1/3}$

Lemma 2.3. $\|\nabla v_{\varepsilon}\|_{L^{3}} = o(\varepsilon^{-1+\alpha})$ if $v \in B_{3,c(N)}^{\alpha}$

Proof. Claim: $\varepsilon^{1-\alpha}\nabla(\eta_{\varepsilon}*\cdot): B_{3,\infty}^{\alpha} \to L^3$ is uniformly bounded.

$$\|\nabla v_{\varepsilon}\|_{L_x^3} \lesssim \varepsilon^{-1+\alpha} \|v\|_{B_{3,\infty}^{\alpha}}$$

Let $\delta > 0$ be given, choose $\tilde{v} \in C^{\infty}$ s.t. $\|v - \tilde{v}\|_{B^{\alpha}_{3,\infty}} < \frac{\delta}{2C_2}$.

$$\begin{split} \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * v \right\|_{L^{3}_{x}} & \leq \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * (v-\tilde{v}) \right\|_{L^{3}_{x}} + \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * \tilde{v} \right\|_{L^{3}_{x}} \\ & \leq \frac{\delta}{2} + \varepsilon^{1-\alpha} \| \nabla \eta_{\varepsilon} * \tilde{v} \|_{L^{3}_{x}} \\ & \leq \frac{\delta}{2} + \varepsilon^{1-\alpha} \tilde{c} \quad \text{for} \varepsilon^{1-\alpha} < \frac{\delta}{2\tilde{c}} \text{ and } \left\| \varepsilon^{1-\alpha} \nabla \eta_{\varepsilon} * v \right\|_{L^{3}_{x}} < \delta \end{split}$$

$$\begin{array}{l} \int_{I} \frac{d}{dt} \int \frac{|v_{\varepsilon}|^{2}}{2}(t,x) dx dt \leq \limsup_{\varepsilon \to 0} \int_{I} \int \left| \nabla_{j} v_{\varepsilon l} R_{\varepsilon}^{j\ell} \right| dx dt \\ \leq \limsup_{\varepsilon \to 0} \int_{I} \left\| \nabla v_{\varepsilon}(t) \right\|_{L_{x}^{3}} \varepsilon^{2\alpha} \left\| v \right\|_{B_{3,\infty}^{\alpha}}^{2} dt \end{array}$$

For a.e. $t, v \in B_{3,C(N)}^{1/3}$, the integrant is bounded by $o(\varepsilon^{-1+2/3})\varepsilon^{3/2} = o(1)$. Thus above integral is dominated by:

$$\int_{I} \varepsilon^{-1\times 1/3 + 2/3} \|v(t)\|_{B^{1/3}_{3,\infty}}^3 dt \leq \int_{I} \|v(t)\|_{B^{1/3}_{3,\infty}}^3 dt$$

By assumption and DCT, bounded.

Theorem 2.4. (Isett 18') An energy dissipating solution whose singularities have 0 Lebesgue measure in \mathbb{R}^4 cannot be of class $L_t^r B_{\zeta,\infty}^{1/3}$ if r > 3.

Compared with Meneveau-Sreenivasan [11],

$$< |v(x + \Delta x) - v(x)|^r > = |\Delta x|^{\xi_r}$$

singular support in $L_t^3 B_{3,C(N)}^{1/3}$. (K41) implies $\xi_r \sim \frac{r}{3}$ (only correct when r=3).

Lemma 2.5. (Local energy conservation Duchon-Robert[3] formula $D[v,p] = \partial_t(\frac{|v|^2}{2}) + \nabla(\frac{|v|^2}{2} + p)v^j) = \lim_{\varepsilon \to 0} \nabla_j v_{\varepsilon \to 0} \nabla_j v_{\varepsilon l} R_{\varepsilon}^{j\ell}$ dissipation distribution $v \in L_{t,x}^3$. If D[v,p] = 0 and $v \in L_{t,x}^2 \cap L_{t,x}^3$, then $\int \frac{|v|^2}{2}(t,x)dx$ is constant and D[v,p] if $v,p \in C^1$.

If $v \in L^r_t B^{1/3}_{r,\infty}$ with r > 3 is energy dissipating, since $v \in L^2_{t,x} \cap L^3_{t,x}$, $D[v,p] \neq 0$. Since $\frac{d}{dt} \int \frac{|v|^2}{2} = \int D[v,p] dx$. But we claim that

$$\|D[v,p]\|_{L^{r/3}_{t,x}}<\infty$$

using *Duchon-Robert* formula: $\|\nabla_j v_{\varepsilon l} R_{\varepsilon}^{j\ell}\|_{L_{t,x}^{r/3}}$ is bounded uniformly in $\varepsilon > 0$.

$$\begin{split} \left\|\nabla_{j}v_{\varepsilon}\right\|_{L^{r}_{x}} & \lesssim \varepsilon^{-1+1/3}\|v(t)\|_{B^{1/3}_{r,\infty}} \\ \left\|R^{j\ell}_{\varepsilon}\right\| & \lesssim \varepsilon^{2/3}\|v(t)\|_{B^{1/3}_{r,\infty}}^{2} \\ \Rightarrow & \forall \phi \in C^{i}nfty_{c}(I \times \mathbb{R}^{d}) \quad < D < [v,p], p > \lesssim C\|p\|_{L^{s}_{t,x}} \end{split}$$

Then D[v,p] is in the dual of $L^s_{t,x}$ which is $L^{r/3}_{t,x}$ provided r>3. Let $\frac{1}{s}+\frac{3}{r}=1$. supp D[v,p] has positive Lebesgue measure, but supp $D[u,p]\subset \operatorname{sing}(\operatorname{supp} U)$ also has positive measure. There is an open problem to find a function f(r) s.t. the condition $\frac{\zeta_r}{r}<\frac{1}{3}-f(r)$ works.

Proof. (Proof of Duchon-Robert formula) Considering Euler equation(Euler)

$$\eta_{\varepsilon\delta} * u := J_{\zeta} *_{t} \eta_{\varepsilon} *_{x} u$$

Let's test against $w_{\varepsilon}\delta = \eta_{\varepsilon_{\delta}} * (\phi \eta_{\varepsilon \delta} * v)$.

$$0 = -\int_{I \times \mathbb{R}^d} v^{\ell} \partial_t \eta_{\varepsilon \delta} + (\phi \eta * v_{\ell}) + v^j v^{\ell} \nabla_j \eta_{\varepsilon \delta} * (\phi \eta_{\varepsilon \delta} * v) + p \nabla^{\ell} \eta_{\varepsilon_{\delta}} * (\phi \eta_{\varepsilon \delta} * v_{\ell}) dx dt,$$

where $\phi \in C_c^{\infty}(I \times \mathbb{R}^d)$. Use the definition of self adjointness solution $\eta_{\varepsilon_{\delta}}$ * and divergence-free properties of $\eta_{\varepsilon_{\delta}} * v_{\ell}$. Then Euler equation becomes

$$0 = -\int \partial_t \phi \frac{|\eta_{\varepsilon\delta} * v|^2}{2} + v^j v^\ell \eta_{\varepsilon\delta} \nabla) j\phi \eta_{\varepsilon\delta} * v_\ell + p\eta_{\varepsilon\delta} * (\nabla^\ell \phi \eta_{\varepsilon\delta} * v_\ell) dx dt$$

Let $\varepsilon \to 0$ using uniform bounded ness of $\eta_{\varepsilon}*$ and $\nabla_j \eta_{\varepsilon}*$. As $\delta \to 0$, thanks to $\nabla_j \eta_{\varepsilon}*$, the time derivative naturally goes away. Then

$$0 = -\int \partial_t \phi \frac{v_{\varepsilon}^2}{2} + \nabla_j \phi \left(\frac{|v_{\varepsilon}|^2}{2} v^j + \eta_{\varepsilon} * p v_{\varepsilon}^j\right) dx dt \tag{2}$$

$$+ \int \phi \nabla_j v_{\varepsilon l} R_{\varepsilon}^{j\ell} + Z_{\varepsilon}, \tag{3}$$

where $Z_{\varepsilon} = \int \nabla_j \phi R_{\varepsilon}^{j\ell} v_{\varepsilon l}$. Take both time and space derivative of ϕ . Using $v \in L_{t,x}^2 \cap L_{t,x}^2$ and p = $(-\Delta)^{-1} \nabla_{j} \nabla_{\ell} (v^{j} v^{\ell}) \in L_{t,x}^{3/2}$ $(2) \Rightarrow \langle D[u, p], \phi \rangle \text{ as } \varepsilon \to 0.$ $(3) \Rightarrow \lim_{\varepsilon \to 0} \nabla_{j} v_{\varepsilon j} R_{\varepsilon}^{j\ell} + Z_{\varepsilon}$

$$Z_{\varepsilon} = \int \nabla_{j} \phi(\eta_{\varepsilon} * (v^{j}v^{\ell}) - v_{\varepsilon}^{j} v_{\varepsilon}^{\ell}) v_{\varepsilon l} dx dt =: B_{\varepsilon}[v, v]$$

Here we define the commutator $B_{\varepsilon}[\cdot,\cdot]$.

$$||B_{\varepsilon}[u,w]||_{L_{t,x}^{3/2}} \leqslant C||u||_{L_{t,x}^3}||w||_{L_{t,x}^3}$$

which is independent of t.

If u or $w \in C_c^{\infty}$ $||B_{\varepsilon}[u, w]||_{L_{t,x}^{3/2}} \to 0$ as $\varepsilon \to 0$. By approximation $||B_{\varepsilon}[v, v]||_{L_{t,x}^{3/2}} \to 0$ as $\varepsilon \to 0$.

By Holder inequality,

$$|Z_{\varepsilon}| \leqslant \|\nabla \phi\|_{L^{\infty}} \|B_{\varepsilon}[v,v]\|_{L^{3/2}_{t,r}} \|v_{\varepsilon}\|_{L^{2}} \to 0 \text{ as } \varepsilon \to 0$$

Remark. Improvement:

- Calderon-Zygmund Theorem.
- More regularity in time.

Proof. (supp $D[u, p] \subset \operatorname{sing}(\operatorname{supp} v)$) In fact supp $D[u, p] \subset \operatorname{sing}(\operatorname{supp} L_{\varepsilon}^3 B_{3, C(N)}^{1/3} v)$.

