

layers

February 2, 2023

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[ ]: # %load layers.py
import numpy as np
import pdb

def affine_forward(x, w, b):
    """
    Computes the forward pass for an affine (fully-connected) layer.

    The input x has shape (N, d_1, ..., d_k) and contains a minibatch of N
    examples, where each example x[i] has shape (d_1, ..., d_k). We will
    reshape each input into a vector of dimension D = d_1 * ... * d_k, and
    then transform it to an output vector of dimension M.

    Inputs:
    - x: A numpy array containing input data, of shape (N, d_1, ..., d_k)
    - w: A numpy array of weights, of shape (D, M)
    - b: A numpy array of biases, of shape (M,)

    Returns a tuple of:
    - out: output, of shape (N, M)
    - cache: (x, w, b)
    """

    # ===== #
    # YOUR CODE HERE:
    # Calculate the output of the forward pass. Notice the dimensions
    # of w are D x M, which is the transpose of what we did in earlier
    # assignments.
    # ===== #
    num_inputs = x.shape[0]
    input_shape = x.shape[1:]
    input_size = np.prod(input_shape)
    x_reshape = x.reshape(num_inputs, input_size)
    out = np.dot(x_reshape, w) + b
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pass

# ===== #
# END YOUR CODE HERE
# ===== #

cache = (x, w, b)
return out, cache

def affine_backward(dout, cache):
    """
    Computes the backward pass for an affine layer.

    Inputs:
    - dout: Upstream derivative, of shape (N, M)
    - cache: Tuple of:
      - x: Input data, of shape (N, d_1, ..., d_k)
      - w: Weights, of shape (D, M)

    Returns a tuple of:
    - dx: Gradient with respect to x, of shape (N, d_1, ..., d_k)
    - dw: Gradient with respect to w, of shape (D, M)
    - db: Gradient with respect to b, of shape (M,)
    """
    x, w, b = cache
    dx, dw, db = None, None, None

    # ===== #
    # YOUR CODE HERE:
    # Calculate the gradients for the backward pass.
    # ===== #

    # dout is N x M
    # dx should be N x d1 x ... x dk; it relates to dout through multiplication
    # with w, which is D x M
    # dw should be D x M; it relates to dout through multiplication with x, which
    # is N x D after reshaping
    # db should be M; it is just the sum over dout examples
    num_inputs = x.shape[0]
    input_shape = x.shape[1:]
    input_size = np.prod(input_shape)
    x_reshape = x.reshape(num_inputs, input_size)
    x_shape = x.shape
    db = np.sum(dout, axis = 0)
    dx = np.dot(dout, w.T).reshape(x_shape)
    dw = np.dot(x_reshape.T, dout)

```

```

pass

# ===== #
# END YOUR CODE HERE
# ===== #

return dx, dw, db

def relu_forward(x):
    """
    Computes the forward pass for a layer of rectified linear units (ReLU).

    Input:
    - x: Inputs, of any shape

    Returns a tuple of:
    - out: Output, of the same shape as x
    - cache: x
    """
    # ===== #
    # YOUR CODE HERE:
    # Implement the ReLU forward pass.
    # ===== #
    out = np.maximum(x, 0)
    pass
    # ===== #
    # END YOUR CODE HERE
    # ===== #

    cache = x
    return out, cache

def relu_backward(dout, cache):
    """
    Computes the backward pass for a layer of rectified linear units (ReLU).

    Input:
    - dout: Upstream derivatives, of any shape
    - cache: Input x, of same shape as dout

    Returns:
    - dx: Gradient with respect to x
    """
    x = cache

    # ===== #

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# YOUR CODE HERE:
#   Implement the ReLU backward pass
# ===== #
x[x<0] = 0
x[x>0] = 1
dx = np.multiply(x,dout)
# ReLU directs linearly to those > 0
pass

# ===== #
# END YOUR CODE HERE
# ===== #

return dx

def softmax_loss(x, y):
    """
    Computes the loss and gradient for softmax classification.

    Inputs:
    - x: Input data, of shape (N, C) where x[i, j] is the score for the jth class
      for the ith input.
    - y: Vector of labels, of shape (N,) where y[i] is the label for x[i] and
      0 <= y[i] < C

    Returns a tuple of:
    - loss: Scalar giving the loss
    - dx: Gradient of the loss with respect to x
    """
    probs = np.exp(x - np.max(x, axis=1, keepdims=True))
    probs /= np.sum(probs, axis=1, keepdims=True)
    N = x.shape[0]
    loss = -np.sum(np.log(probs[np.arange(N), y])) / N
    dx = probs.copy()
    dx[np.arange(N), y] -= 1
    dx /= N
    return loss, dx

```