





"We were able to form a model to predict the personality of every single adult in the United States of America – 220 million people." – Alexander Nix, CEO Cambridge Analytica

"For a highly neurotic and conscientious audience, the threat of a burglary."

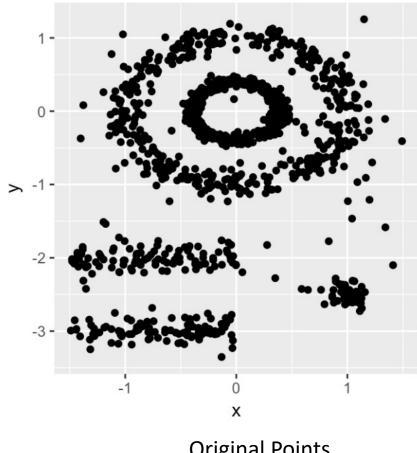


"Conversely, for a closed and agreeable audience. People who care about tradition, and habits, and family."

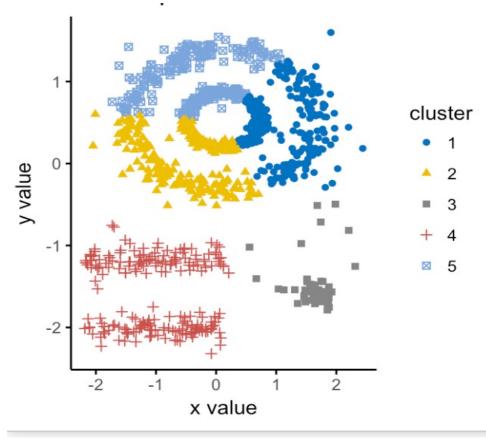


"The model of the voter as a bundle of psychological vulnerabilities to be carefully exploited reduces people to mathematical inputs." –Adrian Chen, *The New Yorker*

Density Based Clustering



Original Points



K-means, K=5

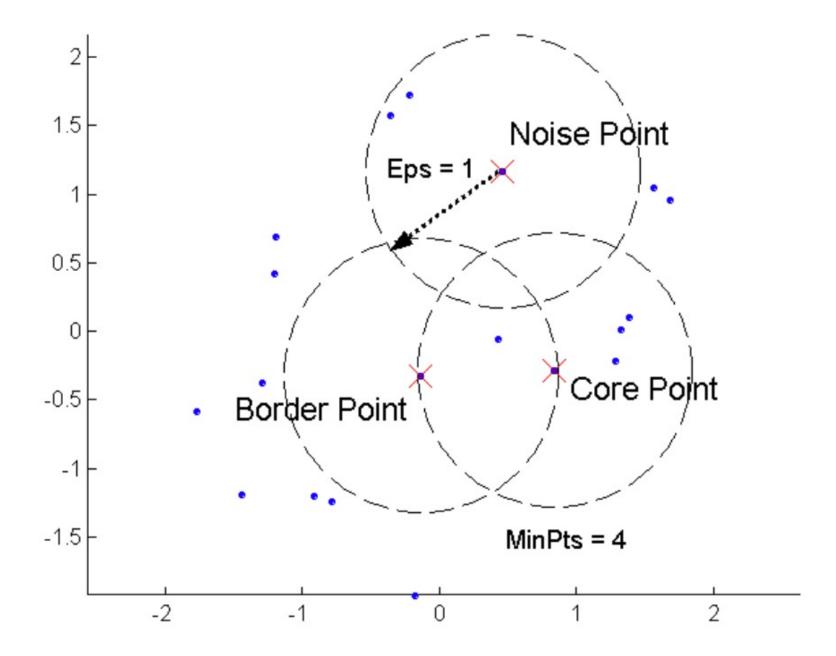
Density-Based Clustering

 Locates regions of high density that are separated by regions of low density

• Center-based density: density is calculated for a particular point in the data set by counting the number of points within a specified radius, Eps, of that point (the count includes the point itself).

Classifying Points

- Core points: Points in the interior of a dense region. If the number of points within Eps of this point meets a certain threshold, MinPts, this point is a core point.
- Border points: Points on the edge of a dense region. A point that is not a core point, but falls within the neighborhood (within Eps) of a core point.
- **Noise points**: Points in sparse regions. Any point that is neither a core point, nor a border point.