What's good for not using Littlewood-Paley definition of Besov space? the solution above can be defined

 $\phi \in C_c^{\infty}(I \times B_q)$ and $B_q' \subset B_q$ a smaller ball with same center q. Let $q \notin \operatorname{sing}(\operatorname{supp} B_{3,C(N)}^{1/3}v)$

$$<\phi,D[v,p]>=\lim_{\varepsilon\to 0}\int_I\int_{B_q'}\phi(t,x)\nabla_jv_{\varepsilon l}R_\varepsilon^{j\ell}\lesssim \|\phi\|_{L^\infty}\int_I\|\nabla v_\varepsilon(t)\|_{L^(B_q')}\|R_\varepsilon\|_{L^{2/3}_x}$$

dominated by $\|\phi\|_{L^{\infty}} \int_{I} \|v(t,\cdot)\|_{B_{3,\infty}^{3/3}(B_{\varepsilon})}^{3}$. For a.e. t, we have $\|\nabla v_{\varepsilon}\|_{L^{3}} \cdot \|R_{\varepsilon}\|_{L^{3/2}} = o(1)$ and $D[u,p] \to 0$ by dominate convergence theorem.

1. Heat flow approach can also be applied to this problem. The proof is quite different[9] and is on a compact Riemann manifold (no convolution can be used).

2. Compressible Euler Case. The problem lies when dealing with commutator estimation.

3 Holder Continuity

The following lecture are basic on [9].

Note that $B_{3,C(\mathbb{N}}^{1/3} \subsetneq B_{3,\infty}^{1/3}$ and we can find a function in $B_{3,\infty}^{1/3} \setminus B_{3,C(N)}^{1/3}$. $\phi(x)\chi_{\{x'>0\}} \subset B_{p,\infty}^{1/p} \quad \forall 1 Let's consider$

$$\partial_t u + \partial_x (\frac{u^2}{2}) = 0 \quad L_t^{\infty} B_{3,\infty}^{1/3}$$

Energy dissipation at time t = 0

$$\frac{d}{dt}e(t) = \int_{\mathbb{T}^d} \nabla_j v_{\varepsilon l} R_{\varepsilon}^{j\ell}(0, x) dx$$

Eyink proved that there exists a divergence-free vector field in the space $C^{1/3}B_{3,C(N)}^{1/3}$, s.t. $\frac{d}{dt}|_{t=0}e(t) < 0$. We have a useful counter example:

$$v(x) = \sum_{q} 2^{2q\alpha} \sin(2^{2q}x) \in \dot{B}_{3,C(N)}^{1/3} \setminus \dot{B}_{3,\infty}^{1/3}$$

Now we consider this problem on compact Riemannian manifold for the conclusion $L_t^3 B_{3,C(N)}^{1/3}$. Consider (Euler), instead of $\eta_{\varepsilon} * v^{\ell}$, we consider

- Estimates(Commutator)
- Keeping divergence-free property

Define the operator $-\Delta_H = d_{\delta} + \delta_d$, which looks like a 1-form. In Hodge heat flow equation,

$$\partial_s v^{\ell} = \Delta_H v^{\ell} = \nabla_i \nabla^j v^{\ell} - \operatorname{Ric}_{\ell}^k v^k$$

Since we know what the solution exactly is,

$$\eta_{\varepsilon} * v^{\ell} \to e^{s\Delta_H} v^{\ell}$$

The square root of heat time $s^{1/2}\sim \varepsilon$ and solution at time s $S_{[s]}v=e^{s\Delta_h}v$. To estimate

$$\eta_{\varepsilon} * \nabla_{i}(v^{j}v^{\ell}) - \nabla_{i}(\eta_{\varepsilon}v^{j}\eta_{\varepsilon} * v^{\ell}),$$

we would need the commutator

$$w^{\ell}(s) = S_{[s]} \nabla_j (v^j v^{\ell}) - \nabla_j (S_{[s]} v^j S_{[s]} v^{\ell})$$

and Riemannian manifold M will be always assumed to be smooth.

$$s \in (0,1]$$

$$\int_{I \times M} \eta(t) [S_{[s]} \nabla_j (v^j v^\ell) - \nabla_j (S_{[s]} v^j S_{[s]} v^\ell) S_{[s]} v_\ell d^{1+d} \text{vol},$$

here volume is in time × space.

Let's calculate

$$(\partial_s - \Delta_H) w^{\ell} = N^{\ell}(t, s)$$
$$w^{\ell}(s) = \int_0^s e^{(s-s')\Delta_H} N^{\ell}(t, s') ds',$$

by d'Alembert's formula.

$$\begin{array}{ll} w^{\ell}(t,s) &= S_{[s]}\nabla_{j}(v^{j}v^{\ell}) - \nabla(S_{[s]}v^{j}S_{[s]}v^{\ell}) \\ (\partial_{s} - \Delta_{H})w^{\ell} &= (\partial_{s} - \Delta_{H})\nabla_{j}(S_{[s]}v^{j}S_{[s]}v^{\ell}) \\ &= (\partial_{s} - \nabla_{i}\nabla^{i})\nabla_{j}(S_{[s]}v^{j}S_{[s]}v^{\ell}) + \text{curvature terms} \\ &= -2\nabla_{j}(\nabla_{i}S_{[s]}v^{j}\nabla^{i}S_{[s]}v^{\ell}) + \text{low order terms} \end{array}$$

$$\begin{array}{ll} \text{Commutator} &= -2 \int_{I \times M} \eta(t) \int_0^s e^{(s-s')\Delta} \nabla_j (\nabla_i S_{[s]} v^j \nabla^i S_{[s]} v^\ell) ds' S_{[s]} v_\ell d^{1+d} \text{vol} \\ \text{Integral by parts} &= 2 \int_{I \times M} \eta(t) \int_0^s \nabla_i S_{[s]} v^j \nabla^i S_{[s]} \cdot \underbrace{S_{[2s-s']}}_{\text{very low frequency}} v_\ell ds' d^{1+d} \text{vol} \\ & \text{very low frequency} \end{array}$$

Assume that $v \in L_t^3 B_{3,\infty}^{\alpha}$, claim that $\|\nabla S_{[s]}v\|_{L^3} \lesssim s^{\frac{-1+\alpha}{2}} \|v\|_{L_t^3 B_{3,\infty}^{\alpha}}$ with $\alpha > 1/3$. First we can try $v \in L_t^3 C^{\alpha}$ or $v \in L_t^3 W^{\alpha,3}$.

$$\begin{array}{ll} |Commutator| & \lesssim \|\eta\|_{L^{\infty}} \int_0^s (2s-s')^{\frac{-1+\alpha}{2}} (s')^{-2\frac{1+\alpha}{2}} ds' \\ & \lesssim s^{-1/2+3\alpha/2} \int_0^1 (2-\sigma)^{\frac{-1+\alpha}{2}} \sigma^{-1+\alpha} d\sigma \to 0 \text{ as } \varepsilon \to 0 \text{ with } \alpha < 1/3 \end{array}$$

No derivatives that we can take over the heat flow. In order to prove the claim: $\|\nabla S_{[s]}v\|_{L^3} \lesssim s^{\frac{-1+\alpha}{2}}\|v\|_{W^{\alpha,3}}$ with $\alpha > 1/3$.

Proof.

$$\begin{aligned} & \left\| \nabla S_{[s]} v \right\|_{L^3} \leqslant s^{-\frac{1}{2}} \|v\|_{L^3} \\ & \left\| \nabla S_{[s]} v \right\|_{L^3} \leqslant \|v\|_{W^{1,3}} \end{aligned}$$

Since $u(s) = e^{s\Delta}u$, $||u||_{L^{\infty}} \lesssim ||u||_{L^{p}}$ $s \in (0,1]$ On compact manifold we have that

$$\|\nabla u\|_{L^p} \lesssim \|\nabla u\|_{L^r} + \|u\|_{L^p}$$

Here let p = 2z where $z \ge 2$ is an integer.

$$\partial_{s}|u|^{2} - \Delta|u| + |\nabla u|^{2} = 0 \text{ (or } -2\operatorname{Ric}_{jk} u^{j} u^{k})$$

$$\Rightarrow \int_{M} |u|^{2} d\operatorname{vol} \searrow \text{ and } \int_{M} u^{2z} d\operatorname{vol} \searrow$$

$$\frac{1}{z} \partial_{s} \int |u|^{2z} d\operatorname{vol} = \int_{M} (\Delta|u|^{2} - 2|\nabla u|^{2})|u|^{2(z-1)} d\operatorname{vol}$$

$$= -\int_{M} \nabla^{j} |u|^{2} \nabla_{j} |u| |u|^{2(z-2)} - 2|\nabla u|^{2} |u|^{2(z-1)} \leqslant 0$$

$$(4)$$

For curvature terms, they can be bounded by $\|\text{Ric}\|_{L^{\infty}} \int_{M} |u|^{2z} dvol$ remains bounded. So $\int_{M} u^{2z} dvol \leq \int_{M} u^{2z} (t=0) dvol$.

$$\partial_s |\nabla u|^2 - \Delta |\nabla u|^2 + |\nabla \nabla u|^2 (BAD) = 0 (\text{ or } Riem(\nabla u \nabla u) + \nabla Riem u \nabla u)$$
(5)

Multiply by $|\nabla u|^{2(z-1)}$

$$\frac{1}{z}\partial_j \int_M |\nabla u|^{2z} d\text{vol} \quad \searrow$$

or

$$\int_{M} |\nabla u|^{2(z-1)} \nabla_{\mathrm{Riem}} u \nabla u d \text{vol} \quad \text{by integration by parts} \\ \leqslant 2 \underbrace{\int_{M} |\nabla \nabla u|^{2} |\nabla u|^{2(z-1)}}_{BAD} + \underbrace{Cz \int_{M} \|R\|_{L^{\infty}} \|\nabla u\|^{2z} + \|\mathrm{Riem}\|^{z+1} \|u\|^{2z}}_{GOOD}$$

which can cancel bad terms from (5).

$$\partial_s(s|\nabla u|^2) - \Delta(s|\nabla u|^2) + 2s|\nabla\nabla u|^2 - |\nabla u|^2 \text{(BAD)}$$

But here the bad term can cancel with (4). Let $\Phi(s) = s|\nabla u|^2 + \frac{1}{2}|u|^2$, then we have

$$\partial_z \Phi_s - \Delta \Phi_s = 2s |\nabla \nabla u|^2$$

Thus

$$\frac{1}{z}\partial_{s} \int_{M} |\Phi_{s}|^{z} (\searrow) \leqslant \frac{1}{z} \int_{M} |\Phi_{s}|^{z} d\text{vol} \leqslant \frac{1}{z} \int_{M} |\Phi_{0}|^{z} = \frac{1}{z} \int_{M} |u|^{2z}$$
$$\frac{1}{z} (\int_{M} |\nabla u|^{2z})^{1/2z} \leqslant s^{-1/2} (\int_{M} |u|^{2z})^{1/2z}$$

Hodge Laplacian commute with derivative d and divergence δ . $(\partial_s - \Delta_H)\delta w_\ell = \delta(\partial_s - \Delta_H)w_\ell = 0$ with 0 initial condition.

3.1 Isentropic Compressible Euler

Mass
$$\partial_t \rho + \nabla_j (\rho v^\ell) = 0$$

Momentum $\partial_t (\rho v^\ell) + \nabla_j (\rho v^j v^\ell) + \nabla^l (P \rho) = 0$ (6)

We made some assumption $p(\rho) = \rho^2 \gamma$ and $\rho \in \mathbb{C}^2$ and away from $\rho \equiv 0$. Here exists a problem: modifier doesn't commute with nonlinearity.

$$\partial_t (\frac{1}{2}\rho|v| + p(\rho)) + \nabla_j ((\frac{1}{2}\rho|v| + p(\rho) + p(\rho)v^j)p(\rho)) = \rho \int_1^\rho \frac{p(r)}{r^2} dr$$

If conservation holds in $B_{3,\infty}^{\alpha}$ in both (t,x), we need to estimate the commutator:= $\eta_{\varepsilon} * (p(\rho)) - p\eta * \rho$.

Remark. • Heat flow also works.

• [5] gives another method

Commutator =
$$\int p(\rho(x-h))\eta_{\varepsilon}(h)dh - p(\int \rho(x-h)\eta_{\varepsilon}(h)dh$$
=
$$\int p(\rho(x-h))\eta_{\varepsilon}(h)dh - p(\int (\rho(x-h)\eta_{\varepsilon}(h))dh = \int (1-\sigma)\int p''((1-\eta)\rho_{\varepsilon}(x) + \sigma\rho(x-h))(\rho(x-h) - \rho_{\varepsilon}(x))dh$$

Therefore bounded.

$$\overline{f(X)} - f(\overline{X}) = \mathbb{E}[f(X)] - f(\mathbb{E}[X]) \tag{7}$$

Since

$$\phi(1) = \phi(0) + \int_0^1 \frac{d}{d\sigma} \phi(\sigma) d\sigma$$

= $\phi(0) + \frac{d}{d\sigma} |_{\sigma=0} \phi(\sigma) + \int_0^1 (1 - \sigma) \frac{d^2}{d\sigma^2} \phi(\sigma) d\sigma$

RHS of (7) becomes

$$\begin{split} &\int +0^{1} \frac{d}{d\sigma} \mathbb{E}[f(1-\sigma)\overline{X} + \sigma(X))] \\ &= \frac{d}{d\sigma}|_{\sigma=0} \mathbb{E}[f(1-\sigma)\overline{X} + \sigma(X)] + \int_{0}^{1} (1-\sigma) \frac{d^{2}}{d\sigma^{2}} \mathbb{E}[f(1-\sigma)\overline{X} + \sigma X) d\sigma \\ &= \mathbb{E}[\nabla_{i} f(\overline{X})(X^{i} - \overline{X}^{i})] + \int_{0}^{1} (1-\sigma) \mathbb{E}[\nabla_{a} \nabla_{b} f((1-\sigma)\overline{X} + \sigma X)(X^{a} - \overline{X}^{b})(X^{b} - \overline{X}^{a}) d\sigma \end{split}$$

Here last term is a quadratic form.

4 Convex Integration

Here "convex" refers to convex linear combination.

Theorem 4.1. (Old conclution) $\forall E(t) \in C^{\infty}$, $E(t) \geq C$, $\forall \alpha < \frac{1}{10}$, $\exists v \in C^{\alpha}_{t,x}(I \times \mathbb{T}^3)$ s.t. $\int \frac{|v|^2}{2}(t,x)dx = E(t)$ conserved.

Theorem 4.2. (Isset [6]) $\forall \alpha < 1/5$, $\exists v \in C^{\alpha}_{t,x}(I \times \mathbb{T}^3, p \in C^{2,\alpha}_{t,x})$. A non trivial solution with compact support in time. (0 is not the only solution stays 0 implies non-uniqueness).

- Question: How to construct continuous solution?
- Idea: Euler-Reynolds flows

For R a symmetric tensor (v, p, R) that solves

$$\partial_t v^l + \nabla_j (v^j v^\ell) + \nabla^\ell p = \nabla_j R^{j\ell}$$
$$\nabla_j v^j = 0$$

Here $R^{j\ell} = R^{lj}$. If R = 0, we have the Euler equation(Euler). If $R \neq 0$, we have a smooth approximation of Euler Equation.

Construction (v_q, p_q, R_q) the Euler-Reynolds flow:

$$R_q \to 0$$
 as $q \to \infty$

and

$$(v_q, p_q)$$

converge uniformly.

$$-\int \partial_t \phi_\ell v_q^l + \nabla_j \phi_\ell + v_q^j v_q^\ell + \nabla^\ell \phi \cdot p_q = \nabla_j \phi R_q^{j\ell} \to 0$$

The idea would make sense if every continuous solution (v, p) is a uniform limit of $(v_{\varepsilon}, p_{\varepsilon}, R_{\varepsilon})$ as $\varepsilon \to 0$. I.e. every Euler flow is a limit of Euler-Reynolds flow. Proof will also be given by modification. To check weather it is a E-R flow, we need to check weather it conserves energy.

Lemma 4.3. (Main Lemma) Given $(v, p, R) \exists new$

$$(\overset{*}{v},\overset{*}{p},\overset{*}{R})$$

with

$$\|\mathbf{R}\|_{0} << \|R\|_{0},$$

where

We expect that $\|V\|_0 \leqslant \|R\|_0^{1/2} \leftarrow \left[\frac{m}{s}\right]$ and $\|P\|_0 \leq \|R\|_0 \leftarrow \left[\frac{m}{s}\right]$ by dimension analysis.

Apply 4.3 over and over again generate (v_q, p_q, R_q) with $||R_q||_0 \to 0$ rapidly. Set $v = v(0) + \sum_q v_q$ and $p = p(0) + \sum_q P_q$. Plug in new 8

$$\partial_t \overset{*^\ell}{\mathbf{v}} + \nabla_j (\overset{*^i *^l}{\mathbf{v}}) + \nabla^\ell \overset{*}{\mathbf{p}} = \nabla_j R^{j\ell} + \partial_t v^\ell + \nabla_j (v^j v^\ell) + \nabla_j (v^j v^\ell) + \nabla^\ell p + \nabla_j (v^j v^\ell)$$

i.e.

$$\mathrm{RHS} = \nabla v^\ell + \nabla_j (v^j V^l \ell) + \nabla_j (V^j V^l + P \delta^{j\ell} + R^{jl}) + \nabla_j (v^l V^j)$$

where R^{jl} is the old error. We want $\nabla_j \mathbf{R}^{*j\ell} = \text{RHS}$ with \mathbf{R}^* small. ¹ The rest is not small. Let them equals to $\nabla_j Q^{jl}$ with $Q^{jl} = Q^{lj}$. Either $\nabla_j (v^{jl} + p\delta^{jl} + R^{jl})$ or $\nabla_j (v^j V^l)$ or $\nabla_j (v^l V^j)$ is not small.

4.1 Non-stationary Phase Lemma

When you can find a small solution $Q^{j\ell} = Q^{\ell j}$ to the symmetric divergence equation

$$\nabla_i Q^{j\ell} = u^l$$

Necessary for u^{ℓ} to be high-frequency $n \geq 1$ and $\int_{\mathbb{T}^3} u^{\ell} dx = 0$. What does v^{ℓ} look like? [2] Beltrami flows.

$$v^{\ell} = \sum_{|k|=R} a_k B_k^{\ell} e^{i\lambda k \cdot x}, \quad k \in \mathbb{R}^d$$

 $\nabla \times v = R\lambda v$ if $(ik) \times B_k = |k|B_k$ and a_kB_k are constant.

$$v^{l} = \sum_{|k|=R} a_{k}(R, E, v, \lambda t) B_{l}^{\ell} e^{i\lambda kx}$$

Construction of frequency:

$$v^\ell = \sum_I v_I^l, \quad v_{\bar{I}}^\ell = \bar{v}_I^l, \quad \nabla_j v_I^j = 0$$

$$v_I^l = \nabla_j w_I^{jl}, \quad w_I^{jl} = -w_I^{lj} \Leftrightarrow$$

 $^{^{1}}$ Here the position of * is decided by whether it is a equation or just math script. The different position of * doesn't have different meaning

 $w^{j}l$ is a curl. For high frequency wave

$$v_I^{\ell} + \delta v_I^{\ell}$$
 with $\lambda >> 1$

$$v_I \cdot \nabla \xi_I = 0$$
 for divergence free

Here ξ_I is always tangent to level phase function.

$$w_I^{jl} = \frac{e^{i\lambda\xi_I}}{i\lambda} w_I^{j\ell} = \frac{e^{i\lambda\xi}}{i\lambda} (\nabla^j \xi_I v_I^{\ell} - v_I^j \nabla^l \xi_I)$$

then it is anti-symmetric. Thus

$$\nabla_j w_I^{j\ell} = e^{i\lambda\xi_I} (\nabla_j \xi_I w_I^{il} + \frac{\nabla_j w^{j\ell}}{i\lambda}) = e^{i\lambda\xi_I} (v_I^{\ell} + \delta v_I^{\ell}),$$

where $\delta_{V_I} = \mathcal{O}(\frac{1}{\lambda})$, thus small. The transport term:

$$\nabla_j R_T^{jl} = \partial_t v^\ell + \nabla_J (v^j V^\ell) + \nabla_j (V^j v^l)$$

want to solve

$$\nabla_j Q^{jl} = u^l = e^{i\lambda \xi_I} v_I^\ell$$

with small $Q^{j\ell} = Q^{\ell j}$ on \mathbb{T}^3 . The equations above are under-determined. So the solution is not unique and we are try to find a small one.

Lemma 4.4. Non-stationary Phase Lemma If $\||\nabla \xi_I|^{-1}\|_0 \le A$ (no zero frequency) and $\int_{\mathbb{T}^3} u^{\ell}(x) dx = 0$. We note that if $|\nabla \xi_I| \to 0$, then we just rotating a constant but there is no waves. Then $\exists Q^{j\ell} = Q^{\ell j}$ of size $\|Q\| \le \mathcal{O}(\lambda^{-1})\|u\|_0 + \mathbb{O}_{(u,\nabla q)}(\lambda^{-2})$. Since $\int \partial_t V^l dx = 0 \Rightarrow \frac{d}{dt} \int v^\ell dx = 0$ conserve the momentum, consistent with solution of Euler.