DBSCAN Algorithm

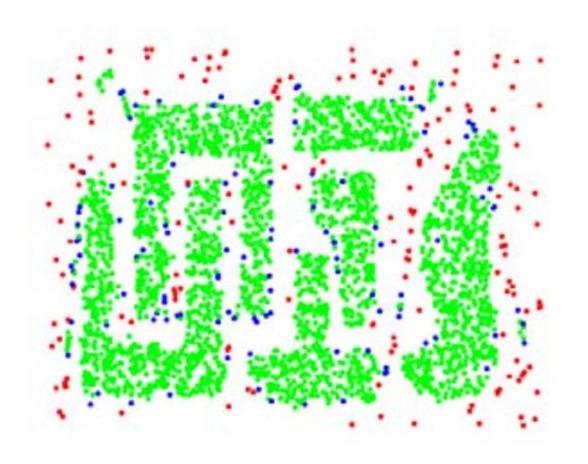
- Classify all points as core, border, or noise, using Eps and MinPts
- Eliminate noise points
- Any two core points that are within Eps of each other are put in the same cluster
- Any border point that is within Eps of a core point is put into the same cluster as the core point. (Ties may need to be resolved.)

Example



Eps = 10, MinPts = 4

Example



Eps = 10, MinPts = 4

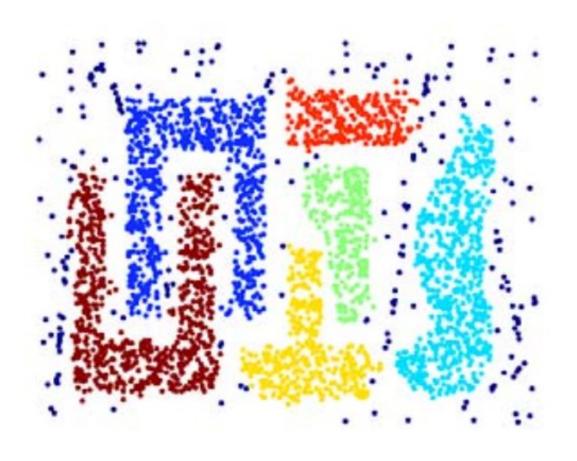
Point types:

Core

Border

Noise

Example

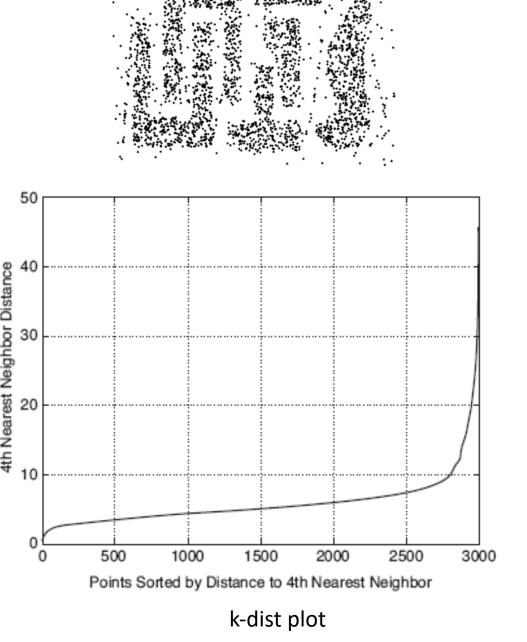


Eps = 10, MinPts = 4

Final Clustering

Determining Parameters

- k-dist: The distance from each point to it's kth nearest neighbor
- Select some k (typically based on domain knowledge, or often k=4 is used)
- Compute the *k-dist* for all data points, sort them in increasing order.
- There will be a sharp change at the value of *k-dist* that corresponds to a suitable value of *Eps*. Select this distance to be *Eps* and *k* to be *MinPts*.



Characteristics of DBSCAN

- Can handle clusters of arbitrary shapes and sizes
- Resistant to noise & outliers
- Curse of dimensionality: distance between points, and thus density, becomes less meaningful as dimensionality increases
- DBSCAN can struggle with clusters of different densities