Proof. d=1.

$$\frac{dQ}{dx} = e^{i\lambda\xi(x)}u(x) \quad \text{ on } \mathbb{T} = \mathbb{R}/\mathbb{Z}$$

 $\Rightarrow Q(x) = \int_0^x e^{i\lambda\xi(x)} u(s) ds$ is periodic because $\int_{\mathbb{T}} u(x) dx = 0$. By integration by parts,

$$=\frac{1}{i\lambda\xi(s)}e^{i\lambda\xi(s)}u(s)|_{s=0}^{x}-\frac{1}{i\lambda}\int_{0}^{x}e^{i\lambda\xi(s)}\frac{d}{ds}(\frac{u(s)}{\xi(s)}ds=\mathcal{O}(\frac{1}{\lambda}+\frac{1}{\lambda}\mathcal{O}(\lambda^{-2}))$$

Let's look at the transport term

$$\begin{split} \nabla R_T^{j\ell} &= \partial_t v^l + \nabla_j (v^j v^\ell) + \nabla_j (v^j v^\ell) = \partial_t v^l + v^j \nabla_j v^l + v^j \nabla_j v^\ell \\ &= (i\lambda) \sum_I e^{i\lambda \xi_I} (\partial_t \xi_I) v_q^\ell + (v^j \nabla_j) \xi_I v^\ell + \sum_I e^{i\lambda \xi_q} \end{split}$$

Apply the Non-stationary Phase Lemma 4.4

$$||R_T||_0 \lesssim \lambda^{-1} ||RHS||_0 \lesssim \lambda^{-1} (\lambda ||(\partial_t + v^j \nabla_j) \xi_I||_0 ||V_I||_0) + \mathcal{O}(\lambda^{-2})$$

Impose the phase function:

$$(\partial_t + V \cdot \nabla)\xi_I = 0$$

$$D_t \xi_I = 0$$
(9)

Taylor hypothesis: High frequency flows are actually carried by low frequency flows. So it make sense with our assumption. If $\left\| \left| \nabla \xi_I \right|^{-1} \right\|_0 \leqslant A$ fails to control the amplitude, we include time cut-offs in v_I . Look at $\nabla_j (v^j v^l + p \delta^{jl} + R^{jl})$, want it to be div of something small. Want $R_{small}^{j\ell} = \sum_I v_I^j \bar{v}_I^\ell + P_0 \delta + R^{j\ell}$

$$\sum_{I} v_I^j \bar{v}_I^\ell + P_0 \delta^{j\ell} + \sum_{j \neq \bar{I}} v_I^j v_j^\ell + P_{Ij} \delta^{j\ell} = \sum_{I} v_I^j \bar{v}_I^\ell + P_0 \delta^{j\ell} + R^{j\ell} + \sum_{I} \delta v_I^j v^\ell \left(= 0 + \mathcal{O}(\frac{1}{\lambda}) \right)$$

14

Let's pick a t to make this = 0 pointwisely.

$$\sum_{I} v_{I}^{j} \bar{v}_{j}^{\ell} = -P_{0} \delta^{i\ell} - R^{j\ell} = e(t) \delta^{j\ell} - E^{j\ell}$$

Choose $e(t) \ge 10^4 ||R||_0$ on supp R, here e(t) is the lifting function.

$$\Rightarrow ||V_I||_0 \lesssim e^{1/2} \lesssim ||R||_0^{1/2}$$

We need to choose time depending on amplitude. Note that supp, $e \subset B(\operatorname{supp} R, \varepsilon)$,

$$\Rightarrow$$
 supp_t(New Error) \subset supp_t e

For (8), we rewrite our (Euler) as:

$$\begin{array}{ll} \partial_t v^{\ell} + \nabla_j (v^j v^{\ell}) + \nabla^{\ell} p &= \nabla_j R^j l \\ \nabla_j v^j &= 0 \end{array} \tag{10}$$

where we decompose $v^{\ell} = \sum_{I} v_{I}^{l}$ and $\nabla_{j} V_{I}^{j} = 0$ by $v^{l} = \nabla_{j} w_{I}^{jl}$ since w_{I}^{jl} is anti-symmetric tensor. $V_{I}^{l} = e^{i\lambda\xi_{I}}(v_{I}^{\ell} + \delta v_{I}^{\ell})$, where $\delta v_{I}^{\ell} \sim \mathbb{O}(\lambda^{-1})$. As for phase $\xi_{I} \in \mathbb{C}$, we have $\left\| |\nabla \xi_{I}|^{-1} \right\|_{0} \leq A$, $V_{I} \cdot \nabla \xi_{I} = 0$. Let's impose $(\partial_{t} + v \cdot \nabla)\xi_{I} = 0 \Rightarrow$ We need time cut offs inside v_{I} to maintain the non-stationary phase. Let $\|R\|_{0} \leqslant e_{R}$

$$\mathbf{R}^* = \begin{array}{ccc} R_T^{j\ell} + & R_L^{j\ell} + & R_S^{j\ell} + & R_H^{j\ell} \\ & \text{Transport Low Frequency} & \text{Stress} & \text{High Frequency} \end{array}$$

$$\begin{split} &\nabla_{j}R_{T}^{j\ell} = \partial_{t}v^{l} + \nabla_{j}(v_{j}V^{\ell}) \\ &\nabla_{j}R_{L}^{j\ell} = \nabla_{j}(v^{j}V^{L}) \\ &\nabla_{j}R_{S}^{j\ell} = \nabla_{j}(\sum_{I}v_{I}^{j}\bar{v}_{I}^{\ell} + p\delta^{j\ell} + R^{j\ell}) \\ &\nabla_{j}R_{H}^{j\ell} = \sum_{j\neq \bar{I}}\nabla_{j} \end{split}$$

$$R_S^{j\ell} = \sum_I V_I^j \bar{v}_I^\ell + \rho \delta^{j\ell} + R^{j\ell} + \mathbb{O}(\delta v_I)$$

(Phase cancel thus high frequency disappear)

$$\sum_{I} V_I^j V_I^{-\ell} = -P_0 \delta^{j\ell} - R^{j\ell}$$

Let's set $p_0 = -e(t)$, $e(t) \geqslant Ke_R(\text{error})$. $\sum_I v_I^j v_I^{-\ell} = e(t) \delta^{i\ell} - R^{j\ell}$. $e(t) \geqslant Ke_\ell$ on supp R.

What about the high frequency?

$$\nabla_{j} R_{H}^{j\ell} = \sum_{J \neq \bar{I}} \nabla_{j} (V_{I}^{j} \bar{V}_{I}^{l}) + \nabla^{l} P_{IJ}
= \frac{1}{2} \sum_{J \neq \bar{I}} V_{I}^{j} \nabla_{j} V_{J}^{\ell} + V_{J}^{j} \nabla_{j} V_{I}^{\ell} + \nabla^{\ell} P_{IJ}
= (i\lambda) \sum_{J \neq \bar{J}} e^{i\lambda(\xi_{I} + \xi_{J})} \nabla_{J} \xi_{J} V_{J}^{\ell} + \text{L.O.T}
\|R_{H}\|_{0} \lesssim \lambda^{-1} \|\text{RHS}\|_{0} + \mathbb{O}(\lambda^{-2} \|\text{RHS}\|)
= \lambda^{-1} \lambda \|V_{I}\|_{0} \|\nabla \xi_{I}\| \|V_{\bar{I}}\|_{0} \lesssim e_{R}^{1/2} 1 e_{R}^{1/2}$$
(11)

Better way "write V_I as a steady state solution".

Idea: If $\nabla \cdot V_I = \lambda V_I$ and $\nabla \cdot V_J = \lambda V_J$ then $V_I + V_J$ is steady state for E-R flow with appropriate pressure P_{Ij} s.t.

$$V_I^j \nabla_i V_I^i + V_I^j \nabla_i V_I^i + \nabla^i P_{IJ} = 0$$

To make $\nabla \times V_I \sim \lambda V_I$

$$\nabla \times (e^{1\lambda\xi_I}V_I) = \lambda e^{i\lambda\xi_I}((i\nabla\xi_I) \times V_I)$$
$$(i\nabla\xi_I) \times V_I = |\nabla\xi_I|V_I \sim \lambda e^{i\lambda\xi_I}|\nabla\xi_I| \times V_I$$

Here $|\nabla \xi_I|$ is eigenvalue. If $|||\nabla \xi_I| - 1||_0 << 1$, (by sharp time cut-off)

$$(i\nabla \xi_I) \times V_I = -(\nabla \xi) \times b_I + i(\nabla \xi_I) \times a_I$$

 $|\nabla \xi_I| \cdot V_I = |\nabla \xi_I| a_I + i|\nabla \xi_I| b_I$

choose $b_I \in \langle \nabla \xi_I \rangle^+$ and set $a_I = \frac{-(\nabla \xi_I) \times b_I}{|\nabla \xi_I|}$, thus

$$(\nabla \xi_I) \times a_I = -\nabla \xi_I \times \frac{(\nabla \xi_I \times b_I)}{|\nabla \xi_I|} = \frac{-(-|\nabla \xi|^2 b_I)}{|\nabla \xi_I|} = |\nabla \xi_2| b_I$$
$$e^{i\lambda \xi_I} V_I^l = e^{i\lambda \xi_I} (a_J^l + ib^l + I) = \cos \lambda \xi_I a_I^\ell - \sin \lambda \xi_I b_I^\ell$$
$$a_I = \frac{-\nabla \xi_I \times b_I}{|\xi_I|}$$

By (11)

$$\frac{1}{2} \sum_{J+I} (V_I)_j (\nabla^j V_J^j) + (V_J)_j (\nabla^j V_I^{\ell} - \nabla^{\ell} v_I^j) + \nabla^{\ell} \frac{V_i V_J}{2} + \nabla^{\ell} P_{IJ},$$

 $\nabla^{\ell} \frac{V_i V_J}{2} + \nabla^{\ell} P_{IJ} = 0$ by our choice of P_{IJ} .

$$P_{IJ} = -\frac{1}{2}V_I V_J = -\frac{1}{2} \sum_{J \neq \bar{I}} (V_I \times (\nabla \times V_J) + V_J \times (\nabla \times V_I)) = 0$$

If V_j , V_I are eigen-function of $\nabla \times$.

$$P_{IJ} = -\frac{1}{2}V_I V_J = \lambda e^{\lambda(\xi_I \xi_J)} (V_I \times ((i\nabla \xi_J) \times V_j) + V_J \times (i\nabla \xi_I)V_I)) + \text{L.O.T}$$
$$= \lambda e^{\lambda(\xi_I \xi_J)} (V_I \times (|\nabla \xi_J| - 1)V_J) - V_J \times (|\nabla \xi_I| - 1)V_I) + \text{L.O.T}$$

for $V_I \times V_j + V_J \times V_I = 0$. Since non-stationary phase $\left\| \left| \nabla \xi_I + \nabla \xi_J \right|^{-3} \right\| \leqslant A$.

$$\begin{split} & \left\| R_H \right\|_0 \lesssim \lambda \cdot \lambda \max_I \left\| V_I \right\|_0^2 \cdot \max_I \left\| \left| \nabla \xi_I \right| - 1 \right\|_0 \\ & \lesssim e_R \max_I \left\| \left| \nabla \xi_I \right| - 1 \right\|_0 + \text{L.O.T} \end{split}$$

Can be made small with a sharp time cut off in each V_I : $\tau \sim b|\nabla V|^{-1}$. Then we need to pay the price for time cut-off.

$$\nabla_{j} R_{T}^{j\ell} = \partial_{t} v^{\ell} + \nabla_{j} (v^{j} V^{\ell}) = \partial_{t} v^{\ell} + v^{j} \nabla_{j} V^{\ell}$$
$$= \sum_{I} \exp(i\lambda \xi_{I}) (\partial_{t} + v^{j} \nabla_{j}) V_{I}^{\ell}$$
$$\|R_{T}\|_{0} \lesssim \lambda^{-1} \text{RHS} + \mathcal{O}(\lambda^{-2}) \lesssim \lambda^{-1} \tau^{-1}$$

Choose $\lambda >> \tau^{-1} \Rightarrow ||R_{\tau}||_0$ is arbitrarily small.

Remark. • Convex linear combination problem $\sum v^j \bar{v}_I^\ell = e(t)\delta^{jl} - R^{jl}$

• Integration means using $\nabla R^{j\ell}$ to approximate $R^{j\ell}$.

Lemma 4.5. (Main Lemma) $\exists K, \exists C > 1 \text{ s.t. } \forall \varepsilon > 0 \ \forall (v, p, R) \ uniformly C^3 \ solution to Euler-Reynolds with <math>supp R \subset I \times \mathbb{T}^3$, and $\|R\|_0 \leqslant e_R$. Let $e(t) : \mathbb{R} \to \mathbb{R}^*$, s.t.

$$\frac{d}{dt}e^{\frac{1}{2}}(t) \in C^{\infty}$$

and $e(t) \geqslant Ke_R$ on a neighbourhood of $supp\ R$. $\exists (\mathbf{v}^*, \mathbf{p}^*, \mathbf{R}^*), \ \mathbf{v}^* = v + V, \ \mathbf{p}^* = p + P$. $supp(V, P, R) \subset supp\ I \times \mathbb{T}^3$, with $\|V\|_0 \lesssim e_R^{1/2}$, $\|P\|_0 \lesssim e_R$ and $\|\mathbf{R}^*\|_0 < \varepsilon \ \forall \varepsilon > 0$ by choosing arbitrarily big λ . $\left\|\int_{\mathbb{T}^3} |\mathbf{v}^*|^2 - \int_{\mathbb{T}^3} |v|^2 + e(t) dx\right\|_0 \leqslant \varepsilon$ (i.e. nice low frequency).

Proof.

$$\int_{\mathbb{T}^3} \left| \mathbf{v}^* \right|^2 - \left| \mathbf{v}^* \right|^2 = \int_{\mathbb{T}^3} |v + V|^2 - |v|^2 dx = \int_{\mathbb{T}^3} 2vV + V^2 dx$$

The cross term is the correction of high frequency and is small because v, V are almost orthogonal. Claim: $\int_{\mathbb{T}^3} |V|^2 2dx + \mathcal{O}(\lambda^{-1})$. Let $V^{\ell} = \nabla_j W^{j\ell}$, where $W^{j\ell} - \frac{1}{\lambda} e^{i\lambda \xi_I} (w_I^{j\ell})$.

$$\int vV = -\int \nabla_{j} v_{\ell} W_{I}^{i\ell} dx = \mathcal{O}(\lambda^{-1})$$
$$\int |V|^{2} dx = \sum_{I} \int V_{I} \overline{V}_{I} + \sum_{I \neq \overline{I}} \int V_{I} \cdot V_{J}$$

 $\sum_{J\neq \bar{I}} \int V_I \cdot V_J \text{ is small because for } \sum_{J\neq \bar{I}} \int e^{i\lambda_I + \lambda_J)} V_I V_J dx, \text{ since } \left\| \left| \nabla \xi_I + \nabla \xi_J \right|^{-1} \right\|_0 \leqslant A. \text{ If } \left| \nabla \xi \right|^{-1} \leqslant A \text{ failed.}$

$$e^{i\lambda\xi} = \frac{\nabla^a \xi_I \nabla_a \xi_J}{(i\lambda)|\nabla\xi|^2} \qquad \xi = \xi_I + \xi_J$$
$$= \sum_{J \neq \bar{I}} \int e^{i\lambda_I + \lambda_J} \frac{\nabla^a \xi}{|\nabla\xi|^2} V_I V_J dx$$
$$= \mathcal{O}(\lambda^{-1}) \qquad \text{by IBP}$$

$$\sum_{I} \int V^{I} \bar{V}_{I}, \qquad V_{I} = e^{i\lambda\xi_{I}} (V_{I}^{l} + \delta V_{I}^{\ell})$$

$$\int \delta_{jl} \sum_{I} V_{I}^{j} \bar{V}_{I}^{\ell} dx \quad \text{since } \sum_{I} V_{I}^{j} \bar{V}_{I}^{\ell} = -P_{0} \lambda^{j\ell} - R^{j\ell}$$

$$= \delta_{jl} \int (-P_{0} \delta^{j\ell} - R^{j\ell})$$

$$= \delta_{jl} \int (e(t) \frac{\delta^{j\ell}}{d} - \mathring{R}^{j\ell}) dx \quad \text{by choose } p_{0} = -\frac{e(t)}{d} - \frac{\delta_{ij} R^{j\ell}}{d}$$

Since $V_I^J \nabla_j V_J^\ell = (V_I)_j (\nabla^j V_j^I - \nabla_J^j) = -V_I \times (\nabla \times V_J)$. Define $(\nabla \times V_J)^c = \varepsilon^{cdf} \nabla_d V_{Jf}$. we notice that here:

$$\varepsilon^{abs} = -\varepsilon^{bac} = -\varepsilon^{cbs}$$

etc. And $\varepsilon^{123} = 1$,

$$\varepsilon^{\ell j c} \varepsilon^{c d f} = \delta_d^\ell \delta_f^j - \delta_f^\ell \delta_d^j$$

We find it anti-symmetric in ℓj and df. Proof:

$$\varepsilon^{12c}\varepsilon^{cdf} = \begin{cases} 0 & \text{if } df \notin \{(12)or(21)\} \\ 1 & \text{if } df = (12) \\ -1 & \text{if } df = (21) \end{cases} = \delta_d^\ell \delta_f^j - \delta_f^\ell \delta_d^j$$

$$V_{I} \times \nabla \times V_{J} = \varepsilon^{\ell j c} (V_{I})_{j} (\nabla \times V_{J})_{c}$$

$$= \varepsilon^{\ell j c} (V_{I})_{j} \varepsilon^{c d f} \nabla^{d} V_{j}^{f}$$

$$= (\delta_{d}^{\ell} \delta_{f}^{j} - \delta_{f}^{\ell} \delta_{d}^{j}) (V_{I})_{j} \nabla^{d} V_{J}^{\ell}$$

$$= (V_{I})_{j} \nabla^{\ell} V_{J}^{j} - (V_{I})_{j} \nabla^{j} V_{J}^{\ell}$$

$$= (V_{I})_{j} (\nabla^{\ell} V_{J}^{j} 0 \nabla^{j} V_{J}^{\ell})$$

Lemma 4.6. (Main Lemma) $\exists k \geq 1 \ \exists C \geq 1 \ s.t. \ \forall \varepsilon > 0, \ \forall (v, p, R) \ uniform \ C^1 \ Euler-Reynolds flow with <math>supp \ R \subset I \times \mathbb{T}^3, \ \|R\|_0 \leqslant e_R.$ For any $e(t) \ \mathbb{R}^* \to \mathbb{R}^+$

- $e^{1/2}(t)$ is C_s^{∞}
- $e(t) \geqslant Ke_R$ on a neighbourhood of I.

 $\exists (\mathbf{v}^*, \mathbf{p}^*, \mathbf{R}^*), \ where \ \mathbf{v}^* = v + V, \ \mathbf{p}^* = p + P, \ \|R\|_0 < \varepsilon \ supp(v, p, R) \subset supp I \times \mathbb{T}^d$

Proof.

$$\left\| \int \left| v \right|^* dx - \int (|v|^2 + e(t)) dx \right\|_0 \le \varepsilon$$

$$\int |v|^2 dx = \int \sum_{I} V_I \bar{V}_I + \sum_{I \neq \bar{I}} V_J \cdot V_I$$

Since $V_I = e^{i\lambda\xi_I}(V_I + \delta V_I) = e^{i\lambda\xi_I}\tilde{V}_I$,

$$\sum_{I \neq \bar{I}} \int e^{i\lambda(\xi_I + \xi_J)} \tilde{V}_I \cdot \tilde{V}_J dx \quad \text{not exactly } \tilde{V}_I \cdot \tilde{V}_J)$$

$$\int \nabla_a e^{i\lambda(\xi_a+\xi_J)} \frac{\nabla^a \xi_I + \nabla^a \xi_J}{\left|\nabla^a \xi_I + \nabla^a \xi_J\right|^2} \tilde{V}_I \tilde{V}_J dx$$

They are oscillations in orthogonal direction, thus integral by parts gives cancellation. Set (v, p, R) = (0, 0, 0)Let $e^{1/2}(t)$ be a function smooth and supported in a simple connected area, and apply lemma 4.6 with $\varepsilon_{(1)} = e_R(1) = \frac{1}{10k} ||e^{1/2}||_0^2$.

$$\dots \leqslant \varepsilon_{(2)} \leqslant \varepsilon_{(1)} \leqslant \varepsilon_{(0)}.$$

By choosing the lifting function to have larger L^{∞} norm and smaller support. Then $||R_{(k)}|| \leq e_{R,(k)} \leq \varepsilon_{(k)} \searrow 0$ rapidly. $||v_{(k)}||_0 \leq Ce_{R,(k)}^{1/2} \searrow 0$ rapidly. $||P_{(k)}|| \leq Ce_{R,(k)} \searrow 0$ rapidly. Thus $\sum_k v_{(k)}^{\ell}$ converges to some solution v^{ℓ} and $\sum_k P_{(k)}$ converge to some P. And since $||R_{(k)}||_0 \searrow 0$ (v,p) is a weak solution to Euler

$$\begin{array}{ll} \partial_t v^\ell + \nabla_j (v^j v^\ell) + \nabla^\ell p = & \nabla_j R^{j\ell} \\ \nabla_j v^j &= 0 \end{array} \tag{12}$$

$$\int |v_k|^2 - |v_{(k-1)}|^2 (t, x) dx \ge \int e(k)(t) dx - e(0)$$

Choose $e_{(k)} < \frac{1}{2} \int e_k(0) dx$

$$\int |v_k|^2 - |v_{(k-1)}|^2(0, x)dx \geqslant \frac{1}{2} \int e_k(0)dx \ge 0,$$

by assumption. Thus the continuous solution we found was nontrivial and compactly supported.

We have a To-Do list: For non-stationary phase

$$\nabla_{j}Q^{j\ell} = u_{j}^{\ell} = e^{i\lambda\xi}u_{j}^{\ell} \quad \left\| |\nabla\xi|^{-1} \right\|_{0} \le A, \quad \int u^{\ell}dx = 0$$

$$\exists Q^{j\ell} = Q^{\ell j}, \quad \|Q\|_{0} \le \lambda^{-1} \|u\|_{0} + \mathcal{O}_{a,\nabla\xi}(\lambda^{-2})$$

- 1. How to solve $\sum_I V_I^j \bar{V}_I^\ell = e(t) \delta^{j\ell}/d \mathbf{R}^{oj\ell}$
- 2. How to ensure $\left\| \left| \nabla \xi \right|^{-1} \right\|_0$, $\left\| \left(\nabla \xi_I \cdot \nabla \xi_J \right)^{-1} \right\|_0 \leqslant A$ with $J \neq \bar{I}$ that interact and $\left\| \left| \nabla \xi_I \right| 1 \right\|_0 \lesssim b$ small.

Suppose
$$u^{\ell} = e^{i\lambda\xi}u^{\ell} \left\| \left| \nabla \xi \right|^{-1} \right\|_{0} \le A \int u^{\ell} dx = 0.$$

(Pair symmetric) From a solution of the form

$$Q^{j\ell} = \frac{e^{i\lambda\xi}}{i\lambda} q_{(1)}^{j\ell} + \tilde{Q}_{(1)}^{j\ell}$$

Take ∇ ,

$$\nabla_j Q^{j\ell} = e^{j\lambda\xi} \nabla_j \xi q_{(1)}^{j\ell} + \frac{e^{i\lambda\xi} \nabla_j q_{(1)}^{j\ell}}{i\lambda} + \nabla_j \tilde{Q}_{(1)}^{j\ell}.$$

Choose $q_{(1)}^{j\ell}$ s.t.

$$\nabla_j \xi q_{(1)}^{j\ell} = u^{\ell}$$

Choose correction $\tilde{Q}_{(1)}^{j\ell}$ s.t.

$$\nabla_j \tilde{Q}_{(1)}^{j\ell} = e^{i\lambda\xi} \left(\frac{-\nabla q_{(1)}^{j\ell}}{i\lambda} \right) = \nabla_j \left(\frac{e^{i\lambda\xi} q_{(1)}^{j\ell}}{i\lambda} \right) - e^{i\lambda\xi} u^\ell - u^\ell, \text{ with integral } 0$$

How to solve $\nabla_j \xi q_{(1)}^{j\ell} = u^\ell$. If we did not need q be symmetric, i.e. $q_{(1)}^{j\ell} = q_{(1)}^{\ell j}$ could use $q_{(1)}^{j\ell} = \frac{\nabla^j \xi u^\ell}{|\nabla \xi|^2}$.

Decomposing $u^{\ell} = u^{\ell}_{\perp} + u^{\ell}_{\parallel} = u^{\ell}_{\perp} + \frac{(u \cdot \nabla \xi) \cdot \nabla^{\ell} \xi}{|\nabla \xi|^{2}}$. Choose $q_{(1)}^{j\ell} = \frac{1}{|\nabla \xi|^{2}} (\nabla^{j} \xi u^{\ell}_{\perp} + \nabla^{\ell} \xi u^{j}_{\perp}) + \frac{(u \cdot \nabla \xi)^{2}}{|\nabla \xi|^{2}} \delta^{j\ell}$. Check that $\nabla_{j} \xi q_{(1)} = u^{\ell}_{\perp} + 0 + u^{\ell}_{\parallel} = u^{\ell}$. This equation is

$$q_{(1)}^{j\ell} = q_a^{(jl)}(\nabla \xi)u^a$$

$$q_a^{j\ell}(\alpha p) = \alpha^{-1}q^{j\ell}(p)$$
 Homogeneous

As for solving $\nabla_j \tilde{Q}_{(1)}^{j\ell} = e^{i\lambda\xi} \frac{\nabla_j q_{(1)}^{i\ell}}{i\lambda}$, $\left\| \tilde{Q} \right\|_0 \lesssim \frac{1}{\lambda}$. $\left\| \tilde{Q}_{(1)}^{j\ell} = e^{i\lambda\xi} u_{(2)}^{\ell}$. By induction, $\tilde{Q}^{j\ell} = \frac{e^{i\lambda\xi}}{i\lambda} q_{(2)}^{j\ell} + \tilde{Q}_{(2)}^{j\ell}$, $q_{(2)}^{j\ell} = q_{(a)}^{j\ell}(\nabla \xi)u_{(2)}^a$

$$\nabla_j \tilde{Q}_{(1)}^{j\ell} = -e^{i\lambda\xi} \frac{\nabla_j q_{(2)}^{j\ell}}{(i\lambda)}$$

gives $\mathcal{O}(\lambda^{-2})$ at the cost of one more derivative.

If we didn't require that $\tilde{Q}^{j\ell} = \tilde{Q}^{\ell j}$, $\nabla_j \tilde{Q}^{j\ell}_{(2)} = u^\ell_{(2)}$, $\tilde{Q}^{j\ell}_{(2)} = \mathbb{P}_{I_0} u_{(2)}^2$. Instead we decompose $u^\ell_{(2)} = \mathcal{H} u^\ell + \nabla^\ell$ (divergence free $+ \nabla^\ell \nabla^{-1} \nabla_a u^a$ gradient part, so $\nabla_\ell H u^\ell = 0$.

$$\begin{split} \tilde{Q}_{(2)}^{j\ell} &= \Delta^{-1}(\nabla^j \mathcal{H} u^\ell + \nabla^\ell \mathcal{H} u^j) + \Delta^{-1} \nabla_a u^a \delta^{j\ell} := R_a^{j\ell}[u_{(2)}^a] \\ & \left\| \tilde{Q}_{(2)} \right\|_0 \lesssim \left\| u_{(2)} \right\|_0. \end{split}$$

Since $\Delta^{-1}\nabla$ is an order -1 operator, it's bounded on C^0 . Check $\nabla_j \tilde{Q}_{(2)}^{j\ell} = \mathbb{P}_{I_0} \mathcal{H} u_{(2)}^{\ell} + 0 + \nabla^{\ell} \Delta^{-1} \nabla_a u_{(2)}^a = 0$ $\mathbb{P}_{I_0}u_{(2)}^{\ell}=u_{(2)}^{\ell}.$

To summarize $Q^{j\ell} = \sum_{k=1}^{2} \frac{e^{i\lambda\xi}}{i\lambda} q_{(k)}^{j\ell} + \tilde{Q}_{(2)}^{j\ell}, \ q_{(k)}^{j\ell} = q_{\alpha}^{j\ell}(\nabla\xi)u^{a}, \ q_{\alpha}^{j\ell}(\alpha p) = \alpha^{-1}q_{\alpha}^{j\ell}(p). \ \nabla_{j}\xi q_{(k)}^{j\ell} = u_{(k)}^{\ell}, \ u_{(1)}^{\ell} = -u_{(1)}^{\ell},$ $u_{(k+1)}^{\ell} = \frac{-\nabla_j q_{(k)}^{j\ell}}{(i\lambda)}$

Proof. Error term

$$\begin{split} &\nabla_{j}(V^{j}V^{\ell} + p\delta^{j\ell} + R^{j\ell}) \\ &= \nabla_{j}(\sum_{I} V_{I}^{j}V_{I}^{\ell} + p\delta^{j\ell} + R^{j\ell}) \\ &= \nabla_{j}(\sum_{I} \tilde{V}_{I}^{j}\tilde{V}_{I}^{\ell} + p\delta^{j\ell} + R^{j\ell}) \\ &= \nabla_{j}(\sum_{I} V_{I}^{j}V_{I}^{\ell} + p\delta^{j\ell} + R^{j\ell}) \\ &= \nabla_{j}(\sum_{I} V_{I}^{j}V_{I}^{\ell} + p\delta^{j\ell} + R^{j\ell} + \mathcal{O}(\delta V_{I}V_{I}) + \ldots) \\ &= \nabla_{j}((\sum_{I} V_{I}^{j}V_{I}^{\ell} + p\delta^{j\ell} + R^{j\ell}) + (\underline{R^{j\ell} - R^{j\ell}_{\varepsilon}}) + \mathcal{O}(\delta V_{I}\bar{V}_{I})) \end{split}$$

small because low frequency concels. small with small ε

$$\begin{split} \sum W_I \bar{V}_I^\ell + p_0 \delta^{j\ell} + R_\varepsilon^{j\ell} &= 0 \\ \partial_t V^\ell + \nabla_j (v^j v^\ell) + \nabla^\ell p &= \nabla_j R^{j\ell} \\ \partial_t \mathbf{v}^{*\ell} + \nabla_j (\mathbf{v}^j \mathbf{v}^\ell) + \nabla^\ell \mathbf{p} &= \nabla_j E^{j\ell} + \text{linear term}(\mathbf{v}) + \nabla_j (v v^\ell) + \nabla^\ell p \end{split}$$

 $^{^{2}}I_{0}$ means integral 0.

Since $V_I^{\ell} = e^{i\lambda\xi_I}(V_I^{\ell} + \delta V_I^{\ell}),$

$$\nabla_{j} \left(\sum W_{I} \bar{V}_{I}^{\ell} + p_{0} \delta^{j\ell} + R_{\varepsilon}^{j\ell} \right) = \sum_{I} V_{I}^{j} \bar{V}_{I}^{\ell} + p_{0} \delta^{j\ell} + R_{\varepsilon}^{j\ell} - (R^{\ell} - R_{\varepsilon}^{j\ell}) + \mathcal{O}(\delta V_{I})$$

$$\sum_{I} V_{I}^{j} \bar{V}_{\Xi}^{\ell} e(t) \frac{\delta^{j\ell}}{d} - R_{\varepsilon}^{oj\ell}^{3} \quad \text{(Must be positive definite)}$$
(13)

Because $p_0 = \frac{e(t)}{d} - \frac{\operatorname{tr} R_{\varepsilon}}{d}$

$$\int \left| \mathbf{v} \right|^2 - |v|^2 dx = \int e(t) dx + \mathcal{O}(\lambda^{-1})$$

 $e(t) \geqslant Ke_R$ on supp R_{ε} . We make a choice of K later. Then we localize and renormalize it by choosing,

$$\eta_{K_0}(t) = \eta(\frac{t - K_0 t}{\tau}),$$

au is the time cut off and $\sum_{K_0} \eta_{K_0}^2(t) = 1$. (Start with $\tilde{\eta}(t) \geq 1$ on $[-\frac{2}{3}, \frac{2}{3}]$ and $\tilde{\eta}(t) \geq 0$ and $\tilde{\eta}($

 $\eta := \frac{\tilde{\eta}(t)}{(\sum\limits_{K \in \mathbb{Z}} \tilde{\eta}(t - K_0)^2)^{1/2}}.$ Thus $\eta^2 := \frac{\tilde{\eta}(t)^2}{(\sum\limits_{K \in \mathbb{Z}} \tilde{\eta}(t - K_0)^2)} = 1$ gives us a partition of unity. Let's localize (13)

RHS =
$$\sum_{K_0} \eta_{K_0}^2(t) (t(t) \frac{\delta^{j\ell}}{d} - R_{\varepsilon}^{j\ell})$$

Let's write $V_I^{\ell} = \eta_{K_0} V_I^{o\ell}$ and $I \in \mathbb{I}(K_0)$ if V_I is positive at time $K_0 \tau$. so

$$LHS = \sum_{K_0} \eta_{K_0}^2 \sum_{I \in \mathbb{I}(K_0)} \overset{o \ j \ \bar{o} \ \ell}{\mathbf{V}} \overset{V}{\mathbf{V}_I}.$$

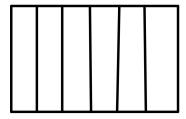
So it's sufficient to solve

$$\sum_{I \in \mathbb{I}(K_0)} \overset{o}{\mathbf{V}} \overset{\bar{o}}{\mathbf{V}} \overset{\ell}{\mathbf{V}}_I = e(t) \frac{\delta^{j\ell}}{d} - \overset{o}{\mathbf{R}}_{\varepsilon}^{j\ell}$$

on every time slice. η_{K_0} only lives for $t \sim \tau$.

Cut off the space.

I need $\left|\nabla\hat{\xi}_{I}\right|=1$ at initial time.



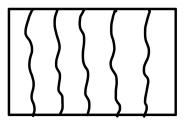


Figure 3: Initial and later phase function

At t=0 Assume $\begin{cases} \nabla \hat{\xi}_I \in \{e_1,e_2,e_3\} \\ \hat{\xi}_I(t(I),x)=e_1 \cdot x \end{cases}$ is smooth enough. $e^{i\lambda \xi(t,x)} \ \lambda \in 2\pi \mathbb{Z}$ and $e^{i\lambda(\xi_I+\xi_J)}$ with $\left\| |\nabla \xi_I + \nabla x i_j|^{-1} \right\|_{C^0} \leqslant A$. Let Ψ_I be spacial cut off. Write $v_I^\ell = \eta_{k_0} \mathring{v}_I^\ell = \eta_{k_0} \Psi_I \mathring{v}_I^\ell$, where $\eta_{k_0} \mathring{v}_I^\ell$ is the active part. Also $\sum_{I \in \mathcal{I}(k_0)} = 1$.

³trace-free

The space cut off is depending on time $\sum_{I \in \mathcal{I}(k_0)} \mathring{v}_I^j \bar{v}_I^\ell = e(\xi) \frac{\delta^{j\ell}}{d} - \mathring{R}_{\varepsilon}^{j\ell}$ on time slice.

$$\sum_{I \in \mathcal{I}(k_0)} \Psi_I^2 \mathring{v}_I^j \mathring{v}_I^\ell = \sum_{I \in \mathcal{I}(k_0)} \Psi_I^2(e(t) \frac{\delta^{j\ell}}{d} - \mathring{R}_{\varepsilon}^{j\ell})$$

$$\Psi_I(t(I), x) = \Psi(k_0 \tau, x)$$

$$\sum_{K \in (\mathbb{Z}/2\mathbb{Z})^3} \Psi(k_0 t, x) = 1$$

Partition of unit is also transported

$$(\partial_t + v \cdot \nabla)\Psi_I(t, x) = 0$$
$$\sum_{K \in (\mathbb{Z}/2\mathbb{Z})^3} \Psi^2 = 1$$

by uniqueness.

Apply the cut off
$$\Psi_I^2(\sum_{I \in \mathbb{I}(K)} \mathring{v}^j \bar{\mathring{v}}_I^J) = \Psi_I^2(e(t) \frac{\delta^{j\ell}}{d} - \mathring{R}_{\varepsilon}^{j\ell})$$

$$v_I^{\ell} = \eta_{t_0}(t)\Psi_I(t,x)\mathring{v}_I^{\ell}$$

where I = (K, f) =(time, direction of oscillation), $K \in \mathbb{Z} \times (\mathbb{Z}/2\mathbb{Z})^3$ location index. Reason that we can use partition of unity: Homogeneous in amplitude.

$$v_I^{\ell} = \eta_{K_0} \Psi_I e^{1/2}(t) \mathring{v}_I^{\ell}$$

LHS
$$\sum_{I} e(t) \mathring{v}^{I} \bar{\mathring{v}}_{I}^{\ell} = e(t) \frac{\delta^{j\ell}}{d} - \mathring{R}_{\varepsilon}^{j\ell}$$
. On supp R_{ε} , $e(t) > Ke_{R} > 0$

$$\sum_{I} \mathring{v}_{I}^{j} \bar{\mathring{v}}_{I}^{\ell} = \frac{\delta^{j\ell}}{d} - \frac{\mathring{R}^{j\ell}}{e(t)} = \frac{\delta^{j\ell}}{d} + \varepsilon^{j\ell}$$

where $\frac{\delta^{j\ell}}{d}$ is the dominated term.

$$\sum_{I} \mathring{v}_{I}^{j} \bar{\mathring{v}}_{I}^{\ell} = \frac{\delta^{j\ell}}{d} + \varepsilon^{j\ell} \qquad \varepsilon = \mathcal{O}(\frac{1}{K})$$

$$\sum_{I} \mathring{v}_{I}^{j} \bar{\mathring{v}}_{I}^{\ell} = \frac{\delta^{j\ell}}{d} - \varepsilon^{j\ell}$$
(14)

What we know about v_I ?

1.
$$v_I^{\ell} \cdot \xi_I = 0$$

2.
$$(i\nabla \xi_I) \times V_I = |\nabla \xi_I| v_I$$

$$\mathring{b}_I \in <\nabla \xi_I>^\perp$$

$$\mathring{a}_I = -\frac{\nabla \xi_I}{|\xi_I|} \times b_I \Leftarrow \text{rotation in plane } <\nabla \xi>^\perp$$

Thus $(14) = \sum_{I} (\mathring{a}_{I} + i\mathring{b}_{I}^{j})(\mathring{a}_{I}^{\ell} - i\mathring{b}_{I}^{\ell}) = 2\sum_{I} (a_{I}^{j}\mathring{a}_{I}^{\ell} + \mathring{b}_{I}^{j}b_{I}^{\ell}) = \sum_{I} (\delta^{j\ell} - \frac{\nabla^{j}\xi_{I}\nabla^{d}\xi_{I}}{|\nabla\xi_{I}|^{2}} \cdot \left|\mathring{b}_{I}\right|^{2}$, is true because the imaginary part cancels. $(\frac{\mathring{a}_{I}}{|\mathring{b}_{I}|}, \frac{\mathring{b}_{I}}{|\nabla\xi_{I}|}, \frac{\nabla^{l}\xi_{I}}{|\nabla\xi_{I}|})$ are orthogonal frame. Thus the identity

$$\delta^{j\ell} = \frac{\mathring{a}_I^{j\ell} \mathring{a}_I^{\ell}}{\left|\mathring{b}_I\right|^2} + \frac{\mathring{b}_I^{j\ell} \mathring{b}_I^{\ell}}{\left|\mathring{b}_I\right|^2} + \frac{\nabla^j \xi_I \nabla^{\ell} \xi_I}{\left|\nabla \xi_I\right|^2} \tag{15}$$

by renormalization. Choose $\mathring{b}_{I}^{\ell} = \gamma_{I} \mathbb{P}_{I}^{\perp}(\nabla \xi_{\sigma_{I}}) = \gamma_{I}(\nabla^{\ell} \xi_{I} - \frac{(\nabla \xi_{\sigma_{I}} \nabla \xi_{I}) \nabla^{\ell} \xi_{I}}{|\nabla \xi_{I}|^{2}})$, since $\nabla \xi_{\sigma_{I}}$ is not parallel to $\nabla \xi_{\sigma_{I}}$.

$$\left| \mathring{b}_{I} \right|^{2} = \gamma_{I}^{2} \left(\left| \nabla \xi_{\sigma_{I}} \right|^{2} - 2 \frac{\left(\nabla \xi_{\sigma_{I}} \cdot \nabla \xi_{I} \right)^{2}}{\left| \nabla \xi_{I} \right|^{2}} + \frac{\left(\nabla \xi_{\sigma_{I}} \cdot \nabla \xi_{I} \right)^{2}}{\left| \nabla \xi_{I} \right|^{2}} \right)$$

$$= \gamma_{I}^{2} \left(\frac{\left| \nabla \xi_{\sigma_{I}} \right|^{2} \left| \nabla \xi_{I} \right|^{2} - \left(\nabla \xi_{\gamma_{I}} \nabla \xi_{I} \right)^{2}}{\left| \nabla \xi_{I} \right|^{2}} \right)$$

$$= \gamma_{I}^{2} \left(\frac{\left| \nabla \xi_{\sigma_{I}} \wedge \nabla \xi_{\sigma_{I}} \right|^{2}}{\left| \nabla \xi_{I} \right|^{2}} \right)$$

$$(16)$$

$$\sum_{I} \gamma_{I}^{2} \frac{\left|\nabla \xi_{\sigma_{I}} \wedge \nabla \xi_{I}\right|^{2}}{\left|\nabla \xi_{I}\right|^{2}} \left(\delta^{j\ell} - \frac{\nabla^{j} \xi_{I} \nabla^{\ell} \xi_{I}}{\left|\nabla \xi_{I}\right|^{2}}\right) = \frac{\delta^{j\ell}}{d} + \varepsilon^{j\ell}$$

where $(\nabla \xi_I^{\perp})^{j\ell}$.

$$\sum \gamma_I^2 \frac{\left|\nabla \xi_{\sigma_I} \wedge \nabla \xi_{\sigma_I}\right|^2}{\left|\nabla \xi_I\right|^2} (\nabla \xi_I^\perp)^{j\ell} \nabla_J \xi_J \nabla_\ell \xi_J = \frac{\left|\nabla \xi_J\right|^2}{d} + \varepsilon^{j\ell} \nabla_J \xi_J \nabla_\ell \xi_J$$

Plug (16), (15) back in

$$\sum_{I} \gamma_{I}^{2} A(\nabla \xi)_{J}^{I} = \frac{|\nabla \xi_{J}|^{2}}{d} + \varepsilon^{j\ell} \nabla_{J} \xi_{J} \nabla_{\ell} \xi_{J}$$

We need 12 waves in 6 direction and their conjugate. Letting $I = (k, f) \in \mathbb{Z} \times (\mathbb{Z}/\mathbb{Z}\tau)^3 \times \mathbb{F}$, F are the faces of regular dodecahedron.

$$\sum_{I \in K \times \mathbb{F}} \gamma_I^2 A(\nabla \xi_J^I) = \frac{\left| \nabla \xi_J \right|^2}{2d} + \varepsilon^{j\ell} \frac{\nabla_j \xi_J \nabla \xi_\ell \xi_J}{2}$$

 $\exists \ c > 0, \text{ s.t. } \left\| A_J^T - A(\nabla \hat{xi}_J^I \right\| \leqslant C, \ \left\| \xi_J - \frac{|\nabla \xi_J|^2}{2d} \right\| \leqslant C. \text{ The equation } \sum_{I \in \mathbb{F}} A_J^I \gamma_I^2 = y_I \text{ has a solution } \gamma_I = \gamma_f(A_J^I, y_I) \text{ depending smoothly with uniform bounds on } \partial_A \gamma_F \text{ and } \gamma_y \gamma_f \text{ and higher derivative.}$

$$\sum_{I} A(\nabla \xi)_{J}^{I} \gamma_{I}^{2} = \frac{|\nabla \xi_{I}|^{2}}{2d} + \varepsilon^{j\ell} \nabla_{J} \xi_{J} \nabla_{J} \xi_{J}$$

where $\varepsilon^{j\ell} \sim \mathcal{O}(\frac{1}{k})$.

Proof. (inverse function theorem) Rewrite as $F(\gamma, A, y) = 0$, $F_J(\gamma, A, y) = \sum_I A_J^I \gamma_I^2 - y_J$. It is sufficient to check that $\frac{\partial F_J}{\partial \gamma_\gamma}(?)$ is invertible.

$$\gamma_I, A_J^T, y_J) = (\hat{\gamma_f}, A(\nabla \hat{\xi})_J^I, \frac{|\nabla \xi_J|^2}{2d})$$

If h_I is in the null space at this point

$$\frac{\partial f_J}{\partial \gamma} H_I = 2A(\nabla \hat{\xi})_J^I \hat{\gamma}_I h_I = 0 \quad \Rightarrow \quad \hat{\gamma}_I h_I = 0 \quad \forall I$$

since $A(\nabla \hat{\xi})^I$ is invertible. $\Rightarrow h_I = 0 \ \forall I \text{ since } \hat{\gamma}_I \neq 0 \ \forall I$.

$$\begin{split} V_{I} &= e^{i\lambda\xi_{I}}(v_{I}^{\ell} + \delta v_{I}^{\ell}) \\ I_{M}(V_{I}) &= \eta_{K_{0}}(t)\Psi_{I}e^{1/2}(t)(\gamma_{I}P_{I}^{\perp}(\delta\xi_{\sigma_{I}})) \\ R_{\ell}v_{I} &= -\frac{\nabla\xi_{I}}{|\nabla\xi_{I}|} \times I_{m}V_{I} \\ \|V_{I}\|_{0}) \leqslant \|\eta\|\|\Psi\| \|e^{1/2}\|\|\gamma_{I}\|\|\nabla\xi_{\sigma_{I}}\| \end{split}$$

$$\begin{split} \sum_{K_0} \eta_{K_0}^2(t) &= 1 \qquad e(t) \geqslant K e_R \\ \sum_{I} \gamma_I^2 \frac{\left|\nabla \xi_I \wedge \nabla \xi_{\sigma_I}\right|^2}{\left|\nabla \xi_I\right|^2} \left(\delta^{j\ell} - \frac{\nabla^j \xi_I \nabla^\ell \xi_I}{\left|\nabla \xi_I\right|^2}\right) &= \frac{\delta^{j\ell}}{d} + \varepsilon^{j\ell} \end{split}$$

where
$$\varepsilon^{j\ell} = \frac{-\mathring{R}_{\varepsilon}^{j\ell}}{e(t)}$$
.

Introduce Frequency Energy levels

Let $\Sigma \geqslant 2$ $e_v > e_R > 0$, $L \ge 1$. Say $(v, p, R) \leqslant (\Sigma, e_v, e_R)$ if

$$\|\nabla_{\overleftarrow{a}}v\|_o\leqslant \Sigma^{\left|\overrightarrow{a}\right|}e_v^{1/2}\quad 1\leqslant |\overrightarrow{a}|\leqslant L$$

$$\|\nabla_{\overleftarrow{a}} R\|_{o} \leqslant \Sigma^{|\overrightarrow{a}|} e_{R}$$

we always begin with Renyolds flow from previous stage. $||v||_0$ close to/converge to real solutions.

$$\|\nabla \check{V}\|_{0} = \|\nabla V\|_{0} + \|\nabla V\|_{0}$$

The correction $\|V\|_0 \lesssim e_R^{1/2}$, $\|\nabla v\|_0 \lesssim \lambda e^{1/2}$ from the previous stage. $\|\nabla v\| \to \Sigma e_v^{1/2}$. Taking derivative cost a factor if Σ .

Lemma 4.7. (Practice main lemma) $\exists \ \hat{c} \geqslant 1$ such that the following holds. If $(v, p, R) \leqslant (\Sigma, e_v, e_R)$ if $N \geqslant (\frac{e_v}{e_R}) \ \exists (\check{v}, \check{p}, \check{R}) \leqslant (\check{\Sigma}, \check{e_v}, \check{e_R})$. Here we want \check{e}_R as small as possible and $\check{v} = v + V \ \check{p} + P$

$$\begin{split} \|v\|_0 \leqslant \hat{c}e_R^{1/2} & \quad \|p\|_0 \leqslant ce_R \end{split}$$

$$\|\nabla v\| \leqslant c(N\Sigma)e_R^{1/2} & \quad \|\nabla P\|_0 \leqslant c(N\Sigma)e_R$$

How big is \check{e}_R ?

1. High-Low interaction term

$$\nabla_j R_L^{j\ell} = \nabla_j (v^j v^\ell) = v^j \nabla_j v^\ell = \Sigma_I e^{i\lambda \xi_I} \tilde{v}_I^j \nabla_j v^\ell$$

Non-stationary phase

$$||R_L||_0 \lesssim \frac{1}{\lambda} ||v||_0 ||\nabla v||_0 \leqslant (N\Sigma)^{-1} e_R^{1/2} (\Sigma e_v^{1/2}) = \frac{e_v^{1/2} e_R^{1/2}}{N}$$

We hope that $\check{e}_R = \frac{e_v^{1/2} e_R^{1/2}}{N}$

2. transport $\nabla_j R_T^{j\ell} = \partial_t v^\ell + \nabla_j (v^j v^\ell) = (\partial_t + v^j \nabla_j (v^j v^\ell) = (\partial_t + v^j \nabla_j) v^\ell$

$$||R_T||_0 \le \lambda^{-1} ||v||_0 ||\nabla v_1||_0 \le (N\Sigma)^{-1} \cdot 1 \cdot \Sigma e_R^{1/2} = N^{-1} e^{1/2}$$

where $R_T^{j\ell} = \sum_I \frac{e^{i\lambda\xi_I}}{i\lambda} q_a^{j\ell}(\nabla\xi_I) D_t V_1$. In the result we missing $e_v^{1/2}$ which make this even worse to $\frac{1}{3+\sqrt{8}}$.

To optimizing, we keep the transport term.

$$||R_T||_0 \lesssim \lambda^{-1} ||(\partial_t + v^j \nabla_j) V_I||_0 = (N\Sigma)^{-1} (||D_t||) e_R^{1/2}$$
$$(\partial_t + v^i \nabla_i) \xi_I = 0$$
$$(\partial_t + v^i \nabla_i) \nabla_a \xi_I = -\nabla_a v^i \nabla_i \xi \sim \Sigma e_v^{1/2} \cdot 1$$

The result $\left\|R_T\right\|_0 = \frac{e_v^{1/2}e_R^{1/2}}{N}$ is ideal

$$\sum_{I} v_{I}^{j} v_{I}^{\ell} = e(t) \frac{\delta^{j\ell}}{d} - \mathring{R}_{\varepsilon}^{j\ell}$$

And more for frequency level:

$$\|\nabla_{\overrightarrow{a}}(\partial_t + v\nabla)R\|_0 \leqslant \Sigma^{|\overrightarrow{a}|+1}e_v^{1/2}e_R \quad 0 \leqslant |\overrightarrow{a}| \leqslant L - 1$$

better for space derivative.

Actual Frequency Levels

References

- [1] Peter Constantin, Edriss S Titi, and F Weinan. Onsager's conjecture on the energy conservation for solutions of euler's equation. *Communications in Mathematical Physics*, 165(1):207, 1994.
- [2] Camillo De Lellis and László Székelyhidi Jr. Continuous dissipative euler flows and a conjecture of onsager. In European Congress of Mathematics, pages 13–29. Eur. Math. Soc. Zürich, 2013.
- [3] Jean Duchon and Raoul Robert. Inertial energy dissipation for weak solutions of incompressible euler and navier-stokes equations. *Nonlinearity*, 13(1):249, 2000.
- [4] Gregory L Eyink and Katepalli R Sreenivasan. Onsager and the theory of hydrodynamic turbulence. Reviews of modern physics, 78(1):87, 2006.
- [5] Eduard Feireisl, Piotr Gwiazda, Agnieszka Świerczewska-Gwiazda, and Emil Wiedemann. Dissipative measure-valued solutions to the compressible navier-stokes system. *Calculus of Variations and Partial Differential Equations*, 55(6):141, 2016.
- [6] Philip Isett. Hölder continuous Euler flows in three dimensions with compact support in time, volume 196. Princeton University Press, 2017.
- [7] Philip Isett. On the endpoint regularity in onsager's conjecture. arXiv preprint arXiv:1706.01549, 2017.
- [8] Philip Isett. A proof of onsager's conjecture. Annals of Mathematics, 188(3):871–963, 2018.
- [9] Philip Isett and Sung-Jin Oh. A heat flow approach to onsager's conjecture for the euler equations on manifolds. *Transactions of the American Mathematical Society*, 368(9):6519–6537, 2016.
- [10] Philip James Isett et al. Hölder continuous euler flows with compact support in time. 2013.
- [11] Charles Meneveau, KR Sreenivasan, P Kailasnath, and MS Fan. Joint multifractal measures: Theory and applications to turbulence. *Physical Review A*, 41(2):894, 1990.
- [12] Vladimir Scheffer. An inviscid flow with compact support in space-time. The Journal of Geometric Analysis, 3(4):343–401, 1993.
- [13] Alexander Shnirelman. On the nonuniqueness of weak solution of the euler equation. Communications on Pure and Applied Mathematics: A Journal Issued by the Courant Institute of Mathematical Sciences, 50(12):1261–1286, 1997.